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Trajectory Planning and Object Recognition for Robot Sensing and Control

Guest Editors:

Dr. Gang Peng

School of Artificial Intelligence
and Automation, Huazhong
University of Science and
Technology, Wuhan 430074,
China

Prof. Dr. Zhun Fan

College of Engineering, Shantou
University, Shantou 515063,
China

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Message from the Guest Editors

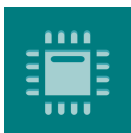
An increasing number of robots are entering our lives and industry production. Trajectory planning and object recognition are thus becoming important research hotspots, with tasks such as 3D grasping, flexible operation, and navigation depending on machine vision and multi-sensor fusion. This Special Issue aims to publish sensor-based robot control theory and engineering applications, trajectory planning and target tracking methods, and relative techniques for manipulator motion planning, mobile robot path planning, and navigation systems.

This Special Issue therefore aims to put together original research and review articles on recent advances, technologies, solutions, applications, and new challenges in the field of intelligent robot systems.



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Special Issue



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Prof. Dr. Vittorio M. N. Passaro

Dipartimento di Ingegneria
Elettrica e dell'Informazione
(Department of Electrical and
Information Engineering),
Politecnico di Bari, Via Edoardo
Orabona n. 4, 70125 Bari, Italy

Message from the Editor-in-Chief

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Sensors Editorial Office
MDPI, St. Alban-Anlage 66
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