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Vehicle Sensing and Dynamic Control

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Message from the Guest Editors

This Special Issue will address innovative research in the following areas:

The modeling and control of vehicle behavior: vehicle model, tire dynamic model, online learning and adaptation, model-based controller, linear-quadratic regulator (LQR), sliding mode control (SMC), H-infinity, and model predictive control (MPC).

Vehicle state estimation: Sensor fusion, Kalman Filtering (EKF,UKF), Recursive Least Squares (RLSs), Particle Filter, and Complementare Filter.

Active safety systems: development of intelligent control algorithms for anti-lock braking systems (ABSs), traction control systems (TCSs), electronic stability program (ESP), advanced driver assistance systems (ADASs), and the integration of related active safety features/devices into new vehicles.













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Message from the Editor-in-Chief

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