



Motion Optimization of Mechanical Structures

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Message from the Guest Editors

Motion control is a key requirement in many fields, such as engineering, micromanufacturing, biotechnology, and nanotechnology. Although great advances have been made in control engineering, it is still challenging to achieve the desired performance level in precision motion control systems. In high-dimensional manipulation platforms, this optimization is so computationally complex that traditional approaches have long focused primarily on solution feasibility rather than local optimality. Efforts to holistically understand the optimization problem and exploit the structure of the problem to increase computational efficiency begin to pay off. There are very fast constrained optimizers that use second-order information to enhance convergence and exploit the geometry of the problem much more efficiently than conventional planners.

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Message from the Editor-in-Chief

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