



# Modelling of Intra-Field Winter Wheat Crop Growth Variability Using in Situ Measurements, Unmanned Aerial Vehicle-Derived Vegetation Indices, Soil Properties, and Machine Learning Algorithms<sup>†</sup>

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**Abstract:** Crop growth and yield often vary, not only between farms, but also at the sub-field level. These variations can stem from sub-field heterogeneities of soil and plant biophysical parameters. This means that soil and plant biophysical data can be used to predict intra-field crop growth and yield variability. This study used soil properties and vegetation indices (VIs) derived from unmanned aerial vehicle (UAV) imagery as predictor variables, and monthly measurements of crop height (cm) as a response variable to predict crop growth rate in two winter wheat farms in South Africa. These datasets were analyzed using two regression models including Gaussian process regression (GPR) and ensemble learning that uses least-squares boosting (LSboost) and bagging (Bag) in MATLAB. The results showed that soil properties, particularly Ca, Mg, K and clay, were more important than VIs in predicting actual crop growth. Furthermore, GPR ( $R^2 = 0.68$  to 0.75, RMSE = 15.85 to 18.38 cm) performed slightly better than LSboost-Bag-ER ( $R^2 = 0.64$  to 0.70 and RMSE = 17.26 to 19.34 cm) in predicting crop growth. These findings are useful for crop agronomic management.

**Keywords:** wheat; UAV; vegetation indices; soil properties; Gaussian process regression; least-squares boosting and bagging regression

## 1. Introduction

Wheat is one of the most widely grown cereal crops around the world [1]. Approximately 36% of the world human population consume wheat products [2]. Due to the inevitable human population growth, there is a rapid increase in demand for cereal production and supply. Achieving food security and meeting the growing human population demands requires improvements in crop yields. Crop yield-related factors such as soils and plant biophysical parameters are spatially heterogeneous, and their complex interactions greatly affect crop growth rate and yields [3]. This heterogeneity can occur at an intra-field level; hence, it is important to investigate and understand the influence of soil properties and plant biophysical parameters on crop development and crop yields.

Soil physical and chemical properties including texture, phosphorus (P), nitrogen (N), potassium (K), sodium (Na), calcium (Ca), magnesium (Mg), and pH influence crop growth. The essential soil physio-chemical properties for crops occur in low concentration levels



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**Copyright:** © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). within arid and semi-arid environments, which has a negative impact on crop growth [4]. Other factors that impede crop development include droughts, frost, waterlogging, salinity, high temperatures, diseases, weeds, and pests infestation [4].

Vegetation indices (VIs) are good indicators of plant health, and they can be used to monitor intra-field crop stress [4]. UAVs provide high-resolution remote sensing images that can be used for the intra-field monitoring of crop fields. In addition to UAV-derived high-resolution imagery, machine learning algorithms have been used for estimating the biophysical parameters of crops [5]. This study explores kernel-based GPR and non-kernel-based LSboost-Bag-ER machine learning for modelling wheat growth variability from UAV and soil property data fusion. The aim of this study was to investigate the contribution of soil properties and UAV data to improve the modelling accuracy of intra-field crop growth variability for winter wheat. The following objectives helped to achieve the overall aim of the study: (1) investigate and understand the contribution of soil properties and VIs in the modelling of crop height of winter wheat in a dryland environment; (2) assess the prediction accuracy of a VI-only scenario, and a scenario involving the combination of Vis and soil properties, (3) compare the performances off the GPR and LSboost-Bag-ER algorithms in the modelling of intra-field wheat growth variability.

#### 2. Materials and Methods

## 2.1. Study Area

The study was conducted in two winter wheat farms (Figure 1, farms A and B) that cover about 30 and 17 hectares, respectively. The farms are in Clarens, which is in the Thabo Mofutsanyane District Municipality, Free State Province, South Africa. The fertilizer application rate was 100 kg/ha of Cireun fertilizer with the ratio N:55:P:15:K:8, and the wheat cultivar was PAN: 3161. The PAN: 3161 is a winter wheat cultivar suitable for dryland production areas of the Free State Province.



**Figure 1.** An overview of the Clarens wheat farms, and their location within the borders of Free State Province and South Africa.

#### 2.2. *Methodology*

Figure 2 is a summary of the methodology used to investigate the performances of VIs and soil properties in the prediction of crop growth variability. The soil data were used to produce interpolated and continuous distribution maps. Additionally, the UAV data was used to compute VI distribution maps. Both the soil and VI datasets were used as input variables for predicting crop height (response variable). Datasets were split into 80% training and 20% testing for GRP and LSboost-Bag-ER models. The training and testing included a VI experiment scenario and an integration of VIs and soil properties. The accuracies of the models were evaluated using mean absolute error (MAE), root mean square error (RMSE), and coefficient of determination ( $R^2$ ).



Figure 2. Methodology flowchart for intra-field crop growth modelling used in this study.

2.3. UAV Camera Properties and Vegetation Indices Used in This Study

Table 1 presents the spectral band information of MicaSense RedEdge-MX multispectral sensor with wavelength (475–840nm) and bandwidth (20–40 nm). Table 2 summarizes the VIs generated using UAV imagery bands. Figure 3a shows a multi-rotor DJI-Matrice 600 Pro UAV with a MicaSense RedEdge-MX multispectral sensor. Figure 3b depicts calibration reflectance panel (CRP) with serial number: RP04-1918107-OB and constant laboratory CRP values ranging from 0.529 to 0.536, respectively.

Table 1. Properties of UAV MicaSense RedEdge-MX series sensor.

Bands	Center Wavelength (nm)	Band Width	CRP
Blue	475	20	0.536
Green	560	20	0.536
Red	668	10	0.534
RedEdge	717	10	0.529
Near Infrared (NIR)	840	40	0.533

Vegetation Indices	Formula	References
Normalized Difference RedEdge Index (RENDI)	<u>NIR – Red Edge</u> NIR + Red Edge	[3,4]
Normalized Difference VegetationIndex (NDVI)	$\frac{NIR - Red}{NIR + Red}^{\circ}$	[3,4]
Normalized Difference Index (NDI)	RedEdge – Red RedEdge + Red	[3,4]
Ratio Vegetation Index 2 (RVI2)	Red Red RedEdge	[4]

Table 2. List of vegetation indices used in this study.



**Figure 3.** Multi-rotor DJI-Matrice 600 Pro UAV (**a**) and Calibration Reflectance Panel serial number: RP04-1918107-OB (**b**).

## 3. Results

## 3.1. Correlation Matrix

Correlation analyses showed that soil properties, in particular Ca, Mg, K and clay, were more important than VIs in representing actual crop growth (Figures 4 and 5). In addition, there was a high intra-field variability of soil properties in farm A and farm B. For instance, farm B Mg (r = 0.7), K (r = 0.61), and clay (r = 0.49) had a higher correlation with actual crop height than farm A Mg (r = 0.34), k (r = 0.33), and clay (r = 0.18), respectively.



Figure 4. Farm A; Pearson correlation matrix of VIs and soil physical and chemical properties.



Figure 5. Farm B; Pearson correlation matrix of VIs and soil physical and chemical properties.

#### 3.2. Model Evaluation

The performance statistics of GPR and LSboost-Bag-ER are summarized in Table 3. The GPR ( $R^2 = 0.68$  to 0.75, RMSE = 15.85 to 18.38 cm) model performed better than LSboost-Bag-ER ( $R^2 = 0.64$  to 0.70 and RMSE = 17.26 to 19.34 cm) for both farms. Furthermore, GPR achieved the highest accuracy when soil properties and UAV-derived VI were combined. The standalone use of VI generated the lowest modelling accuracies.

Wheat Farms	<b>Predictor Variables</b>	Model	<b>R</b> <sup>2</sup>	MAE	RMSE
Farm A	VIs	GPR	0.72	12.11	16.63
	VIs and soil properties	GPR	0.75	11.43	15.85
	VIs	LSboost-Bag-ER	0.70	12.51	17.41
	VIs and soil properties	LSboost-Bag-ER	0.70	12.65	17.26
Farm B	VIs	GPR	0.67	12.38	18.63
	VIs and soil properties	GPR	0.68	12.77	18.38
	VIs	LSboost-Bag-ER	0.64	12.66	19.35
	VIs and soil properties	LSboost-Bag-ER	0.64	13.02	19.34

Table 3. GPR and LSboost-Bag-ER model performance.

## 4. Conclusions

This study investigated the performances of in-situ soil data and monthly UAV data in predicting intra-field crop growth variability in a winter wheat farm. Findings revealed that the standalone use of VIs, as well as the combined use of VIs and soil properties can accurately predict wheat height which was used as a proxy for crop growth. The key findings from this study are associated with the efficiency of the data fusion approach to enhance modelling precision and provide useful information about the influence of soil properties on the prediction of crop height growth. This study will benefit crop agronomic management and increase potential yields. Author Contributions: Conceptualization, L.N. and C.M.; methodology; software and data preprocessing, L.N. and C.M; writing—original draft preparation, L.N.; writing—review and editing, C.M., J.G.C., A.M.K., Z.M.-M., W.M. and P.E.R.; supervision, J.G.C., C.M., A.M.K., Z.M.-M. and W.M. All authors have read and agreed to the published version of the manuscript.

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