

Article

On Momentum Operators Given by Killing Vectors Whose Integral Curves Are Geodesics

Thomas Schürmann

Jülich Supercomputing Centre, Jülich Research Centre, D-52425 Jülich, Germany; t.schurmann@icloud.com

Abstract: The paper considers momentum operators on intrinsically curved manifolds. Given that momentum operators are Killing vector fields whose integral curves are geodesics, the corresponding manifold is flat or of the compact type with positive constant sectional curvature and dimensions equal to 1, 3, or 7. Explicit representations of momentum operators and the associated Casimir element are discussed for the 3-sphere S^3 . It is verified that the structural constants of the underlying Lie algebra are proportional to $2\hbar/R$, where R is the curvature radius of S^3 and \hbar is the reduced Planck's constant. This results in a countable energy and momentum spectrum of freely moving particles in S^3 . The maximal resolution of the possible momenta is given by the de Broglie wave length, $\lambda_R = \pi R$, which is identical to the diameter of the manifold. The corresponding covariant position operators are defined in terms of geodesic normal coordinates, and the associated commutator relations of position and momentum are established.

Keywords: generalized uncertainty principle; curved spacetime; extended uncertainty principle; quantization in curved space



Citation: Schürmann, T. On Momentum Operators Given by Killing Vectors Whose Integral Curves Are Geodesics. *Physics* **2022**, *4*, 1440–1452. <https://doi.org/10.3390/physics4040093>

Received: 23 September 2022

Accepted: 17 November 2022

Published: 15 December 2022

Publisher's Note: MDPI stays neutral with regard to jurisdictional claims in published maps and institutional affiliations.



Copyright: © 2022 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

1. Introduction

Every generalization of the ordinary momentum operator in quantum mechanics to intrinsically curved manifolds strongly depends on the assumptions that are supposed to be established. Those assumptions are mostly based on the rules of quantum mechanics in Cartesian coordinates of the flat Euclidean space.

Let M be an n -dimensional smooth Riemannian manifold with metric g (occasionally denoted by $\langle \cdot, \cdot \rangle$). At every point $p \in M$, smooth manifolds admit a tangent space, $T_p M$, which is an n -dimensional real vector space. For every smooth function f on M , consider the action of differential form, df . Since df is a map on tangential space $T_p M$ at point $p \in M$, the gradient of f is defined, such that

$$df(v) = \langle v, \text{grad} f \rangle \quad (1)$$

for every smooth vector field $v \in T_p M$. From this definition, one can obtain the formal expression of the gradient vector field by

$$\text{grad} f = (\text{grad} f)^k \partial_k \quad (2)$$

with contravariant components $(\text{grad} f)^i = g^{ik} \partial_k f$, where g^{ik} are components of the inverse metric g , $\{\partial_k\}$ is the natural basis of $T_p M$, and the Latin letters denote the space indexes, $k = 1, 2, \dots, n$. With this notation, the traditional momentum operator of Euclidean space in Cartesian coordinates is given by covariant components, $\hat{p}_k f = -i\hbar(\text{grad} f)_k$, which are commonly written as

$$\hat{p}_k = -i\hbar \partial_k \quad (3)$$

in physics textbooks; here, \hbar is the reduced Planck’s constant. Following De Witt [1,2], for intrinsically curved manifolds, one can obtain more general momentum operators that also satisfy the canonical commutation relations:

$$[\hat{x}^j, \hat{p}_k] = i\hbar\delta_k^j, \tag{4}$$

$$[\hat{p}_j, \hat{p}_k] = [\hat{x}_j, \hat{x}_k] = 0. \tag{5}$$

This yields an enhanced quantization rule

$$\hat{p}_k = -i\hbar\left(\partial_k + \Gamma_{jk}^j(x)\right), \tag{6}$$

where the curvature of the manifold is reflected by the contracted Christoffel symbols $\Gamma_{jk}^j(x)$. Compared to the Cartesian quantization rule in Euclidean space (3), the ordinary partial derivative is replaced by the definition (6). An advantage of this quantization rule is its applicability to a wide range of curved spaces and the validity of the canonical commutator relations. However, in order to set up a quantum Hamiltonian, one has to keep in mind that there is no unique prescription to quantize the classical curved space Hamilton function. This is because of operator orderings of the kinetic energy term result in different, inequivalent quantum corrections, such that the correct Hamiltonian can only be confirmed empirically.

On the other hand, a particular property that is, in a sense, self-evident for the Cartesian case is that the partial derivatives ∂_k of the momentum representation in Equation (3) can be understood as *orthonormal* Killing vectors whose isometries are “translations” in Euclidean space. Strictly speaking, the integral curves of this Killing vectors (called Killing trajectories) are geodesics, especially for a particle moving in a force-free surrounding. If this idea is generalized, for instance, to a freely moving particle on the 3-sphere of radius R , then it is already known that the (geodesic) Killing trajectories are the greater circles. Hence, the structural coefficients of the underlying Lie algebra are proportional to the fraction \hbar/R and thereby different from zero; one is compelled to relax the form of canonical commutator relations (4) and (5).

One of the first attempts in this direction was proposed by Segal [3], and later developed by Śniatycki [4], Doebner, Tolar, and Nattermann [5,6]. Without going into any detail (a review can be found in Ref. [7]), a generalized momentum operator is obtained by projection onto a given smooth vector field X on M according to

$$P_X = -i\hbar\left(\nabla_X + \frac{1}{2}\text{div}X\right), \tag{7}$$

where $\text{div}X$ is the covariant divergence of vector field X . A straightforward computation (that is here omitted) yields the general commutation relation,

$$[P_X, P_Y] = -i\hbar P_{[X,Y]}, \tag{8}$$

where $[X, Y]$ denotes the commutator of two vector fields X and Y in the usual sense of the theory of manifolds [3]. In the case of a linear manifold, this vanishes for two infinitesimal translations, and Equation (8) specializes to the commutativity of the conventional linear momenta.

Apparently, operator (6) of De Witt can be recovered for vector fields X of the special form $X_k = \partial_k$, with $\Gamma_{jk}^j = \partial_k \log \sqrt{g} \equiv \Gamma_k$. However, that means $\text{div}X_k = \Gamma_k \neq 0$, such that the vector fields X_k cannot be Killing vectors if the underlying manifold is intrinsically curved.

The paper is organized as follows. In Section 2, the question of the hermiticity of momentum operators (7) is discussed. This draws attention to the special importance of Killing frame fields. A classification of manifolds with such a structure and the correspond-

ing Lie algebra are discussed in Section 3. Possible examples S^1 , S^3 , and S^7 are considered in Section 4. In Section 5, a covariant position operator on S^3 is defined in terms of geodesic normal coordinates and the associated commutator relations of position and momentum are established. Lastly, a summary and outlook are given in Section 6.

2. Hermitian Momentum Operators

Let us consider the Hilbert space of square integrable complex functions $L^2(U, \mu)$ on a compact subset, $U \subseteq M$, with smooth boundary ∂U endowed by the inner product,

$$(f, g) = \int_U d\mu f^* g, \quad f, g \in L^2(U, \mu), \tag{9}$$

where μ is the standard volume measure on $U \subseteq M$. The statement that momentum operators are Hermitian with respect to an inner product is typically based on the assumption that the boundary terms vanish after partial integration. Indeed, one cannot define a momentum operator on a bounded domain without specifying boundary conditions. In mathematical terms, choosing the boundary conditions amounts to choosing an appropriate domain for the operator. If one uses no boundary conditions, too many functions are eigenvectors, so the spectrum of P_x is the whole complex plane. On the other hand, if Dirichlet boundary conditions are imposed, the situation is too restrictive, and one cannot find an orthonormal basis. Thus, if functions $f \in L^2(U, \mu)$ are smooth on U , but constant functions at ∂U , finding a domain such that P_x is self-adjoint is a compromise to obtain an orthonormal basis of countable spectrum. In what follows, the focus is on the Hilbert spaces $\mathcal{H}_U \subset L^2(M, \mu)$, with

$$\mathcal{H}_U = \left\{ f \in C^1(U) : f|_{\partial U} = \text{const.} \right\} \tag{10}$$

At this point, one must check whether momentum operator (7) still remains Hermitian because the elements in \mathcal{H}_U are not supposed to vanish at the boundary.

Proposition 1. *Let X be a smooth and divergenceless vector field on $U \subseteq M$. Then, P_x is Hermitian on \mathcal{H}_U .*

Proof. Let $f, h \in \mathcal{H}_U$. The divergence of product fX can be written as

$$\text{div}(fX) = f \text{div}(X) + \nabla_x f. \tag{11}$$

On the other hand, one has the decomposition

$$\begin{aligned} h^* \nabla_x f &= \langle h^* X, \text{grad} f \rangle \\ &= \text{div}(fh^* X) - f \text{div}(h^* X). \end{aligned} \tag{12}$$

This equation can be integrated with respect to the volume form $d\mu$ on U as follows:

$$\begin{aligned} (h, \nabla_x f) &= - \int_U d\mu f \text{div}(h^* X) \\ &\quad + \int_{\partial U} d\mu_{\partial} f h^* \langle X, \nu \rangle. \end{aligned} \tag{13}$$

Here, Stokes' theorem is applied, where $d\mu_{\partial}$ is the volume measure with respect to the boundary ∂U and ν is the non-negative outward normal on ∂U . Now, since f and h were assumed to be constant at the boundary of U , they could be taken out of the integration in (13), and one can apply Stokes' theorem once more, such that the remaining boundary integral on the right-hand side in (13) becomes

$$\int_{\partial U} d\mu_{\partial} \langle X, \nu \rangle = \int_U d\mu \text{div} X. \tag{14}$$

With the assumption $\text{div}X = 0$, it follows

$$(h, \nabla_x f) = - \int_U d\mu f \text{div}(h^*X). \tag{15}$$

Finally, Equation (11) is applied and one gets

$$(h, \nabla_x f) + (\nabla_x h, f) = - \int_U d\mu h^* f \text{div}(X). \tag{16}$$

The term on the right-hand side can be absorbed into each term on the left-hand side with a prefactor $1/2$. By multiplication of the equation with $-i\hbar$, and after applying definition (7), one lastly obtains

$$(h, P_x f) = (P_x h, f) \tag{17}$$

for all $f, h \in \mathcal{H}_U$. □

At this point, to emphasise is that the boundary term in Equation (14) is not necessarily zero under more general conditions. This renders the divergence criterion of the vector field X necessary to ensure hermiticity. The possible manifolds that are available under these circumstances are discussed in the next Section.

3. Geodesic Momentum Operators

The classification of manifolds that are compatible to the conditions of Proposition 1 can be described with the following definition of Killing frames:

Definition 1. (Killing frame) [8]. A Riemannian manifold M has the Killing property if, in some neighborhood of each point of M , there exists an orthonormal frame, X_1, \dots, X_n , such that each X_i , $i = 1, \dots, n$ is a Killing vector field (local infinitesimal isometry). Such a frame is called a Killing frame.

Since any linear combination with constant coefficients of Killing vector fields is again a Killing vector field, a manifold has the Killing property if and only if it is always possible to find frames consisting of Killing vector fields, such that $\langle X_i, X_j \rangle = \text{const}$ for each choice of i and j . The normality condition of the definition implies that the integral curves of the isometries are geodesics, since a necessary and sufficient condition for this is that the Killing vector fields have constant length ([9], p. 349; [10], p. 50).

For instance, let x, y and r, φ denote Cartesian and polar coordinates on the Euclidean plane \mathbb{R}^2 endowed with Euclidean metric. Then, the Killing vector fields corresponding to translations and rotations are $X_1 = \partial_x$, $X_2 = \partial_y$ and $X_3 = \partial_\varphi$. Their squared vector norms are $X_1^2 = 1$, $X_2^2 = 1$ and $X_3^2 = r^2$. Killing vector fields X_1 and X_2 had a constant length on the whole plane. Their trajectories are straight lines, which are geodesics. The Killing trajectories corresponding to rotations X_3 are concentric circles around the origin. The length of X_3 is constant along the circles, but nonconstant on the whole plane. The corresponding Killing trajectories are circles that are not geodesics [11].

In the context given so far, one comes to the following.

Definition 2. (Momentum operator).

Let M be an n -dimensional Riemannian manifold with Killing frame X_1, \dots, X_n on M . The set of operators defined by

$$P_{X_k} = -i\hbar X_k, \tag{18}$$

$k = 1, \dots, n$, are called (geodesic) momentum operators in the direction X_k on M .

This definition is compatible with Equation (7), since every Killing vector field X_i is a priori divergenceless, i.e., $\text{div} X_i = 0, i = 1, \dots, n$. Moreover, the Lie bracket of two Killing fields is still a Killing field. The momentum operators (18) thus form a Lie subalgebra of vector fields on M . If M is a complete manifold, this is the Lie algebra of the translation group. In this case, the commutation relations of the Killing vector fields are given by

$$[X_i, X_j] = c_{ij}^k X_k, \tag{19}$$

where structural coefficients, c_{ij}^k , express the multiplication of pairs of vectors as a linear combination. The corresponding commutator relations of the momenta are obtained by multiplication with the physical units $(-\hbar)^2$ on both sides of Equation (19) and subsequently applying the definition (18), i.e.,

$$[P_{X_i}, P_{X_j}] = -\hbar^2 c_{ij}^k P_{X_k}, \tag{20}$$

which is compatible with the general expression (8). The associated Casimir element of this Lie algebra is given by [8]:

Proposition 2. *Let M be an n -dimensional manifold and X_1, \dots, X_n be a Killing frame on M . There is a decomposition of the Laplace–Beltrami operator, such that*

$$\sum_{j=1}^n P_{X_j}^2 = -\hbar^2 \Delta. \tag{21}$$

Proof. Vector fields, X_j , can be expressed as a linear combination of the coordinate vector fields, $\partial_\alpha = \partial/\partial x^\alpha$, with the Greek letters denoting indices of the local chart, such that

$$X_i = \zeta_i^\alpha \partial_\alpha, \tag{22}$$

where each ζ_i^α is a function. For every smooth f on M , one can write

$$\sum_j X_j^2 f = \partial_\alpha (g^{\alpha\beta} \partial_\beta f) - \delta^{ij} (\partial_\alpha \zeta_i^\alpha) \zeta_j^\beta \partial_\beta f, \tag{23}$$

which was obtained by the product rule of differentiation. On the other hand, the Laplace–Beltrami operator in the natural frame is

$$\Delta f = \partial_\alpha (g^{\alpha\beta} \partial_\beta f) + \frac{1}{\sqrt{g}} (\sqrt{g})_{,\alpha} g^{\alpha\beta} \partial_\beta f. \tag{24}$$

Now, it follows that expression (23) is equal to Equation (24) for every f if it can be shown that

$$\frac{1}{\sqrt{g}} (\sqrt{g})_{,\alpha} g^{\alpha\beta} + \delta^{ij} (\partial_\alpha \zeta_i^\alpha) \zeta_j^\beta = 0. \tag{25}$$

Using the basic property, $\nabla g = 0$, of the Levi-Civita connection together with $\delta^{ij} \zeta_i^\alpha \zeta_j^\beta = g^{\alpha\beta}$, one obtains the following condition:

$$\delta^{ij} (\nabla_{X_i} \zeta_j^\alpha) = 0. \tag{26}$$

This identity can be confirmed as follows:

$$\begin{aligned}
 0 &= \nabla_{\partial_i} g^{lk} \\
 &= \delta^{ij} \nabla_{\partial_i} (\zeta_i^l \zeta_j^k) \\
 &= \delta^{ij} \left(\operatorname{div} X_i \zeta_j^k + \nabla_{X_i} \zeta_j^k \right) \\
 &= \delta^{ij} \nabla_{X_i} \zeta_j^k
 \end{aligned}
 \tag{27}$$

and thus,

$$\sum_j X_j^2 f = \Delta f.
 \tag{28}$$

With Definition (18), in physical units, one obtains statement (21). □

According to this decomposition of the covariant Laplacian, there is no ambiguity concerning operator orderings of the kinetic energy term. Decomposition (21) is independent of the particular choice of the orthonormal basis [12]. Moreover, the commutator of Δ with the elements X_j of Lie algebra (19) is given by

$$[X_j, \Delta] = 0.
 \tag{29}$$

From a mathematical point of view, the Casimir element has a meaning only for the theory of representations, but not as an element of the Lie algebra, since the product in Equation (21) is not defined for the algebra itself. However, from linear algebra we know that the eigenvectors of a linear operator always form a basis for the vector space in question. In addition, for any Lie group, one or more of the generators can be simultaneously diagonalized using similarity transformations. The set of generators that can be diagonalized simultaneously are called Cartan generators. Thus, a suggestive and particularly easy basis for the vector space of each representation is given by the eigenvectors of the Cartan generators (see below).

The scope of the concept given so far asks for a mathematical classification of manifolds with Killing property. A Riemannian manifold having the Killing property must be locally symmetric [8]. Thus, each point of a connected Riemannian manifold having the Killing property has an open neighbourhood that is isometric to an open neighbourhood in a simply connected Riemannian symmetric space M . Then, M also has the Killing property and global Killing frames. Actually, a local Killing frame exists on M because of the given local isometry and can be extended uniquely to give a global Killing frame. The extension of each Killing vector field to a global Killing vector field is possible since the symmetry implies completeness. This extension remains orthonormal, since the Riemannian structure on M is subordinate to a real analytic Riemannian structure (cf. [13], p. 240; [14], p. 187). A simply connected Riemannian symmetric space is said to be irreducible if it is not the product of two or more Riemannian symmetric spaces. It can then be shown that any simply connected Riemannian symmetric space is a Riemannian product of irreducible ones.

Therefore, the calculations furthermore are restricted to the irreducible, simply connected Riemannian symmetric spaces. Any simply connected Riemannian symmetric space M is of one of the following three types: (i) Euclidean type: M has a vanishing curvature and is thereby isometric to a Euclidean space. (ii) Compact type: M has a non-negative (but not identically zero) sectional curvature. (iii) Noncompact type: M has a nonpositive (but not identically zero) sectional curvature. Strictly negatively curved manifolds imply that there are no nontrivial (real valued) orthonormal Killing fields.

Manifolds of constant positive curvature [8] have the Killing property only if the dimension of M is equal to 1, 3, or 7. For the spheres S^1 , S^3 and S^7 , actually, there is a global Killing frame. The construction depends essentially on the existence of a multiplication in \mathbb{R}^2 (complex numbers), \mathbb{R}^4 (quaternions), and \mathbb{R}^8 (Cayley numbers).

4. Applications

From the discussion of the previous Section and the particular role of Killing frames, it is straightforward to consider the designated cases of constant curvature manifolds S^1 , S^3 and S^7 in more detail. Let us begin with the "trivial" case S^1 .

4.1. Circle

For the circle, one can take X_1 to be the unit tangent vector field pointing, say, in the counterclockwise direction. More precisely, consider the situation of a compact subset $M \subset S^1$ embedded in \mathbb{R}^2 . The general solution of the Killing equation $\mathcal{L}_{X_1}g = 0$ on S^1 , with metric $ds^2 = \rho^2 d\varphi^2$ is given by $X_1 = \zeta^\varphi \partial_\varphi$, for $\zeta^\varphi \in \mathbb{R}$. Let $\zeta^\varphi = 1/\rho$, where ρ is the constant (hyper-)radius of the circle; then, we have $X_1^2 = 1$, and the Killing trajectory is a geodesic. The associated momentum operator is

$$P_\varphi = -i\hbar \frac{1}{\rho} \frac{\partial}{\partial \varphi}. \tag{30}$$

This operator is symmetric on any compact set $M \subset S^1$, with $f = \text{const.}$ on the boundary. In Ref. [15], it is reported that, in quantum mechanics on a circle with standard commutation relation for φ and p_φ , the uncertainty relation cannot be stronger than $\sigma_p \sigma_\varphi \geq 0$, where σ_φ and σ_p are the standard deviations of position and momentum. Indeed, this inequality is not informative at all, since a product of two nonnegative values cannot be negative. Alternatively, one is referred to the approach in Ref. [16], which is not affected by difficulties arising in defining a proper measure of position uncertainty on manifolds mentioned in Ref. [17]. By applying the substitution $r = \rho\varphi$ that corresponds to the arc-length on S^1 , the uncertainty principle of Ref. [16] is given by

$$\sigma_p \Delta r \geq \pi\hbar, \tag{31}$$

where Δr is the measure (length) of a compact domain on S^1 .

Before turning over to the case of S^3 , let us briefly mention that indeed each single component, L_1, L_2 , and L_3 of the ordinary textbook angular momentum operator \mathbf{L} is a Killing vector on S^2 and moreover, $\mathbf{L}^2 = L_1^2 + L_2^2 + L_3^2$ actually corresponds to the Laplace–Beltrami operator on S^2 . Although this seems quite promising, these vector fields are not normalizable. All vector fields on the 2-sphere are actually inappropriate for this purpose because of the hairy-ball theorem of differential topology that states that there is generally no nonvanishing continuous tangent vector field on even-dimensional n -spheres. This hinders thinking about what kind of vector fields should be appropriate for an adequate description of momentum operators on S^2 . The discussion in the literature regarding which momentum operators on S^2 might be considered to be appropriate extends up to the present day.

4.2. 3-Sphere

The 3-sphere of radius $R > 0$ can be understood as the three-dimensional hypersurface in the four-dimensional Euclidean space. This can be naturally described by the standard spherical coordinates of \mathbb{R}^4 given by [18]

$$\begin{aligned} x^1 &= R \cos \chi, \\ x^2 &= R \sin \chi \cos \theta, \\ x^3 &= R \sin \chi \sin \theta \cos \varphi, \\ x^4 &= R \sin \chi \sin \theta \sin \varphi. \end{aligned}$$

In order to cover all points of the 3-sphere with both positive and negative values of the coordinates x^i , it is necessary that $0 \leq \chi, \theta \leq \pi, 0 \leq \varphi < 2\pi$. In these coordinates, the metric of S^3 takes the form:

$$ds^2 = R^2(d\chi^2 + \sin^2\chi(d\theta^2 + \sin^2\theta d\varphi^2)). \tag{32}$$

The corresponding Killing equation is solved for the unit sphere ($R = 1$) and the following orthonormal Killing frame is selected :

$$\begin{aligned} X_1 = & \sin \theta \cos \varphi \partial_\chi & (33) \\ & + (\cot \chi \cos \theta \cos \varphi - \sin \varphi) \partial_\theta \\ & - (\cot \chi \csc \theta \sin \varphi + \cot \theta \cos \varphi) \partial_\varphi, \end{aligned}$$

$$\begin{aligned} X_2 = & \sin \theta \sin \varphi \partial_\chi & (34) \\ & + (\cot \chi \cos \theta \sin \varphi + \cos \varphi) \partial_\theta \\ & + (\cot \chi \csc \theta \cos \varphi - \cot \theta \sin \varphi) \partial_\varphi, \end{aligned}$$

$$X_3 = \cos \theta \partial_\chi - \cot \chi \sin \theta \partial_\theta + \partial_\varphi. \tag{35}$$

Case $R \neq 1$ can be obtained by dividing the right-hand side by R . The orthonormality relation $g(X_i, X_j) = \delta_{ij}$ is straightforwardly verified. The corresponding representation in Cartesian coordinates, $p = (x^1, x^2, x^3, x^4)$, of the Euclidean embedding space \mathbb{R}^4 is also determined and given by

$$X_1(p) = (-x^4, -x^3, x^2, x^1), \tag{36}$$

$$X_2(p) = (x^3, -x^4, -x^1, x^2), \tag{37}$$

$$X_3(p) = (-x^2, x^1, -x^4, x^3), \tag{38}$$

which satisfies $X_i(p) \cdot X_j(p) = \delta_{ij}$ with respect to the Euclidean scalar product. One can also check that the Lie algebra generated by $\{X_1, X_2, X_3\}$ is given by the following commutation relations,

$$[X_i, X_j] = -\frac{2}{R} \epsilon_{ijk} X_k, \tag{39}$$

where ϵ_{ijk} is the Levi-Civita symbol in three dimensions. In physical units, this can be rewritten as

$$[P_{X_i}, P_{X_j}] = \frac{2i\hbar}{R} \epsilon_{ijk} P_{X_k}. \tag{40}$$

The corresponding Hamilton operator, H , of a free particle is given by

$$H = \frac{1}{2m} \sum_{i=1}^3 P_{X_i}^2 = -\frac{\hbar^2}{2m} \Delta, \tag{41}$$

which is equal to the Casimir element of Proposition 2 in three dimensions. Thus, it follows that

$$[H, P_{X_i}] = 0 \tag{42}$$

for $i = 1, 2$, and 3 .

Alternative decompositions of the Laplacian in Equation (41) by using six (nonorthonormal) Killing vector fields instead of three were proposed in Santander et al. [19]. One essential point of the approach in Ref. [19] is that the structural coefficients of the associated

commutator relations are not constants, such that the Hamiltonian cannot be considered as a Casimir element of the operator algebra. This makes the analysis of the eigenvalues and the corresponding eigenspaces quite complicated. There seems to be no reason why one should regard a decomposition of the free Hamiltonian in terms of additional angular momenta whose integral curves are not geodesics.

Another interesting approach is the momentum-space quantization of a particle moving on the $SU(2)$ group manifold by Guerrero et al. [20]. Their algorithm also exhibits a proper and unambiguous realization of the basic operators and of the Hamiltonian, which also turns out to be the Laplace–Beltrami operator on S^3 . Although the right-invariant generators (62) in Ref. [20] are different from the Killing frame fields X_i introduced above, they are compatible with the algebra given in (39). However, the question whether the generators in Ref. [20] also form a Killing frame was not explicitly discussed.

The eigenvalues of H can be obtained by the hyperspherical harmonics on S^3 , which were discussed as part of investigations of a variety of gravitational physics problems in spaces with the topology of the 3-sphere [21,22]. According to Ref. [22], these hyperspherical harmonics on S^3 are denoted by Y^{nlm} . The integers n, l and m with $n \geq l \geq 0$ and $l \geq m \geq -l$ indicate the order of the harmonic. These harmonics are eigenfunctions of the covariant Laplacian according to

$$\Delta Y^{nlm} = -\frac{n(n+2)}{R^2} Y^{nlm}. \tag{43}$$

The corresponding energy eigenvalues E_n of H are given by

$$E_n = \frac{\hbar^2}{2m} \frac{n(n+2)}{R^2}. \tag{44}$$

for $n = 0, 1, \dots$

Now let us consider the corresponding eigenvalue spectrum of the momentum operators. Although P_{x_i} and H are commuting Hermitian operators, it is not necessarily given that each eigenbasis of H is also an eigenbasis of P_{x_i} . Indeed, most of the functions Y^{nlm} given in Equation (43) are not eigenfunctions of the momentum operator P_{x_3} . A simultaneous eigenbasis can be obtained by applying the standard textbook formalism, but on the basis of the specific algebra given by Equation (40). Rather than working with the operators P_{x_1} and P_{x_2} , it is convenient to work with the non-Hermitian linear combinations:

$$P_{\pm} = P_{x_1} \pm iP_{x_2}, \tag{45}$$

where by definition $(P_{-})^{\dagger} = P_{+}$. Using (40) and (42), it is straightforward to show that

$$[P_{+}, P_{-}] = 4\frac{\hbar}{R} P_{x_3}, \tag{46}$$

$$[P_{x_3}, P_{\pm}^k] = \pm 2k\frac{\hbar}{R} P_{\pm}^k \tag{47}$$

for $k = 0, 1, 2, \dots$. Certainly, one also has

$$[H, P_{\pm}^k] = 0. \tag{48}$$

In order to obtain a simultaneous eigenbasis of H and P_{x_3} for every fixed $n \in \mathbb{N}$, let us consider the set of orthogonal states $\{\psi_{\pm}^{nk}\}_{k=0}^n$ given by applying the "ladder" operators P_{\pm} according to

$$\psi_{\pm}^{nk} = P_{\pm}^k Y^{nn(\mp n)}, \tag{49}$$

where $k = 0, 1, \dots, n$. From this definition it follows that $P_{\pm} \psi_{\pm}^{n0} = 0$. By applying the general commutator rule (47), all of these states are eigenstates of the momentum operator, such that

$$P_{X_3} \psi_{\pm}^{nk} = \pm p_{nk} \psi_{\pm}^{nk}, \tag{50}$$

$$p_{nk} = \left(k - \frac{n}{2}\right) \frac{2\hbar}{R} \tag{51}$$

for $k = 0, 1, \dots, n$. The physical interpretation becomes straightforward by recalling that the diameter of the 3-sphere is, by definition, the maximal possible geodesic distance (πR) between two points on S^3 . If one applies the original definition of Planck’s constant $\hbar = h/2\pi$, the maximal resolution $\Delta p_{nk} = p_{nk+1} - p_{nk}$ of the possible momenta in Equation (51) is given by

$$\Delta p_{nk} = \frac{h}{\pi R}. \tag{52}$$

This unit of momentum corresponds to the de Broglie wavelength,

$$\lambda_R = \pi R, \tag{53}$$

which is identical to the diameter of the manifold. It is hard to think of higher resolutions than this.

On the other hand, the energy eigenvalues can be verified by applying commutator (48), such that we obtain the following eigenvalue equations:

$$H \psi_{\pm}^{nk} = E_n \psi_{\pm}^{nk}, \tag{54}$$

where E_n is given in Equation (44). For numerical purposes, it is helpful to know the explicit form of the initial functions ψ_{\pm}^{n0} , which are given by

$$\psi_{\pm}^{n0} = C_n \sin^n \chi \sin^n \theta e^{\mp i n \varphi}, \tag{55}$$

and the normalization constant is

$$C_n = \frac{\sqrt{2^{2n-1}(n+1)} n!(2n-1)!!}{\pi (2n)!}. \tag{56}$$

The representation of operators P_{X_1} and P_{X_2} can be obtained by inverting relation (45) in order to express them in terms of the ladder operators. This completes the brief analysis of momentum operators on S^3 .

4.3. 7-Sphere

Physical applications involving higher-dimensional spheres can be found almost exclusively in the context of $N = 1$ supergravity in 11 dimensions, which is beyond the scope of this study. Therefore, let us discuss (for information only) some aspects regarding the approach given so far. The sphere S^7 , considered to be a Riemannian manifold embedded in \mathbb{R}^8 in the usual way, is also designated to have the Killing property. Explicitly, writing points p in \mathbb{R}^8 as column vectors and identifying the tangent spaces to S^7 with hyperplanes, the vector fields $X_i(p)$, for $i = 1, \dots, 7$, are expressed in Table 1 below [8]. Since $p \cdot X_i(p) = 0$ and $X_i(p) \cdot X_j(p) = \delta_{ij}$, this gives a global orthonormal frame on S^7 , which is also a Killing frame. If \mathbb{R}^4 is embedded in \mathbb{R}^8 as a subset $x^5 = x^6 = x^7 = x^8 = 0$, the restrictions of X_1, X_2, X_3 yield a Killing frame on S^3 corresponding to the previous Section (up to sign conventions).

Table 1. Orthonormal Killing vector representation at point p on S^7 embedded in \mathbb{R}^8 .

p	$X_1(p)$	$X_2(p)$	$X_3(p)$	$X_4(p)$	$X_5(p)$	$X_6(p)$	$X_7(p)$
x^1	x^2	x^3	x^4	x^5	x^6	x^7	x^8
x^2	$-x^1$	$-x^4$	x^3	$-x^6$	x^5	$-x^8$	x^7
x^3	x^4	$-x^1$	$-x^2$	$-x^7$	x^8	x^5	$-x^6$
x^4	$-x^3$	x^2	$-x^1$	x^8	x^7	$-x^6$	$-x^5$
x^5	x^6	x^7	$-x^8$	$-x^1$	$-x^2$	$-x^3$	x^4
x^6	$-x^5$	$-x^8$	$-x^7$	x^2	$-x^1$	x^4	x^3
x^7	x^8	$-x^5$	x^6	x^3	$-x^4$	$-x^1$	$-x^2$
x^8	$-x^7$	x^6	x^5	$-x^4$	$-x^3$	x^2	$-x^1$

According to this representation, the Killing vector fields X_i of the frame bundle and their associated momentum operators P_{X_i} on S^7 can be well expressed in terms of hyperspherical coordinates. Moreover, the calculation of eigenvectors and eigenvalues of the corresponding Laplace–Beltrami operator on S^7 is straightforward and can be obtained by projecting harmonic fields in Euclidean \mathbb{R}^8 onto the unit sphere.

5. Covariant Position Operator on S^3

Lastly, some remarks concerning the notion of position operators. Segal defines [3] the position operator Q as follows: if f is a general function on M , then Q_f is defined as the operation of multiplication by f . For real f, g , operators Q_f and Q_g are Hermitian, such that there is no difficulty in verifying the commutation relations:

$$[Q_f, P_X] = i\hbar Q_{Xf}, \tag{57}$$

$$[Q_f, Q_g] = 0. \tag{58}$$

In order to define a covariant position operator on S^3 , it is straight to consider the notion of geodesic distance. Since no point of S^3 is particularly distinguished, without loss of generality, the origin in hyperspherical coordinates is chosen by the "North Pole" $p = (R, 0, 0, 0) \in \mathbb{R}^4$. Geodesic normal coordinates, $q = (q^1, q^2, q^3)$, around this origin are such that every element of S^3 can be reached by the exponential map

$$\exp_p : T_p S^3 \longrightarrow S^3; \tag{59}$$

$$\exp_p(X) = p \cos\left(\frac{s}{R}\right) + R \sin\left(\frac{s}{R}\right) \frac{X(p)}{\|X(p)\|}, \tag{60}$$

with $X = q^i X_i \in T_p S^3$ and the geodesic distance function,

$$s : q \longrightarrow s = \|q\|, \tag{61}$$

where $\|\cdot\|$ is the Euclidean norm in $T_p S^3$. Let

$$X_q = \hat{q}^k X_k \tag{62}$$

be the corresponding tangent vector field in the unit direction, $\hat{q} = q/s$. Then, applying the smooth transition map from the hyperspherical chart to geodesic coordinates,

$$\begin{aligned} q^1 &= R\chi \sin \theta \cos \varphi, \\ q^2 &= R\chi \sin \theta \sin \varphi, \\ q^3 &= R\chi \cos \theta, \end{aligned}$$

it follows via straightforward computation that X_q can be expressed by

$$X_q = \frac{\partial}{\partial s}. \quad (63)$$

Accordingly, a geodesic position operator on S^3 is defined by Q_s , and commutator (57) can be expressed by

$$[Q_s, P_{x_q}] = i\hbar. \quad (64)$$

A covariant uncertainty relation of position and momentum that is compatible with this approach and was applied to S^3 can be found in Refs. [23,24]. A further generalization to the case of S^7 is also possible, but it is left to further considerations.

6. Summary and Outlook

The description of momentum operators by Killing vector fields is a long-established concept in momentum-space quantization on differentiable manifolds. On the other hand, from classical general relativity, the fundamental importance of geodesic trajectories as a key concept of the theory is also known.

If one wishes to unify these two concepts together in the approach of momentum-space quantization, this leads to the notion of Killing frames on manifolds. These special frames are implicitly part of the classical Cartan formalism. However, the orthonormal frame fields in the Cartan approach are usually not provided as Killing vector fields. A fundamental principle in the Cartanian approach is to choose the moving frames most suitable to the particular problem. Some consequences for the possible manifolds arising from the additional Killing frame property were discussed.

The present study is mainly focused on irreducible, simply connected Riemannian manifolds. However, many product manifolds can be constructed out of these irreducible components which also possess the Killing frame property. A straightforward example would be the temporally infinite but spatially finite case $\mathbb{R} \times S^3$. A further generalization is the case of 11-dimensional supergravity with $\mathbb{R} \times S^3 \times S^7$. Such possibilities and the extended analysis of the associated spin connections are the subject of further investigations.

Funding: This research received no external funding.

Data Availability Statement: Not applicable.

Conflicts of Interest: The author declares no conflict of interest.

References

1. DeWitt, B.S. Point transformations in quantum mechanics. *Phys. Rev.* **1952**, *85*, 653–661. [CrossRef]
2. DeWitt, B.S. Dynamical theory in curved spaces. I. A review of the classical and quantum action principles. *Rev. Mod. Phys.* **1957**, *29*, 377–397. [CrossRef]
3. Segal, I.E. Quantization of nonlinear systems. *J. Math. Phys.* **1960**, *1*, 468–488. [CrossRef]
4. Śniatycki, J. *Geometric Quantization and Quantum Mechanics*; Springer: New York, NY, USA, 1980. [CrossRef]
5. Doebner, H.-D.; Nattermann, P. Borel quantization: kinematics and dynamics. *Acta Phys. Polon.* **1996**, *27*, 2327–2339.
6. Doebner, H.-D.; Šťovíček, P.; Tolar, J. Quantization of kinematics on configuration manifolds. *Rev. Math. Phys.* **2001**, *13*, 1–47. [CrossRef]
7. Ali, S.T.; Engliš, M. Quantization Methods: A guide for physicists and analysts. *Rev. Math. Phys.* **2005**, *17*, 391–490. [CrossRef]
8. D’Atri, J.E.; Nickerson, H.K. The existence of special orthonormal frames. *J. Differ. Geom.* **1968**, *2*, 393–409. [CrossRef]
9. Schouten, J.A. *Ricci-Calculus*; Springer: Berlin/Heidelberg, Germany, 1954. [CrossRef]
10. Yano, K. *The Theory of Lie Derivatives and Its Applications*; North-Holland Publishing Co.: Amsterdam, The Netherlands, 1955. Available online: <https://archive.org/details/theoryofliederiv029601mbp/> (accessed on 15 November 2022).
11. Katanaev, M.O. Killing vector fields and a homogeneous isotropic universe. *Phys.-Usp.* **2016**, *59*, 689–700. . UFNe.2016.05.037808 [CrossRef]
12. Hall, B.C. *Lie Groups, Lie Algebras, and Representations*; Springer International Publishing Switzerland: Cham, Switzerland, 2015. [CrossRef]

13. Wolf, J.A. *Spaces of Constant Curvature*; AMS Chelsea Publishing: Providence, RI, USA, 2011. Available online: <https://bookstore.ams.org/chel-372-h> (accessed on 15 November 2022).
14. Helgason, S. *Differential Geometry and Symmetric Spaces*; Academic Press: New York, NY, USA, 1978. Available online: <https://www.sciencedirect.com/bookseries/pure-and-applied-mathematics/vol/80/suppl/C> (accessed on 15 November 2022).
15. Golovnev, A.V.; Prokhorov, L.V. Uncertainty relations in curved spaces. *J. Phys. A Math. Gen.* **2004**, *37*, 2765–2775. [[CrossRef](#)]
16. Schürmann, T.; Hoffmann, I. A closer look at the uncertainty relation of position and momentum. *Found. Phys.* **2009**, *39*, 958. [[CrossRef](#)]
17. Trifonov, D.A. Position uncertainty measures on the sphere. In *Proceedings of the Fifth International Conference on Geometry, Integrability and Quantization, Varna, Bulgaria, 5–12 June 2003*; Mladenov, I.M., Hirshfeld, A.S.; Eds.; SOFTEX: Sofia, Bulgaria, 2003; pp. 211–224. [[CrossRef](#)]
18. Griffiths, J.B.; Podolský, J. *Exact Space-Times in Einstein's General Relativity*; Cambridge University Press: New York, NY, USA, 2009. [[CrossRef](#)]
19. Cariñena, J.F.; Rañada, M.F.; Santander, M. The quantum free particle on spherical and hyperbolic spaces: A curvature dependent approach. II. *J. Math. Phys.* **2012**, *53*, 102109. [[CrossRef](#)]
20. Guerrero, J.; López-Ruiz, F.F.; Aldaya, V. $SU(2)$ -particle sigma model: momentum-space quantization of a particle on the sphere S^3 . *J. Phys. A Math. Theor.* **2020**, *53*, 145301. [[CrossRef](#)]
21. Lachièze-Rey, M.; Caillerie, S. Laplacian eigenmodes for spherical spaces. *Class. Quant. Grav.* **2005**, *22*, 695–708. [[CrossRef](#)]
22. Lindblom, L.; Taylor, N.W.; Zhang, F. Scalar, vector and tensor harmonics on the three-sphere. *Gen. Rel. Grav.* **2017**, *49*, 140. [[CrossRef](#)]
23. Schürmann, T. Uncertainty principle on 3-dimensional manifolds of constant curvature. *Found. Phys.* **2018**, *48*, 716–725 [[CrossRef](#)]
24. Schürmann, T. On the uncertainty principle in Rindler and Friedmann spacetimes. *Eur. Phys. J. C* **2020**, *80*, 141. [[CrossRef](#)]