



Article On Pantograph Problems Involving Weighted Caputo Fractional Operators with Respect to Another Function

Saeed M. Ali D

Department of Basic Engineering Sciences, College of Engineering, Imam Abdulrahman Bin Faisal University, P.O. Box 1982, Dammam 34151, Saudi Arabia; smsali@iau.edu.sa

Abstract: In this investigation, weighted *psi*-Caputo fractional derivatives are applied to analyze the solution of fractional pantograph problems with boundary conditions. We establish the existence of solutions to the indicated pantograph equations as well as their uniqueness. The study also takes into account the situation where $\psi(x) = x$. With the aid of Banach's and Krasnoselskii's classic fixed point results, we have established a the qualitative study. Different values of $\psi(x)$ and w(x) are discussed as special cases that are relevant to our current results. Additionally, in light of our findings, we provide a more general fractional system with the weighted ψ -Caputo-type that takes into account both the new problems and certain previously existing, related problems. Finally, we give two illustrations to support and validate the outcomes.

Keywords: fractional pantograph system; Caputo fractional operator; fixed point theorem

MSC: 34A08; 34A12; 47H10

1. Introduction

Fractional calculus (FC) is an extension of the integer order differential and integral. In recent years, a large number of definitions of FC have been developed in response to practical problem modeling requirements, such as Riemann–Liouville, Caputo, Hadamard, Erdelyi–Kober, and Hilfer versions, see [1–4].

In the past few decades, many classes of fractional differential equations (FDEs) have undergone in-depth research and analysis. For instance, concepts concerning the existence and uniqueness of solutions have been mentioned in [5–7] and references therein.

An essential aspect of the theory of FDEs was addressed by the qualitative characteristics of solutions. The area that was previously described has been thoroughly explored for classical differential equations. Nevertheless, there are a number of FDE-related problems and systems that need further research and analysis. Utilizing THE Riemann–Liouville (Caputo, Hilfer) fractional operator, and other fractional operators, the existence and uniqueness have been closely examined; for more information, see [8–13] and the references therein.

Several authors have studied generalized FDs, and their applications. For instance, Kilbas et al. [2] provided some interesting ψ -Riemann–Liouville FD characteristics. Almedia [14] described the ψ -Caputo FD. In the Hilfer sense, Sousa and Oliveira [15] presented another generalization. A singular kernel can be found in the aforementioned derivatives. The substitution of a nonsingular kernel for a singular kernel has resulted in the presentation of new types of FDs by certain authors; for more information, [16–18]. According to [19–22], nonlocal FDs with nonsingular kernels have been shown to be a respectable tool for simulating actual problems in a variety of engineering and scientific fields.

Another significant class of FDEs are the pantograph equations (PEs), which have not been investigated as completely in the context of innovative FDs. PEs are a crucial class of delay equations that provide changes in the dependant worth at a previous time [23],



Citation: Ali, S.M. On Pantograph Problems Involving Weighted Caputo Fractional Operators with Respect to Another Function. *Fractal Fract.* 2023, 7, 559. https://doi.org/ 10.3390/fractalfract7070559

Academic Editor: Agnieszka B. Malinowska

Received: 17 June 2023 Revised: 12 July 2023 Accepted: 16 July 2023 Published: 19 July 2023



Copyright: © 2023 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). and are used in deterministic circumstances. A pantograph is essentially a measuring and drawing tool. Currently, electric trains and electric cells employ this device [24–26]. In 1971, Ockendon and Taylor [27] investigated what is now known as PE, or how electric flow is collected by the pantograph of an electric train. Since then, numerous researchers have investigated it and used it in numerous mathematical and scientific domains, including pharmacology, electrodynamics, probability, number theory, and more (see [27–29] and the references therein). Several authors have thought carefully about the analytical and numerical approaches of the following delay equation

$$\omega'(\mathbf{x}) = a\omega(\mathbf{x}) + b\omega(\lambda \mathbf{x}), \ \mathbf{x} \in [0, T], \ 0 < \lambda < 1,$$

$$\omega(0) = \omega_0,$$
 (1)

see [30–32]. The PEs were accurately studied in [33,34]. The following nonlinear PE

$$\begin{cases} \omega'(\mathsf{x}) = \mathsf{g}(\mathsf{x}, \omega(\mathsf{x}), \omega(\lambda_1 \mathsf{x}), ..., \omega(\lambda_m \mathsf{x})), \ \mathsf{x} \in [0, T] \\ \omega(0) = \omega_0, \ 0 < \lambda_1 < ... < \lambda_m < 1 \end{cases}$$
(2)

has been studied by Liu et al. [35]. In contrast, Sezer et al. [36] considered the nonlinear neutral PE:

$$\begin{cases} \omega'(\mathbf{x}) = \mathbf{g}(\mathbf{x}, \omega(\mathbf{x}), \omega(\lambda \mathbf{x}), \omega'(\lambda \mathbf{x})), \ \mathbf{x} > 0, \\ \omega(0) = \omega_0, \ 0 < \lambda < 1. \end{cases}$$
(3)

Because of the importance of fractional PE in many fields, it has been the subject of many studies. For instance, the following Caputo pantograph problem

$$\begin{cases} {}^{C}\mathbb{D}_{0^{+}}^{\vartheta}\varpi(\mathsf{x}) = \mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda\mathsf{x})), \ \mathsf{x} \in [0,T], \ 0 < \vartheta < 1\\ \varpi(0) = \varpi_{0} + h(\varpi) \end{cases}$$
(4)

was the subject of discussion by Balachandran et al. [37].

In contrast, Agarwal [38], Kolokoltsov [39] and Jarad et al. [40] discussed weighted FDs first, second, and third, respectively. Due to the importance of FDEs in many fields of research, some recent studies addressed the existence of solutions to FDEs; for instance, Abdo et al. [41,42], discussed the following problems ${}_{0}^{C} \mathfrak{D}_{\psi,w}^{\nu} | \varpi(x) = g(x, \varpi(x)), 0 < x \leq 1$, $\varpi(0) = \varpi_{0}$, and ${}_{0}^{PC} \mathfrak{D}_{\psi}^{\nu} \varpi(x) = g(x, \varpi(x), \varpi(\lambda_{1}x), ..., \varpi(\lambda_{m}x)), 0 \leq x \leq b, \varpi(0) = \varpi_{0} + h(\varpi)$, where $0 < \nu < 1$, ${}_{0}^{C} \mathfrak{D}_{\psi,w}^{\nu} |$ and ${}_{0}^{PC} \mathfrak{D}_{\psi}^{\nu} |$ are the ψ -Caputo FD and piecewise Caputo FD, respectively. In this regard, Al-Rafai and Jarrah [43], obtained the uniqueness result of the Cauchy problem involving the [w, ψ]-Caputo–Fabrizio FD with ψ and w which are monotone and weight functions, respectively.

Motivated by the aforementioned works, this paper focuses on novel classes of weighted pantograph FDEs:

$$\begin{cases} {}^{C}_{a}\mathfrak{D}^{\nu}_{\mathsf{x},\mathsf{w}(\mathsf{x})}\,\mathscr{O}(\mathsf{x}) = \mathsf{g}(\mathsf{x},\mathscr{O}(\mathsf{x}),\mathscr{O}(\lambda_{1}\mathsf{x}),...,\mathscr{O}(\lambda_{m}\mathsf{x})),\,\mathsf{x}\in\mho,\\ {}^{\mathcal{O}}_{a}(a) = \mathscr{O}_{a},\,\mathscr{O}(b) = \mathscr{O}_{b}, \end{cases}$$
(5)

and

۲

$$\begin{cases} {}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,\varpi(\mathsf{x}) = \mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda_{1}\mathsf{x}),...,\varpi(\lambda_{m}\mathsf{x})),\,\mathsf{x}\in\mho,\\ {}^{\mathcal{O}}_{a}(a) = \varpi_{a},\,\varpi(b) = \varpi_{b}, \end{cases}$$
(6)

where $1 < \nu < 2$, $x \in \mathcal{V} := [a, b]$, $0 < \lambda_i < 1$, for $i = 1, 2, ..., m, m \in \mathbb{N}$, $g : \mathcal{O} \times \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}$ is a given function, ${}^C\mathfrak{D}^{\nu}_{x,w(x)}$ and ${}^C\mathfrak{D}^{\nu}_{\psi(x),w(x)}$ are weighted Caputo FD and ψ -weighted Caputo FD, respectively, $\psi(x)$ and w(x) are monotone and weight functions, respectively, with $w, \psi \in C^1(\mathcal{O})$ with $w, w', \psi' > 0$ on \mathcal{O} , and $\omega_a, \omega_b \in \mathbb{R}$.

The presented problems have not been addressed yet. By selecting particular kernel functions in the derivative and weight functions, some current results that concentrate on the novel fractional operators, including [40,43–46], are enhanced and supplemented.

Remark 1.

(i) If $\psi(x) = x$, then problem (6) is reduced to problem (5).

(*ii*) Problem (6) with $\omega(0) = \omega_0 + h(\omega)$ reduces to the problem (4) if $\psi(x) = x$, w(x) = 1 and m = 1, see [37].

(iii) Problem (6) with $\psi(x) = x$, w(x) = 1, v = 1 and $\omega(0) = \omega_0$ reduces to the Cauchy problem (2), as shown in [35].

(iv) Our current results for the problem (6) stay available on problem (5).

(v) Our current problems cover a wide range of problems which uses less general derivatives operators by make use of different values of ψ and w.

The following is an outline of the paper's content. Some basic results about weighted FC are presented in Section 2. In Section 3, we present our main results for problems (5) and (6). Section 4 gives a more general pantograph problem. Section 5 offers two examples illustration that demonstrates the validity of the theories. The conclusions of the work are included in the final section.

2. Primitive Results

We first give some notions and definitions of the generalized weighted fractional calculus, and then we state some fundamental results and remarks. Let $\mho := [a, b]$, $a < b < \infty$. The spaces $\mathcal{L}^1_{\psi}(\mho)$, $\mathcal{C}^1_{\psi}(\mho)$ and $\mathcal{AC}^n_{\psi}(\mho)$ are defined as in [46].

Definition 1 ([46]). Let $0 < v, \rho \in \mathcal{L}^1_{\psi}(\mathcal{V})$ and $\psi, w \in \mathcal{C}^1_{\psi}(\mathcal{V})$. The weighted ψ -RL fractional integral is defined as

$${}^{RL}_{a}\mathfrak{I}^{
u}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,
ho(\mathsf{x})=rac{1}{\Gamma(
u)\mathsf{w}(\mathsf{x})}\int_{a}^{\mathsf{x}}\psi'(artheta)(\psi(\mathsf{x})-\psi(artheta))\mathsf{w}(artheta)
ho(artheta)dartheta.$$

Definition 2 ([46]). Let 0 < v, and $\rho \in AC^n$. The weighted ψ -Caputo FD is defined as

$${}^{C}_{a}\mathfrak{D}^{\nu;\psi}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,\rho(\mathsf{x}) = {}^{RL}_{a}\mathfrak{I}^{n-\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,\left(\mathfrak{D}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\right)^{n}\rho(\mathsf{x}),$$

where $\mathfrak{D}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\rho(\mathsf{x}) := \frac{1}{\mathsf{w}(\mathsf{x})\psi'(\mathsf{x})}\frac{d}{d\mathsf{x}}(\mathsf{w}(\mathsf{x})\rho(\mathsf{x})) = \frac{1}{\psi'(\mathsf{x})}\left[\frac{d}{d\mathsf{x}} + \frac{\mathsf{w}'(\mathsf{x})}{\mathsf{w}(\mathsf{x})}\right]\rho(\mathsf{x}).$

Lemma 1 ([46]). Let $\rho \in C^n_{\psi}(\mho)$. Then

$$^{C}\mathfrak{D}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu}\mathfrak{I}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu}\rho(\mathbf{x}) = \rho(\mathbf{x}),$$

$${}_{a}\mathfrak{I}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu}\operatorname{a}^{C}\mathfrak{D}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu}\rho(\mathbf{x}) = \rho(\mathbf{x}) - \sum_{k=0}^{n-1}\frac{\left[\psi(\mathbf{x}) - \psi(a)\right]^{k}}{k!}\frac{\mathbf{w}(a^{+})}{\mathbf{w}(\mathbf{x})}\lim_{\mathbf{x}\to a^{+}}\left(\mathfrak{D}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}\right)^{k}\rho(\mathbf{x}).$$

Lemma 2 ([46]). The weighted RL and Caputo operators of ρ with respect to ψ are given as follows:

$${}^{RL}_{a} \mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \frac{\left[\psi(\mathsf{x}) - \psi(a)\right]^{\beta}}{\mathsf{w}(\mathsf{x})} = \frac{\Gamma(\beta+1)}{\Gamma(\beta-\nu+1)} \frac{\left[\psi(\mathsf{x}) - \psi(a)\right]^{\beta-\nu}}{\mathsf{w}(\mathsf{x})}, \ \nu \in \mathbb{C}, Re(\beta) > -1;$$

$${}^{C}_{a} \mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \frac{E_{\nu} \left(\lambda \left[\psi(\mathsf{x}) - \psi(a)\right]^{\nu}\right)}{\mathsf{w}(\mathsf{x})} = \lambda \frac{E_{\nu} \left(\lambda \left[\psi(\mathsf{x}) - \psi(a)\right]^{\nu}\right)}{\mathsf{w}(\mathsf{x})}, \ \lambda \in \mathbb{C}, Re(\beta) > -1,$$

where E_{ν} is the Mittag–Leffler function.

We will require Krasnoselskii's fixed point theorem [47] and Banach's contraction map [48] for our upcoming analysis.

3. Main Results

Here, we provide some qualitative analyses of pantograph problems (5) and (6).

3.1. Basic Result

Lemma 3. Let $0 < \nu < 1$, and $\omega \in AC$. Then the Cauchy problem

$$\begin{cases} {}^{C}_{a} \mathfrak{D}^{\nu}_{\psi(\mathbf{x}), \mathbf{w}(\mathbf{x})} \, \boldsymbol{\omega}(\mathbf{x}) = f(\mathbf{x}), \\ \boldsymbol{\omega}(a) = \boldsymbol{\omega}_{a} \end{cases}$$
(7)

has the unique solution

$$\omega(\mathsf{x}) = \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\omega_a + \frac{1}{\Gamma(\nu)\mathsf{w}(\mathsf{x})}\int_a^\mathsf{x}\psi'(\vartheta)(\psi(\mathsf{x}) - \psi(\vartheta))\mathsf{w}(\vartheta)f(\vartheta)d\vartheta, \,\mathsf{x}\in\mho.$$
(8)

Proof. Assume ω satisfies the first equation of (7). From Lemma 1, we have

$${}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, \, {}_{a}^{C}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\, \mathscr{O}(\mathsf{x}) = \mathscr{O}(\mathsf{x}) - \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\mathscr{O}(a). \tag{9}$$

Further, from (7), we obtain

$${}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, \, {}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, \mathcal{O}(\mathsf{x}) = {}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} f(\mathsf{x}).$$
(10)

By (9) and (10), we find that

/ \

$$\varpi(\mathsf{x}) = \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} \varpi(a) + {}_a \mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} f(\mathsf{x}).$$

Hence, by initial condition $\omega(a) = \omega_a$, we obtain

$$\boldsymbol{\omega}(\mathbf{x}) = \frac{\mathbf{w}(a)}{\mathbf{w}(\mathbf{x})}\boldsymbol{\omega}_a + {}_a\boldsymbol{\mathfrak{I}}^{\boldsymbol{\nu}}_{\boldsymbol{\psi}(\mathbf{x}),\mathbf{w}(\mathbf{x})}f(\mathbf{x}),$$

which is (8).

Conversely, if ω satisfies (8), then by Lemmas 2 and 1, we have

$${}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,\varpi(\mathsf{x}) = {}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,\frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\,\varpi_{a} + {}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,f(\mathsf{x}) = {}^{C}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,{}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\,f(\mathsf{x}) = f(\mathsf{x}).$$

Moreover, the condition $\omega(a) = \omega_a$ is directly achieved by taking $x \to a$ of the Equation (8). \Box

Lemma 4. Let $1 < \nu < 2$, $0 < \lambda < 1$ and assume that g is a continuous. Then the following ψ -weighted pantograph FDE

$$\begin{aligned}
& C \\
& a \\
& \psi(x), w(x) \\
& \omega(a) = \omega_a, \ \omega(b) = \omega_b,
\end{aligned}$$
(11)

has the unique solution

Proof. Assume ω satisfies the first equation of (11). It follows from Lemma 1 that

$${}_{a}\mathfrak{I}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\nu}{}_{a}^{C}\mathfrak{D}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\nu}\varpi(\mathsf{x}) = \varpi(\mathsf{x}) - \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\varpi(a) - [\psi(\mathsf{x}) - \psi(a)] \\ \times \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\lim_{\mathsf{x}\to a}\frac{1}{\psi'(\mathsf{x})}\left[\frac{d}{d\mathsf{x}} + \frac{\mathsf{w}'(\mathsf{x})}{\mathsf{w}(\mathsf{x})}\right]\varpi(\mathsf{x}).$$
(13)

By (11), we have

$${}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, {}^{C}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, \varpi(\mathsf{x}) = {}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \, \mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda\mathsf{x})).$$
(14)

From (13) and (14), we have

$$\begin{split} \boldsymbol{\omega}(\mathsf{x}) &= \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})}\boldsymbol{\omega}(a) + [\boldsymbol{\psi}(\mathsf{x}) - \boldsymbol{\psi}(a)] \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} \left(\frac{\boldsymbol{\omega}'(a)}{\boldsymbol{\psi}'(a)} + \frac{\boldsymbol{\omega}(a)\mathsf{w}'(a)}{\boldsymbol{\psi}'(a)\mathsf{w}(a)} \right) \\ &+ a \mathfrak{I}_{\boldsymbol{\psi}(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\boldsymbol{\nu}} \mathsf{g}(\mathsf{x},\boldsymbol{\omega}(\mathsf{x}),\boldsymbol{\omega}(\lambda\mathsf{x})) \end{split}$$

By boundary conditions $\omega(a) = \omega_a$ and $\omega(b) = \omega_b$, we get

$$\begin{split} \varpi_b &= \frac{\mathsf{w}(a)}{\mathsf{w}(b)} \varpi_a + [\psi(b) - \psi(a)] \frac{\varpi_a}{\mathsf{w}(b)} \frac{\mathsf{w}'(a)}{\psi'(a)} \\ &+ {}_a \mathfrak{I}^{\nu}_{\psi(b),\mathsf{w}(b)} \mathsf{g}(b, \varpi(b), \varpi(\lambda b)), \end{split}$$

which implies

$$\omega_{a} = \frac{1}{\chi} \bigg(\omega_{b} - \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \int_{a}^{b} \psi'(\vartheta) (\psi(b) - \psi(\vartheta))^{\nu-1} \mathsf{w}(\vartheta) \mathsf{g}(\vartheta, \omega(\vartheta), \omega(\lambda\vartheta)) d\vartheta \bigg).$$

Hence,

$$\begin{split} \varpi(\mathsf{x}) &= \frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} \frac{1}{\chi} \Big(\varpi_b - {}_a \mathfrak{I}^{\nu}_{\psi(b),\mathsf{w}(b)} \,\mathsf{g}(b, \varpi(b), \varpi(\lambda b)) \Big) \\ &+ [\psi(\mathsf{x}) - \psi(a)] \frac{1}{\mathsf{w}(\mathsf{x})} \frac{\frac{1}{\chi} \Big(\varpi_b - {}_a \mathfrak{I}^{\nu}_{\psi(b),\mathsf{w}(b)} \,\mathsf{g}(b, \varpi(b), \varpi(\lambda b)) \Big) \mathsf{w}'(a)}{\psi'(a)} \\ &+ {}_a \mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \,\mathsf{g}(\mathsf{x}, \varpi(\mathsf{x}), \varpi(\lambda \mathsf{x})) \end{split}$$

which is (12).

Conversely, if ω satisfies (12), then by Lemma 1, we have

$$\begin{aligned} {}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\varpi(\mathsf{x}) &= & \frac{1}{\chi}{}^{C}_{a}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} + [\psi(\mathsf{x}) - \psi(a)]\frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathsf{x})}\right) \\ & & \left(\varpi_{b} - {}_{a}\mathfrak{I}^{\nu}_{\psi(b),\mathsf{w}(b)}\mathsf{g}(b,\varpi(b),\varpi(\lambda b))\right) \\ & + & {}^{C}\mathfrak{D}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} {}_{a}\mathfrak{I}^{\nu}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda \mathsf{x})) \\ & = & \mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda \mathsf{x})). \end{aligned}$$

Moreover, $\omega(a) = \omega_a$ and $\omega(b) = \omega_b$. \Box

Hence, we can deduce the next corollary:

Corollary 1. Let $1 < \nu < 2$ and $0 < \lambda_i < 1$, for i = 1, 2, ..., m. Assume that g is continuous function. The problem (6) is equivalent to

where χ is defined as Lemma 4.

Regarding Corollary 1, we define an operator $\mathcal{K} : \mathcal{AC} \to \mathcal{AC}$ by

$$(\mathcal{K}\varpi)(\mathsf{x}) = \frac{1}{\chi} \left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} + [\psi(\mathsf{x}) - \psi(a)] \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathsf{x})} \right) \left(\varpi_b - \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \right)$$
$$\times \int_a^b \psi'(\vartheta)(\psi(b) - \psi(\vartheta))^{\nu-1} \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi(\vartheta), \varpi(\lambda_1\vartheta), ..., \varpi(\lambda_m\vartheta))) d\vartheta \right)$$
$$+ \frac{1}{\Gamma(\nu)\mathsf{w}(\mathsf{x})} \int_a^\mathsf{x} \psi'(\vartheta)(\psi(\mathsf{x}) - \psi(\vartheta))^{\nu-1} \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi(\vartheta), \varpi(\lambda_1\vartheta), ..., \varpi(\lambda_m\vartheta))) d\vartheta$$
(16)

The following assumptions are necessary in order to prove the main results:

- $\begin{aligned} (\mathbf{P}_1) \ |\mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\varpi_1,...,\varpi_{m+1}) \mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\overline{\varpi}_1,...,\overline{\varpi}_{m+1})| &\leq L_{\mathsf{g}}\sum_{j=1}^{m+1} |\varpi_j \overline{\varpi}_j|, \, \forall \mathsf{x} \in \mho, \, L_{\mathsf{g}} > 0, \\ & \varpi_j, \overline{\varpi}_j \in \mathbb{R}. \end{aligned}$
- $(\mathbf{P}_2) |\mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x}, \omega_1, ..., \omega_{m+1})| \le n_\mathsf{g} + m_\mathsf{g} \sum_{j=1}^{m+1} |\omega_j|, \forall \mathsf{x} \in \mho, \omega_j \in \mathbb{R}, n_\mathsf{g}, m_\mathsf{g} > 0.$

For convenience, let us set $\omega_{\lambda}(\mathsf{x}) := (\omega(\lambda_1\mathsf{x}), ..., \omega(\lambda_m\mathsf{x})), \psi_{\mathsf{x},a}^{\nu} := (\psi(\mathsf{x}) - \psi(a))^{\nu}, \psi_{\mathsf{x},a}^{\nu-1} := \psi'(\vartheta)(\psi(\mathsf{x}) - \psi(\vartheta))^{\nu-1},$

$$\begin{split} \Lambda &:= \left| \frac{\mathsf{w}(a)}{\mathsf{w}(b)} \right| + [\psi_{b,a}] \left| \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(b)} \right|, \\ \Pi &:= \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} L_{\mathsf{g}}(m+1) \left(\frac{\Lambda}{|\chi|} + 1 \right), \\ \Delta &:= \left(\frac{\Lambda}{|\chi|} + 1 \right) \mathsf{w}_0 \mathsf{g}_0 \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} + \frac{\Lambda}{|\chi|} |\varpi_b|. \end{split}$$

3.2. Existence Results

Theorem 1. Assume that $(wg) : \Im \times \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}$ is a continuous and satisfies the condition (\mathbf{P}_1) with

$$\left[\frac{\Lambda}{\chi}+1\right]\frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)}(m+1)L_{g}<1,$$
(17)

then the ψ -weighted pantograph problem (6) has a unique solution.

Proof. Let $\max_{x \in \mathcal{O}}(w(x)g(x, 0, ..., 0)) = w_0g_0$ and choosing $r \ge \frac{\Delta}{1-\Pi}$, where $\Pi > 0$. First, we prove that $\mathcal{KB}_r \subset \mathcal{B}_r$, where $\mathcal{B}_r = \{ \varpi \in \mathcal{AC} : \|\varpi\| \le r \}$. Indeed, for $\varpi \in \mathcal{B}_r$, we have

$$\begin{split} |(\mathcal{K}\varpi)(\mathbf{x})| &\leq \frac{1}{|\mathcal{X}|} \left(\left| \frac{\mathbf{w}(a)}{\mathbf{w}(\mathbf{x})} \right| + [\psi_{\mathbf{x},a}] \left| \frac{\mathbf{w}'(a)}{\psi'(a)\mathbf{w}(\mathbf{x})} \right| \right) \left(|\varpi_b| + \frac{1}{\Gamma(\nu)|\mathbf{w}(b)|} \\ &\times \int_a^b \psi_{b,\theta}^{\nu-1}[| \ \mathbf{w}(\theta)\mathbf{g}(\theta, \varpi(\theta), \varpi_\lambda(\theta)) - \mathbf{w}(\theta)\mathbf{g}(\theta, 0, 0)| + |\mathbf{w}(\theta)\mathbf{g}(\theta, 0, 0)|] d\theta \\ &+ \frac{1}{\Gamma(\nu)|\mathbf{w}(\mathbf{x})|} \int_a^{\mathbf{x}} \psi_{\mathbf{x},\theta}^{\nu-1}[| \ \mathbf{w}(\theta)\mathbf{g}(\theta, \varpi(\theta), \varpi_\lambda(\theta)) - \mathbf{w}(\theta)\mathbf{g}(\theta, 0, 0)| \\ &+ |\mathbf{w}(\theta)\mathbf{g}(\theta, 0, 0)|] d\theta \\ &\leq \frac{\Lambda}{|\mathcal{X}|} \left(|\varpi_b| + \frac{1}{\Gamma(\nu)|\mathbf{w}(b)|} \int_a^b \psi_{b,\theta}^{\nu-1}[L_{\mathbf{g}}(|\varpi| + |\varpi_1| + ... + |\varpi_m|) + \mathbf{w}_{0}\mathbf{g}_0] \ d\theta \right) \\ &+ \frac{1}{\Gamma(\nu)|\mathbf{w}(\mathbf{x})|} \int_a^{\mathbf{x}} \psi_{\mathbf{x},\theta}^{\nu-1}[L_{\mathbf{g}}(|\varpi| + |\varpi_1| + ... + |\varpi_m|) + \mathbf{w}_{0}\mathbf{g}_0] \ d\theta \\ &\leq \frac{\Lambda}{|\mathcal{X}|} \left(|\varpi_b| + [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] \frac{1}{\Gamma(\nu)|\mathbf{w}(b)|} \int_a^b \psi_{b,\theta}^{\nu-1} d\theta \right) \\ &+ [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] \frac{1}{\Gamma(\nu)|\mathbf{w}(\mathbf{x})|} \int_a^{\mathbf{x}} \psi_{\mathbf{x},\theta}^{\nu-1} d\theta \\ &= \frac{\Lambda}{|\mathcal{X}|} \left(|\varpi_b| + [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] a\mathcal{I}_{\psi(b),\mathbf{w}(b)}^{\nu} \mathbf{w}^{-1}(b) \right) \\ &+ [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] a\mathcal{I}_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu} \mathbf{w}^{-1}(\mathbf{x}) \\ &\leq \frac{\Lambda}{|\mathcal{X}|} \left(|\varpi_b| + [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \right) \\ &+ [L_{\mathbf{g}}(m+1)r + \mathbf{w}_{0}\mathbf{g}_0] \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \\ &= \Pi r + \Delta \leq r. \end{split}$$

Next, we show that \mathcal{K} is contraction in \mathcal{AC} . For $\omega(x), \overline{\omega}(x) \in \mathcal{AC}$ and for each $x \in \mho$, we have

$$\begin{split} |(\mathcal{K}\varpi)(\mathbf{x}) - (\mathcal{K}\overline{\varpi})(\mathbf{x})| \\ &\leq \frac{1}{\chi} \left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathbf{x})} + \psi_{\mathbf{x},a} \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathbf{x})} \right) \\ &\times \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \int_{a}^{b} \psi_{b,\vartheta}^{\nu-1} |\mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi, \varpi_{\lambda}) - \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \overline{\varpi}, \overline{\varpi}_{\lambda})| d\vartheta \\ &+ \frac{1}{\Gamma(\nu)\mathsf{w}(\mathbf{x})} \int_{a}^{\mathbf{x}} \psi_{\mathbf{x},\vartheta}^{\nu-1} |\mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi, \varpi_{\lambda}) - \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \overline{\varpi}, \overline{\varpi}_{\lambda})| d\vartheta \\ &\leq \frac{\Lambda}{\chi} \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \int_{a}^{b} \psi_{b,\vartheta}^{\nu-1} L_{\mathsf{g}} \sum_{j=1}^{m+1} |\varpi_{j}(\vartheta) - \overline{\varpi}_{j}(\vartheta)| d\vartheta \\ &+ \frac{1}{\Gamma(\nu)\mathsf{w}(\mathbf{x})} \int_{a}^{\mathbf{x}} \psi_{\mathbf{x},\vartheta}^{\nu-1} L_{\mathsf{g}} \sum_{j=1}^{m+1} |\varpi_{j}(\vartheta) - \overline{\varpi}_{j}(\vartheta)| d\vartheta \\ &= \frac{\Lambda}{\chi} a \mathfrak{I}_{\psi(b),\mathsf{w}(b)}^{\nu} \mathsf{w}^{-1}(b) L_{\mathsf{g}} \sum_{j=1}^{m+1} |\varpi_{j}(b) - \overline{\varpi}_{j}(b)| \\ &+ a \mathfrak{I}_{\psi(\mathbf{x}),\mathsf{w}(\mathbf{x})}^{\nu} \mathsf{w}^{-1}(\mathbf{x}) L_{\mathsf{g}} \sum_{j=1}^{m+1} |\varpi_{j}(\mathbf{x}) - \overline{\varpi}_{j}(\mathbf{x})| \\ &\leq \left[\frac{\Lambda}{\chi} + 1\right] \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{\mathsf{g}} ||\varpi - \overline{\varpi}||. \end{split}$$

 \mathcal{K} is a contraction in accordance with condition (17), and thanks to the Banach fixed point theorem, \mathcal{K} has a unique fixed point, which is an unique solution to (6). \Box

Then, in order to prove existence results, we apply Krasnoselskii's fixed point theorem [47].

Theorem 2. Let wg : $\mathfrak{O} \times \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}$ be a continuous satisfying (P₂). If

$$\frac{\Lambda}{\chi} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{\mathsf{g}} < 1, \tag{18}$$

Then the ψ *-weighted pantograph problem (6) has a least one solution.*

Proof. From (16), we define the operators $\mathcal{K}_1, \mathcal{K}_2 : \mathcal{AC} \to \mathcal{AC}$ by

$$\begin{aligned} (\mathcal{K}_{1}\varpi)(\mathsf{x}) &= \frac{1}{\chi} \left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} + \psi_{\mathsf{x},a} \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathsf{x})} \right) \\ &\times \left(\varpi_{b} - \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \int_{a}^{b} \psi_{b,\vartheta}^{\nu-1} \mathsf{w}(\vartheta) \mathsf{g}(\vartheta, \varpi(\vartheta), \varpi_{\lambda}(\vartheta)) d\vartheta \right), \, \mathsf{x} \in \mho, \end{aligned}$$

and

$$\mathcal{K}_{2}\omega)(\mathsf{x}) = \frac{1}{\Gamma(\nu)\mathsf{w}(\mathsf{x})} \int_{a}^{\mathsf{x}} \psi_{\mathsf{x},\vartheta}^{\nu-1}\mathsf{w}(\vartheta)\mathsf{g}(\vartheta,\varpi(\vartheta),\varpi_{\lambda}(\vartheta))d\vartheta, \,\mathsf{x}\in\mho,$$

where $(\mathcal{K}_1 \omega + \mathcal{K}_2 \omega)(\mathsf{x}) = (\mathcal{K} \omega)(\mathsf{x})$. Let us define $\mathcal{B}_{\overline{r}} = \{\omega \in \mathcal{AC} : \|\omega\| \le \overline{r}\}$, we fix

$$\bar{r} \geq \frac{n_{\mathsf{g}} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \left(\frac{\Lambda}{\chi}+1\right) + \frac{\Lambda}{\chi} |\omega_{b}|}{1 - m_{\mathsf{g}}(m+1) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \left(\frac{\Lambda}{\chi}+1\right)}.$$
(19)

For $\omega, \omega \in \mathcal{B}_{\overline{r}}$, we find that

(

$$\begin{split} |(\mathcal{K}_{1}\omega + \mathcal{K}_{2}\omega)(\mathbf{x})| &\leq |(\mathcal{K}_{1}\omega)(\mathbf{x})| + |(\mathcal{K}_{2}\omega)(\mathbf{x})| \\ &\leq \frac{\Lambda}{\chi} \left(|\omega_{b}| + \frac{1}{\Gamma(\nu)\mathbf{w}(b)} \int_{a}^{b} \psi_{b,\theta}^{\nu-1} |\mathbf{w}(\theta)\mathbf{g}(\theta, \omega(\theta), \omega_{\lambda}(\theta))| d\theta \right) \\ &\quad + \frac{1}{\Gamma(\nu)\mathbf{w}(\mathbf{x})} \int_{a}^{x} \psi_{\mathbf{x},\theta}^{\nu-1} |\mathbf{w}(\theta)\mathbf{g}(\theta, \omega(\theta), \omega_{\lambda}(\theta))| d\theta \\ &\leq \frac{\Lambda}{\chi} \left(|\omega_{b}| + \frac{1}{\Gamma(\nu)\mathbf{w}(b)} \int_{a}^{b} \psi_{b,\theta}^{\nu-1} \left(n_{\mathbf{g}} + m_{\mathbf{g}} \sum_{j=1}^{m+1} |\omega_{j}(\theta)| \right) d\theta \right) \\ &\quad + \frac{1}{\Gamma(\nu)\mathbf{w}(\mathbf{x})} \int_{a}^{x} \psi_{\mathbf{x},\theta}^{\nu-1} \left(n_{\mathbf{g}} + m_{\mathbf{g}} \sum_{j=1}^{m+1} |\omega_{j}(\theta)| \right) d\theta \\ &\leq \frac{\Lambda}{\chi} \left(|\omega_{b}| + \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \right) ||\omega_{j}|| \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \right) \\ &\quad + \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \right) ||\omega_{j}|| \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \\ &\leq \frac{\Lambda}{\chi} \left(|\omega_{b}| + \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \overline{r} \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \right) \\ &\quad + \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \overline{r} \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \\ &\leq \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \overline{r} \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \\ &\leq \left(n_{\mathbf{g}} + m_{\mathbf{g}}(m+1) \overline{r} \right) \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \left(\frac{\Lambda}{\chi} + 1 \right) + \frac{\Lambda}{\chi} |\omega_{b}| \\ &= m_{\mathbf{g}}(m+1) \overline{r} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \left(\frac{\Lambda}{\chi} + 1 \right) + n_{\mathbf{g}} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} \left(\frac{\Lambda}{\chi} + 1 \right) + \frac{\Lambda}{\chi} |\omega_{b}|. \end{split}$$

Due to (19), we deduce that $\|\mathcal{K}_1 \omega + \mathcal{K}_2 \overline{\omega}\| \leq \overline{r}$.

Further, \mathcal{K}_1 is a contraction operator. Indeed, for each $\omega(x)$, $\overline{\omega}(x) \in \mathcal{AC}$, and for each $x \in \mathcal{V}$, we have

$$\begin{split} &|\mathcal{K}_{1}\varpi(\mathbf{x}) - \mathcal{K}_{1}\overline{\varpi}(\mathbf{x})| \\ &\leq \frac{1}{\chi} \left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathbf{x})} + \psi_{\mathsf{x},a} \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathbf{x})} \right) \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \\ &\times \int_{a}^{b} \psi_{b,\vartheta}^{\nu-1} | \ \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi(\vartheta), \varpi_{\lambda}(\vartheta)) - \mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \overline{\varpi}(\vartheta), \overline{\varpi}_{\lambda}(\vartheta)) | d\vartheta \\ &\leq \frac{\Lambda}{\chi} \frac{1}{\Gamma(\nu)\mathsf{w}(b)} \int_{a}^{b} \psi_{b,\vartheta}^{\nu-1} L_{\mathsf{g}} \sum_{j=1}^{m+1} | \varpi_{j}(\vartheta) - \overline{\varpi}_{j}(\vartheta) | d\vartheta \\ &= \frac{\Lambda}{\chi}_{a} \Im_{\psi(b),\mathsf{w}(b)}^{\nu} \mathsf{w}^{-1}(b) L_{\mathsf{g}} \sum_{j=1}^{m+1} | \varpi_{j}(b) - \overline{\varpi}_{j}(b) | \\ &\leq \frac{\Lambda}{\chi} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{\mathsf{g}} \| \varpi - \overline{\varpi} \|. \end{split}$$

From (17), \mathcal{K}_1 is a contraction.

Continuity of g, w and ψ implies that \mathcal{K}_2 is continuous. Further, \mathcal{K}_2 is uniformly bounded on $\mathcal{B}_{\overline{r}}$ as

$$|(\mathcal{K}_{2}\omega)(\mathsf{x})| \leq (n_{\mathsf{g}} + m_{\mathsf{g}}(m+1)\overline{r})\frac{\psi_{b,a}^{*}}{\Gamma(\nu+1)}.$$

Now, we prove that \mathcal{K}_2 is compact. In fact

$$\begin{split} \left| (\mathcal{K}_{1} \varpi)'(\mathsf{x}) \right| &\leq D_{\mathsf{w}} \left(\frac{1}{\Gamma(\nu)\mathsf{w}(\mathsf{x})} \int_{a}^{\mathsf{x}} \psi_{\mathsf{x},\vartheta}^{\nu-1} |\mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi(\vartheta), \varpi_{\lambda}(\vartheta))| d\vartheta \right) \\ &= D_{\mathsf{w}\,a} \mathfrak{I}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\nu} \mathsf{g}(\mathsf{x}, \varpi(\mathsf{x}), \varpi_{\lambda}(\mathsf{x})) \\ &= a \mathfrak{I}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\nu-1} \mathsf{g}(\mathsf{x}, \varpi(\mathsf{x}), \varpi_{\lambda}(\mathsf{x})) \\ &= \frac{1}{\Gamma(\nu-1)\mathsf{w}(\mathsf{x})} \int_{a}^{\mathsf{x}} \psi_{\mathsf{x},\vartheta}^{\nu-2} |\mathsf{w}(\vartheta)\mathsf{g}(\vartheta, \varpi(\vartheta), \varpi_{\lambda}(\vartheta))| d\vartheta \\ &\leq (n_{\mathsf{g}} + m_{\mathsf{g}}(m+1)\overline{r}) \frac{\psi_{b,a}^{\nu-1}}{\Gamma(\nu)}. \end{split}$$

Let $\omega \in \mathcal{B}_{\overline{r}}$, and $x \in \mho$ with $x_{\varepsilon} < x_{\delta} \in \mho$. Then

$$|(\mathcal{K}_{1}\varpi)(\mathsf{x}_{\delta}) - (\mathcal{K}_{1}\varpi)(\mathsf{x}_{\epsilon})| = \int_{\mathsf{x}_{\epsilon}}^{\mathsf{x}_{\delta}} |(\mathcal{K}_{1}\varpi)'(\vartheta)| d\vartheta \leq (n_{\mathsf{g}} + m_{\mathsf{g}}(m+1)\overline{r})\frac{\psi_{b,a}^{\nu-1}}{\Gamma(\nu)}(\mathsf{x}_{\delta} - \mathsf{x}_{\epsilon}).$$

Thus, $|(\mathcal{K}_1 \varpi)(\mathsf{x}_{\delta}) - (\mathcal{K}_1 \varpi)(\mathsf{x}_{\epsilon})| \to 0$ as $\mathsf{x}_{\epsilon} \to \mathsf{x}_{\delta}$. Thus, \mathcal{K}_1 is equicontinuous on $\mathcal{B}_{\overline{r}}$. Hence, \mathcal{K}_1 is relatively compact on $\mathcal{B}_{\overline{r}}$ as a result of the steps that came before, and according to the Arzela–Ascoli theorem, \mathcal{K}_1 has at least one fixed point. The Krasnoselskii theorem [47] shows that there is at least one solution to the problem (6). \Box

Remark 2. When $\psi(x) = x$, the results on the problem (6) still hold true for the problem (5).

4. Weighted ψ -Caputo Fractional System

Consider a more general problem as

$$\begin{cases} {}^{C}_{a}\mathfrak{D}^{\nu_{k}}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}\mathfrak{\omega}_{k}(\mathsf{x}) = \mathsf{g}_{k}(\mathsf{x},\mathfrak{\omega}_{1,\lambda_{i}}(\mathsf{x}),\mathfrak{\omega}_{2,\lambda_{i}}(\mathsf{x}),...,\mathfrak{\omega}_{n,\lambda_{i}}(\mathsf{x})), \,\mathsf{x} \in \mathfrak{V} := [a,b],\\ {}^{\mathcal{O}}_{k}(a) = \mathfrak{\omega}_{a}^{k}, \, \mathfrak{\omega}_{k}(b) = \mathfrak{\omega}_{b}^{k}, \, , \, k = 1,...,n, \, i = 1,...,m \end{cases}$$
(20)

where $1 < \nu_k < 2$, ${}^{C}_{a} \mathfrak{D}^{\nu_k}_{\psi(x),w(x)}$ is the generalized weighted Caputo FD of order ν_i and

It is possible to write the system (20) as

$$\begin{cases} {}^{C}_{a} \mathfrak{D}^{Y}_{\psi(x),w(x)} \mathcal{V}(x) = \mathsf{G}(x, \mathcal{V}_{\lambda}(x)), \ x \in \mathfrak{V}, \\ \mathcal{V}(a) = \mathcal{V}_{a}, \ \mathcal{V}(b) = \mathcal{V}_{b}, \end{cases}$$
(21)

where

$$\mathcal{V}(\mathbf{x}) = \begin{bmatrix} \omega_{1}(\mathbf{x}) \\ \omega_{2}(\mathbf{x}) \\ \vdots \\ \omega_{n}(\mathbf{x}) \end{bmatrix}, \quad \mathsf{G}(\mathbf{x}, \mathcal{V}_{\lambda}(\mathbf{x})) = \begin{bmatrix} \mathsf{g}_{1}(\mathbf{x}, \omega_{1,\lambda_{i}}(\mathbf{x})) \\ \mathsf{g}_{2}(\mathbf{x}, \omega_{2,\lambda_{i}}(\mathbf{x})) \\ \vdots \\ \mathsf{g}_{n}(\mathbf{x}, \omega_{n,\lambda_{i}}(\mathbf{x})) \end{bmatrix}, \quad \text{and}$$
$$\mathcal{V}(a) = \begin{bmatrix} \omega_{1}(a) \\ \omega_{2}(a) \\ \vdots \\ \omega_{n}(a) \end{bmatrix}, \quad \mathcal{V}(b) = \begin{bmatrix} \omega_{1}(b) \\ \omega_{2}(b) \\ \vdots \\ \omega_{n}(b) \end{bmatrix}, \quad \mathcal{V}_{c} = \begin{bmatrix} \omega_{c}^{1} \\ \omega_{c}^{2} \\ \vdots \\ \omega_{c}^{n} \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} v_{1} \\ v_{2} \\ \vdots \\ v_{n} \end{bmatrix}.$$

By using Corollary 1, the system (21) has the following solution

$$\mathcal{V}(\mathsf{x}) = \frac{1}{\chi} \left(\frac{\mathsf{w}(a)}{\mathsf{w}(\mathsf{x})} + [\psi(\mathsf{x}) - \psi(a)] \frac{\mathsf{w}'(a)}{\psi'(a)\mathsf{w}(\mathsf{x})} \right) \\ \times \left(\mathcal{V}_b - {}_a \mathfrak{I}^{\mathsf{Y}}_{\psi(b),\mathsf{w}(b)} \mathsf{G}(b, \mathcal{V}_\lambda(b)) \right) \\ + {}_a \mathfrak{I}^{\mathsf{Y}}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})} \mathsf{G}(\mathsf{x}, \mathcal{V}_\lambda(\mathsf{x})),$$
(22)

where χ is defined as Lemma 4. We can write the system (22) as

$$\begin{cases} \omega_{1}(\mathbf{x}) = \begin{cases} \frac{1}{\chi} \left(\frac{\mathbf{w}(a)}{\mathbf{w}(\mathbf{x})} + [\psi(\mathbf{x}) - \psi(a)] \frac{\mathbf{w}'(a)}{\psi'(a)\mathbf{w}(\mathbf{x})} \right) \\ \times \left(\omega_{b}^{1} - a \Im_{\psi(b),\mathbf{w}(b)}^{\nu_{1}} \mathbf{g}_{1}(b, \omega_{1}(b), \omega_{1}(\lambda_{1}b), ..., \omega_{1}(\lambda_{m}b)) \right) \\ + a \Im_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu_{1}} \mathbf{g}_{1}(\mathbf{x}, \omega_{1}(\mathbf{x}), \omega_{1}(\lambda_{1}\mathbf{x}), ..., \omega_{1}(\lambda_{m}\mathbf{x}), \\ \frac{1}{\chi} \left(\frac{\mathbf{w}(a)}{\mathbf{w}(\mathbf{x})} + [\psi(\mathbf{x}) - \psi(a)] \frac{\mathbf{w}'(a)}{\psi'(a)\mathbf{w}(\mathbf{x})} \right) \\ \times \left(\omega_{b}^{2} - a \Im_{\psi(b),\mathbf{w}(b)}^{\nu_{2}} \mathbf{g}_{2}(b, \omega_{2}(b), \omega_{2}(\lambda_{1}b), ..., \omega_{2}(\lambda_{m}b)) \right) \\ + a \Im_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu_{2}} \mathbf{g}_{2}(\mathbf{x}, \omega_{2}(\mathbf{x}), \omega_{2}(\lambda_{1}\mathbf{x}), ..., \omega_{2}(\lambda_{m}\mathbf{x}), \\ \vdots \\ \omega_{n}(\mathbf{x}) = \begin{cases} \frac{1}{\chi} \left(\frac{\mathbf{w}(a)}{\mathbf{w}(\mathbf{x})} + [\psi(\mathbf{x}) - \psi(a)] \frac{\mathbf{w}'(a)}{\psi'(a)\mathbf{w}(\mathbf{x})} \right) \\ \times \left(\omega_{b}^{n} - a \Im_{\psi(b),\mathbf{w}(b)}^{\nu_{n}} \mathbf{g}_{n}(b, \omega_{n}(b), \omega_{n}(\lambda_{1}b), ..., \omega_{n}(\lambda_{m}b)) \right) \\ + a \Im_{\psi(\mathbf{x}),\mathbf{w}(\mathbf{x})}^{\nu_{n}} \mathbf{g}_{n}(\mathbf{x}, \omega_{n}(\mathbf{x}), \omega_{n}(\lambda_{1}\mathbf{x}), ..., \omega_{n}(\lambda_{m}\mathbf{x}). \end{cases} \end{cases}$$
(23)

Banach's and Krasnoselskii's fixed point theorem can be used to present the following theorems without the need for proofs.

Theorem 3. Assume that $(wg_k) : \Im \times \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}$ is a continuous and satisfies

 $(P_3) |\mathsf{w}(\mathsf{x})\mathsf{g}_k(\mathsf{x}, \varpi_1, ..., \varpi_{m+1}) - \mathsf{w}(\mathsf{x})\mathsf{g}_k(\mathsf{x}, \overline{\varpi}_1, ..., \overline{\varpi}_{m+1})| \leq L_{\mathsf{g}_k} \sum_{j=1}^{m+1} |\varpi_j - \overline{\varpi}_j|, \text{ for } k = 1, ...,$ $n, x \in \mathcal{V}, L_{\mathbf{g}_k} > 0, \omega_i, \overline{\omega}_i \in \mathbb{R}$ with

$$\left[rac{\Lambda}{\chi}+1
ight]rac{\psi_{b,a}^{
u_k}}{\Gamma(
u_k+1)}(m+1)L_{\mathsf{g}_k}<1.$$

Then the ψ *-weighted pantograph system* (21) *has a unique solution.*

Theorem 4. Let $wg_k : \mathfrak{O} \times \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}$ be a continuous satisfying

 $(P_4) |\mathsf{w}(\mathsf{x})\mathsf{g}_k(\mathsf{x}, \varpi_1, ..., \varpi_{m+1})| \leq n_{\mathsf{g}_k} + m_{\mathsf{g}_k} \sum_{j=1}^{m+1} |\varpi_j|, \text{ for } k = 1, ..., n, \ \mathsf{x} \in \ \mho, \ \varpi_j \in \ \mathbb{R},$ $n_{\mathsf{g}_k}, m_{\mathsf{g}_k} > 0$

$$\frac{\Lambda}{\chi} \frac{\psi_{b,a}^{\nu_k}}{\Gamma(\nu_k+1)} (m+1) L_{\mathsf{g}_k} < 1.$$

Then the ψ *-weighted pantograph system* (21) *has a least one solution.*

Remark 3. Theorems 3 and 4 for the nonlinear system (21) in light of the formula (22) or (23) can be proved using the same procedure as in the preceding sections.

5. Examples

To illustrate our acquired results, we provide two examples.

Example 1. Consider the following weighted ψ -Caputo-type problem

$$\begin{cases} C \mathfrak{D}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\nu} \middle| \mathfrak{O}(\mathsf{x}) = \mathsf{g}(\mathsf{x},\mathfrak{O}(\mathsf{x}),\mathfrak{O}(\lambda_{1}\mathsf{x}),\mathfrak{O}(\lambda_{2}\mathsf{x})), \ 0 \le \mathsf{x} \le 1, \\ \mathfrak{O}(0) = 1, \ \mathfrak{O}(1) = 2, \end{cases}$$
(24)

where m = 2, $g(x, \omega(x), \omega(\lambda_1 x), \omega(\lambda_2 x)) = \frac{\cos \left|\omega(x) + \omega(\frac{x}{4})\right| + \sin \left|\omega(\frac{x}{6})\right|}{10 + x} + \frac{x+1}{10}$, $\nu = \frac{5}{4}$, $\psi(x) = e^{\frac{x}{3}}$, $w(x) = e^{-x}$, a = 0, b = 1, $\omega_0 = 1$, $\omega_1 = 2$, $\lambda_1 = \frac{1}{4}$, and $\lambda_2 = \frac{1}{6}$. (1) Application of Theorem 1: For $x \in [0, 1]$, and $\omega, \omega \in [0, \infty)$, we have

$$\begin{split} &|\operatorname{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda_{1}\mathsf{x}),\varpi(\lambda_{2}\mathsf{x})) - \mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\omega(\mathsf{x}),\omega(\lambda_{1}\mathsf{x}),\omega(\lambda_{2}\mathsf{x}))| \\ &\leq \frac{1}{e^{\mathsf{x}}(10+\mathsf{x})} \mid \varpi(\mathsf{x}) - \omega(\mathsf{x})| + \left| \varpi(\frac{\mathsf{x}}{4}) - \omega(\frac{\mathsf{x}}{4}) \right| + \left| \varpi(\frac{\mathsf{x}}{6}) - \omega(\frac{\mathsf{x}}{6}) \right| \\ &\leq \frac{1}{10} \sum_{j=1}^{3} \left| \varpi_{j} - \omega_{j} \right| \end{split}$$

where $|\omega_1(x) - \omega_1(x)| = |\omega(x) - \omega(x)|$, $|\omega_2(x) - \omega_2(x)| = |\omega(\frac{x}{4}) - \omega(\frac{x}{4})|$ and $|\omega_3(\mathbf{x}) - \omega_3(\mathbf{x})| = |\omega(\frac{\mathbf{x}}{4}) - \omega(\frac{\mathbf{x}}{4})|.$

Thus, (P_1) holds with $L_g = \frac{1}{10}$. Moreover, the condition (17) holds. Indeed,

$$\left[\frac{\Lambda}{\chi}+1\right]\frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)}(m+1)L_{g} = \left[\frac{3e^{\frac{4}{3}}-2e}{e-3e^{\frac{4}{3}}}+1\right]\frac{\left[e^{\frac{1}{3}}-1\right]^{\frac{4}{3}}}{\Gamma(\frac{7}{4})}\frac{3}{10} < 1$$

5

where $\Lambda = 3e^{\frac{4}{3}} - 2e$ and $\chi = e - 3e^{\frac{4}{3}}$. Thus, Theorem 1 shows that (24) has a unique solution on [0,1].

(II) Application of Theorem 2: For $x \in [0, 1]$, and $\omega \in [0, \infty)$, we have

$$\begin{aligned} |\operatorname{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda_{1}\mathsf{x}),\varpi(\lambda_{2}\mathsf{x}))| &\leq \quad \frac{\left|\varpi(\mathsf{x}) + \varpi(\frac{\mathsf{x}}{4})\right| + \left|\varpi(\frac{\mathsf{x}}{6})\right|}{e^{\mathsf{x}}(10+\mathsf{x})} + \frac{\mathsf{x}+1}{10} \\ &\leq \quad \frac{1}{5} + \frac{1}{10}\sum_{j=1}^{3} |\varpi_{j}|, \end{aligned}$$

where $|\omega_1(\mathsf{x})| = |\omega(\mathsf{x})|, |\omega_2(\mathsf{x})| = |\omega(\frac{\mathsf{x}}{4})|$ and $|\omega_3(\mathsf{x})| = |\omega(\frac{\mathsf{x}}{4})|.$ Thus, (P₂) holds with $n_g = \frac{1}{5}$ and $m_g = \frac{1}{10}$. Also,

$$\frac{\Lambda}{\chi} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{\mathsf{g}} = \left[\frac{3e^{\frac{4}{3}} - 2e}{e - 3e^{\frac{4}{3}}} \right] \frac{\left[e^{\frac{1}{3}} - 1\right]^{\frac{5}{4}}}{\Gamma(\frac{5}{4})} \frac{3}{10} < 1$$

Consequently, (P₂) holds with $n_g = \frac{1}{5}$ and $m_g = \frac{1}{10}$. Thus, Theorem 2's presumptions are all satisfied. As a result, (24) has a solution on [0, 1].

Example 2. Consider the following weighted ψ -Caputo-type problem

$$\begin{cases} C_{0}\mathfrak{D}_{\psi(\mathsf{x}),\mathsf{w}(\mathsf{x})}^{\frac{4}{3}} \middle| \varpi(\mathsf{x}) = \mathsf{g}(\mathsf{x}, \varpi(\mathsf{x}), \varpi(\frac{1}{2}\mathsf{x})), \ 0 \le \mathsf{x} \le \frac{1}{2}, \\ \varpi(0) = 1, \ \varpi(\frac{1}{2}) = 2, \end{cases}$$
(25)

where m = 1, $g(x, \omega(x), \omega(\lambda_1 x)) = e^{-x^{\nu}}\omega(x) + e^{-x^{\nu}}\omega(\frac{x}{2}) + \frac{1}{8}$, $\nu = \frac{4}{3}$, $\psi(x) = \frac{x}{3}$, $w(x) = \frac{e^{-x}}{4}$, $a = 0, b = \frac{1}{2}, \omega_0 = 1, \omega_1 = 2, and \lambda_1 = \frac{1}{2}.$ (1) Application of Theorem 1: For $x \in [0, 1]$, and $\omega, \omega \in [0, \infty)$, we have

$$\begin{split} &|\operatorname{w}(\mathsf{x})\mathsf{g}(\mathsf{x}, \boldsymbol{\omega}(\mathsf{x}), \boldsymbol{\omega}(\lambda_{1}\mathsf{x})) - \mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x}, \boldsymbol{\omega}(\mathsf{x}), \boldsymbol{\omega}(\lambda_{1}\mathsf{x}))| \\ &\leq \frac{1}{4e^{\mathsf{x}}} \left(\frac{1}{e^{\mathsf{x}^{\boldsymbol{\nu}}}} | \; \boldsymbol{\omega}(\mathsf{x}) - \boldsymbol{\omega}(\mathsf{x})| + \frac{1}{e^{\mathsf{x}^{\boldsymbol{\nu}}}} \left| \boldsymbol{\omega}(\frac{\mathsf{x}}{2}) - \boldsymbol{\omega}(\frac{\mathsf{x}}{2}) \right| \right) \\ &\leq \frac{1}{4} \Big(\; |\boldsymbol{\omega}(\mathsf{x}) - \boldsymbol{\omega}(\mathsf{x})| + \left| \boldsymbol{\omega}(\frac{\mathsf{x}}{2}) - \boldsymbol{\omega}(\frac{\mathsf{x}}{2}) \right| \Big). \end{split}$$

Thus, (P_1) holds with $L_g = \frac{1}{4}$. Moreover, the condition (17) holds. Indeed,

$$\left[\frac{\Lambda}{\chi} + 1\right] \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{g} = 0.098424 < 1.$$

where $\Lambda = \frac{73}{72\sqrt{e}}$ and $\chi = \frac{1}{\sqrt{e}} - \frac{1}{72\sqrt{e}}$. Thus, Theorem 1 shows that (25) has a unique solution on $[0, \frac{1}{2}].$

(II) Application of Theorem 2: For $x \in [0, \frac{1}{2}]$, and $\omega \in [0, \infty)$, we have

$$\begin{aligned} |\mathsf{w}(\mathsf{x})\mathsf{g}(\mathsf{x},\varpi(\mathsf{x}),\varpi(\lambda_{1}\mathsf{x}))| &\leq \quad \frac{\left| e^{-\mathsf{x}^{\nu}}\varpi(\mathsf{x})\right| + \left| e^{-\mathsf{x}^{\nu}}\varpi(\frac{\mathsf{x}}{2})\right|}{4e^{\mathsf{x}}} + \frac{1}{8} \\ &\leq \quad \frac{1}{8} + \frac{1}{4} \Big(|\varpi(\mathsf{x})| + \left| \varpi(\frac{\mathsf{x}}{4}) \right| \Big). \end{aligned}$$

Consequently, (P₂) holds with $n_g = \frac{1}{8}$ and $m_g = \frac{1}{4}$. Also,

$$\frac{\Lambda}{\chi} \frac{\psi_{b,a}^{\nu}}{\Gamma(\nu+1)} (m+1) L_{g} = 0.099791 < 1.$$

Thus, Theorem 2's presumptions are all satisfied. As a result, (25) has a solution on $[0, \frac{1}{2}]$ *.*

6. Conclusions

The current paper was epitomized as follows: Sufficient conditions were provided to investigate some qualitative results for the solution of fractional pantograph equations with boundary conditions in scalar real spaces. Weighted ψ -Caputo FDs have been applied; these were based on the weighted Caputo FD which was defined by Jarad et al. [40] and Al-Refai et al. [43]. Recently, it was discovered that the relevant differential operator is a potent tool for spotting crossover behavior in many evolutionary processes. We have established

the existence and uniqueness of boundary value problems for pantograph equations as further contributions to this area of study. As a result of Banach and Krasnoselskii's recognized fixed point theorems, we have also established a substantial analysis. Additionally, in light of our most recent discoveries, a more general problem for the fractional pantograph system has been presented, which includes problems comparable to the one being studied. Finally, we have provided two related examples to illustrate potential applications, hence, validating the main results. It would be interesting to study the present problem in the context of the modern operators introduced by Atangana-Baleanu [18] and Al-Refai [44].

Funding: This research was personally funded by Saeed M. Ali.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: No real data were used to support this study. The data used in this study are hypothetical.

Acknowledgments: The author thanks Imam Abdulrahman Bin Faisal University for its support. He is also indebted to the anonymous referee for her/his careful reading and valuables remarks.

Conflicts of Interest: The author declares no conflict of interest.

References

- 1. Osler, J. Leibniz rule for fractional derivatives generalized and an application to infinite series. *SIAM J. Appl. Math.* **1970**, *18*, 658–674. [CrossRef]
- Kilbas, A.A.; Srivastava, H.M.; Trujillo, J.J. Theory and Applications of Fractional Differential Equations. In North–Holland Mathematics Studies; Elsevier Science B.V.: Amsterdam, The Netherlands, 2006; Volume 204.
- 3. Samko, S.G.; Kilbas, A.A.; Marichev, O.I. *Fractional Integrals and Derivatives, Theory and Applications*; Gordon and Breach: Amsterdam, The Netherlands, 1993.
- 4. Diethelm, K.; Ford, N.J. Analysis of fractional differential equations. J. Math. Anal. Appl. 2002, 265, 229–248. [CrossRef]
- 5. Abdo, M.S. Boundary value problem for fractional neutral differential equations with infinite delay. *Abhath J. Basic Appl. Sci.* 2022, 1, 1–18. [CrossRef]
- Jarad, F.; Abdeljawad, T.; Hammouch, Z. On a class of ordinary differential equations in the frame of Atangana-Baleanu fractional derivative. *Chaos Solitons Fractals* 2018, 117, 16–20. [CrossRef]
- Abbas, S.; Benchohra, M.; N'Guérékata, G.M. Topics in Fractional Differential Equations; Springer Science & Bussines Media: Berlin/Heidelberg, Germany, 2012; Volume 27.
- 8. Ahmad, B.; Ntouyas, S.K. Existence results for a coupled system of Caputo-type sequential fractional differential equations with nonlocal integral boundary conditions. *Appl. Math. Comput.* **2015**, *266*, 615–622. [CrossRef]
- 9. Ntouyas, S.K. Global existence results for certain second order delay integrodifferential equations with nonlocal conditions. *Dyn. Syst. Appl.* **1998**, *7*, 415–426.
- 10. Lakshmikantham, V.; Vatsala, A.S. Basic theory of fractional differential equations. Nonlinear Anal. 2008, 69, 2677–2682. [CrossRef]
- 11. Gu, H.; Trujillo, J.J. Existence of mild solution for evolution equation with Hilfer fractional derivative. *Appl. Math. Comput.* **2015**, 257, 344–354. [CrossRef]
- Wang, J.; Zhang, Y. Nonlocal initial value problems for differential equations with Hilfer fractional derivative. *Appl. Math. Comput.* 2015, 266, 850–859. [CrossRef]
- Abdo, M.S. Existence and stability analysis to nonlocal implicit problems with ψ-piecewise fractional operators. *Abhath J. Basic Appl. Sci.* 2022, 1, 11–17. [CrossRef]
- Almeida, R. A Caputo fractional derivative of a function with respect to another function. *CommuN. Nonlinear Sci. Numer. Simul.* 2017, 44, 460–481. [CrossRef]
- 15. Sousa, J.V.C.; Oliveira, E.C. On the ψ-Hilfer fractional derivative. Commu. Nonlinear Sci. Numer. Simul. 2018, 60, 72–91. [CrossRef]
- 16. Caputo, M.; Fabrizio, M. New definition of fractional derivative without singular kernel. Prog. Fract. Differ. Appl. 2015, 1, 73–85.
- 17. Losada, J.; Nieto, J. Properties of a new fractional derivative without singular kernel. *Prog. Fract. Differ. Appl.* 2015, 1, 87–92.
- Atangana, A.; Baleanu, D. New fractional derivative with non-local and non-singular kernel. *Therm. Sci.* 2016, 20, 757–763. [CrossRef]
- 19. Thabet, S.; Abdo, M.S.; Shah, K. Theoretical and numerical analysis for transmission dynamics of COVID-19 mathematical model involving Caputo-Fabrizio derivative. *Adv. Differ. Equ.* **2021**, 2021, 184. [CrossRef]
- Abdo, M.S.; Panchal, S.K.; Shah, K.; Abdeljawad, T. Existence theory and numerical analysis of three species prey-predator model under Mittag-Leffler power law. *Adv. Differ. Equ.* 2020, 2020, 1–16. [CrossRef]
- Atangana, A.; Gómez-Aguilar, J.F. Fractional derivatives with no-index law property: Application to chaos and statistics. *Chaos Solitons Fractals* 2018, 114, 516–535. [CrossRef]

- 22. Ghanbari, B.; Kumar, S.; Kumar, R. A study of behaviour for immune and tumor cells in immunogenetic tumour model with non-singular fractional derivative. *Chaos Solitons Fractals* **2020**, *133*, 109619. [CrossRef]
- Hale, J.K.; Lunel, S.M. Introduction to Functional Differential Equations; Springer Science and Bussines Media: New York, NY, USA, 2013.
- 24. Brunt, B.; Zaidi, A.A.; Lynch, T. Cell division and the pantograph equation. ESAIM Proc. Surv. 2018, 62, 158–167. [CrossRef]
- 25. Sedaghat, S.; Ordokhani, Y.; Dehghan, M. Numerical solution of the delay differential equations of pantograph type via Chebyshev polynomials. *Commun. Nonlinear Sci. Numer. Simul.* **2012**, *17*, 4815–4830. [CrossRef]
- 26. Bahsi, M.; Cevik, M.; Sezer, M. Orthoexponential polynomial solutions of delay pantograph differential equations with residual error estimation. *Appl. Math. Comput.* **2015**, *271*, 11–21.
- 27. Ockendon, J.R.; Taylor, A.B. The dynamics of a current collection system for an electric locomotive. *Proc. R. Soc. Lond. Ser.A* **1971**, 322, 447–468.
- Ajello, W.G.; Freedman, H.I.; Wu, J. A model of stage structured population growth with density depended time delay. SIAM J. Appl. Math. 1992, 52, 855–869.
- 29. Weiner, G.J. Activation of NK Cell Responses and Immunotherapy of Cancer. Current Cancer Res. 2014, 12, 57–66.
- 30. Langley, J.K. A certain functional-differential equation. J. Math. Anal. Appl. 2000, 244, 564–567. [CrossRef]
- 31. Liu, M.Z. Asymptotic behavior of functional-differential equations with proportional time delays. *Eur. J. Appl. Math.* **1996**, *7*, 11–30. [CrossRef]
- 32. Li D.; Liu, M.Z. Runge-Kutta methods for the multi-pantograph delay equation. Appl. Math. Comput. 2005, 163, 383–395. [CrossRef]
- 33. Derfel, G.A.; Iserles, A. The pantograph equation in the complex plane. J. Math. Anal. Appl. 1997, 213, 117–132. [CrossRef]
- 34. Iserles, A. Exact and discretized stability of the pantograph equation. Appl. Numer. Math. 1997, 24, 295–308. [CrossRef]
- 35. Liu, M.Z.; Li, D. Properties of analytic solution and numerical solution of multi-pantograph equation. *Appl. Math. Comput.* **2004**, *155*, 853–871. [CrossRef]
- Sezer M.; Yalcinbas S.; Sahin N. Approximate solution of multi-pantograph equation with variable coefficients. J. Comput. Appl. Math. 2008, 214, 406–416. [CrossRef]
- Balachandran, K.; Kiruthika, S.; Trujillo, J. Existence of solutions of nonlinear fractional pantograph equations. *Acta Math. Sci.* 2013, 33, 712–720. [CrossRef]
- Agarwal, O. Some generalized fractional calculus operators and their applications in integral equations. *Fract. Calc. Appl. Anal.* 2012, 15, 700–711. [CrossRef]
- 39. Kolokoltsov, V.N. The probabilistic point of view on the generalized fractional partial differential equations. *Fract. Calc. Appl. Anal.* **2019**, 22, 543–600. [CrossRef]
- Jarad, F.; Abdeljawad, T.; Shah, K. On the weighted fractional operators of a function with respect to another function. *Fractals* 2020, 28, 2040011. [CrossRef]
- 41. Abdo, M.S.; Abdeljawad, T.; Ali, S.M.; Shah, K.; Jarad, F. Existence of positive solutions for weighted fractional order differential equations. *Chaos Solitons Fractals* **2020**, *141*, 110341. [CrossRef]
- 42. Abdo, M.S.; Shammakh, W.; Alzumi, H.Z.; Alghamd, N.; Albalwi, M.D. Nonlinear Piecewise Caputo Fractional Pantograph System with Respect to Another Function. *Fractal Fract.* **2023**, *7*, 2023. [CrossRef]
- Al-Refai, M.; Jarrah, A.M. Fundamental results on weighted Caputo–Fabrizio fractional derivative. *Chaos Solitons Fractals* 2019, 126, 7–11. [CrossRef]
- 44. Al-Refai, M. On weighted Atangana-Baleanu fractional operators. Adv. Differ. Equ. 2020, 3, 1–11. [CrossRef]
- Liu, J.G.; Yang, X.J.; Feng, Y.Y.; Geng, L.L. Fundamental results to the weighted Caputo-type differential operator. *Appl. Math. Lett.* 2021, 121, 107421. [CrossRef]
- 46. Fernandez, A.; Fahad, H.M. Weighted fractional calculus: A general class of operators. Fractal Fract. 2022, 6, 208. [CrossRef]
- 47. Krasnoselskii, M.A. Two remarks on the method of successive approximations. Usp. Mat. Nauk. 1955, 10, 123–127.
- 48. Zhou, Y. Basic theory of Fractional Differential Equations; World Scientific: Singapore, 2014.

Disclaimer/Publisher's Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.