# Group Classification of the Unsteady Axisymmetric Boundary Layer Equation 

Alexander V. Aksenov ${ }^{1, *(\mathbb{D})}$ and Anatoly A. Kozyrev ${ }^{2(1)}$<br>1 Faculty of Mechanics and Mathematics, Lomonosov Moscow State University, 1 Leninskie Gory, Main Building, 119991 Moscow, Russia<br>2 Dukhov All-Russia Research Institute of Automatics, Rosatom, 22 Suschevskaya St., 127055 Moscow, Russia; anatoly.kozyrev@gmail.com<br>* Correspondence: aksenov@mech.math.msu.su


#### Abstract

Unsteady equations of flat and axisymmetric boundary layers are considered. For the unsteady axisymmetric boundary layer equation, the problem of group classification is solved. It is shown that the kernel of symmetry operators can be extended by no more than four-dimensional Lie algebra. The kernel of symmetry operators of the unsteady flat boundary layer equation is found and it is shown that it can be extended by no more than a five-dimensional Lie algebra. The non-existence of the unsteady analogue of the Stepanov-Mangler transformation is proved.


Keywords: symmetry operator; Lie algebra; group classification; axisymmetric boundary layer; Stepanov-Mangler transformation

MSC: 35B06; 35G20; 35Q35; 76D10; 76M60

## Contents

1. Introduction
1.1. Preliminary Remarks
1.2. The Main Results
2. Basic Equations
3. Group Classification
3.1. The System of Determining Equations
3.2. Solving the System of Determining Equations
3.3. Group Classification Results
4. Non-Existence of the Unsteady Analogue of Stepanov-Mangler Transformation
5. Conclusions

References

## 1. Introduction

### 1.1. Preliminary Remarks

The equations of flat and axisymmetric laminar boundary layers in incompressible fluid are considered in this paper. The boundary layer equations were first presented by Ludwig Prandtl at the Third Mathematical Congress in Heidelberg in 1904 as a simplification of the system of Navier-Stokes equations. The classical equations of the unsteady flat boundary layer in an incompressible viscous fluid have the form [1,2]

$$
\begin{align*}
& u_{t}+u u_{x}+v u_{y}=-\frac{1}{\rho} p_{x}+v u_{y y}  \tag{1}\\
& u_{x}+v_{y}=0 .
\end{align*}
$$

Here, $u=u(x, y, t), v=v(x, y, t)$ are the components of the velocity vector; $\rho=$ const is the density; $p=p(x, t)$ is the pressure determined through the external flow; $v$ is the
kinematic viscosity coefficient. By introducing the stream function $\Psi(x, y, t)$, defined by the equalities $u=\Psi_{y}, v=-\Psi_{x}$, the system of Equation (1) simplifies to a single equation (which coincides with Equation (5) for $r_{0}(x)=1$ ).

The system of Equation (1) is generalized to the case of a curved streamlined surface. For an axisymmetric boundary layer on a body of rotation, the system of equations has the form [1-3]

$$
\begin{align*}
& u_{t}+u u_{z}+v u_{r}=-\frac{1}{\rho} p_{z}+v u_{r r}  \tag{2}\\
& \left(r_{0} u\right)_{z}+\left(r_{0} v\right)_{r}=0
\end{align*}
$$

where $r_{0}=r_{0}(z)$ is the surface equation of a streamlined body of rotation. Introducing the stream function $\Psi=\Psi(z, r, t)$ defined by the equalities

$$
u=\frac{1}{r_{0}}\left(r_{0} \Psi\right)_{r}, \quad v=-\frac{1}{r_{0}}\left(r_{0} \Psi\right)_{z}
$$

the system of Equation (2) becomes a single equation (Equation (3)).
In $[4,5]$, the transformation (4) shows that the equivalence of the steady equations of flat and axisymmetric boundary layers was obtained. In the present paper, the existence of such a transformation for steady equations is investigated.

One of the most important applications of boundary layer theory is the calculation of the friction drag of bodies in a flow, e.g., the drag of a flat plate at zero incidence, the friction drag of a ship, an airfoil, the body of an airplane, or a turbine blade. Due to its practical importance, the usage of different methods of studying nonlinear equations to boundary layer equations is widely covered in the literature. In particular, the group properties have been investigated by Ovsiannikov [6]. Self-similar solutions of boundary layer equations were considered in $[7,8]$. Some partially invariant solutions of the boundary layer equations were considered in [9]. The study of boundary layer equations using the direct ClarksonKruskal method [10] was described in [11]. In [12-15], reductions of the boundary layer equations were obtained. The application of the method of non-classical symmetries and the finding of some other solutions for the equations of flat and axisymmetric boundary layers were described in [16-20]. Exact solutions classes of boundary layer equations using the method of functional and generalized separation of variables are given in [21-27].

### 1.2. The Main Results

The main results of this article are the following:

- Group classification of the unsteady axisymmetric boundary layer equation is carried out; it is shown that the kernel of symmetry operators can be extended by no more than a four-dimensional Lie algebra;
- It is obtained that the kernel of symmetry operators of the flat unsteady boundary layer equation can be extended by no more than a five-dimensional Lie algebra;
- It is shown that there is no unsteady analogue of the Stepanov-Mangler transformation.


## 2. Basic Equations

Consider an equation describing the unsteady axisymmetric motion of a viscous incompressible fluid in a laminar boundary layer on the surface of a body of rotation $[1,2]$

$$
\begin{equation*}
u_{y t}+u_{y} u_{x y}-\left(u_{x}+\frac{r_{0}^{\prime}(x)}{r_{0}(x)} u\right) u_{y y}-u_{y y y}-f_{0}(x, t)=0 \tag{3}
\end{equation*}
$$

Equation (3) is written in dimensionless variables. Here, $u(x, y, t)$ is the stream function; $f_{0}(x, t)=-\partial p / \partial x$ is the given function; $p(x, t)$ is the pressure; the function $r_{0}(x)$ defines the shape of the streamlined surface.

To simplify further calculations, we use the Stepanov-Mangler transformation [3-5], which transforms the equation of a steady axisymmetric boundary layer into the equation of a steady flat boundary layer. This transformation is given by

$$
\begin{equation*}
\bar{x}=\int_{0}^{x} r_{0}^{2}(s) d s, \quad \bar{y}=r_{0}(x) y, \quad \bar{u}=r_{0}(x) u \tag{4}
\end{equation*}
$$

Then, substituting (4) into Equation (3), we obtain

$$
\frac{1}{r_{0}^{2}(x)} \bar{u}_{\bar{y} t}+\bar{u}_{\bar{y}} \bar{u}_{\bar{x} \bar{y}}-\bar{u}_{\bar{x}} \bar{u}_{\bar{y} \bar{y}}-\bar{u}_{\bar{y} \bar{y} \bar{y}}-\frac{f_{0}(x, t)}{r_{0}^{2}(x)}=0 .
$$

Let us introduce the notation $\bar{r}(\bar{x})=1 / r_{0}^{2}(x(\bar{x})), \bar{f}(\bar{x}, t)=f_{0}(x(\bar{x}), t) / r_{o}^{2}(x(\bar{x}))$. Omitting the bar, we obtain the following equation:

$$
\begin{equation*}
r(x) u_{y t}+u_{y} u_{x y}-u_{x} u_{y y}-u_{y y y}-f(x, t)=0 . \tag{5}
\end{equation*}
$$

In the following, we will consider Equation (5) as the main equation.
Remark 1. Transformation (4) is a point transformation and, therefore, Equations (3) and (5) are equivalent. It is more convenient to find symmetries for Equation (5).

## 3. Group Classification

3.1. The System of Determining Equations

We are looking for the symmetry operator of Equation (5) in the following form:

$$
X=\xi^{x}(x, y, t, u) \frac{\partial}{\partial x}+\xi^{y}(x, y, t, u) \frac{\partial}{\partial y}+\xi^{t}(x, y, t, u) \frac{\partial}{\partial t}+\eta(x, y, t, u) \frac{\partial}{\partial t} .
$$

Using the invariance criterion [6] (see also [28,29]) and substituting the expression for the highest derivative $u_{y y y}$

$$
u_{y y y}=r(x) u_{y t}+u_{y} u_{x y}-u_{x} u_{y y}-f(x, t),
$$

into it, we obtain the following relation:

$$
\begin{align*}
& -3 u_{x y y} u_{y} \xi_{u}^{x}-3 u_{x y y} \xi_{y}^{x}-3 u_{y y t} \xi_{y}^{t}-3 u_{y y t} u_{y} \xi_{u}^{t}+u_{x x} u_{y} \xi_{y}^{x}+u_{x x} u_{y}^{2} \xi_{u}^{x} \\
& +u_{x y} u_{t} u_{y} \xi_{u}^{t}+u_{x y}\left(\xi_{y}^{t}+r(x) \xi_{u}^{x}\right)-u_{x y} u_{x} \xi_{y}^{x}-u_{x y} u_{y}^{2}\left(\xi_{u}^{y}+3 \xi_{u u}^{x}\right) \\
& +u_{x y} u_{y}\left(\xi_{x}^{x}-\xi_{y}^{y}-6 \xi_{y u}^{x}-\eta_{u}^{u}\right)-3 u_{x y} u_{y y} \xi_{u}^{x}+u_{x y}\left(r(x) \xi_{t}^{x}-3 \xi_{y y}^{x}\right) \\
& -u_{y y} u_{t} u_{x} \xi_{u}^{t}-3 u_{y y} u_{t} u_{y} \xi_{u u}^{t}+u_{y y} u_{t}\left(r(x) \xi_{u}^{y}-3 \xi_{y u}^{t}-\xi_{x}^{t}\right)-u_{y y} u_{x}^{2} \xi_{u}^{x} \\
& +u_{y y} u_{x} u_{y}\left(\xi_{u}^{y}-3 \xi_{u u}^{x}\right)+u_{y y} u_{x}\left(\xi_{y}^{y}+\eta_{u}^{u}-\xi_{x}^{x}-3 \xi_{y u}^{x}\right)-6 u_{y y} u_{y}^{2} \xi_{u u}^{y} \\
& +3 u_{y y} u_{y}\left(\eta_{u u}^{u}-3 \xi_{y u}^{y}\right)-3 u_{y y} u_{y t} \xi_{u}^{t}+u_{y y}\left(3 \eta_{y u}^{u}+r(x) \xi_{t}^{y}+\eta_{x}^{u}-3 \xi_{y y}^{y}\right) \\
& +u_{x t} u_{y}^{2} \xi_{u}^{t}+u_{x t} u_{y}\left(\xi_{y}^{t}+r(x) \xi_{u}^{x}\right)+u_{x t} r(x) \xi_{y}^{x}+u_{y t} u_{t} r(x) \xi_{u}^{t}-2 u_{y t} u_{x} \xi_{y}^{t} \\
& -u_{y t} u_{x} u_{y} \xi_{u}^{t}+u_{y t} u_{t} r(x) \xi_{u}^{t}-3 u_{y t} u_{y}^{2} \xi_{u u}^{t}+u_{y t} u_{y}\left(\xi_{x}^{t}-2 r(x) \xi_{u}^{y}-6 \xi_{y u}^{t}\right) \\
& -u_{y t}\left(2 r(x) \xi_{y}^{y}+3 \xi_{y y}^{t}+\xi^{x} r^{\prime}(x)-r(x) \xi_{t}^{t}\right)-u_{y y} u_{t} u_{x} \xi_{u}^{t}-3 u_{y y} u_{t} u_{y} \xi_{u u}^{t} \\
& +u_{y y} u_{t}\left(r(x) \xi_{u}^{y}-\xi_{x}^{t}-3 \xi_{y u}^{t}\right)-u_{y y} u_{x}^{2} \xi_{u}^{x}+u_{y y} u_{x}\left(\eta_{u}^{u}+\xi_{y}^{y}-\xi_{x}^{x}-3 \xi_{y u}^{x}\right) \\
& +u_{y y} u_{x} u_{y}\left(\xi_{u}^{y}-3 \xi_{u u}^{x}\right)-6 u_{y y} u_{y}^{2} \xi_{u u}^{y}+3 u_{y y} u_{y}\left(\eta_{u u}^{u}-3 \xi_{y u}^{y}\right)  \tag{6}\\
& +u_{y y}\left(3 \eta_{y u}^{u}+r(x) \xi_{t}^{y}+\eta_{x}^{u}-3 \xi_{y y}^{y}\right)+u_{t t} u_{y} r(x) \xi_{u}^{t}+u_{t t} r(x) \xi_{y}^{t}
\end{align*}
$$

$$
\begin{aligned}
& -u_{y}^{4} \xi_{u u u}^{y}+u_{y}^{3}\left(\eta_{u u u}^{u}+\xi_{x u}^{y}-3 \xi_{u u u}^{t}\right)-u_{y}^{3} u_{x} \xi_{u u u}^{x}-u_{y}^{3} u_{t} \xi_{u u u}^{t} \\
& +u_{y}^{2} u_{t}\left(\xi_{x u}^{t}+r(x) \xi_{u u}^{y}-3 \xi_{y u u}^{t}\right)+u_{y}^{2} u_{x}\left(\xi_{x u}^{x}-\xi_{y u}^{y}-3 \xi_{y u u}^{x}\right) \\
& +u_{y}^{2}\left(r(x) \xi_{t u}^{y}+3 \eta_{y u u}^{u}+\xi_{x y}^{y}-\eta_{x u}^{u}-3 \xi_{y y u}^{y}\right)+u_{y} u_{t}^{2} r(x) \xi_{u u}^{t} \\
& +u_{y} u_{t} u_{x}\left(r(x) \xi_{u u}^{x}-\xi_{y u}^{t}\right)+u_{y} u_{t}\left(r(x) \xi_{t u}^{t}-r(x) \eta_{u u}^{u}+r(x) \xi_{y u}^{y}+\xi_{x y}^{t}\right. \\
& \left.-3 \xi_{y y u}^{t}\right)-u_{y} u_{x}^{2} \xi_{y u}^{x}+u_{y} u_{x}\left(\xi_{x y}^{x}+\eta_{y u}^{u}+r(x) \xi_{t u}^{x}-3 \xi_{y y u}^{x}-\xi_{y y}^{y}\right) \\
& +u_{y}\left(3 \eta_{y y u}^{u}+r(x) \xi_{t y}^{y}+4 f(x, t) \xi_{u}^{y}-\eta_{x y}^{u}-r(x) \eta_{t u}^{u}-\xi_{y y y}^{y}\right) \\
& +u_{t}^{2} r(x) \xi_{y u}^{t}+u_{t} u_{x}\left(r(x) \xi_{y u}^{x}-\xi_{y y}^{t}\right)+u_{t}\left(f(x, t) \xi_{u}^{t}+r(x) \xi_{y t}^{t}-\xi_{y y y}^{t}-\eta_{y u}^{u}\right) \\
& -u_{x}^{2} \xi_{y y}^{x}+u_{x}\left(r(x) \xi_{y t}^{x}+\eta_{y y}^{u}+f(x, t) \xi_{u}^{x}-\xi_{y y y}^{x}\right)+\eta_{y y y}^{u}-r(x) \eta_{y t}^{u} \\
& \quad-f(x, t) \eta_{u}^{u}+\xi^{t} f_{t}(x, t)+\xi^{x} f_{x}(x, t)+3 f(x, t) \xi_{y}^{y}=0 .
\end{aligned}
$$

Relation (6) is fulfilled for all values of the derivatives of the function $u(x, y, t)$. Splitting it into various partial derivatives of $u(x, y, t)$, we obtain a system of determining equations

$$
\begin{align*}
\xi_{u}^{x} & =\xi_{u}^{t}=\xi_{u}^{y}=\xi_{y}^{x}=\xi_{y}^{t}=\xi_{x}^{t}=\eta_{u u}=\eta_{y u}=\eta_{y y}=\xi_{y y}^{y}=\eta_{x u}=0, \\
\xi_{x y}^{y} & =r(x) \xi_{t}^{y}+\eta_{x}=r(x) \xi_{t}^{x}-\eta_{y}=-r^{\prime}(x) \xi^{x}+r(x) \xi_{t}^{t}-2 r(x) \xi_{y}^{y} \\
& =\xi^{x}-\eta_{u}-\xi_{y}^{y}=-\eta_{x y}+r(x) \xi_{t}^{y}-r(x) \eta_{u t}  \tag{7}\\
& =-r(x) \eta_{y t}+\xi^{t} f_{t}(x, t)+\xi^{x} f_{x}(x, t)+\left(3 \xi_{y}^{y}-\eta_{u}\right) f(x, t)=0 .
\end{align*}
$$

### 3.2. Solving the System of Determining Equations

It follows from the system of determining Equation (7) that the components of the allowed symmetry operators can be searched in the following form:

$$
\begin{align*}
& \xi^{x}=a_{1}(t) x+a_{2}(t), \quad \xi^{y}=b_{1}(t) y+b_{2}(x, t) \\
& \xi^{t}=c_{1}(t), \quad \eta^{u}=d_{1}(x, t) y+d_{2}(t) u+d_{3}(x, t) . \tag{8}
\end{align*}
$$

Then, the system of determining Equation (7) can be written as follows:

$$
\begin{align*}
& d_{2}(t)-a_{1}(t)+b_{1}(t)=0, \quad r(x)\left(a_{1}^{\prime}(t) x+a_{2}^{\prime}(t)\right)-d_{1}(x, t)=0, \\
& r(x) b_{1}^{\prime}(t)+d_{1 x}(x, t)=0, \quad r(x) d_{2}^{\prime}(t)+d_{1 x}(x, t)-r(x) b_{1}^{\prime}(t)=0, \\
& r(x) c_{1}^{\prime}(t)-\left(a_{1}(t) x+a_{2}(t)\right) r^{\prime}(x)-2 r(x) b_{1}(t)=0,  \tag{9}\\
& c_{1}(t) f_{t}(x, t)+\left(a_{1}(t) x+a_{2}(t)\right) f_{x}(x, t) \\
& \quad+\left(3 b_{1}(t)-d_{2}(t)\right) f(x, t)-r(x) d_{1 t}(x, t)=0 .
\end{align*}
$$

From the third and fifth equations of system (9), one can obtain

$$
d_{2}^{\prime}(t)=2 b_{1}^{\prime}(t)
$$

or

$$
\begin{equation*}
d_{2}(t)=2 b_{1}(t)+a, \quad a=\text { const } \tag{10}
\end{equation*}
$$

Given relation (10), the first equation of the system of Equation (9) will take the form

$$
a_{1}(t)=3 b_{1}(t)+a .
$$

Further, excluding $d_{1}(x, t)$ from the third and sixth equations of the system by virtue of the second, system (9) can be rewritten as follows:

$$
\begin{align*}
& d_{1}(x, t)=r(x)\left(3 b_{1}^{\prime}(t) x+a_{2}^{\prime}(t)\right), \\
& 4 r(x) b_{1}^{\prime}(t)+r^{\prime}(x)\left(3 b_{1}^{\prime}(t) x+a_{2}^{\prime}(t)\right)=0, \\
& r(x)\left(c_{1}^{\prime}(t)-2 b_{1}(t)\right)-r^{\prime}(x)\left(\left(3 b_{1}(t)+a\right) x+a_{2}(t)\right)=0,  \tag{11}\\
& c_{1}(t) f_{t}(x, t)+\left(\left(3 b_{1}(t)+a\right) x+a_{2}(t)\right) f_{x}(x, t) \\
& \quad+\left(b_{1}(t)-a\right) f(x, t)-r^{2}(x)\left(3 b_{1}^{\prime \prime}(t) x+a_{2}^{\prime \prime}(t)\right)=0 .
\end{align*}
$$

### 3.3. Group Classification Results

The analysis of the system of determining Equation (11) shows that it has a solution only in the following cases.

1. $r(x), f(x, t)$ are arbitrary functions. In this case, the kernel of the symmetry operators of Equation (5) is infinite-dimensional and consists of symmetry operator

$$
\begin{equation*}
X=b_{2}(x, t) \frac{\partial}{\partial y}+d_{3}(x, t) \frac{\partial}{\partial u} \tag{12}
\end{equation*}
$$

where the functions $b_{2}(x, t), d_{3}(x, t)$ satisfy the relation

$$
r(x) b_{2 t}(x, t)+d_{3 x}(x, t)=0
$$

2. $r(x)=\alpha(x+\beta)^{-4 / 3}$.
2.1. $f(x, t)=\alpha^{2}(x+\beta)^{-5 / 3} q(t)$. In this case, the kernel of symmetry operators is expanded by operators

$$
\begin{aligned}
X_{i}= & -\frac{3 c_{i}^{\prime}(t)}{2}(x+\beta) \frac{\partial}{\partial x}-\frac{c_{i}^{\prime}(t)}{2} y \frac{\partial}{\partial y}+c_{i}(t) \frac{\partial}{\partial t} \\
& -\left(\frac{3 \alpha}{2}(x+\beta)^{-\frac{1}{3}} c_{i}^{\prime \prime}(t) y+c_{i}^{\prime}(t) u\right) \frac{\partial}{\partial u}, \quad i=1,2,3, \\
X_{4}= & (x+\beta) \frac{\partial}{\partial x}+\frac{2 y}{3} \frac{\partial}{\partial y}+\frac{u}{3} \frac{\partial}{\partial u} .
\end{aligned}
$$

Here, $c_{i}(t)$ are linearly independent solutions of the ordinary differential equation

$$
3 c^{\prime \prime \prime}(t)+4 c^{\prime}(t) q(t)+2 c(t) q^{\prime}(t)=0 .
$$

2.2. $f(x, t)=g(x)(t+\delta)^{-2}, g(x) \neq \varepsilon(x+\beta)^{\kappa}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=y \frac{\partial}{\partial y}+2(t+\delta) \frac{\partial}{\partial t}+u \frac{\partial}{\partial u} .
$$

3. $r(x)=\alpha(x+\beta)^{\gamma}, \quad \gamma \neq-4 / 3 ; 0$.
3.1. $f(x, t)=0$. In this case, the kernel of symmetry operators is expanded by the operators

$$
\begin{align*}
& X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=y \frac{\partial}{\partial y}+2 t \frac{\partial}{\partial t}-u \frac{\partial}{\partial u},  \tag{13}\\
& X_{3}=2(x+\beta) \frac{\partial}{\partial x}-\gamma y \frac{\partial}{\partial y}+(\gamma+2) u \frac{\partial}{\partial u} .
\end{align*}
$$

3.2. $f(x, t)=$ const, const $\neq 0$. In this case, the kernel of symmetry operators is expanded by the operators

$$
X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=2(x+\beta) \frac{\partial}{\partial x}+\frac{y}{2} \frac{\partial}{\partial y}+(2 \gamma+1) t \frac{\partial}{\partial t}+\frac{3 u}{2} \frac{\partial}{\partial u} .
$$

3.3. $f(x, t) \neq \delta(x+\beta)^{\kappa}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=\frac{\partial}{\partial t} .
$$

3.4. $f(x, t)=\delta(x+\beta)^{\kappa}$. In this case, the kernel of symmetry operators is expanded by the operators

$$
\begin{aligned}
& X_{1}=\frac{\partial}{\partial t}, \\
& X_{2}=2(x+\beta) \frac{\partial}{\partial x}-\frac{(\kappa-1) y}{2} \frac{\partial}{\partial y}+(2 \gamma+1-\kappa) t \frac{\partial}{\partial t}+\frac{(\kappa+3) u}{2} \frac{\partial}{\partial u} .
\end{aligned}
$$

3.5. $f(x, t)=\delta(t+\varepsilon)^{-2}$. In this case, the kernel of symmetry operators is expanded by the operators

$$
\begin{aligned}
& X_{1}=(x+\beta) \frac{\partial}{\partial x}+\frac{y}{4} \frac{\partial}{\partial y}+\frac{3 u}{4} \frac{\partial}{\partial u}, \\
& X_{2}=\frac{y}{2}+(t+\varepsilon) \frac{\partial}{\partial t}-\frac{u}{2} \frac{\partial}{\partial u} .
\end{aligned}
$$

3.6. $f(x, t)=\delta(t+\varepsilon)^{\kappa}, \kappa \neq-2$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=(x+\beta) \frac{\partial}{\partial x}-\frac{(\kappa \gamma-1)}{2(\kappa+2)} \frac{\partial}{\partial y}+\frac{(2 \gamma+1)(t+\varepsilon)}{\kappa+2} \frac{\partial}{\partial t}+\frac{(3+\kappa(\gamma+2))}{2(\kappa+2)} \frac{\partial}{\partial u} .
$$

3.7. $f(x, t)=\delta \exp (\varepsilon t), \varepsilon \neq 0$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=(x+\beta) \frac{\partial}{\partial x}-\frac{\gamma y}{2} \frac{\partial}{\partial y}+\frac{2 \gamma+1}{\varepsilon} \frac{\partial}{\partial t}+\frac{\gamma+2}{2} \frac{\partial}{\partial u} .
$$

3.8. $f(x, t)=g(t)(x+\beta)^{2 \gamma+1}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=(x+\beta) \frac{\partial}{\partial x}-\frac{\gamma y}{2} \frac{\partial}{\partial y}+\frac{(\gamma+2) u}{2} \frac{\partial}{\partial u} .
$$

3.9. $f(x, t)=g(x)(t+\varepsilon)^{-2}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=\frac{y}{2} \frac{\partial}{\partial y}+(t+\varepsilon) \frac{\partial}{\partial t}-\frac{u}{2} \frac{\partial}{\partial u} .
$$

3.10. $f(x, t)=(x+\beta)^{2 \kappa+2 \gamma+1} g\left((x+\beta)^{\kappa}(t+\varepsilon)\right)$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=-2(x+\beta) \frac{\partial}{\partial x}+y(\gamma+\kappa) \frac{\partial}{\partial y}+2 \kappa(t+\varepsilon) \frac{\partial}{\partial t}-(\gamma+\kappa+2) u \frac{\partial}{\partial u} .
$$

4. $r(x)=\alpha \exp (\beta x), \alpha \beta \neq 0$.
4.1. $f(x, t)=0$. In this case, the kernel of symmetry operators is expanded by the operators

$$
\begin{aligned}
& X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=y \frac{\partial}{\partial y}+2 t \frac{\partial}{\partial t}-u \frac{\partial}{\partial u}, \\
& X_{3}=2 \frac{\partial}{\partial x}-\beta y \frac{\partial}{\partial y}+\beta u \frac{\partial}{\partial u} .
\end{aligned}
$$

4.2. $f(x, t)=$ const, const $\neq 0$. In this case, the kernel of symmetry operators is expanded by the operators

$$
X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=\frac{\partial}{\partial x}+\beta t \frac{\partial}{\partial t} .
$$

4.3. $f(x, t)=\delta \exp (\gamma x)$. In this case, the kernel of symmetry operators is expanded by the operators

$$
X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=-4 \frac{\partial}{\partial x}+\gamma y \frac{\partial}{\partial y}+2(\gamma-2 \beta) t \frac{\partial}{\partial t}-\gamma u \frac{\partial}{\partial u} .
$$

4.4. $f(x, t)=\gamma(t+\varepsilon)^{\delta}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=\frac{\delta+2}{\beta} \frac{\partial}{\partial x}-\frac{\delta y}{2} \frac{\partial}{\partial y}+2(t+\varepsilon) \frac{\partial}{\partial t}+\frac{\delta u}{2} \frac{\partial}{\partial u}
$$

4.5. $f(x, t)=\gamma \exp (\varepsilon t)$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=\frac{\varepsilon}{\beta} \frac{\partial}{\partial x}-\frac{\varepsilon y}{2} \frac{\partial}{\partial y}+2 \frac{\partial}{\partial t}+\frac{\varepsilon u}{2} \frac{\partial}{\partial u} .
$$

4.6. $f(x, t)=g(t) \exp (2 \beta x)$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=2 \frac{\partial}{\partial x}-\beta y \frac{\partial}{\partial y}+\beta u \frac{\partial}{\partial u} .
$$

4.7. $f(x, t)=g(x)(t+\varepsilon)^{-2}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=y \frac{\partial}{\partial y}+2(t+\varepsilon) \frac{\partial}{\partial t}-u \frac{\partial}{\partial u}
$$

5. $r(x)$ is arbitrary, $r(x) \neq \alpha(x+\beta)^{\gamma}, r(x) \neq \alpha \exp (\beta x)$.
5.1. $f(x, t)=0$. In this case, the kernel of symmetry operators is expanded by the operators

$$
X_{1}=\frac{\partial}{\partial t}, \quad X_{2}=y \frac{\partial}{\partial y}+2 t \frac{\partial}{\partial t}-u \frac{\partial}{\partial u} .
$$

5.2. $f(x, t)=$ const, const $\neq 0$ or $f(x, t)=g(x)$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=\frac{\partial}{\partial t} .
$$

5.3. $f(x, t)=g(x)(t+\varepsilon)^{-2}$. In this case, the kernel of symmetry operators is expanded by the operator

$$
X_{1}=y \frac{\partial}{\partial y}+2(t+\varepsilon) \frac{\partial}{\partial t}-u \frac{\partial}{\partial u}
$$

Thus, all cases of expansion of the kernel of the symmetry operators of Equation (5) are listed for all possible functions $r(x)$ and $f(x, t)$.

Proposition 1. For arbitrary functions $r(x)$ and $f(x, t)$, Equation (5) admits an infinite-dimensional kernel of symmetry operators of the following form:

$$
X=a(x, t) \frac{\partial}{\partial y}+b(x, t) \frac{\partial}{\partial u},
$$

where the functions $a(x, t), b(x, t)$ satisfy the relation $r(x) a_{t}(x, t)+b_{x}(x, t)=0$. The largest kernel expansion is allowed in case 2.1 when

$$
r(x)=\alpha(x+\beta)^{-4 / 3}, \quad f(x, t)=q(t)(x+\beta)^{-5 / 3}
$$

where $\alpha \neq 0$ and the function $q(t)$ is arbitrary. In this case, the kernel of symmetry operators is expanded by a four-dimensional Lie algebra.

## 4. Non-Existence of the Unsteady Analogue of Stepanov-Mangler Transformation

Consider the equation of an unsteady flat boundary layer [2]

$$
\begin{equation*}
u_{t y}+u_{y} u_{x y}-u_{x} u_{y y}-u_{y y y}-F(x, t)=0 . \tag{14}
\end{equation*}
$$

Equation (14) is a particular case of Equation (5). It coincides with it when $r(x)=1$, $f(x, t)=F(x, t)$.

The components of the allowed symmetry operators of Equation (14) should also be searched for in the form (8). The system of determining equations can also be obtained by substitution in the system of determining Equation (9) $r(x)=1, f(x, t)=F(x, t)$

$$
\begin{align*}
& d_{2}(t)-a_{1}(t)+b_{1}(t)=0, \quad a_{1}^{\prime}(t) x+a_{2}^{\prime}(t)-d_{1}(x, t)=0, \\
& b_{1}^{\prime}(t)+d_{1 x}(x, t)=0, \quad d_{2}^{\prime}(t)+d_{1 x}(x, t)-b_{1}^{\prime}(t)=0, \\
& c_{1}^{\prime}(t)-2 b_{1}(t)=0,  \tag{15}\\
& c_{1}(t) F_{t}(x, t)+\left(a_{1}(t) x+a_{2}(t)\right) F_{x}(x, t) \\
& \quad+\left(3 b_{1}(t)-d_{2}(t)\right) F(x, t)-d_{1 t}(x, t)=0 .
\end{align*}
$$

From the system of Equation (15), it is not difficult to obtain that

$$
b_{1}(t)=b_{10}=\text { const }, \quad d_{2}(t)=d_{20}=\text { const }, \quad a_{1}(t)=b_{10}+d_{10}=\text { const } .
$$

Next, $d_{1}(x, t)=a_{2}^{\prime}(t), c_{1}(t)=2 b_{10} t+c_{20}$. Then, the classifying equation for the function $F(x, t)$ will take the following form:

$$
\begin{align*}
\left(a_{10} x+a_{2}(t)\right) F_{x}(x, t)-a_{2}^{\prime \prime}(t) & +\left(2 b_{10} t+c_{20}\right) F_{t}(x, t)  \tag{16}\\
& +\left(3 b_{10}-d_{20}\right) F(x, t)=0 .
\end{align*}
$$

Proposition 2. The kernel of the symmetry operators of Equation (14) has the form (12)

$$
X=b_{2}(x, t) \frac{\partial}{\partial y}+d_{3}(x, t) \frac{\partial}{\partial u}
$$

where the functions $b_{2}(x, t), d_{3}(x, t)$ satisfy the relation

$$
b_{2 t}(x, t)+d_{3 x}(x, t)=0 .
$$

Theorem 1. There is no analog of the Stepanov-Mangler transformation for unsteady equations of flat and axisymmetric boundary layers.

Proof of Theorem 1. Consider the extension of the kernel of the symmetry operators of Equation (14), allowed for $F(x, t)=0$. Substituting $F(x, t)=0$ into Equation (16) leads to
the relation $a_{2}{ }^{\prime \prime}(t)=0$ or $a_{2}(t)=a_{20} t+a_{30}$. Then the kernel of the symmetry operators of Equation (14) is expanded by a five-dimensional Lie subalgebra with the following basis operators:

$$
\begin{align*}
& X_{1}=\frac{\partial}{\partial x}, \quad X_{2}=t \frac{\partial}{\partial x}+y \frac{\partial}{\partial u}, \quad X_{3}=\frac{\partial}{\partial t} \\
& X_{4}=x \frac{\partial}{\partial x}+y \frac{\partial}{\partial y}+2 t \frac{\partial}{\partial t}, \quad X_{5}=x \frac{\partial}{\partial x}+u \frac{\partial}{\partial u} . \tag{17}
\end{align*}
$$

It is shown in Proposition 1 that the kernel of the symmetry operators of Equation (5) has the widest expansion with Lie subalgebra with dimensions equal to four. If there were an analogue to the Stepanov-Mangler transformation, then the algebras of symmetry operators of Equations (14) and (5) should be isomorphic. But subalgebras with different dimensions could not be isomorphic. This means that there is no analogue of the StepanovMangler transformation for Equations (14) and (5).

## 5. Conclusions

We have considered the unsteady equations of flat and axisymmetric boundary layers. For the unsteady axisymmetric boundary layer equation, we have solved the group classification problem. We have shown that the kernel of symmetry operators can be extended by no more than a four-dimensional Lie algebra. We have found the kernel of symmetry operators of the unsteady flat boundary layer equation and have shown that it can be extended by no more than a five-dimensional Lie algebra. We have proved the non-existence of the unsteady analogue of the Stepanov-Mangler transformation.

The results of group classification can be used to construct new exact solutions and reductions of the unsteady axisymmetric boundary layer equation.

Author Contributions: Conceptualization and methodology, A.V.A. and A.A.K.; formal analysis and investigation, A.V.A. and A.A.K.; construction of symmetries and group classification, A.V.A. and A.A.K.; writing-original draft preparation, A.V.A. and A.A.K.; writing-review and editing, A.V.A.; supervision, A.V.A. All authors have read and agreed to the published version of the manuscript.

Funding: This research received no external funding.
Data Availability Statement: Data are contained within the present article.
Conflicts of Interest: The authors declare no conflicts of interest.

## References

1. Loitsyanskiy, L.G. Laminar Boundary Layers; Fizmatlit: Moscow, Russia, 1962. (In Russian)
2. Schlichting, H. Boundary Layer Theory, 7th ed.; McGraw-Hill: New York, NY, USA, 1975.
3. Loitsyanskiy, L.G. Mechanics of Liquids and Gases; Begell House: New York, NY, USA, 1995.
4. Stepanov, E.I. On the integration of laminar boundary layer equations for motion with axial symmetry. Prikl. Mat. I Mekhanika 1947, 9, 203-204. (In Russian)
5. Mangler, W. Zusammenhang zwischen ebenen und rotationssymmetrischen Grenzschichten in kompressiblen Flussigkeiten. Z. Fur Angew. Math. Und Mech. Ingenieurwissenschaftliche Forschungsarbeiten 1948, 28, 97-103. [CrossRef]
6. Ovsiannikov, L.V. Group Analysis of Differential Equations; Academic Press: Boston, MA, USA, 1982.
7. Pavlovskii, Y.N. Investigation of some invariant solutions to the boundary layer equations. Zhurn. Vychisl. Mat. I Mat. Fiz. 1961, 1, 280-294. (In Russian)
8. Ma, P.K.H.; Hui, W.H. Similarity solutions of the two-dimensional unsteady boundary layer equations. J. Fluid Mech. 1990, 216, 537-559. [CrossRef]
9. Ignatovich, N.V. Partially invariant solutions, that are not reducible to invariant ones, of the equations of a steady boundary layer. Math. Notes 1993, 53, 98-100. [CrossRef]
10. Clarkson, P.A.; Kruskal, M.D. New similarity reductions of the Boussinesq equation. J. Math. Phys. 1989, 30, 2201-2213. [CrossRef]
11. Ludlow, D.K.; Clarkson, P.A.; Bassom, A.P. New similarity solutions of the unsteady incompressible boundary-layer equations. Quart. J. Mech. Appl. Math. 2000, 53, 175-206. [CrossRef]
12. Aksenov, A.V.; Kozyrev, A.A. New Reductions of the Unsteady Axisymmetric Boundary Layer Equation to ODEs and Simpler PDEs. Mathematics 2022, 10, 1673. [CrossRef]
13. Aksenov, A.V.; Kozyrev, A.A. Reductions of Stationary Boundary Layer Equation. Ufa Math. J. 2012, 4, 3-12.
14. Aksenov, A.V.; Kozyrev, A.A. Reductions of the Stationary Boundary Layer Equation with a Pressure Gradient. Dokl. Math. 2013, 87, 236-239. [CrossRef]
15. Aksenov, A.V.; Polyanin, A.D. Methods for constructing complex solutions of nonlinear PDEs using simpler solutions. Mathematics 2021, 9, 345. [CrossRef]
16. Burde, G.I. A class of solutions of the boundary layer equations. Fluid Dyn. 1990, 25, 201-207. [CrossRef]
17. Burde, G.I. New similarity reductions of the steady-state boundary layer equations. J. Phys. A Math. Gen. 1996, 29, 1665-1683. [CrossRef]
18. Burde, G.I. The Construction of Special Explicit Solutions of the Boundary-Layer Equations: Steady Flows. Quart. J. Mech. Appl. Math. 1994, 47, 247-260. [CrossRef]
19. Burde, G.I. The construction of special explicit solutions of the boundary-layer equations: Unsteady flows. Quart. J. Mech. Appl. Math. 1995, 48, 611-633. [CrossRef]
20. Saccomandi, G. A remarkable class of non-classical symmetries of the steady two-dimensional boundary-layer equations. J. Phys. A Math. Gen. 2004, 37, 7005-7017. [CrossRef]
21. Polyanin, A.D. Exact solutions and transformations of the equations of a stationary laminar boundary layer. Theor. Found. Chem. Eng. 2001, 35, 319-328. [CrossRef]
22. Polyanin, A.D.; Zaitsev, V.F. Handbook of Nonlinear Partial Differential Equations, 2nd ed.; CRC Press: Boca Raton, FL, USA, 2012.
23. Polyanin, A.D.; Zhurov, A.I. Separation of Variables and Exact Solutions to Nonlinear PDEs; CRC Press: Boca Raton, FL, USA, 2021.
24. Polyanin, A.D. Transformations and exact solutions containing arbitrary functions for boundary-layer equations. Dokl. Phys. 2001, 46, 526-531. [CrossRef]
25. Polyanin, A.D.; Zaitsev, V.F. Equations of an unsteady-state laminar boundary layer: General transformations and exact solutions. Theor. Found. Chem. Eng. 2001, 35, 529-539. [CrossRef]
26. Polyanin, A.D.; Zhurov, A.I. Unsteady axisymmetric boundary-layer equations: Transformations, properties, exact solutions, order reduction and solution method. Int. J. Non-Linear Mech. 2015, 74, 40-50. [CrossRef]
27. Polyanin, A.D.; Zhurov, A.I. Direct functional separation of variables and new exact solutions to axisymmetric unsteady boundary-layer equations. Commun. Nonlinear Sci. Numer. Simul. 2016, 31, 11-20. [CrossRef]
28. Ibragimov, N.H. Transformation Groups Applied to Mathematical Physics; Springer: Dordrecht, The Netherlands, 1985.
29. Olver, P.J. Applications of Lie Groups to Differential Equations; Springer: New York, NY, USA, 1986.

Disclaimer/Publisher's Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.

