


Supplementary: Robust Online Support Vector Regression with Truncated ε -Insensitive Pinball Loss

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Definition 1. [Strong pseudo-convexity] A function $f : \chi \rightarrow R$ is said to be strongly pseudo-convex (SPC) on $\chi_1 \subset \chi$ with respect to $\bar{x} \in \chi$, if

$$f(x) - f(\bar{x}) \leq K \langle f'(x), x - \bar{x} \rangle \quad (1)$$

holds for all $x \in \chi_1$, with $f'(x)$ a Clarke subgradient of f at x , $K > 0$ is a constant. If the Inequality (1) holds with respect to any $\bar{x} \in \chi_1$, f is called SPC on $\chi_1 \subset \chi$. The collection of SPC functions on χ_1 with $K > 0$ are denoted as $\mathcal{W}_K(\chi_1)$.

Proposition 1. Let $f : R \rightarrow R$ be a univariate continuous function. Assume that on each interval of $(-\infty, a]$, (a, b) , $[b, \infty)$, $f(x)$ is convex, and $f'_-(a) < 0$, $f'_+(b) > 0$, $f'_+(a) \neq 0$, $f'_-(b) \neq 0$. Then we have that the Inequality (1) holds for any fixed $\bar{x} \in R$ and $x \in R$ with

$$K = \max \left\{ 1, \frac{f'_-(a)}{f'_+(a)}, \frac{f'_+(a)}{f'_-(a)}, \frac{f'_-(b)}{f'_+(b)}, \frac{f'_+(b)}{f'_-(b)}, \frac{f'_-(a)}{f'_+(b)}, \frac{f'_+(b)}{f'_-(a)} \right\} \quad (2)$$

Proposition 2. Let $f : R \rightarrow R$ be a univariate continuous function. Let $a_0 < a_1 < \dots < a_m$ be the real numbers, $a_0 = -\infty$ and $a_m = +\infty$. On each interval of $[a_i, a_{i+1}]$, $f(x)$ is convex, and $i = 0, 1, \dots, m-1$. Let S be the set of the minimum points of f on R . Suppose that the optimal solution set $S \in [a_q, a_{q+1}]$. With $q \in [0, \dots, m-1]$. Moreover, suppose that $f(x)$ is strictly decreasing when $X \leq \text{Inf} S$ and strictly increasing when $X \geq \text{Sup} S$. Then, for any fixed $\bar{x} \in [a_0, a_m]$ and $x \in [a_0, a_m]$. Inequality (1) holds with

$$K = \max \left\{ 1, \frac{f'_+(a_\mu)}{f'_-(a_{v+1})}, \frac{f'_-(a_i)}{f'_+(a_j)} \mid q \in [0, \dots, m-1], \mu \in [v+1, \dots, q] \right. \\ \left. v \in [0, \dots, q-1], i \in [q+1, \dots, j], j \in [q+1, \dots, m-1] \right\} \quad (3)$$

Lemma 1. Denote $\Omega_0 = [t_0 - \delta/\tau - C, t_0 - \delta/\tau] \cup [t_0 + \delta, t_0 + \delta + C]$, suppose that $0 \notin \Omega_0$, $f(t) = \frac{1}{2}t^2 + C \cdot L_{TIP}((t - t_0))$ is SPC on $R \setminus \Omega_0$ with $K = \max \left\{ 2, 1 + \frac{C \cdot \tau^2}{\delta}, 1 + \frac{C \cdot \tau}{\delta \cdot \tau - \varepsilon} \right\}$.

Proof:

Suppose that $t_0 \leq 0$

$$C \cdot L'_{TIP}(t - t_0) = \begin{cases} -C \cdot \tau, & -\delta/\tau + t_0 \leq t < -\varepsilon/\tau + t_0 \\ 0, & \text{otherwise} \\ C, & \varepsilon + t_0 \leq t < \delta + t_0 \end{cases} \quad (4)$$

$$\left(\frac{1}{2}t^2 \right)' = t \quad (5)$$

Let $a = t_0 - \delta/\tau$, $b = t_0 + \delta$, $\Omega_1 = (-\infty, a)$, $\Omega_2 = [a, b]$, $\Omega_3 = (b, \infty)$, $\Omega_0 = [a - C, a] \cup [b, b + C]$.

Case 1: $t_0 \in [-\varepsilon/\tau, 0]$

We can see that $f(t)$ is continuous on R and convex on every interval of Ω_i , $i = 1, 2, 3$. The directional derivatives of f at point a are calculated as follows:

$$f'_-(a) = a; f'_+(a) = a - C \cdot \tau \quad (6)$$

As $a < 0$, the above two directional derivatives are negative. The directional derivatives of f at point b are calculated as follows:

$$f'_-(b) = b + C; f'_+(b) = b \quad (7)$$

For $\delta > \frac{\varepsilon}{\tau}$, $b > 0$, both of the above two directional derivatives are positive. By Proposition 1, we have $f(t)$ is strongly pseudoconvex in R for any fixed $\bar{t} \in R$, where

$$K = \max\{1, \frac{a - C \cdot \tau}{a}, \frac{b + C}{b}\} \leq \max\{1 + \frac{C \cdot \tau^2}{\delta}, 1 + \frac{C \cdot \tau}{\tau \cdot \delta - \varepsilon}\}. \quad (8)$$

Case 2: $t_0 \in [-\delta, -\varepsilon/\tau]$

When $f'_-(a) = a < 0$, $f'_+(b) = b > 0$, $t^* \in \operatorname{argmin} f \in \Omega_2$ and $f(t)$ is continuous on R and convex on every interval of Ω_i , $i = 1, 2, 3$. The directional derivative of f at a and b are calculated in the same way with case 1. By Proposition 1, we have $f(t)$ is strongly pseudoconvex in R for any fixed $\bar{t} \in R$, where

$$K = \max\{1, \frac{a - C \cdot \tau}{a}, \frac{b + C}{b}\} \leq \max\{1 + \frac{C \cdot \tau^2}{\varepsilon + \delta}, 1 + \frac{C}{b}\}. \quad (9)$$

The last equation is $0 < b < \delta - \varepsilon/\tau$. Specially, let's consider the strong pseudoconvexity of $f(t)$ on $R \setminus \Omega_0$. Define function $f(t) : R \rightarrow R$ as follows:

$$\tilde{f} = \begin{cases} f(t), & t \in R \setminus (b, b + C) \\ f(b) + \frac{f(b+C) - f(b)}{C} \cdot t, & t \in [b, b + C] \end{cases} \quad (10)$$

Then $\tilde{f}(t)$ is a continuous function of one variable and convex on every interval of Ω_1 , Ω_2 , $[b, b + C]$ and $[b + C, \infty]$. Its directional derivatives at a are the same as the directional derivatives of f calculated in Equation (6). Its directional derivatives at b and $b + C$ are calculated as

$$\tilde{f}'_-(b) = b + C; \tilde{f}'_+(b + C) = b + C \quad (11)$$

$$\tilde{f}'_-(b + C) = b + \frac{1}{2}C; \tilde{f}'_+(b) = b + \frac{1}{2}C \quad (12)$$

According to Proposition 1, we have $\tilde{f}(t) \in \chi_K(R)$, where

$$\begin{aligned} K &= \max\{1, \frac{f'_+(v)}{f'_-(v)}, \frac{f'_-(v)}{f'_+(v)}, \frac{f'_-(b)}{f'_+(b+C)} \mid v \in \{a, b, b + C\}\} \\ &= \max\{1, \frac{a - C \cdot \tau}{a}, \frac{b + C}{b + \frac{1}{2}C}, \frac{b + C}{b + C}\} \\ &\leq \max\{2, 1 + \frac{C \cdot \tau^2}{\delta + \varepsilon}\} \end{aligned} \quad (13)$$

The last two inequalities are true because $a < -\delta - \varepsilon/\tau < 0$, $b > 0$. Since $\tilde{f}(t)$ and $f(t)$ have the same definition on $R \setminus \Omega_0$, we have $f(t) \in \chi_K(R \setminus \Omega_0)$, K is defined by the above equation.

Case 3: $t_0 \in (-\infty, -\delta)$

Consider that $t \in [t_0 + \varepsilon, t_0 + \delta]$. In this interval, $f(t) = C \cdot [(t - t_0) - \varepsilon] + \frac{1}{2}t^2$. Then $f'(t) = C + t$ is increasing with t . The assumption of the lemma implies that $t_0 + \delta < -C$, then $\forall t \in [t_0 + \varepsilon, t_0 + \delta]$, $f'(t) < 0$ for $t \in \Omega_1 \cup \Omega_2$. In this case, $f(t)$ is convex on each

interval of $\Omega_i, i = 1, 2, 3$, and there exists a unique minimizer $t^* \in \Omega$ of $f(t)$. Moreover, $f'(t) < 0$ for $t < t^*$ and $f'(t) > 0$ for $t > t^*$. By Proposition 1, we have that $f(t)$ is strongly pseudo-convex on R with

$$\begin{aligned} K &= \max \left\{ 1, \frac{f'_+(v)}{f'_-(v)}, \frac{f'_-(v)}{f'_+(v)}, \frac{f'_-(a)}{f'_+(b)}, \frac{f'_+(b)}{f'_-(a)} \mid v \in \{a, b\} \right\} \\ &= \max \left\{ 1, \frac{a - C \cdot \tau}{a}, \frac{b}{b + C}, \frac{a}{b}, \frac{b}{a} \right\} \\ &\leq \max \left\{ 1 + \frac{C \cdot \tau^2}{\delta \cdot \tau + \delta}, 1 - \frac{C}{b + C}, 1 + \frac{\delta \cdot \tau + \delta}{C \cdot \tau} \right\} \end{aligned} \quad (14)$$

Particularly, let's consider the strong pseudo-convexity of $f(t)$ on $R \setminus \Omega_0$. Consider the function $\tilde{f}(t) : R \rightarrow R$. It is observed that \tilde{f} is a continuous and piecewise-convex function. Its directional derivations at b , and $b + C$ are calculated as described above. By Proposition 2, we have that $f(t) \in \chi_K(R)$ with

$$\begin{aligned} K &= \max \left\{ 1, \frac{f'_+(v)}{f'_-(v)}, \frac{f'_-(v)}{f'_+(v)}, \frac{f'_-(b)}{f'_+(b + C)}, \frac{f'_+(b + C)}{f'_-(b)} \mid v \in \{a, b, b + C\} \right\} \\ &= \max \left\{ 1, \frac{a - C \cdot \tau}{a}, \frac{b + C}{b + \frac{1}{2}C}, \frac{b + C}{b} \right\} \\ &\leq \max \left\{ 2, 1 + \frac{C \cdot \tau^2}{\delta \cdot \tau + \delta}, 1 \right\} \\ &\leq \max \left\{ 2, 1 + \frac{C \cdot \tau^2}{\delta \cdot \tau + \delta} \right\} \end{aligned} \quad (15)$$

Likewise, we can acquire the proof regarding $t_0 \geq 0$.

In summary, $K = \max \left\{ 2, 1 + \frac{C \cdot \tau^2}{\delta \cdot \tau + \delta}, 1 + \frac{C \cdot \tau}{\delta \cdot \tau - \varepsilon} \right\}$.

Assumption 1: We assume that $X > 0$ exists such that $K(\mathbf{X}_t, \mathbf{X}_t) \leq X^2$ for all t . The following proposition could be obtained according to the assumption:

(1) For each $f \in \mathcal{H}$, $|f(\mathbf{X}_t)| = |\langle f, K(\mathbf{X}_t, -) \rangle| \leq X \cdot \|f\|_{\mathcal{H}}$.

(2) For given that $L'_{TIP} < 1$, we have $\left\| \partial_f L_{TIP}(f(\mathbf{X}_t) - y_t) \right\|_{\mathcal{H}} \leq \frac{X}{C}$ and

$\left\| \partial_f R_{inst}[f, \mathbf{X}_t, y_t] \right\|_{\mathcal{H}} \leq CX + \|f\|_{\mathcal{H}} \leq 2X$ for any $f : \|f\|_{\mathcal{H}} \leq X$.

(3) For fixed $C > 0$ and $t = 1, 2, \dots, f^t$ generated by TIPOSVR satisfied $f : \|f\|_{\mathcal{H}} \leq X$.

Proof:

$$\begin{aligned} \|f^{t+1}\|_{\mathcal{H}} &\leq \|(1 - \gamma_t)f^t - C \cdot \eta_t L'_{TIP}(f(\mathbf{X}_t) - y_t)K(\mathbf{X}_t, \cdot)\|_{\mathcal{H}} \leq (1 - \gamma_t)\|f^t\|_{\mathcal{H}} \\ &+ \gamma_t X \end{aligned}$$

Given $f^0 = 0$, we have $\|f\|_{\mathcal{H}} \leq X$.

Lemma 2: Let the sequence instance (\mathbf{X}_t, y_t) satisfy $k(\mathbf{X}_t, \mathbf{X}_t) \leq X^2$. For a fixed $g \in \mathcal{H}$

$$u^t = (f^t - g) / \|f^t - g\|, t_0 = y_t - g(\mathbf{X}_t) + u^t(\mathbf{X}_t) \cdot \langle u^t, g \rangle,$$

$$\Omega_0 = \left[-\delta/\tau - (u^t(\mathbf{X}_t))^2, -\delta/\tau \right] \cup \left[\delta, \delta + (u^t(\mathbf{X}_t))^2 \right]$$

Assuming $t_0 \notin \Omega_0, \xi_t = f^t(\mathbf{X}_t) - y_t \notin \Omega_0$, we have

$$R_{inst}[f^t, \mathbf{X}_t, y_t] - R_{inst}[g, \mathbf{X}_t, y_t] \leq K \cdot \left\langle \partial_f R_{inst}[f^t, \mathbf{X}_t, y_t] \Big|_{f=f^t}, f^t - g \right\rangle_{\mathcal{H}} \text{ with}$$

$$K = \max \left\{ 2, 1 + \frac{C \cdot \tau^2 X^2}{\delta}, 1 + \frac{C \cdot \tau X^2}{\delta \cdot \tau - \varepsilon} \right\}. \quad (16)$$

Proof:

Let $f = g + \alpha u^t$, $\|u^t\| = 1$.

According to the definition of R_{inst} :

$$R_{inst}[f, \mathbf{X}_t, y_t] = C \cdot L_{TIP}[g(\mathbf{X}_t) + \alpha u^t(\mathbf{X}_t) - y_t] + \frac{1}{2}\|g + \alpha u^t\|^2 + \text{constant},$$

Let $\xi = g(\mathbf{X}_t) + \alpha u^t(\mathbf{X}_t) - y_t \in R$, $t_0 = y_t - g(\mathbf{X}_t) + u^t(\mathbf{X}_t)(u^t, g)$,

$$\xi + t_0 = \alpha u^t(\mathbf{X}_t) + u^t(\mathbf{X}_t)(u^t, g) = u^t(\mathbf{X}_t)[\alpha + (u^t, g)]$$

With the definition of $\|u^t\| = 1$, $R_{inst}[f, \mathbf{X}_t, y_t]$ satisfies the strong pseudoconvex inequality, i.e.,

$$R_{inst}[f^t, \mathbf{X}_t, y_t] - R_{inst}[g, \mathbf{X}_t, y_t] \leq K \cdot \left\langle \partial_f R_{inst}[f^t, \mathbf{X}_t, y_t] \Big|_{f=f^t}, f^t - g \right\rangle_{\mathcal{H}}$$

holds as the univariate function on the right-hand side of as α is strongly pseudoconvex.

We have

$$\phi(\xi) = R_{inst}[f, \mathbf{X}_t, y_t] = C \cdot L_{TIP}[\xi] + \frac{1}{2[u^t(\mathbf{X}_t)]^2}[\xi + t_0]^2 + \text{constant}$$

Therefore, according to the above lemma, $\phi(\xi + t_0)$ satisfies strong pseudoconvexity when $\xi \in R \setminus \Omega_0$ with

$$\begin{aligned} K &= \max \left\{ 2, 1 + \frac{C \cdot \tau^2 [u^t(\mathbf{X}_t)]^2}{\delta}, 1 + \frac{C \cdot \tau [u^t(\mathbf{X}_t)]^2}{\delta \cdot \tau - \varepsilon} \right\} \\ &\leq \max \left\{ 2, 1 + \frac{C \cdot \tau^2 X^2}{\delta}, 1 + \frac{C \cdot \tau X^2}{\delta \cdot \tau - \varepsilon} \right\}. \end{aligned} \quad (17)$$

Theorem 1: Set example sequence $S = \{(\mathbf{X}_t, y_t)\}_{t=0}^T$ be $k(\mathbf{X}_t, \mathbf{X}_t) \leq X^2$ holds for all t . (f^0, \dots, f^T) represents a hypothetical sequence produced by TIPOSVR, $R_{inst}[g, S] = \frac{1}{T} \sum_{t=1}^T R_{inst}[g, \mathbf{X}_t, y_t]$, and $\hat{g} = \arg \min_{g \in \mathcal{H}} R_{inst}[g, S]$. Fixed $C, \varepsilon > 0, 0 < \eta < C$ and set the learning rate $\eta_t = \eta \cdot t^{-1/2}$. We assume that each hypothesis f^t generated by TIPOSVR satisfies the hypothesis stated in Lemma 2, for $t = 0, 1, 2 \dots T$. And then we have the following expression

$$\frac{1}{T} \sum_{t=1}^T R_{inst}[f^t, \mathbf{X}_t, y_t] \leq R_{inst}[\hat{g}, S] + \alpha T^{-1/2} + o(T^{-1/2}) \quad (18)$$

Among them, $\alpha = \frac{2KX^2}{\eta} + 4KX^2\eta$, $K = \max \left\{ 2, 1 + \frac{C \cdot \tau^2 X^2}{\delta}, 1 + \frac{C \cdot \tau X^2}{\delta \cdot \tau - \varepsilon} \right\}$

Proof:

From the strong pseudo-convexity of R_{inst} in lemma 2 and the Lipschitz property of R_{inst} in the first argument, the following expressions are derived:

$$\begin{aligned} &\|f^t - \hat{g}\|_{\mathcal{H}}^2 - \|f^{t+1} - \hat{g}\|_{\mathcal{H}}^2 \\ &= -\|f^{t+1} - f^t\|_{\mathcal{H}}^2 - \left\langle f^{t+1} - f^t, f^{t+1} - \hat{g} \right\rangle_{\mathcal{H}} \\ &= -\eta_t^2 \left\| \partial_f R_{inst}[f^t, \mathbf{X}_t, y_t] \right\|_{\mathcal{H}}^2 + 2\eta_t \left\langle \partial_f R_{inst}[f^t, \mathbf{X}_t, y_t] \Big|_{f=f^t}, f^t - \hat{g} \right\rangle_{\mathcal{H}} \\ &\geq -4\eta_t^2 X^2 - \frac{2\eta_t}{K} (R_{inst}[\hat{g}, \mathbf{X}_t, y_t] - R_{inst}[f^t, \mathbf{X}_t, y_t]) \end{aligned}$$

Here, $K = \max \left\{ 2, 1 + \frac{C \cdot \tau^2 X^2}{\delta}, 1 + \frac{C \cdot \tau X^2}{\delta \cdot \tau - \varepsilon} \right\}$,

Then there are

$$\begin{aligned}
& \frac{1}{\eta_t} \|f^t - \hat{g}\|_{\mathcal{H}}^2 - \frac{1}{\eta_{t+1}} \|f^{t+1} - \hat{g}\|_{\mathcal{H}}^2 \\
&= \frac{1}{\eta_t} \left(\|f^t - \hat{g}\|_{\mathcal{H}}^2 - \|f^{t+1} - \hat{g}\|_{\mathcal{H}}^2 \right) + \left(\frac{1}{\eta_t} - \frac{1}{\eta_{t+1}} \right) \|f^{t+1} - \hat{g}\|_{\mathcal{H}}^2 \\
&\geq -4\eta_t X^2 - \frac{2}{K} \left(R_{inst}[\hat{g}, \mathbf{X}_t, y_t] - R_{inst}[f^{t+1}, \mathbf{X}_t, y_t] \right) + \left(\frac{1}{\eta_t} - \frac{1}{\eta_{t+1}} \right) 4X^2
\end{aligned}$$

Considering $\|f^{t+1} - \hat{g}\|_{\mathcal{H}} \leq 2X$, $\eta_{T+1} = \eta(T+1)^{-1/2}$, by summing $\sum_{t=1}^T \eta_t \leq 2\eta T^{1/2}$, we get the following expression

$$\begin{aligned}
& \frac{1}{\eta} \|f^1 - \hat{g}\|_{\mathcal{H}}^2 - \frac{1}{\eta_{T+1}} \|f^{T+1} - \hat{g}\|_{\mathcal{H}}^2 \\
&\geq \sum_{t=1}^T -4\eta_t X^2 - \frac{2}{K} \sum_{t=1}^T (R_{inst}[\hat{g}, \mathbf{X}_t, y_t] - R_{inst}[f^t, \mathbf{X}_t, y_t]) + \left(\frac{1}{\eta} - \frac{1}{\eta_{T+1}} \right) 4X^2
\end{aligned}$$

So,

$$\begin{aligned}
& -\frac{2}{K} \sum_{t=1}^T (R_{inst}[\hat{g}, \mathbf{X}_t, y_t] - R_{inst}[f^t, \mathbf{X}_t, y_t]) \\
&\leq \frac{1}{\eta} \|f^1 - \hat{g}\|_{\mathcal{H}}^2 - \frac{1}{\eta_{T+1}} \|f^{T+1} - \hat{g}\|_{\mathcal{H}}^2 - \left(\frac{1}{\eta} - \frac{(T+1)^{1/2}}{\eta} \right) 4X^2 + 8\eta X^2 T^{1/2} \\
&\leq \frac{4X^2}{\eta} - \frac{(2X)^2}{\eta_{T+1}} + \frac{(T+1)^2 - 1}{\eta} 4X^2 + 8\eta X^2 T^{1/2} \\
&\leq \frac{X^2}{\eta} + \frac{T^{1/2}}{\eta} 4X^2 + 8\eta X^2 T^{1/2}
\end{aligned}$$

And we can get,

$$\begin{aligned}
& -\frac{1}{T} \sum_{t=1}^T (R_{inst}[\hat{g}, \mathbf{X}_t, y_t] - R_{inst}[f^t, \mathbf{X}_t, y_t]) \\
&\leq \frac{2KX^2}{\eta} T^{-1} + 4KX^2 \eta T^{-1/2} + \frac{2KX^2}{\eta} T^{-1/2} \\
&= \frac{2KX^2}{\eta} T^{-1} + \alpha T^{-1/2} \\
&\alpha = \frac{2KX^2}{\eta} + 4KX^2 \eta.
\end{aligned}$$