



Article Research on Rumor-Spreading Model with Holling Type III Functional Response

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Abstract: In this paper, a rumor-spreading model with Holling type III functional response was established. The existence of the equilibrium points was discussed. According to the Routh–Hurwitz criteria, the locally asymptotic stability of the equilibrium points was analyzed. The global stability of the equilibrium points was proven based on Lasalle's invariance principle and generalized Bendixson–Dulac theorem. Numerical simulations were carried out to illustrate the impact of different parameters on the spread of rumors. When the stifling rate λ increases, or the predation capacity β or the system coming rate *k* decreases, the number of rumor-spreaders is reduced to extinction. The results provide theory, method and decision support for effectively controlling the spread of rumors.

Keywords: rumor-spreading model; Holling type III; generalized Bendixon–Dulac theorem; stability

MSC: 90B99



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1. Introduction

Most rumors are not based on corresponding facts but fabricated and spread by certain means. They are kinds of false information that deviates from the truth or is widely spread as "truth" when the truth is temporarily missing, and the information has not been verified [1]. As an unfavorable social phenomenon, the spread of rumors hinders the healthy development of public opinions and affects the stability of society when it becomes serious [2,3]. With the wide use of social media, such as the open, convenient and efficient WeChat and Micro-blog, various kinds of rumors add to the pressure on the information supervision of major platforms and challenge public social security and crisis management. Therefore, how to effectively control the spread of rumors is not only a practical problem that needs to be solved by major platform managers, government departments and corporations but also one of the essential scientific issues to be studied in the fields of public social security, social governance and crisis management.

Allport and Postman believed that the spread of rumors is related to its importance and fuzziness and put forward the rumor intensity formula: $R = I \times A$, where *R* represents the intensity of the spread of rumors, *I* is the importance of rumors to the public and *A* is the fuzziness of information [4]. In other words, the emergence of rumors is proportional to the importance and the fuzziness of events. The more important and the fuzzier the events are, the greater effect the rumors may exert. The two elements are indispensable to the formation of rumors. When one of them is zero, rumors cannot exist.

The spread of rumors is similar to the spread of infectious. In 1965, Daley and Kendall, based on the classical SIR epidemic model, first proposed the rumor propagation dynamics model, namely the DK model [5–7]. Murray developed the DK model and proposed a mathematical model to study rumors [8]. Maki and Thomson revised the propagation rules of the DK model in 1973 and proposed the MT model [9]. When a spreader meets another spreader, he only changes to an immune person when the spreader loses interest,

while other spreaders are not affected. A rumor-spreading model with a latent period was proposed by Huo et al. The model assumes that a susceptible person first experiences a latent period after infection and then becomes a spreader or a stifler [10].

In recent years, the study of rumor propagation has experienced a variety of explorations. Some studies focus on the spreading of rumors online [11–13]. Based on the actual situation of the investor network, Yao and Gao et al. discussed a SE2IR rumor-spreading model with a hesitating mechanism [14]. Xu et al. researched an online rumor model with on scale-free networks considering psychological factors [15]. Liu et al. analyzed an SEIR rumor-spreading model on a heterogeneous network considering removing nodes [16]. According to the differences of individual behavior response in a complex network, Zhao et al. proposed a rumor-spreading model considering forgetting and remembering mechanisms in an inhomogeneous network [17]. Some scholars pay attention to the time delay of rumor propagation. In the epidemic model, time delays are often indicated immune period or latent period [18]. By considering the forgetting effect, Li et al. studied a rumor-spreading model with time delay [19]. By considering a saturated control function, li et al. established a time delay rumor-spreading model in emergencies [20,21].

Scholars have improved and studied the rumors spreading model from different perspectives. However, there are relatively few models referring to the interaction among species in mathematical ecology. The predator–prey model can be used to describe the interaction between two species. Holling proposes three kinds of functional response functions, which play an important role in predator–prey system [22,23]. Some scholars have studied the dynamics system with Holling type III functional response [24–27]. A rumor-spreading model with Holling-II functional response was established by Huo et al. [28]. The Holling type III functional response $f(x) = \frac{\beta x^2}{\alpha + x^2}$ represents the predation capacity of vertebrates. β is the maximum intake of the spread of rumors and α is semi saturation constant.

This paper integrates it with Holling type III functional response in mathematical ecology to construct a new rumor-spreading model; theoretical analysis and numerical simulation of the dynamic behavior of the model was conducted, and the change in parameters on rumor spreading was discussed. The findings of this paper provide a theoretical basis for the government management departments to control the spread of rumors effectively.

2. Model Construction

(2)

In this paper, the individuals are subdivided into three groups: susceptible person S, rumor-spreading person I and stiflers R. Rumor susceptible person S is the rumor ignorant person, who has never heard rumors and has not received relevant science education, so he is easily affected by rumors. The rumor-spreading person I, not only knows rumors but also spreads rumors to a susceptible person S. Stiflers R is the one who receives rumors but does not spread them.

Basic assumptions of the model:

(1) *k* is the coming rate of the susceptible person;

When the susceptible person *S* meets the rumor-spreading person *I*, they spread the rumor with Holling type III functional response $\frac{\beta SI^2}{\alpha + I^2}$ and become the rumor-spreading person; β is the capture rate of the rumor-spreading person and the maximum intake of the spread of rumors. α is semi saturation constant;

- (3) The rumor-spreading person *I* transits to the stiflers *R* with probability λ ;
- (4) μ is the leaving rate of the population.

Based on the basic assumptions of the model, the rumor-spreading process with Holling type III functional response is shown in Figure 1:



Figure 1. Structure of the rumor-spreading process with Holling type III functional response.

According to the above assumptions, the following mathematical model is established:

$$\begin{cases} \frac{dS}{dt} = k - \frac{\beta S I^2}{\alpha + I^2} - \mu S = f_1, \\ \frac{dI}{dt} = \frac{\beta S I^2}{\alpha + I^2} - \lambda I R - \mu I = f_2, \\ \frac{dR}{dt} = \lambda I R - \mu R = f_3, \end{cases}$$
(1)

The model satisfies the initial condition:

Lemma 1. Closed set $\Omega = \{(S, I, R) \in R^3_+, S + I + R \leq \frac{k}{\mu}\}$ is a positive invariant set of the model.

Proof. Defining function W = S + I + R, we have

$$\frac{dW}{dt} = \frac{dS}{dt} + \frac{dI}{dt} + \frac{dR}{dt} = k - \mu(S + I + R) = k - \mu W,$$

that

$$\frac{dW}{dt} + \mu W = k,$$

we obtain

$$W(t) = \frac{k}{\mu} + (W(0) - \frac{k}{\mu})e^{-\mu t}$$

then

 $\lim_{t\to+\infty}W(t)=\frac{k}{\mu},$

thus

$$0 \le S(t) + I(t) + R(t) \le \frac{k}{\mu}$$

Therefore, the closed set Ω is a positive invariant set of the model, and the model is positive bounded. \Box

3. The Existence of Equilibrium Points

There are four equilibrium points in the model. The condition for the existence of the four equilibrium points are shown in Table 1:

The Equilibrium Point	The Condition for Existence of the Equilibrium Point
$E_1 = \left(rac{k}{\mu}, 0, 0 ight)$	None
$E_2 = \left(rac{k(eta+2\mu)+\sqrt{\Lambda}}{2\mu(eta+\mu)},rac{keta-\sqrt{\Lambda}}{2\mu(eta+\mu)},0 ight)$	$rac{k^2eta^2}{4lpha\mu^3(eta+\mu)}>1$
$\overline{E_3 = \left(rac{k(eta+2\mu)-\sqrt{\Lambda}}{2\mu(eta+\mu)}, rac{keta+\sqrt{\Lambda}}{2\mu(eta+\mu)}, 0 ight)}$	$rac{k^2eta^2}{4lpha\mu^3(eta+\mu)}>1$
$E_4 = \left(\frac{k(\alpha\lambda^2 + \mu^2)}{\mu(\alpha\lambda^2 + \beta\mu + \mu^2)}, \frac{\mu}{\lambda}, \frac{k\beta\lambda - \mu(\alpha\lambda^2 + \beta\mu + \mu^2)}{\alpha\lambda^3 + \lambda\mu(\beta + \mu)}\right)$	$rac{keta\lambda}{\mu(lpha\lambda^2+eta\mu+\mu^2)}>1$

Table 1. The condition for the existence of the four equilibrium points.

Among them, $\Lambda = k^2 \beta^2 - 4\alpha \mu^3 (\beta + \mu)$.

4. Stability of the Equilibrium Points

The Jacobian matrix of the model is

$$J = \begin{pmatrix} -\frac{\beta I^2}{\alpha + I^2} - \mu & -\frac{2\alpha\beta SI}{(\alpha + I^2)^2} & 0\\ \frac{\beta I^2}{\alpha + I^2} & \frac{2\alpha\beta SI}{(\alpha + I^2)^2} - \lambda R - \mu & -\lambda I\\ 0 & \lambda R & \lambda I - \mu \end{pmatrix}$$
(2)

4.1. Stability of the Equilibrium Point E_1

The characteristic roots of the Jacobian matrix (2) for the equilibrium point $E_1 = (\frac{k}{\mu}, 0, 0)$ is

$$\rho_i = -\mu < 0, \ (i = 1, 2, 3).$$

Therefore, the rumor-free equilibrium point E_1 is locally asymptotically stable according to Routh–Hurwitz criteria.

Constructing Lyapunov function

$$V = \frac{1}{2}(S - S_1 + I - I_1 + R - R_1)^2$$

obviously

$$V(t) \ge 0,$$

and

$$\begin{aligned} \frac{dV}{dt} &= (S - S_1 + I - I_1 + R - R_1) \left(\frac{dS}{dt} + \frac{dI}{dt} + \frac{dR}{dt} \right) \\ &= (S + I + R - (S_1 + I_1 + R_1))(k - \mu(S + I + R)) \\ &= \left(S + I + R - \frac{k}{\mu} \right) (k - \mu(S + I + R)) \\ &= -\frac{1}{\mu} (k - \mu(S + I + R))^2 \le 0. \end{aligned}$$

Thus, the equilibrium point E_1 is global asymptotically stable according to Lasalle's invariance principle.

4.2. Stability of the Equilibrium Point $E_2 = (S_2, I_2, 0)$

The characteristic roots of the Jacobian matrix (2) for the equilibrium point $E_2 = (S_2, I_2, 0)$ is:

$$\rho_1 = -\mu < 0,$$

$$\rho_2 = \frac{k\beta\lambda - 2\beta\mu^2 - 2\mu^3 - \lambda\sqrt{\Lambda}}{2\mu(\beta+\mu)},$$

$$\rho_3 = \frac{-\Lambda + k(\beta+2\mu)\sqrt{\Lambda}}{2\beta(k^2 + \alpha\mu^2)},$$

because $k\beta > \sqrt{\Lambda}$, $k\beta\sqrt{\Lambda} > \Lambda$, $-\Lambda + k(\beta + 2\mu)\sqrt{\Lambda} > 0$, so $\rho_3 > 0$.

Consequently, the equilibrium point E_2 is unstable based on the Routh–Hurwitz stability judgment.

4.3. Stability of the Equilibrium Point $E_3 = (S_3, I_3, 0)$

Theorem 1. *The equilibrium point* E_3 *is locally asymptotically stable if*

$$\frac{\lambda\left(k\beta+\sqrt{\Lambda}\right)}{2\mu^2(\beta+\mu)} < 1.$$
(3)

Proof. The characteristic roots of the Jacobian matrix (2) for the equilibrium point $E_3 = (S_3, I_3, 0)$ is: - 0

$$\begin{array}{l} \rho_1 = -\mu < 0,\\ \rho_2 = \frac{k\beta\lambda - 2\beta\mu^2 - 2\mu^3 + \lambda\sqrt{\Lambda}}{2\mu(\beta+\mu)},\\ \rho_3 = \frac{-\Lambda - k(\beta+2\mu)\sqrt{\Lambda}}{2\beta(k^2 + \alpha\mu^2)} < 0, \end{array}$$

when $\rho_2 < 0$, if $\frac{\lambda(k\beta+\sqrt{\Lambda})}{2\mu^2(\beta+\mu)} < 1$. As a result, according to the Routh–Hurwitz stability judgment, the equilibrium point *E*₃ is locally asymptotically stable if $\frac{\lambda(k\beta+\sqrt{\Lambda})}{2\mu^2(\beta+\mu)} < 1.$

Considering the Lyapunov function

$$V = \frac{1}{2}(S - S_3 + I - I_3 + R - R_3)^2,$$

obviously

$$V(t)\geq 0,$$

and

$$\frac{dV}{dt} = (S - S_3 + I - I_3 + R - R_3) \left(\frac{dS}{dt} + \frac{dI}{dt} + \frac{dR}{dt} \right)$$

= $(S + I + R - (S_3 + I_3 + R_3))(k - \mu(S + I + R))$
= $\left(S + I + R - \frac{k}{\mu} \right)(k - \mu(S + I + R))$
= $-\frac{1}{\mu}(k - \mu(S + I + R))^2 \le 0.$

Hence, Lasalle's invariance principle implies the equilibrium point E_3 is global asymptotically stable.

4.4. Stability of the Equilibrium Point $E_4 = (S_4, I_4, R_4)$

Theorem 2. The equilibrium point $E_4 = (S_4, I_4, R_4)$ is locally asymptotically stable if

$$\frac{\mu^2 (k\lambda + \alpha \lambda^2 + \beta \mu + \mu^2)}{\alpha k \lambda^3} > 1.$$
(4)

Proof. By computing, the characteristic roots of the Jacobian matrix (2) for the equilibrium E_4 is

$$\rho_1 = -\mu < 0$$

 ρ_2 , ρ_3 are the roots of the quadratic equation

$$A\rho^2 + B\rho + C = 0, (5)$$

among them, where

$$\begin{split} A &= 1 > 0, \\ B &= \frac{\lambda k \beta (-\alpha \lambda^2 + \mu^2) + \beta \mu^2 (\alpha \lambda^2 + \beta \mu + \mu^2)}{(\alpha \lambda^2 + \mu^2) (\alpha \lambda^2 + \beta \mu + \mu^2)}, \\ C &= \frac{\mu (k \beta \lambda - \mu (\alpha \lambda^2 + \beta \mu + \mu^2))}{\alpha \lambda^2 + \mu^2} > 0, \end{split}$$

when B > 0, if $\mu^2 (k\lambda + \alpha \lambda^2 + \beta \mu + \mu^2) > \alpha k \lambda^3$, then, $\rho_2 < 0$, $\rho_3 < 0$.

According to the Routh–Hurwitz criteria, the interior equilibrium point E_4 is locally asymptotically stable if

$$\frac{\mu^2(k\lambda+\alpha\lambda^2+\beta\mu+\mu^2)}{\alpha k\lambda^3}>1.$$

Denote that $\Omega_1 = \left\{ (S, I, R) \in R^3_+, S + I + R = \frac{k}{\mu} \right\}$ is a closed set, obviously Ω_1 is a positively attractive invariant subset of Ω . It was proved below that the model has no periodic solution. Let us first introduce the following Lemma 2.

Lemma 2 (Generalized Bendixson–Dulac Theorem). Assume $f : \mathbb{R}^3 \to \mathbb{R}^3$ is a Lipschitz continuous vector field, $\Gamma(t)$ is boundary curve of smooth directional surface $S \in \mathbb{R}^3$, it is closed, piecewise smooth. If $g : \mathbb{R}^3 \to \mathbb{R}^3$ is smooth in a neighborhood of S, satisfy for all t

$$g(\Gamma(t)) \cdot f(\Gamma(t)) \le 0 \quad (\ge 0), (Curlg) \cdot n \ge 0 \quad (\le 0),$$

on S, and point on S exists to satisfy

$$(Curlg) \cdot n > 0 (< 0),$$

where *n* is the normal unit vector of the surface *S*, then the direction of $\Gamma(t)$ and *n* form a righthanded system and $\Gamma(t)$ cannot be composed of the trajectories of the system x' = f(x) [29].

Theorem 3. The equilibrium point E_4 is global asymptotically stable if

$$\frac{\mu^2 (k\lambda + \alpha \lambda^2 + \beta \mu + \mu^2)}{\alpha k \lambda^3} > 1.$$
(6)

Proof. Let $f = (f_1, f_2, f_3)^T$, because $S + I + R = \frac{k}{\mu}$, we gain,

$$f_{1}(S, I) = k - \frac{\beta S I^{2}}{\alpha + I^{2}} - \mu S;$$

$$f_{1}(S, R) = k - \frac{\beta S \left(\frac{k}{\mu} - S - R\right)^{2}}{\alpha + \left(\frac{k}{\mu} - S - R\right)^{2}} - \mu S;$$

$$f_{2}(S, I) = \frac{\beta S I^{2}}{\alpha + I^{2}} - \lambda I \left(\frac{k}{\mu} - S - I\right) - \mu I;$$

$$f_{2}(I, R) = \frac{\beta \left(\frac{k}{\mu} - I - R\right) I^{2}}{\alpha + I^{2}} - \lambda I R - \mu I;$$

$$f_{3}(S, R) = \lambda \left(\frac{k}{\mu} - S - R\right) R - \mu R;$$

$$f_{3}(I, R) = \lambda I R - \mu R.$$

Let $g = (g_1, g_2, g_3) = \frac{1}{SIR} (S, I, R)^T \times f$, among of there, where

$$g_{1} = \frac{f_{3}(S,R)}{SR} - \frac{f_{2}(S,I)}{SI};$$

$$g_{2} = \frac{f_{1}(S,I)}{SI} - \frac{f_{3}(I,R)}{IR};$$

$$g_{3} = \frac{f_{2}(I,R)}{IR} - \frac{f_{1}(S,R)}{SR};$$

Obviously, we have $g \cdot f = 0$. By calculating, we obtain

$$\frac{\partial g_3}{\partial I} - \frac{\partial g_2}{\partial R} = \frac{\beta \left(k(\alpha - I^2) + \mu R(I^2 - \alpha) - 2\alpha \mu I\right)}{\mu R(\alpha + I^2)^2};$$

$$\frac{\partial g_1}{\partial R} - \frac{\partial g_3}{\partial S} = -\frac{\lambda}{S} + \frac{1}{RS} \left(\frac{2\beta SI}{\alpha + I^2} - \frac{\beta I^2}{\alpha + I^2} - \frac{2\beta SI^3}{(\alpha + I^2)^2} - \mu \right) - \frac{1}{RS^2} \left(k - \frac{\beta SI^2}{\alpha + I^2} - \mu S\right);$$

$$\frac{\partial g_2}{\partial S} - \frac{\partial g_1}{\partial I} = \frac{\lambda}{S} - \frac{k}{IS^2} - \frac{\beta (I^2 - \alpha)}{(\alpha + I^2)^2}.$$

By taking the normal vector n = (1, 1, 1) of the closed set Ω_1 , as the rotation of the vector *g* is

$$\operatorname{Curlg} = \operatorname{det} \begin{pmatrix} i & j & k \\ \frac{\partial}{\partial S} & \frac{\partial}{\partial I} & \frac{\partial}{\partial R} \\ g_1 & g_2 & g_3 \end{pmatrix},$$
(7)

so there is

$$(\operatorname{Curlg}) \cdot n = \left(\frac{\partial g_3}{\partial I} - \frac{\partial g_2}{\partial R}\right) + \left(\frac{\partial g_1}{\partial R} - \frac{\partial g_3}{\partial S}\right) + \left(\frac{\partial g_2}{\partial S} - \frac{\partial g_1}{\partial I}\right)$$
$$= -\frac{k}{IS^2} - \frac{k}{RS^2} - \frac{k\beta I^2}{\mu R(\alpha + I^2)^2} + \frac{k\alpha\beta}{\mu R(\alpha + I^2)^2},$$
(8)

by substituting the equilibrium point $E_4 = (S_4, I_4, R_4)$ into the above Formula (8), we gain

$$(\operatorname{Curlg}) \cdot n = \frac{\beta \lambda^2 (\alpha \lambda^2 + \mu \beta + \mu^2) (\mu^2 (k\lambda + \alpha \lambda^2 + \beta \mu + \mu^2) - \alpha k \lambda^3)}{\mu (\mu (\alpha \lambda^2 + \mu \beta + \mu^2) - k \lambda \beta) (\alpha \lambda^2 + \mu^2)^2}.$$
(9)

Thus, there is

$$(\operatorname{Curlg}) \cdot n < 0, \tag{10}$$

if

$$\frac{\mu^2 \left(k\lambda + \alpha \lambda^2 + \beta \mu + \mu^2\right)}{\alpha k \lambda^3} > 1$$

Based on Lemma 2, the system (1) has no periodic solution, homoclinic orbit and directional heteroclinic orbit in the closed set Ω_1 . Consequently, if

$$\frac{\mu^2(k\lambda+\alpha\lambda^2+\beta\mu+\mu^2)}{\alpha k\lambda^3}>1,$$

the equilibrium point E_4 is global asymptotically stable. \Box

5. Numerical Simulation

The above analysis indicates that if the parameters satisfy certain conditions, the three equilibrium points E_1 , E_3 , E_4 of the model are locally asymptotically stable and global asymptotically stable. We selected parameters values that satisfy the stability condition of the equilibrium points and conducted numerical simulation with MATLAB software so as to validate the theoretic analysis as well as analyze the influence of parameters β , λ and k in the model on rumor spreading.

By taking parameters k = 0.5, $\beta = 1.88$, $\alpha = 30$, $\lambda = 0.09$, $\mu = 0.1$ and using the fourth-order Runge–Kutta method, we established in Figure 2 that the model converges to the equilibrium point $E_1(5, 0, 0)$. No matter what the initial value of the individuals is in the initial state of the model, the number of susceptible people decreases rapidly first and then increases slowly and finally reaches a stable state, while the number of rumor-spreading persons decreases rapidly and reaches a balanced state. The number of stiflers increases rapidly, then decreases slowly and reaches a balanced state. In the end, there are only susceptible persons left in the model, and there are no rumor-spreading people and stiflers. Rumor-spreading persons will no longer exist, and the rumor will eventually disappear.



Figure 2. The stability of the equilibrium point E_1 .

By taking parameters k = 0.5, $\beta = 0.9$, $\alpha = 20$, $\lambda = 0.01$ and $\mu = 0.1$, we established in Figure 3 that the model converges to the equilibrium point $E_3(1, 4, 0)$. No matter what the initial value of the individuals is in the initial state of the model, the number of susceptible people decreases rapidly first and then increases slowly and finally reaches a stable state. The number of rumor-spreading people first rises rapidly, then declines rapidly, and then rises slowly to reach a balanced state. The stiflers descend rapidly and reach a balanced state. In the end, there are only susceptible people and rumor-spreading people, and there are no stiflers. Rumor-spreading people will always exist, and the rumors will not disappear.



Figure 3. The stability of the equilibrium point E_3 .

By taking parameters k = 0.4, $\beta = 0.3$, $\alpha = 0.001$, $\lambda = 0.1$, $\mu = 0.15$, we establish in Figure 4 that the model converges to the equilibrium point $E_4(0.89, 1.5, 0.28)$. No matter what the initial value of the individuals is in the initial state of the model, the number of susceptible people decreases rapidly to reach a stable state. The number of rumor-spreading people drops rapidly and then increases slowly and reaches a balanced state. The number of stiflers increases rapidly, then decreases slowly and reaches a balanced state. Finally, susceptible persons, rumor-spreading people and stiflers will exist.



Figure 4. The stability of the equilibrium point E_4 .

By taking parameters k = 0.5, $\alpha = 20$, $\lambda = 0.01$, $\mu = 0.1$, Figure 5 illustrates how the number of the rumor-spreading people changes over time with different predation capacities β , such as $\beta = 4$, $\beta = 2$, $\beta = 1.5$ and $\beta = 1$. From Figure 5, we can establish that when the predation capacity β decreases, the number of rumor-spreading people decreases. Therefore reducing the predation capacity β can control the spread of rumors. Popular science education refers to the use of various media to introduce natural science and social science knowledge to the general public in a simple way that is easy for the public to understand, accept and participate. Popular science education is a universal education of scientific knowledge, scientific spirit and scientific and technological achievements for the society, which is very conducive to the public's innovative spirit and practical ability. In order to reduce the predation capacity β , the public is required to quickly identify rumors under the role of popular science education so that the number of rumor-spreading people will be greatly reduced and will not harm society. Consequently, popular science education is the most fundamental means to eliminate rumors.



Figure 5. Trends in the number of the rumor spreading with different β values.

By taking parameters k = 0.5, $\beta = 0.5$, $\alpha = 1$ and $\mu = 0.1$, the plot in Figure 6 describes how the number of rumor-spreading people changes over time with different stifling rates λ , such as $\lambda = 0.01$, $\lambda = 0.03$, $\lambda = 0.06$ and $\lambda = 0.1$. From Figure 6, we establish that when the stifling rate λ increases, the number of rumor-spreading people decreases and eventually disappears; thus, increasing the stifling rate λ can fundamentally inhibit the spread of rumors. Scientific knowledge includes space exploration, biology, scientific history, earth story, life science, scientific life, UFO, military science and technology, science fiction world, digital appliances, healthy diet and other knowledge.



Figure 6. Trends in the number of the rumor spreading with different λ values.

In order to increase the stifling rate λ , we should generally improve the level of scientific knowledge of the public in society. This way, the public can clearly identify general rumors and not easily believe and spread them.

By taking parameters $\beta = 1$, $\alpha = 22$, $\mu = 0.1$ and $\lambda = 0.01$, the plot in Figure 7 demonstrates how the number of the rumor-spreading people changes over time with different the system coming rates k, such as k = 0.9, k = 0.7, k = 0.4 and k = 0.1. From Figure 7, we can establish that when the system coming rate k decreases, the number of rumor-spreading people decreases and eventually disappears. It shows that reducing the coming rate k of the model can fundamentally restrain the spread of rumors. In order to reduce the coming rate k, the government can take closed measures. If it is network communication, network blocking can be adopted. Network blocking refers to banning it from public communication on the network for someone or something in the whole network.



Figure 7. Trends in the number of the rumor spreading with different *k* values.

6. Case Analysis—Taking the Prime Minister of Brazil Infected New COVID-19 Incident as an Example

Since the outbreak of new COVID-19, rumors of the epidemic, epidemic prevention and the vaccine have given rise to many problems and even panic to people's lives, which has caused material and spiritual losses to a certain extent, seriously affecting people's lives, work and study, and even threatening social and political stability. On 12 March 2020, Fabio Wajngarten, the head of media affairs at the Brazilian presidential palace, diagnosed a new COVID-19. Wajngarten is an important member of the ruling team of Brazilian President Jair Bolsonarno. From 7 to 10 March, Wajngarten visited the United States with Brazilian President Bosonaro. After returning to Brazil on the morning of 11 March, Wajngarten showed symptoms of the new COVID-19 and accepted the COVID-19 test; the results were positive. On the same day, the presidential palace of Brazil announced the cancellation of Bosonaro's domestic official trip on that day. Bosonaro also accepted the COVID-19 test.

On 13 March 2020, according to the Mirror, the COVID-19 test of Bosonaro was positive. Bosonaro became the first head of state who was diagnosed with COVID-19. The major media reprinted one after another and soon attracted wide public attention. We attempt to use the rumor data of the event on the "Zhiweishijian" website [30]. On 13 March, as soon as the news was released, such as through microblog and Wechat, online media immediately reprinted and the number of rumor links increased to 657. On 14 March, the number of rumor links reached the peak of 1642. After the release of official rumor refutation information, the number of rumor links amounted to 268 on 15 March and only 61 on 16 March. Then, the accident subsided. By taking parameters k = 0.5, $\beta = 1$, $\alpha = 100$, $\lambda = 0.0015$ and $\mu = 0.1$, the time series diagram of the model was drawn by using Matlab software. It can be seen from Figure 8 that the curve of the model is roughly the same as the trend of the rumor data. On the other hand, on the condition that the other parameters mentioned above remain unchanged if the predation capacity β drops to 0.6, Figure 8 shows that the peak value of the rumor will greatly reduce. As COVID-19 is closely related to public health and safety, it draws great attention from the public. Shortly after the news was launched, the false information was on a sharp increase. With the release of official rumor refutation information, the rumors declined rapidly and eventually disappeared.



Figure 8. Time series diagram of t-I based on the rumor data.

7. Conclusions

In this paper, a rumor-spreading model with Holling-III functional response was constructed. Individuals of the model are subdivided into three categories: the susceptible person *S*, the rumor-spreading person *I* and the stiflers *R*. The existence of the equilibrium points was discussed. By using the Routh–Hurwitz criteria, the locally asymptotic stability of the equilibrium points was analyzed. The global stability of the equilibrium points was proved based on Lasalle's invariance principle and generalized Bendixson–Dulac theorem. The correctness of the theoretical analysis is verified by numerical simulation. Parameter changes help to control the spread of rumors. By reducing the system coming rate *k* or increasing the stifling rate λ , the number of rumor-spreaders is reduced to extinction. Reducing the predation capacity β can not only control the spread of rumors but also reduce the peak value of the spread of rumors. The release of rumor refutation information has an important impact on the spread of rumors. The role of rumor refutation information in the spread of rumors needs to be further studied.

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