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Note on the Numerical Solutions of Unsteady Flow and Heat Transfer of Jeffrey Fluid Past Stretching Sheet with Soret and Dufour Effects

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Abstract: A numerical investigation of unsteady boundary layer flow with heat and mass transfer of non-Newtonian fluid model, namely, Jeffrey fluid subject, to the significance of Soret and Dufour effects is carried out by using the local nonsimilarity method and homotopy analysis method. An excellent agreement in the numerical results obtained by both methods is observed and we establish a new mathematical approach to obtain the solutions of unsteady-state flow with heat and mass transfer phenomenons. Similarity transformation is applied to governing boundary layer partial differential equations to obtain the set of self-similar, nondimensional partial differential equations. Graphical results for different emerging parameters are discussed. The dimensionless quantities of interest skin friction coefficient, Sherwood number, and Nusselt number are discussed through tabulated results. The main novelty of the current work is that the average residual error of the *mth*-order approximation of the OHAM scheme for steady-state solution is decreased for higher-order approximation. Further, a rapid development of the boundary layer thickness with the increasing values of dimensionless time τ is observed. It is noted that for large values of τ , the steady state in the flow pattern is gained. It is worth mentioning that the magnitude of Sherwood number is increased with the increasing values of Schmidt number Sc and Dufour number D_f . The magnitude of local Nisselt number is increased for the increasing values of Soret number, Sr.

Keywords: Jeffery fluid; stretching; Soret and Dufour effects

MSC: 76D05, 76D10

1. Introduction

The significance of boundary layer flow of Newtonian/non-Newtonian fluids past a stretching surface has gained the attention of many researchers due to their applications in science and engineering, e.g., polymer extrusion, food processing, and many others. With this understanding, first, we focus on the work of the community engaged in this field. Initially, the boundary layer flow of viscous fluid was discussed by Crane [1] theoretically. The case of heat and mass transfer analysis with suction and blowing was studied by Gupta and Gupta [2]. Magnetohydrodynamic flow and heat transfer of viscous fluid past stretching sheet was discussed by Chakrabarti and Gupta [3] numerically. The uniqueness of solutions of the Navier–Stokes fluid past a stretching sheet was determined by Mcleod and Rajagopal [4] in detail. The numerical solutions of boundary layer flow of viscous fluid past stretching plate were simulated by Liao [5], and they presented the obtained



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). results graphically as well as in tabular form. Magnetohydrodynamic flow due to vertical stretching sheet with heat transfer was studied by Ishak et al. [6] theoretically. Further, the MHD free convection flow past vertical stretching plate under the influence of heat generation and viscous dissipation was studied by Khaleque and Samad [7]. The stagnation point flow of upper convected Maxwell fluid past stretching sheet with melting heat transfer was studied by Hayat et al. [8]. Further extension in this model for similar flow for third-grade fluid with viscous dissipation was discussed by Hayat et al. [9]. Three-dimensional flow of Oldroyd-B fluid over a bidirectional stretching sheet with surface temperature and surface heat flux generation was studied by Hayat et al. [10].

The real-world formulation of emerging phenomenons is not adequate when the constitutive relations for viscous fluid are applied. Therefore, to completely describe the true behavior, we must take into consideration non-Newtonian fluid models which are more adequate to describe the nature of fluid flow. A large variety of non-Newtonian fluid models have been studied for boundary layer flows of non-Newtonian fluids, among which is the Jeffrey fluid model. This fluid model is capable of describing the characteristics of relaxation and retardation times of the non-Newtonian fluids. Analysis of an endoscope and magnetic field on the peristalsis involving Jeffrey fluid were carried out by Hayat et al. [11]. Magnetohydrodynamic peristaltic flow of Jeffery fluid through finite length of cylindrical tube was studied by Tripathi et al. [12]. Further, the MHD peristaltic flow of a Jeffrey fluid under the influence of slip and heat transfer in inclined asymmetric porous channel was studied by Das [13], and heat source or sink effects past stretching sheet for Jeffrey fluid were discussed by Qasim [14]. Three-dimensional stretched flow of Jeffrey fluid under the influence of variable thermal conductivity and thermal radiation was discussed by Hayat et al. [15]. Lifting of a Jeffrey fluid on a vertical belt under influence of magnetic field and wall slip conditions was discussed by Farooq et al. [16]. The time-dependent analysis of flow and heat transfer of Jeffrey fluid along stretching sheet was carried out by Hayat et al. [17]. The stagnation-point flow of Jeffrey fluid under the effects of melting heat transfer and mass transfer with Soret and Dufour effects was studied by Hayat et al. [18]. Moreover, the Jeffrey fluid flow between two torsionally oscillating disks was discussed by Reddy et al. [19].

When heat and mass transfer occur simultaneously between two mediums, the relations between the fluxes and the driving potentials are significant in nature. Experimental studies showed that an energy flux can be generated not only by temperature gradients but by composition of gradient as well, which can be given by the Fick's laws of diffusion. This type of energy flux is known as Dufour or diffusion-thermo effect. In a similar manner, we also have mass fluxes being created by temperature gradient, which can be given by the Fourier's laws of heat conduction, and this phenomenon is known as Soret or thermal-diffusion. The energy and concentration generation due to Dufour and Soret effects are comparatively small in magnitude as compared to other effects; however, these effects are significantly important for the light molecular weight substances. Forced and natural convection boundary layer flow with the significance of Soret and Dufour effects was studied by Abreu et al. [20]. Soret and Dufour effects with the inclusion of variable wall temperature and concentration are discussed by Cheng [21]. The MHD Hiemenz flow and mass transfer with Soret and Dufour effects through porous medium along the stretching sheet were studied by Addel-Rahman [22]. Mixed convection flow of second-grade fluid subject to Hall and ion-slip currents with Soret and Dufour effects were studied by Hayat and Nawaz [23]. Three-dimensional flow in a viscoelastic fluid past stretching surface with significance of Soret and Dufour effects was studied by Hayat et al. [24]. The natural convection heat and mass transfer flow past a horizontal surface in porous medium with variable viscosity with significance of Soret and Dufour effects was investigated by Moorthy et al. [25]. Axisymmetric flow of a Jeffery fluid over a stretching surface with significance of Newtonian heating along with thermal-diffusion and diffusion-thermo effects was studied by Awais et al. [26].

Homotopy analysis method was developed by Liao [27]. The homotopy analysis method has been successfully applied to many highly nonlinear problems in the last

decade; some of them are [5,8–10,15,17,18,23,24,26]. The development in the homotopy analysis method was made by many researchers. One of them is the optimal homotopy analysis method (OHAM), in which the convergence of homotopy solution is determined by the optimization of convergence control parameters against the residual error, as mentioned in [28,29]. The local nonsimilarity method was introduced by Sparrow and Yu [30], and the solutions of nonsimilar equations arising in mixed convection flow was discussed. The numerical analysis of the local nonsimilarity method at third level of truncation was carried out by Yu and Sparrow [31], and Rabadi and Dweik applied this method in the mixed convective flow with flux [32]. Massoudi discussed the local nonsimilarity solutions for the flow of a non-Newtonian fluid over a wedge [33]. Yian and Norsarahaida [34] studied vertical free convection boundary layers flow using local nonsimilarity method. Mushtag et al. [35] studied the mixed convection flow of second-grade subject to vertical stretching flat surface with variable surface temperature. Recently, Kairi et al. [36] conducted a numerical study on the influence of viscous dissipation and thermo-diffusion subjected to doublediffusive convection over a vertical cone in a non-Darcy porous medium saturated by a non-Newtonian fluid with variable heat and mass fluxes. Sardar et al. [37] investigated the local nonsimilar solutions in the convective flow of Carreau fluid with the inclusion of MHD and radiative heat transfer. Swarajya and Rao [38] applied this method to study variations in drag and heat transfer at a vertical plate due to steady flow of a colloidal suspension of the nanofluid. RamReddy et al. [39] studied the significance of nonlinear Boussinesq approximation on natural convective flow with the method of local nonsimilarity approach. Keeping in view the above literature review, our current problem deals with the unsteady flow and heat transfer of Jeffrey fluid past a stretching sheet with the inclusion of Soret and Dufour effects. As far as our approach and knowledge, the local nonsimilarity method has never been applied to unsteady flow phenomenons so far, so we are the first to use this method in conjunction with the homotopy analysis method and also carry out a numerical compression for both approaches.

2. Mathematical Formulation

We consider the unsteady incompressible bidirectional boundary layer flow of the Jeffrey fluid with constant viscosity μ and density ρ past a stretching sheet. Initially, the fluid and the plate are at rest. The flow is induced by the sudden stretching of the sheet with constant velocity $u_w(x) = cx$, where *c* is a positive (stretching sheet) constant. The stretching sheet is raised to a temperature T_w , and T_∞ is the embedded temperature of the fluid such that ($T_w > T_\infty$), as shown in Figure 1. The conservation equations for the proposed model take the following forms:

$$\nabla \cdot \mathbf{V} = 0, \tag{1}$$

$$\rho \frac{D\mathbf{V}}{Dt} = div\tau_1 + \rho \mathbf{F},\tag{2}$$

$$\rho C_p \left(\frac{DT}{Dt}\right) = k \nabla^2 T + \Phi + \mathbf{J},\tag{3}$$

$$\frac{DC}{Dt} = D\nabla^2 C + \mathbf{R}_c. \tag{4}$$

where **V** is the velocity, ρ is density, *T* is the temperature, C_p is the specific heat and constant pressure, *k* is thermal conductivity of the fluid, Φ is the viscous dissipation, **J** is the Dufour effect, *C* is the concentration of diffusion species, *D* is the diffusion coefficient, **R**_c is the Soret effect, $\frac{D}{Dt}$ is the material derivative, **F** is the body for force, and τ_1 is the Cauchy stress tensor. For incompressible Jeffrey fluid, this tensor is given by

$$\tau_1 = -p\mathbf{I} + \mathbf{S},\tag{5}$$

where p is pressure and the extra stress tensor **S** is given by

$$\mathbf{S} = \frac{\mu}{1+\lambda_1} \left[\mathbf{A}_1 + \lambda_2 \frac{D\mathbf{A}_1}{Dt} \right],\tag{6}$$

where μ is the viscosity of the fluid, λ_2 is the ratio of relaxation and retardation time, and λ_1 is retardation time, respectively. **A**₁ is the first Rivlin–Erickson tensor, given by

$$\mathbf{A}_1 = (\nabla \mathbf{V}) + (\nabla \mathbf{V})^*,\tag{7}$$

where \star denotes the transpose. The heat flux J, also known as known as Dufour or diffusionthermo effect, can be given by Frick's law of diffusion, as follows:

$$\mathbf{J} = \frac{\rho D K_t}{C_s} \nabla^2 C,\tag{8}$$

where C_s is the specific heat capacity of the solid surface, K_T is the thermal diffusion ratio, and \mathbf{R}_c is the concentration flux generated by the temperature gradient, known as Soret or thermo-diffusion effect, given by Fourier's law of heat conduction:

$$R_c = \frac{q}{A} = \frac{Dk_T \nabla^2 T}{T_m}.$$
(9)

where T_m is the mean temperature of the fluid. We assume that viscous dissipation Φ is insignificant and we consider the thermal and radiative heat transfer along with the Soret and Dufour effect in this unsteady fluid flow. It is also assumed that all the thermal properties are taken as constant. Body forces are negligible and the pressure *p* is constant for the fluid flow. The governing boundary layer equations under the standard Prandtl boundary layer approximations are given by

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \tag{10}$$

$$\frac{\partial u}{\partial t} + u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = \frac{v}{1+\lambda_2} \left[\frac{\partial^2 u}{\partial y^2} + \lambda_1 \left(\frac{\partial^3 u}{\partial y^2 \partial t} + u\frac{\partial^3 u}{\partial x \partial y^2} - \frac{\partial u}{\partial x}\frac{\partial^2 u}{\partial y^2} + \frac{\partial u}{\partial y}\frac{\partial^2 u}{\partial x \partial y} + v\frac{\partial^3 u}{\partial y^3} \right) \right], \quad (11)$$

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \frac{k}{\rho C_P} \frac{\partial^2 T}{\partial y^2} + \frac{16\sigma^* T_\infty^3}{3\rho C_P k^*} \frac{\partial^2 T}{\partial y^2} + \frac{Dk_T}{C_S} \frac{\partial^2 C}{\partial y^2},$$
(12)

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D \frac{\partial^2 C}{\partial y^2} + \frac{Dk_T}{T_m} \frac{\partial^2 T}{\partial y^2},$$
(13)

subject to boundary conditions

$$t \leq 0: \qquad u = 0, v = 0, T = T_{\infty}, C = C_{\infty} \qquad \text{for any } x, y$$

$$t > 0: \qquad u = u_w(x) = ax, v = 0, T = T_w, C = C_w \text{ at } y = 0, \qquad (14)$$

$$u \to 0, v \to 0, T \to T_{\infty}, C \to C_{\infty} \text{ as } y \to \infty,$$

where σ^* is the Stefan–Boltzmann constant and k^* is Rosseland mean absorption coefficient. The expressions for skin friction coefficient C_{f_x} , local Nusselt number Nu_x , and local Sherwood number *Sh* are given by

$$C_{f_x} = \frac{\tau_w}{1/2\rho[u_w(x)]^2}, \quad Nu_x = \frac{xq_w}{k(T_w - T_\infty)}, \quad Sh_x = \frac{xj_w}{D(C_w - C_\infty)}, \tag{15}$$

where the wall skin friction τ_w , wall heat flux q_w , and mass flux j_w are given by

$$\tau_{w} = \frac{\mu}{1+\lambda_{2}} \left[\frac{\partial u}{\partial y} + \lambda_{1} \left\{ u \frac{\partial^{2} u}{\partial y \partial x} + \frac{\partial^{2} u}{\partial y \partial t} + v \frac{\partial^{2} u}{\partial y^{2}} \right\} \right]_{y=0},$$

$$q_{w} = -\left[\left(k + \frac{16\sigma^{*}T_{\infty}^{3}}{3k^{*}} \right) \frac{\partial T}{\partial y} \right]_{y=0}, \quad j_{w} = -D\left(\frac{\partial C}{\partial y} \right)_{y=0}.$$

$$(16)$$

We introduce the similarity variables of the form

$$\eta = \sqrt{\frac{a}{\nu\xi}}y, \quad u = axf'(\eta,\xi), \quad v = -\sqrt{a\nu\xi}f(\eta,\xi), \quad \xi = 1 - \exp[-\tau],$$

$$\tau = at, \quad \theta(\eta,\xi) = \frac{T - T_{\infty}}{T_w - T_{\infty}}, \quad \phi(\eta,\xi) = \frac{C - C_{\infty}}{C_w - C_{\infty}},$$
(17)

Using (17) in Equations (10)–(13) along the initial and boundary conditions (14), we obtain the following transformed system of self-similar partial differential equations:

$$\{\xi - \beta(1-\xi)\}f''' + (1+\lambda_2) \left\{\xi(1-\xi)(\frac{\eta}{2}f'' - \xi\frac{\partial f'}{\partial\xi}) - \xi^2(f'^2 - ff'')\right\} + \beta \left\{\xi(1-\xi)\frac{\partial f'''}{\partial\xi} - \frac{\eta}{2}(1-\xi)f^{iv} + \xi\left(f''^2 - ff''''\right)\right\} = 0,$$
(18)

$$\theta'' + \Pr_{eff}(1-\xi) \left[\frac{\eta}{2} \theta' - \xi \frac{\partial \theta}{\partial \xi} \right] + \Pr_{eff} \xi f \theta' + \Pr_{eff} D_f \phi'' = 0, \tag{19}$$

$$\phi'' + Sc(1-\xi) \left[\frac{\eta}{2} \phi' - \xi \frac{\partial \phi}{\partial \xi} \right] + Sc\xi f \phi' + ScSr\theta'' = 0, \tag{20}$$

with the initial and boundary conditions

$$f(0,\xi) = 0, \quad f'(0,\xi) = 1, \quad \theta(0,\xi) = 1, \quad \phi(0,\xi) = 1, \\ f'(\infty,\xi) = 0, \ \theta(\infty,\xi) = 0, \\ \phi(\infty,\xi) = 0, \quad (21)$$

where

$$\beta = a\lambda_1, \quad \Pr = \frac{\rho C_P v}{k}, \quad R_d = \frac{4\sigma^* T_\infty^3}{kk^*}, \quad \Pr_{eff} = \frac{\Pr}{1 + \frac{4}{3}R_d},$$

$$D_f = \frac{Dk_T (C_w - C_\infty)}{C_P C_S (T_w - T_\infty)}, \quad Sc = \frac{v}{D}, \quad Sr = \frac{Dk_T (T_w - T_\infty)}{T_m (C_w - C_\infty)},$$
(22)

where prime denotes the derivatives with respect to η , β is the Deborah number, Pr is Prandtl number, R_d is the radiation parameter, \Pr_{eff} is the effective Prandtl number, D_f is the Dufour number, Sc is the Schmidt number, and Sr is the Soret number. The similarity expression for skin friction coefficient C_{f_x} , local Nusselt number Nu_x , and local Sherwood number Sh_x are given by using (17) in Equations (15) and (16). We have

$$1/2\xi^{\frac{1}{2}}(Re_{x})^{1/2}C_{f} = \frac{1}{1+\lambda_{2}} \left[(1+\beta)f''(0,\xi) + \beta(1-\xi) \left\{ \frac{\partial f''(0,\xi)}{\partial \xi} - \frac{1}{2\xi}f''(0,\xi) \right\} \right],$$

$$\xi^{\frac{1}{2}}(Re_{x})^{-1/2}Nu_{x} = -\left(1 + \frac{4}{3}R_{d}\right)\theta'(0,\xi), \quad \xi^{\frac{1}{2}}(Re_{x})^{-1/2}Sh = -\phi'(0,\xi),$$
(23)

where $Re_x = ax^2/\nu = U_w x/\nu$ is the local Reynolds number.



Figure 1. The physical geometry of the fluid flow.

3. Steady-State Flow

To obtain the steady-state flow problem we input $\xi = 1$ in Equations (18)–(20), and we obtain

$$f''' + (1 + \lambda_2)(-f'^2 + ff'') + \beta \left(f''^2 - ff'''' \right) = 0,$$
(24)

$$\theta'' + \Pr_{eff} f \theta' + \Pr_{eff} D_f \phi'' = 0, \qquad (25)$$

$$\phi'' + Scf\phi' + ScSr\theta'' = 0, \tag{26}$$

with the conditions

$$f(0) = 0, \quad f'(0) = 1, \quad \theta(0) = 1, \quad \phi(0) = 1,$$

$$f'(\infty) = 0, \quad \theta(\infty) = 0, \quad \phi(\infty) = 0.$$
 (27)

It is important to note that the exact solution of Equation (24), subject to boundary conditions (27), has the form

$$f(\eta) = \frac{1 - e^{-m\eta}}{m}; \quad m = \sqrt{\frac{1 + \lambda_2}{1 + \beta}}.$$
 (28)

Substituting the expression of $f(\eta)$ from Equation (28) into Equations (25) and (26), the resulting differential equation can be solved numerically by the symbolic computation software Mathematica version 13.1, Wolfram Research, Champaign, Illinois.

4. Solution Methodology

- 4.1. Local Nonsimilarity Method
- 4.1.1. First Level of Truncation

At the first level of truncation, the terms containing $\xi \frac{\partial(.)}{\partial \xi}$ in Equations (18)–(20) are neglected under the assumption that the terms involving ξ are small [37]. This is particularly true when $\xi << 1$. Thus, the terms with $\xi \frac{\partial(.)}{\partial \xi}$ of Equations (18)–(20) are neglected to obtain the following system of equations:

$$\{\xi - \beta(1 - \xi)\}f''' + (1 + \lambda_2) \{\xi(1 - \xi)(\frac{\eta}{2}f'') - \xi^2(f'^2 - ff'')\} + \beta \{\xi(f''^2 - ff^{iv} - \frac{\eta}{2}(1 - \xi)f^{iv})\} = 0,$$
(29)

$$\theta'' + \Pr_{eff}(1-\xi) \left[\frac{\eta}{2}\theta'\right] + \Pr_{eff}\xi f\theta' + \Pr_{eff}D_f\phi'' = 0, \tag{30}$$

$$\phi'' + Sc(1-\xi) \left[\frac{\eta}{2}\phi'\right] + Sc\xi f\phi' + ScSr\theta'' = 0, \tag{31}$$

with the initial and boundary conditions

$$f(0,\xi) = 0, \quad f'(0,\xi) = 1, \quad \theta(0,\xi) = 1, \quad \phi(0,\xi) = 1, \\ f'(\infty,\xi) = 0, \ \theta(\infty,\xi) = 0, \\ \phi(\infty,\xi) = 0, \quad (32)$$

It can be seen that Equations (29)–(31) can be treated as a system of ordinary differential equations for the functions $f(\eta)$ and $\theta(\eta)$ and $\phi(\eta)$ with ξ as a parameter.

4.1.2. Second Level of Truncation

To find the higher level of truncation, we introduce the following new functions:

$$g(\eta,\xi) = \frac{\partial f}{\partial\xi}, \quad h(\eta,\xi) = \frac{\partial f}{\partial\xi}, \quad j(\eta,\xi) = \frac{\partial f}{\partial\xi},$$
 (33)

At the second level, the governing equations, Equations (18)–(20), for the function $f(\eta, \xi)$, $\theta(\eta, \xi)$, and $\phi(\eta, \xi)$, respectively, are retained intact, and are as follows:

$$\{\xi - \beta(1-\xi)\}f''' + (1+\lambda_2) \{\xi(1-\xi)(\frac{\eta}{2}f'' - \xi g') - \xi^2(f'^2 - ff'')\} + \beta \{\xi(1-\xi)g''' - \frac{\eta}{2}(1-\xi)f^{iv} + \xi (f''^2 - ff'''')\} = 0,$$
(34)

$$\theta'' + Pr_{eff}(1-\xi) \left[\frac{\eta}{2}\theta' - \xi h'\right] + Pr_{eff}\xi f\theta' + Pr_{eff}D_f\phi'' = 0, \tag{35}$$

$$\phi'' + Sc(1-\xi) \left[\frac{\eta}{2}\phi' - \xi j'\right] + Sc\xi f\phi' + ScSr\theta'' = 0, \tag{36}$$

with the initial and boundary conditions

$$f(0,\xi) = 0, \quad f'(0,\xi) = 1, \quad \theta(0,\xi) = 1, \quad \phi(0,\xi) = 1, \\ f'(\infty,\xi) = 0, \quad \theta(\infty,\xi) = 0, \\ \phi(\infty,\xi) = 0, \quad (37)$$

To derive the subsidiary equations for $g(\eta; \xi)$, $h(\eta; \xi)$, and $j(\eta; \xi)$ and their boundary conditions, we take the derivatives of Equations (34)–(36) with respect to ξ . Thus, we obtain

$$(1+\beta)f''' + \xi(1-\beta)g''' + (1+\lambda_2)\left\{(1-2\xi)\frac{\eta}{2}f'' + (3\xi^2 - 2\xi)g' + \xi(1-\xi)\frac{\eta}{2}g'' - 2\xi(f'^2 - ff'')\right\} - \xi^2(2f'g' - f''g - fg'')\right\} + \beta\left\{\frac{\eta}{2}f^{(iv)} - \frac{\eta}{2}(1-\xi)g^{(iv)} + f''^2 - ff^{iv} + \xi\left(2f''g'' - gf^{(iv)} - fg^{(iv)}\right)\right\} = 0,$$
(38)

$$h'' + Pr_{eff} \left[(2\xi - 1)h - \frac{\eta}{2}\theta' + (1 - \xi)\frac{\eta}{2}h' \right] + Pr_{eff} \left[f\theta' + \xi \left(g\theta' + fh' \right) \right] + Pr_{eff} D_f j'' = 0$$
(39)

$$j'' + Sc\left[(2\xi - 1)j - \frac{\eta}{2}\phi' + (1 - \xi)\frac{\eta}{2}j'\right] + Sc\left[f\phi' + \xi(g\phi' + fj')\right] + ScSrh'' = 0$$
(40)

subject to boundary conditions

$$g(0,\xi) = 0, \quad g'(0,\xi) = 0, \quad h(0,\xi) = 0, \quad j(0,\xi) = 0, \\ g'(\infty,\xi) = 0, \quad h(\infty,\xi) = 0, \\ j(\infty,\xi) = 0.$$
(41)

At this level of truncation, the terms $\frac{\partial g}{\partial \xi}$, $\frac{\partial h}{\partial \xi}$, and $\frac{\partial j}{\partial \xi}$ and their derivative terms with respect to η are neglected. Considering the present scheme, solutions of the equations for the functions $f(\eta;\xi)$, $\theta(\eta;\xi)$, $\phi(\eta;\xi)$, $g(\eta;\xi)$, $h(\eta;\xi)$, and $j(\eta;\xi)$ are obtained using the MatLab built-in package *bvp4c*.

4.2. Homotopy Analysis Method

We select the initial guesses and the linear operator for the homotopy analysis method (HAM) and the optimal homotopy analysis method (OHAM) as

$$f_0(\eta) = 1 - e^{-\eta}, \quad \theta_0(\eta) = e^{-\eta}, \quad \phi_0(\eta) = e^{-\eta},$$
 (42)

$$\mathcal{L}_{f}(f) = f'' - f',$$

$$\mathcal{L}_{\theta}(f) = f'' - f,$$

$$\mathcal{L}_{\phi}(f) = f'' - f,$$
(43)

where \mathcal{L}_f , \mathcal{L}_{θ} , and \mathcal{L}_{ϕ} satisfy the following properties:

$$\mathcal{L}_{f} \begin{bmatrix} A_{1} + A_{2}e^{\eta} + A_{3}e^{-\eta} \end{bmatrix} = 0,$$

$$\mathcal{L}_{\theta} \begin{bmatrix} A_{4}e^{\eta} + A_{5}e^{-\eta} \end{bmatrix} = 0,$$

$$\mathcal{L}_{\phi} \begin{bmatrix} A_{6}e^{\eta} + A_{7}e^{-\eta} \end{bmatrix} = 0,$$
(44)

where A_i (i = 1-7) are the arbitrary constants and have to be determined later.

5. Results and Discussion

The system of self-similar partial differential Equations (18)–(20) subject to the boundary conditions (21) is solved directly by the homotopy analysis method, whereas local nonsimilarity is applied at the second level of truncation. The system of self-similar ordinary differential Equations (34)–(36) subject to the boundary conditions (37) for the functions f, θ , and ϕ and Equations (38)–(40) subject to the boundary conditions (41) for the g, h, and j with ξ as a parameter is solved numerically. Table 1 shows the numerical comparison of the values of $f''(0,\xi)$, $\theta'(0,\xi)$, and $\phi'(0,\xi)$ obtained by the 15th-order homotopy analysis method, and with the values of convergence control parameters $\hbar_f = -0.70$, $\hbar_{\theta} = -1.2$, and $\hbar_{\phi} = -0.16$ and the numerical solution of system of ordinary differential equations with the help of computer software MatLab by considering arbitrary values of the emerging parameters. We observe a significant agreement in the numerical results obtained by both mathematical approaches.

Table 1. Comparison of numerical solutions with $\beta = 0.1$, $\lambda_2 = 0.2$, $\Pr_{eff} = 1.0$, $D_f = 0.5$, Sc = 1.0, and Sr = 0.5 for $\tau = 0.75$ and $\eta \in [0, 10]$.

	HAM	LNS
$f''(0,\xi)$	-0.837139	-0.833349
$\theta'(0,\xi)$	-0.414291	-0.414302
$\phi'(0,\xi)$	-0.668850	-0.661738

For $\xi = 1$, the steady-state flow given by Equations (24)–(26), we first obtain the optimized values of the convergence control parameter by using Module *GetOptiVar*[*m*] of the MATHEMATICA package *BVPH* 2.0. Table 2 shows the corresponding values of convergence control parameters at different order of homotopy approximations. Table 3 shows the average residual error of *m*th-order approximation of OHAM steady-state solution, and we observe a decrease in the residual error for higher-order approximations. Table 4 shows the convergence of steady-state approximations of OHAM solutions with optimized values of convergence control parameters as $\hbar_f = -1.3$, $\hbar_{\theta} = -1.0$, and $\hbar_{\phi} = -1.0$.

Order of Approximation <i>m</i>	\hbar_f	ħ _θ	$\hbar_{oldsymbol{\phi}}$	E_m^{tot}
2	-1.3564	-0.8199	-0.8199	1.0655×10^{-3}
4	-1.3864	-0.9012	-0.9012	$9.3333 imes10^{-5}$
6	-1.4128	-0.9500	-0.9500	$1.4189 imes10^{-6}$
8	-1.4325	-0.9832	-0.9832	2.7762×10^{-6}
10	-1.3173	-1.0091	-1.0091	7.0329×10^{-7}

Table 2. Optimal values of convergence control parameters with $\beta = 0.1$, $\lambda_2 = 0.2$, $\Pr_{eff} = 1.0$, $D_f = 0.5$, Sc = 1.0, and Sr = 0.5 for $\eta \in [0, 10]$ and $\xi = 1.0$.

Table 3. Average residual error of *mth*-order approximation of OHAM steady-state solution $\beta = 0.1$, $\lambda_2 = 0.2$, $\Pr_{eff} = 1.0$, $D_f = 0.5$, Sc = 1.0, and Sr = 0.5 for $\eta \in [0, 10]$ and $\xi = 1.0$.

Order of Approximation <i>m</i>	E_m^f at $\hbar_f=-1.31$	$E_m^ heta$ at $\hbar_ heta=-1.0$	$E^{oldsymbol{\phi}}_m$ at $\hbar_{oldsymbol{\phi}}=-1.0$	E_m^{tot}
6	8.2948×10^{-8}	$1.2977 imes 10^{-5}$	$1.2968 imes 10^{-5}$	2.6028×10^{-5}
10	$3.2795 imes 10^{-10}$	$3.4395 imes 10^{-7}$	$3.4347 imes10^{-7}$	$6.8775 imes 10^{-7}$
16	$1.1893 imes 10^{-13}$	$3.3040 imes10^{-9}$	$3.2979 imes 10^{-9}$	$6.6020 imes 10^{-9}$
24	$5.0280 imes 10^{-18}$	$1.5758 imes 10^{-10}$	$1.5733 imes 10^{-10}$	$3.1492 imes 10^{-10}$
30	$3.3298 imes 10^{-21}$	$8.8380 imes 10^{-12}$	$8.8210 imes 10^{-12}$	$1.7659 imes 10^{-11}$
36	$2.5201 imes 10^{-24}$	$5.5078 imes 10^{-13}$	$5.4987 imes 10^{-13}$	$1.1006 imes 10^{-12}$
40	$2.2124 imes 10^{-26}$	$9.0373 imes 10^{-14}$	$9.0217 imes 10^{-14}$	$1.8059 imes 10^{-13}$
44	$2.2907 imes 10^{-27}$	$1.5235 imes 10^{-14}$	$1.5203 imes 10^{-14}$	$3.0439 imes 10^{-14}$

Table 4. The convergence of steady-state approximations of OHAM solutions with $\beta = 0.1$, $\lambda_2 = 0.2$, $\Pr_{eff} = 1.0$, $D_f = 0.5$, Sc = 1.0, Sr = 0.5, and $\xi = 1.0$.

т	-f''(0)	- heta'(0)	$-\phi'(0)$
5	1.04567	0.43765	0.43765
10	1.04446	0.43206	0.43206
14	1.04446	0.43043	0.43043
20	1.04446	0.42987	0.42987
25	1.04446	0.42976	0.42976
30	1.04446	0.42973	0.42973
35	1.04446	0.42972	0.42972
40	1.04446	0.42972	0.42972
45	1.04446	0.42972	0.42972
50	1.04446	0.42972	0.42972

5.1. Analysis of Solutions

5.1.1. Transient-State Solutions

Three-dimensional plots are shown in Figures 2–4; these surfaces are generated for dimensionless time unsteady parameter $\xi \in [0, 1]$ and for $\eta \in [0, \infty]$. The growth of solution is observed with increase in ξ , and the effect of stretch vanishes for large values of η .

Figures 5–7 show the behavior of the dimensionless time τ on the development of boundary layer thickness of velocity profile $f'(\eta, \xi)$, temperature profile $\theta(\eta, \xi)$, and concentration profile $\phi(\eta, \xi)$, respectively. We observe a rapid development of boundary layer thickness with increases in dimensionless time τ and gain the steady-state flow as $\tau \to \infty$. Figures 8 and 9 show the influence of the β and λ_2 on velocity profile, respectively, and it is found that the velocity profile is increasing function of β and decreasing function of λ_2 . Figures 10 and 11 show the influence of the D_f and \Pr_{eff} on temperature profile, respectively, and it is found that the temperature profile is increasing function of D_f and decreasing function of \Pr_{eff} . Figures 12 and 13 show the influence of the Sc and Sr on concentration profile, respectively, and it is found that the velocity profile is decreasing function of Sc and increasing function of Sr.



Figure 2. Surface of $f'(\xi, \eta)$ for $\xi \in [0, 1]$ and for $\eta \in [0, \infty]$.



Figure 3. Surface of $\theta(\xi, \eta)$ for $\xi \in [0, 1]$ and for $\eta \in [0, \infty]$.



Figure 4. Surface of $\phi(\xi, \eta)$ for $\xi \in [0, 1]$ and for $\eta \in [0, \infty]$.



Figure 5. Influence of τ on $f'(\eta, \xi)$.



Figure 6. Influence of τ on $\theta(\eta, \xi)$.



Figure 7. Influence of τ on $\phi(\eta, \xi)$.



Figure 8. Influence of β on $f'(\eta, \xi)$.



Figure 9. Influence of λ_2 on $f'(\eta, \xi)$.



Figure 10. Influence of D_f on $\theta(\eta, \xi)$.



Figure 11. Influence of Pr_{eff} on $\theta(\eta, \xi)$.



Figure 12. Influence of *Sc* on $\phi(\eta, \xi)$.



Figure 13. Influence of *Sr* on $\phi(\eta, \xi)$.

5.1.2. Steady-State Solutions

In Figures 14 and 15, we compare the exact solutions of $f'(\eta)$ and the analytical series solution derived by OHAM . It is found that the derived series solution agrees with the exact solution for different values of β and λ_2 . Moreover, the small values of Deborah number β are associated with the liquid-like behavior of the matter, and for the large values of Deborah number β , solid-like behavior is associated. Keeping this fact in mind, we plotted the graphs with only small values of Deborah number β . We observed that the velocity profile $f'(\eta)$ is an increasing function with the increase in Deborah number β . On the other hand, the velocity profile $f'(\eta)$ is a decreasing function of increasing relaxation time λ_2 . Figures 16 and 17 show that the OHAM solution of $\theta(\eta)$ agrees with the numerical solutions obtained by MATHEMATICA. As we know, for the small values of effective Prandtl number Pr_{eff} the fluid is highly conductive. Physically, if Pr_{eff} increases, the thermal diffusivity decreases and this effect leads to the decrease in thermal energy transfer ability; thus, we have a decrease in thermal boundary layer thickness. Figure 17 shows the influence of effective Prandtl number Pr_{eff} on the temperature profile $\theta(\eta)$, and, as expected, with increase in Pr_{eff}, we observe a decrease in temperature and thermal boundary layer thickness. Figure 16 represents the effect of Dufour number D_f on the temperature profile and thermal boundary layer thickness; it is found that the temperature is an increasing function of the Dufour number D_f and we observe increased thermal boundary layer thickness with increasing Dufour number D_f . Figures 18 and 19 show the effect of Schmidt number Sc on the concentration profile and it is found that the concentration profile is the decreasing function of the Schmidt number Sc. There is aneffect of Soret number Sr on the concentration profile, and it is found that the concentration profile is the rapidly increasing function of the Soret number Sr.



Figure 14. Influence of λ_2 on $f'(\eta)$. Solid line: OHAM solution, solid circles: exact solution.



Figure 15. Influence of β on $f'(\eta)$. Solid line: OHAM solution, solid circles: exact solution.



Figure 16. Influence of D_f on $\theta(\eta)$. Solid line: OHAM solution, solid circles: numerical solution.



Figure 17. Influence of Pr_{eff} on $\theta(\eta)$. Solid line: OHAM solution, solid circles: numerical solution.



Figure 18. Influence of *Sc* on $\phi(\eta)$. Solid line: OHAM solution, solid circles: numerical solution.



Figure 19. Influence of *Sr* on $\phi(\eta)$. Solid line: OHAM solution, solid circles: numerical solution.

5.2. Dimensionless Numbers Analysis

The combined effect of Deborah number β and λ_2 on the skin friction coefficient is shown in Table 5. Similar behavior is obtained by HAM and LNS methods, and results indicate that the magnitude of the skin friction coefficient is a decreasing function of β and increasing function of λ_2 . Table 6 shows the numerical values of local Nusselt number and Sherwood number given by (15) with different values of emerging parameters with $\xi = 0.5$ and $R_d = 0.1$. The results indicate that the magnitude of local Nusselt number and Sherwood number increases with increase in Deborah number β and decreases with increase in λ_2 , respectively. The magnitude of local Nusselt number increases with increase in effective Prandtl number Pr_{eff}, whereas Sherwood number is a decreasing function of this parameter. The magnitude of local Nusselt number decreases with increase in Dufour number $D_{f,i}$ in other words, an increase in D_f decreases the temperature. On the other hand, magnitude of Sherwood number increases with increase in D_f . The magnitude of local Nusselt number decreases with increase in Schmidt number Sc,; in other words, an increase in *Sc* decreases the temperature. On the other hand, magnitude of Sherwood number increases with increase in Sc. The magnitude of local Nusselt number increases with increase in Soret number *Sr*; in other words, an increase in *Sr* increases the temperature. On the other hand, magnitude of Sherwood number decreases with increase in Sr.

β	λ_2	$1/2\xi^{\frac{1}{2}}(Re_x)^{1/2}C_{f_x}$	
		HAM	LNS
0.1	0.2	-0.810916	-0.810136579708008
0.2		-0.865708	-0.862813397684096
0.3		-0.92212	-0.928645306198704
0.4		-1.02733	-1.016061707634548
0.1	0.5	-0.716637	-0.715574452433584
	0.6	-0.691239	-0.693642216319338
	0.7	-0.670491	-0.673674640038218
	0.8	-0.655178	-0.655395338946309

Table 5. The impact of emerging parameters on the local skin friction coefficient C_{f_x} .

Table 6. The impact of emerging parameters on the Nusselt number Nu_x and Sherwood number Sh_x with $R_d = 0.1$.

β	λ_2	Pr _{eff}	D_f	Sc	Sr	$\xi^{\frac{1}{2}}(Re_x)^{-1/2}Nu_x$		$\xi^{\frac{1}{2}}(Re_x)^{-1/2}Nu_x \qquad \xi^{\frac{1}{2}}(Re_x)^{-1/2}S$		Sh_x
						HAM	LNS	HAM	LNS	
0.1	0.2	0.1	0.3	0.2	0.3	-0.191064	-0.193536	-0.292952	-0.292298	
0.2						-0.191180	-0.193776	-0.293074	-0.293147	
0.3						-0.191271	-0.193961	-0.293169	-0.293917	
0.4						-0.191341	-0.194120	-0.293238	-0.294629	
0.1	0.5					-0.192781	-0.192170	-0.285601	-0.287609	
	0.6					-0.192543	-0.191798	-0.285316	-0.286282	
	0.7					-0.192313	-0.191454	-0.285040	-0.285050	
	0.8					-0.192091	-0.191134	-0.284773	-0.283899	
	0.2	0.1				-0.193556	-0.193536	-0.292952	-0.292298	
		0.2				-0.272448	-0.277065	-0.286259	-0.288730	
		0.3				-0.347235	-0.344452	-0.285995	-0.286049	
		0.4				-0.402231	-0.400301	-0.285730	-0.283756	
		0.1	0.1			-0.198235	-0.197816	-0.292952	-0.292119	
			0.2			-0.195624	-0.195677	-0.286259	-0.292208	
			0.3			-0.192757	-0.193536	-0.285995	-0.292298	
			0.4			-0.402231	-0.191393	-0.285730	-0.292388	
			0.3	0.1		-0.196925	-0.196511	-0.198721	-0.196626	
				0.2		-0.192260	-0.193536	-0.290406	-0.292298	
				0.3		-0.191285	-0.191183	-0.366907	-0.369898	
				0.4		-0.186176	-0.189153	-0.433794	-0.435793	
				0.3	0.1	-0.193544	-0.193439	-0.298659	-0.295350	
					0.2	-0.193550	-0.193487	-0.297816	-0.293824	
					0.3	-0.193556	-0.193536	-0.293339	-0.292298	
					0.4	-0.193561	-0.193585	-0.290047	-0.290770	

5.3. Closing Remarks

The unsteady flow with heat and mass transfer over stretching sheet with Soret and Dufour effects is numerically studied using two different methods. The homotopy analysis method is straightforward to apply on partial differential equations but requires very long processing time at higher order of approximations, which may be considered as a disadvantage of the homotopy analysis method. On the other hand, the numerical solutions of system of ordinary differential equations at second level of truncation are easily computed with very small processing time. The results obtained by both methods are very close and the impact of emerging parameters is equivalent in both approaches. On the basis of processing time, the local nonsimilarity method is the recommended option. The influence of emerging parameters on velocity, temperature, and concentration profiles can be summarized as follows:

- The analytical solution obtained by OHAM for the similarity equations agrees with the exact solution of steady-state velocity profile and with the numerical solution of steady-state temperature and concentration profile.
- The velocity profile is found to be the increasing function of Deborah number β and decreasing function of λ₂.
- The temperature profile decreases with increase in effective Prandtl number Pr_{eff}, whereas it increases with increase in Dufour number D_f. There is no significant effect of Soret number Sr and Schmidt number Sc on the temperature profile in the steady case.
- The concentration profile $\phi(\eta)$ is an increasing function of Soret number *Sr* and decreasing function of Schmidt number *Sc*. There is no significant effect of effective Prandtl number \Pr_{eff} and Dufour number D_f on the concentration profile in the steady case.
- The behavior of effective Prandtl number Pr_{eff} on the temperature profile is the same as the behavior of Schmidt number *Sc* on the concentration profile. Similarly, the behavior of Dufour number D_f on the temperature profile is the same as the behavior of Soret number *Sr* on the concentration profile, in both steady and transient flow cases.
- We observed a development of velocity, temperature, and concentration boundary layers as the dimensionless time τ increased from 0 and the boundary layers gained the steady state as dimensionless time $\tau \rightarrow \infty$.
- The behavior of all emerging parameters for all profiles is the same as in the case of steady-state flow.
- The skin friction coefficient is a decreasing function of β and increasing function of λ_2 , local Nusselt number is an increasing function of effective Prandtl number \Pr_{eff} , and Sherwood number is a decreasing function of this parameter.
- The local Nusselt number decreases with increase in Dufour number *D_f*, and Sherwood number increases with increase in *D_f*.
- The local Nusselt number decreases with increase in Schmidt number *Sc*, and Sherwood number increases with increase in *Sc*.
- The local Nusselt number increases with increase in Soret number *Sr*, and Sherwood number decreases with increase in *Sr*.

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