



# Communication Research on Outdoor Mobile Music Speaker Battery Management Algorithm Based on Dynamic Redundancy

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**Abstract:** In terms of the battery management system of a mobile music speaker, reliability optimization has always been an important topic. This paper proposes a new dynamic redundant battery management algorithm based on the existing fault-tolerant structure of a lithium battery pack. The internal configuration is adjusted according to the SOC of each battery, and the power supply battery is dynamically allocated. This paper selects four batteries to experiment on with two different algorithms. The simulation results show that compared with the traditional battery management algorithm, the dynamic redundant battery management algorithm extends the battery pack working time by 18.75%, and the energy utilization rate of B<sub>1</sub> and B<sub>4</sub> increases by 96.0% and 99.8%, respectively. This proves that the dynamic redundant battery management algorithm can effectively extend battery working time and improve energy utilization.

Keywords: dynamic redundancy; music speaker battery; state of charge; fault time; passive redundancy

# 1. Introduction

With the gradual development of video and audio technology in the 21st century, the development of portable audio source products is diversified [1-3]. For different use environments and users, there are many types of audio source products, such as split type, combined type, desktop type, portable type and outdoor type. Mobile music speakers have become a hot product in recent years. Mobile music speakers are outdoor speakers that can be carried at any time. In a small range, such as classrooms or bedrooms at home, mobile music speakers are convenient as they can play music at any time. In the outdoor environment, outdoor activities often require speaker equipment support, so mobile music speakers are suitable for use in outdoor collective activities, such as teaching, group meetings, shopping mall broadcasting, dance practice and morning exercise audio. In these cases, a mobile music speaker is a good choice. However, though they are convenient and lightweight, mobile music speaker batteries have a short life, are slow to charge and have other problems. Thus, mobile music speaker battery research is a hot issue today. Most mobile music speakers in China use lithium-ion batteries [4–7]. However, with the increasing demand for energy and the increasingly serious environmental pollution caused by traditional energy in the 21st century, new renewable energy sources such as nanogenerators have emerged [8–11]. Further, new energy batteries have flourished in the era of energy conservation and emission reduction [12,13]. In recent years, research on new energy batteries has continued to strengthen, the energy density of batteries has continued to increase [14-18] and the production cost has dropped significantly. In particular, the emergence of lithium-ion batteries has become a hot spot for new energy batteries [19–22]. How to improve the performance of battery packs and reduce the use cost are the research focus of new energy batteries [23-25]. Figure 1 shows the advantages and problems of mobile music speakers.



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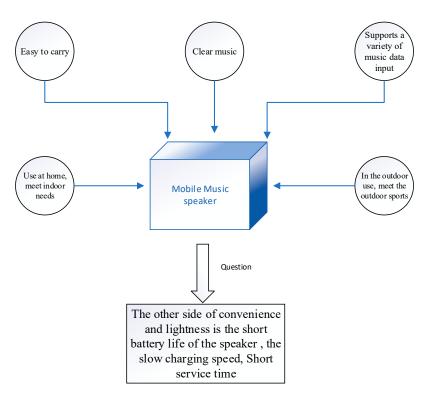


Figure 1. The advantages and problems of mobile music speakers.

In the study of battery pack management systems for mobile music speakers, most researchers improved the service life of the battery pack by studying the inconsistency in batteries [26–30]. This paper proposes a new dynamic redundant battery management algorithm based on the existing fault-tolerant structure of a lithium battery pack, adjusts redundant batteries by identifying the SOC of each battery, minimizes the impact of a single battery failure and improves the overall reliability of the battery pack. Compared with the traditional redundant battery management system, the energy utilization rate of the redundant battery is greatly improved, and the working time of the battery pack is extended, which effectively slows down the aging speed of the battery pack caused by excessive discharge of a single battery. However, the battery management algorithm based on dynamic redundancy uses more batteries, which has a high cost and complex internal circuits that need to be improved.

# 2. Model Building

The architecture of the battery pack is closely related to the reliability of the entire battery system [31,32]. In order to improve the reliability, one can further extend the working time of the battery by adding redundant units and switches to select active units. The main electrical characteristic of the battery is the maximum storage capacity  $Q_0$ . The physical characteristics of the battery are usually characterized by state of charge (SOC) [33–37]. SOC describes the battery's charge Q(t) at time t in the form of a percentage. During calculation, SOC data are equal to the charge quantity Q(t) of the battery at time t divided by the maximum storage capacity  $Q_0$ , and its expression is as follows:

$$SOC = \frac{Q(t)}{Q_0} \times 100\% \tag{1}$$

A single battery can only provide nominal current at a preset voltage [38–40]. In order to meet the requirements of power equipment, power storage systems usually use series to increase voltage and parallel to increase current. For example, for two parallel connections of four batteries in series, the instantaneous failure rate of a battery failure is denoted as  $\lambda$ and the overall failure rate is  $8\lambda$ , resulting in the reliability of the power storage system being greatly reduced. Therefore, it is necessary to use redundant batteries to improve battery reliability. The relationship between reliability R(t) and instantaneous failure rate  $\lambda$  is as follows:

$$R(t) = e^{-\Lambda_{cell} \cdot t} \tag{2}$$

The expression of MTTF, the average battery failure time, is:

$$MTTF_{cell} = \int_{t=0}^{+\infty} R(t) \cdot d_t = \frac{1}{\lambda_{cell}}$$
(3)

Currently, there are two common fault-tolerant structures in batteries [41–43]: seriesparallel fault-tolerant structure (SP) and parallel-series fault-tolerant structure (PS). This paper focuses on the study of the PS structure. In the case of unit failure in the PS structure, the exchange between the basic unit and the redundant unit is enabled by the switch, and the reliability of the battery pack can be improved by adding redundant columns. Due to the parallel structure, the faulty battery can be isolated only by a series switch, and the nominal power of the battery pack is usually guaranteed by adding redundant columns. The PS structure of the battery pack in series is shown in Figure 2.

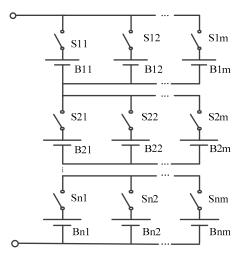


Figure 2. Battery pack parallel-series fault-tolerant structure.

The reliability expression of the PS structure battery is as follows:

$$R_{PS}(t) = e^{-n(m-1)\lambda_{cell}t} (1 + \lambda_{cell}t)^{n(m-1)}$$
(4)

The expression MTTF of the mean failure time of the PS structure battery is:

$$MTTF_{PS} = \sum_{k=0}^{n \cdot (m-1)} \binom{n \cdot (m-1)}{k} \frac{1}{n \cdot (m-1)^k \cdot \lambda_{cell}}$$
(5)

To demonstrate the operation of the algorithm, power is provided by a set of parallel batteries, one of which is an additional redundant cell. The battery redundancy module, as shown in Figure 3, represents a row in the battery pack architecture, which is capable of providing three-times the power of a single cell.

Among them,  $B_1$ ,  $B_2$  and  $B_3$  are the main power supply battery,  $B_4$  is the redundant battery, R is the load and each battery is connected with a diode. The main circuit includes four lithium-ion batteries, four relay switches, four diodes and a load. The four batteries are connected in parallel to simulate the actual working state of the battery pack.

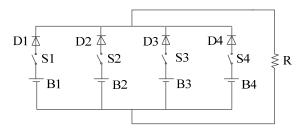


Figure 3. Battery redundancy module.

## 3. Control Strategy

To ensure that the proposed architecture can meet the power requirements of the external load, three batteries are required to supply external power at any one time. Then, one must fully charge the four batteries and set (SOC) = 1(t = 0). Because the internal resistance and discharge depth of each battery are different, battery strings may be inconsistent during external power supply. Assume that the SOC of each battery drops by 30%, 25%, 20% and 15%, respectively, during each discharge cycle. During each cycle, the SOC of the battery is recorded.

When the traditional redundant battery management system detects that the battery voltage of the working group is lower than the limit value, the redundant battery is started to replace the battery to improve the battery life and anti-interference ability [44,45]. As shown in Table 1, after the 3.3 discharge cycle, the SOC of  $B_1 = 0$ . It is then isolated and replaced with  $B_4$  redundant batteries. When the SOC of  $B_2$  is 0, the battery string cannot meet the requirement of a triple power supply current. Therefore, the battery string stops supplying power at the fourth discharge cycle.

				SOC/%
Period of Discharge	<b>B</b> <sub>1</sub>	B <sub>2</sub>	B <sub>3</sub>	B <sub>4</sub>
0	100	100	100	100
1	70	75	80	100
2	40	50	60	100
3	10	25	40	100
3.3	0	17	33	100
4	0	0	20	85

Table 1. Traditional redundant battery management algorithm discharge process.

On this basis, a battery management algorithm based on dynamic redundancy is proposed, as shown in Table 2. Each battery is then charged, with  $B_1$ ,  $B_2$  and  $B_3$  powered first. After one discharge period,  $B_1$  has the lowest battery capacity and is isolated as a redundant battery.  $B_2$ ,  $B_3$  and  $B_4$  start to supply the external power. At the end of the second discharge cycle,  $B_2$  has the lowest power, and it is isolated as a new redundant battery, and  $B_1$ ,  $B_3$  and  $B_4$  supply power. After the end of the fifth discharge cycle, the quantity of  $B_2$  is zero, and only three batteries are left to supply power. After the end of the second the triple power supply current and the power supply stops. Through the battery management algorithm based on dynamic redundancy, the battery pack discharge period is extended to 5.3. Compared with the traditional redundant battery management algorithm, the working time is significantly extended. Meanwhile, the remaining power of each battery is lower, which improves the utilization rate of energy.

					SOC/%
Period of Discharge	<b>B</b> <sub>1</sub>	<b>B</b> <sub>2</sub>	B <sub>3</sub>	<b>B</b> <sub>4</sub>	Supply Current
0	100	100	100	100	$B_1 B_2 B_3$
1	70	75	80	100	$B_2 B_3 B_4$
2	70	50	60	85	$B_1 B_3 B_4$
3	40	50	40	70	$B_1 B_2 B_4$
4	10	25	40	55	$B_2 B_3 B_4$
5	10	0	20	40	$B_1 B_3 B_4$
5.3	0	0	13	35	

Table 2. Dynamic redundant battery management algorithm discharge process.

An algorithm flowchart is shown in Figure 4.

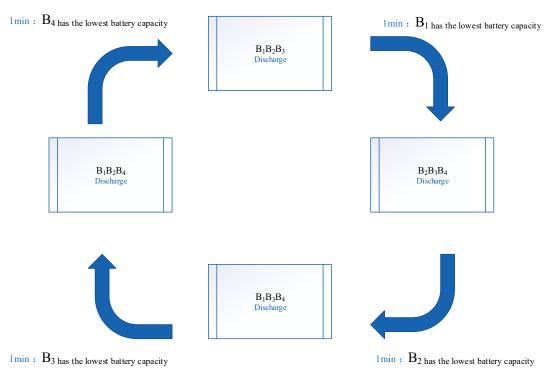


Figure 4. Algorithm flow chart.

#### 4. Simulation Results and Analysis

MATLAB was used for simulation experiments. The initial capacity of the battery was set to 200 mAh, the rated voltage was set to 4 V and the load resistance was set to 5  $\Omega$ . In this paper, four batteries were simulated to provide electric energy for power equipment. Due to different production and manufacturing factors and equivalent resistance inside batteries, the initial SOC of the four batteries was selected to be 100%, 90%, 80% and 100%, respectively, in order to make the experiment more universal. When the early discharge of a battery ends, the failed battery is replaced by redundant batteries to ensure the normal operation of the entire battery pack.

The following is the construction of the simulation diagram, divided into main circuit and control circuit, using MATLAB FUNCTION in MATLAB to replace the MCU simulation. First, the main circuit is built. The main circuit consists of four lithium-ion batteries, four relay switches, four diodes, four resistors and one load. The selected battery model can set initial voltage, initial capacity, voltage at full charge and initial SOC. This will facilitate the test of this project. The selected relay switch can be set with internal resistance. In order to simulate the operation under ideal conditions, the internal resistance of the relay is set very small, which can be basically ignored. The same diode can also be set as internal resistance. In order to simulate the operation under ideal conditions, this simulation will set the internal resistance of the diode as very small to facilitate subsequent test analysis. The load selected for the main circuit is also adjustable, so as to facilitate waveform analysis. This is the complete device introduction of the main circuit, and the main circuit is shown in Figure 5 below.

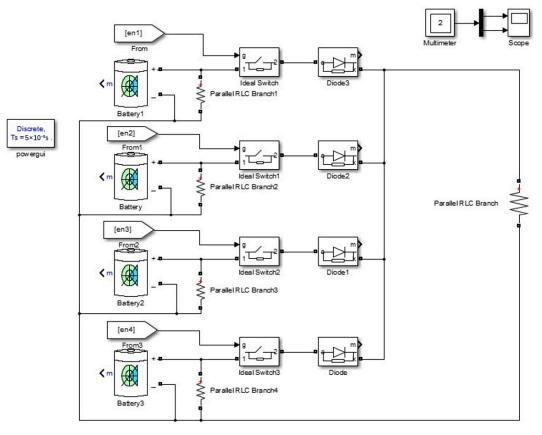


Figure 5. Main circuit of algorithm.

The control circuit is shown in Figure 6. Firstly, MATLAB FUNCTION is used to simulate the single chip microcomputer to realize the algorithm research. This function can realize the same function as the single chip microcomputer. Then, the control circuit is built. The specific idea is as follows: when the high level of the pulse generator is produced, the timing will start when only the delayed input also enters a high level. Knowing that the next pulse is high, the delayed pulse will arrive along the rising edge, thus realizing the function of the cycle and having a time period that can be adjusted. Then, MATLAB programming is utilized for each cycle of the collected voltage analysis. Selecting the battery with the lowest voltage as the standby battery, power is supplied to the other three batteries. After one cycle, MATLAB collects the voltage again and then selects the lowest voltage from the four batteries as the new standby battery. This cycle equalizes the battery pack.

The discharge process of traditional redundant battery management algorithms is as follows:  $B_1$ ,  $B_2$  and  $B_3$  are discharged first, and  $B_4$  is used as the redundant battery.  $B_3$  is the first battery whose SOC decreases to 0. When the SOC of  $B_3$  decreases to 0, it is replaced by  $B_4$ ,  $B_1$ ,  $B_2$  and  $B_4$  to continue the work.

The discharge process of the battery management algorithm based on dynamic redundancy is shown in Figure 7. During the working process of the battery pack, the sampling time t = 1 min is set, and the SOC of the four batteries is compared every 1 min, so as to ensure that the battery with the highest SOC always supplies power to the outside in each time period. As can be seen from the figure, at the beginning of discharge, the SOC of the

four batteries is compared, and  $B_3$  is the least redundant battery, while  $B_1$ ,  $B_2$  and  $B_4$  work. At the 80th minute,  $B_2$  with the smallest SOC is selected as the redundant battery, and  $B_1$ ,  $B_3$  and  $B_4$  continue to work. At the next sampling time, the same operation is carried out, and the cycle is carried out. Compared with the traditional redundant battery discharge method, the operating time of the dynamically redundant battery pack reaches 190 min, which is 18.75% longer.

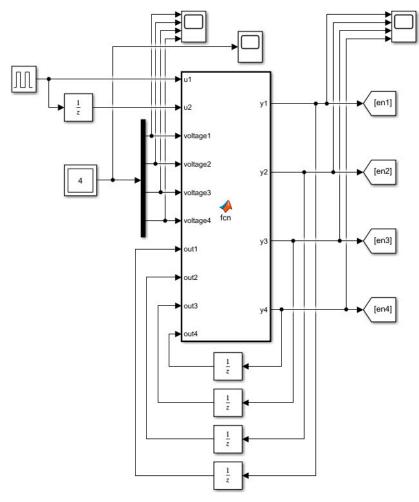


Figure 6. Control circuit of algorithm.

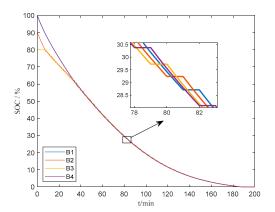


Figure 7. Dynamic redundant battery management algorithm working process diagram.

The simulation circuit is run, and the relay operation process of each battery in series is shown in Figure 8. A large resistance is connected in parallel at both ends of the relay to detect the opening and closing of the relay. The high level represents the closing of the relay, while the low level represents the disconnection of the relay. As can be seen from the figure, in each discharge cycle, three batteries are at a high level and one battery is at a low level to meet the load requirements. The power supply process for the whole battery pack is a process of dynamic selection.

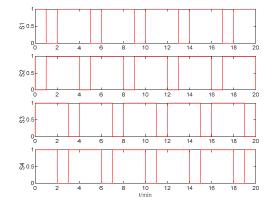


Figure 8. Relay switch action.

The SOC after a single discharge of the traditional redundant battery management algorithm is shown in Table 3. It can be seen that when the traditional redundant battery management algorithm ends the discharge of 160 min, the remaining SOC of B<sub>1</sub> is 2.5%, B<sub>2</sub> and B<sub>3</sub> are reduced to 0 and the remaining SOC of B<sub>4</sub> is 58.1%.

t/min	B <sub>1</sub>			SOC/% B4
		B <sub>2</sub>	B <sub>3</sub>	
0	100.0	90.0	80.0	100.0
30	63.3	55.7	48.4	100.0
60	37.7	31.4	27.1	100.0
100	14.4	11.1	7.7	100.0
130	5.6	4.3	0	100.0
160	2.5	0	0	58.1

Table 3. Traditional redundant battery management algorithm.

The SOC after a single discharge of the battery management algorithm based on dynamic redundancy is shown in Table 4. At the end of 190 min of discharge, the remaining SOC of  $B_1$  is 0.1%,  $B_2$  and  $B_3$  are reduced to 0 and the remaining SOC of  $B_4$  is 0.1%. Compared with the traditional redundant battery management algorithm, the remaining battery power is significantly lower, and the energy utilization rate of  $B_1$  and  $B_4$  is increased by 96.0% and 99.8%, respectively.

Table 4. Dynamic redundant battery management algorithm.

				SOC/%
t/min	B <sub>1</sub>	B <sub>2</sub>	B <sub>3</sub>	B <sub>4</sub>
0	100.0	90.0	80.0	100.0
30	65.5	64.6	63.8	66.4
60	42.8	42.3	43.0	42.7
100	19.7	20.0	19.9	19.6
130	9.2	8.9	9.0	8.9
160	3.0	2.9	2.9	3.1
190	0.1	0	0	0.1

Although the battery management algorithm based on dynamic redundancy can improve the energy utilization rate of the battery and improve the reliability of the battery pack, the battery management algorithm based on dynamic redundancy needs to be improved due to the high cost and complex internal circuit.

### 5. Conclusions

In this paper, a battery management algorithm based on dynamic redundancy is proposed for the battery management system of a mobile music speaker. Through dynamic adjustment of redundant batteries under various working conditions, the voltage output can be stable, and the working time of battery packs can be extended. Through MATLAB simulation to verify the algorithm, a single discharge process of the battery pack working time increased from 160 min to 190 min, extended by 18.75%; At the same time, the energy utilization rates of B1 and B4 were increased by 96.0% and 99.8% respectively based on the remaining power of redundant batteries. The results show that the proposed battery management scheme can greatly reduce the impact of single battery failure, improve the reliability of the battery and slow down the aging speed of the battery caused by excessive discharge of a single battery.

**Author Contributions:** The named authors have substantially contributed to conducting the underlying research and drafting this manuscript. Conceptualization, X.Y.; methodology, X.Y.; software, Y.L.; validation, X.L., L.W.; formal analysis, X.L.; investigation, L.W.; data curation, K.W.; writing—original draft preparation, X.Y.; writing—review and editing, Y.L.; visualization, L.W.; supervision, K.W.; project administration, K.W.; funding acquisition, K.W. All authors have read and agreed to the published version of the manuscript.

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