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Battery Parameter Analysis through Electrochemical Impedance Spectroscopy at Different State of Charge Levels

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Abstract: This paper presents a systematic approach to extract electrical equivalent circuit model (ECM) parameters of the Li-ion battery (LIB) based on electrochemical impedance spectroscopy (EIS). Particularly, the proposed approach is suitable to practical applications where the measurement noise can be significant, resulting in a low signal-to-noise ratio. Given the EIS measurements, the proposed approach can be used to obtain the ECM parameters of a battery. Then, a time domain approach is employed to validate the accuracy of estimated ECM parameters. In order to investigate whether the ECM parameters vary as the battery's state of charge (SOC) changes, the EIS experiment was repeated at nine different SOC levels. The experimental results show that the proposed approach is consistent in estimating the ECM parameters. It is found that the battery parameters, such as internal resistance, capacitance and inductance, remain the same for practical SOC ranges starting from 20% until 90%. The ECM parameters saw a significant change at low SOC levels. Furthermore, the experimental data show that the resistive components estimated in the frequency domain are very close to the internal resistance estimated in the time domain. The proposed approach was applied to eight different battery cells consisting of two different manufacturers and produced consistent results.

Keywords: Li-ion battery (LIB); battery management system; electrochemical impedance spectroscopy (EIS); electrical equivalent circuit models; battery impedance estimation



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1. Introduction

Lithium-based rechargeable battery packs have been widely adopted in electric vehicles (EVs). The behavior of the lithium-ion battery (LIB) is highly nonlinear. A battery management system (BMS) [1] ensures the safety, efficiency and reliability of electric vehicles by continuously monitoring the battery packs. The main component of a BMS is the battery fuel gauge (BFG). The BFG estimates all the critical parameters of the battery, such as state of charge (SOC), state of health (SOH), time to shut down (TTS) and remaining useful life (RUL) [2–4]. In order for the BFG to achieve all these aspects, identifying a battery model and estimating its parameters remains a crucial step [5].

So far, two approaches have been developed in the literature for estimating a battery's electrical equivalent circuit model (ECM) parameters: time domain and frequency domain approaches [6]. In the time domain approach, voltage and current measurements from the battery are used [7,8] to estimate the ECM parameters. The EIS is a well-known frequency domain technique in which the output response is the impedance of the battery [9] at different frequencies; it was introduced by Heaviside in 1894 [10]. In electrochemical impedance spectroscopy (EIS), special excitation signals with varying frequencies are superimposed on the charging or discharging current of the battery. The measured time domain responses (voltage and current) are converted to frequency domain using Fast Fourier Transform (FFT) [11] and the impedance is computed in the frequency domain. The battery's ECM parameters can be estimated based on the impedance computed at a specified range of frequencies.

Significant work has been reported in the literature about the application of the EIS technique in battery management. In [9], the measurement accuracy was enhanced by using an improved input excitation method and a precise impedance measurement technique which can clip offset and amplify signals together with FFT. Instead of using FFT to estimate the battery's EIS, Felder et al. [12] estimated a battery's EIS by computing the signal's amplitude and phase; furthermore, changing sampling frequency does not affect the accuracy of this approach. Allagui et al. [13] analyzed the stability, linearity, dissipation, and degradation of a battery cell's electrochemical behavior in frequency and time domain and found that a modified constant phase element can be used to fit EIS data in low frequency. Physics-based battery modeling was addressed in [14] by using the EIS technique. Models using the EIS technique to estimate the battery's SOC based on fractional order impedance have been developed in [15,16]. Battery aging identification and quantification was completed using EIS for four parallel Li-ion cells in [17]. A power converter was used in a closed loop with a step perturbation current for better control of the output from EIS [18].

Nonlinear least square (NLS) estimation techniques were used in [19] to estimate the ECM parameters of the battery. NLS techniques were employed to estimate battery ECM parameters in the presence of Gaussian noise with a high signal-to-noise ratio (SNR) [20]. However, in [20], the estimated parameters were not analyzed against SOC. A circuit parameter extraction algorithm for the LIB charging system using online EIS was performed in [21]. In [22], ECM parameters were extracted using the recursive time and frequency domain estimation approach. Additionally, EIS at different SOC levels of a battery was performed in [23]; however, the estimation accuracy was not shown. Parameter estimation in both the time and frequency domain using the least square genetic algorithm (LSGA) was demonstrated in [16]; however, the resulting parameters at different SOC levels were not shown. In [24], EIS at different SOC levels was performed; however, the experimentation was not for estimating parameters but rather for investigating the effect in SOH. Feng et al. [25] applied complex nonlinear least-squares (CNLS) to estimate ECM parameters with the EIS data measured from one battery at different SOC and temperatures; however, their parameter estimation approach was based on a simplified ECM (SECM) which aims to model the solid-liquid electrolyte lithium-ion batterie (SLELB); in addition, they only estimated resistive components of the SECM and did not employ any independent approaches to validate the estimated parameters. Pastor-Fernández et al. [26] applied a CNLS fitting algorithm to extract ECM parameters with the EIS data measured from four 3 Ah 18650 NCA-C Lion-ion batteries; their estimation approach is based on AR-ECM, but they only estimated the ohmic, solid electrolyte interface (SEI), charge transfer (CT), and Warburg resistance of the AR-ECM at 20%, 50%, and 90% SOC over different aging cycles.

In general, the EIS approach has been significantly employed in the literature for battery analysis. However, little had been accomplished to develop closed-form approaches to estimate the ECM parameters of the battery. Such approaches to battery parameter estimation need to be tested using data from multiple, yet identical batteries for consistency. It is also important to verify the efficacy of the parameter extraction approach with alternate methods. The existing works in the literature lack these avenues, and the present paper aims to contribute toward closed-form battery parameter estimation based on EIS.

The contributions of this paper can be summarized as follows:

1. This paper uses the parameter estimation approach presented in [27] to extract the battery ECM parameters based on EIS at multiple SOC levels.
2. For the first time, the closed-form ECM parameters obtained using the frequency domain (EIS) approach were compared to the ECM parameters obtained using a time domain approach at multiple SOC levels. This time domain ECM parameter estimation approach [28] exploits the pulse stream current profile to reduce the error due to measurement noise. Furthermore, the proposed parameter estimation approach was partially tested based on parameters reported by the scientific grade measurement system.

3. The ECM parameter estimation approach was applied to four different battery cells belonging to two different manufacturers, and the results were found to be consistent.

The remainder of the paper is organized as follows: Section II describes the algorithms used to estimate ECM parameters in the frequency domain. Section III describes the algorithms used to estimate ECM parameters in the time domain. The experimental procedure is explained in Section IV. Results are discussed in Section V. Section VI concludes the paper.

2. Frequency Domain Approach to ECM Parameter Estimation

EIS is a widely used technique to study the impedance response of the battery. In EIS, a small perturbation current with a wide range of frequencies (0.01 Hz to 10 kHz) is supplied to the battery, and its impedance at those frequencies can be measured. The battery impedance is then represented by real values on the x-axis and imaginary values on the y-axis in a Nyquist plot [29,30]. This plot represents the impedance spectrum of the battery from which the model parameters are estimated with algorithms using identified feature points on the curve.

The frequency domain approach uses the Adaptive Randles equivalent circuit model (AR-ECM) shown in Figure 1. The AR-ECM consists of the following elements: battery voltage source, ohmic resistance (R_Ω), stray inductance (L), resistance due to SEI layer (R_{SEI}), capacitance due to SEI layer (C_{SEI}), charge transfer resistance (R_{CT}), double layer capacitance (C_{DL}) and Warburg impedance (Z_w). Figure 2.1(b) in [27] shows the Nyquist plot relevant to the AR-ECM.

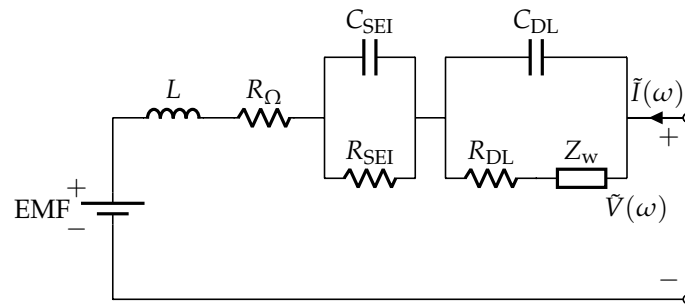


Figure 1. Adaptive Randles equivalent circuit model (AR-ECM) of a battery.

According to Figure 1, the AC impedance $Z(\omega)$ corresponding to AR-ECM can be written as [27]

$$\begin{aligned}
 Z(\omega) &\triangleq Z(j\omega) \\
 &= j\omega L + R_\Omega + \frac{1}{\frac{1}{R_{SEI}} + j\omega C_{SEI}} + \frac{1}{\frac{1}{R_{CT} + Z_w(j\omega)} + j\omega C_{DL}} \\
 &= \underbrace{j\omega L + R_\Omega}_{Z_{RL}} + \underbrace{\frac{R_{SEI}}{1 + j\omega R_{SEI} C_{SEI}}}_{Z_{SEI}} + \underbrace{\frac{R_{CT} + Z_w(j\omega)}{1 + j\omega (R_{CT} + Z_w(j\omega)) C_{DL}}}_{Z_{CT\&DF}}
 \end{aligned} \tag{1}$$

where Z_{RL} denotes the impedance in the RL arc, Z_{SEI} denotes the impedance in the SEI arc, and $Z_{CT\&DF}$ denotes the impedance in the CT arc and Diffusion arc.

In Figure 2, the feature points are selected manually, which are indicated by index k_{DF1} , k_{DF2} , k_{CT1} , k_{CT2} , k_{SEI1} , k_{SEI2} , k_{RL1} and k_{RL2} . From Figure 1, it is clear that the measured Nyquist plot needs to be divided into several parts to see how it is directly related to the AR-ECM. Different parts of the Nyquist plot represent the battery's impedance at different frequencies.

- k_{DF1} is the index of the first data point, that is, $k_{DF1} = 1$.
- k_{DF2} is selected such that the data points from k_{DF1} to k_{DF2} follow the linear line.

- k_{CT1} is selected at the beginning of the CT arc such that the data points start to follow the arc.
- k_{CT2} is selected at the end of CT arc such that k_{CT1} to k_{CT2} follows the CT arc to achieve the best fit.
- Similarly, k_{SEI1} is selected at the beginning of the SEI arc.
- k_{SEI2} is selected at the end of the SEI arc such that k_{SEI1} to k_{SEI2} follow the SEI arc to achieve the best fit.
- k_{RL1} is selected at the beginning of the RL arc.
- k_{RL2} is selected at the end of the RL arc.

To solve the problem of ECM parameter estimation, using the least squares (LS) algorithm to fit the real Nyquist plot as shown in Figure 2 is a promising approach, as this can reduce the effect of measurement noise to increase the accuracy of estimated parameters. The following section will summarize the LS approach [27] to ECM parameters estimation based on the manually selected feature points.

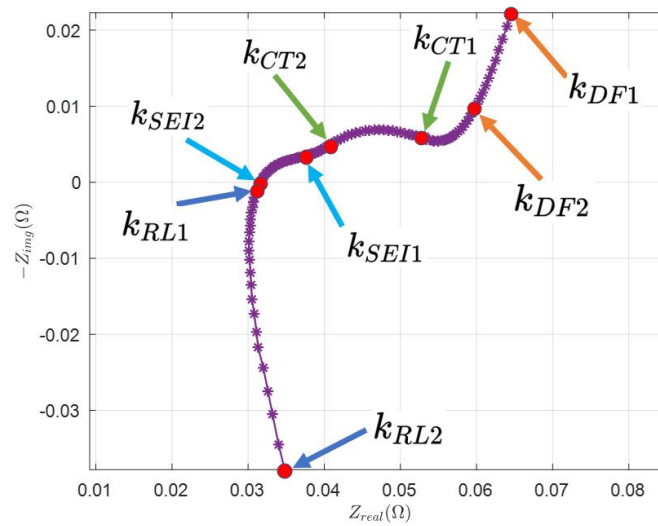


Figure 2. Selection of feature points from the real Nyquist plot.

2.1. Estimation of Ohmic Resistance and Stray Inductance

From the previous work in [27], ohmic resistance R_Ω can be estimated as

$$\hat{R}_\Omega = \frac{1}{k_{RL2} - k_{RL1} + 1} \sum_{k=k_{RL1}}^{k_{RL2}} z_r(k) \quad (2)$$

and stray inductance L can be estimated as

$$\hat{L} = \frac{1}{k_{RL2} - k_{RL1} + 1} \sum_{k=k_{RL1}}^{k_{RL2}} \frac{z_i(k)}{\omega_k} \quad (3)$$

where $z_r(k) = \text{Re}(Z(\omega_k))$ and $z_i(k) = \text{Im}(Z(\omega_k))$, and $\omega_{k_{RL1}} \leq \omega_k \leq \omega_{k_{RL2}}$.

2.2. Estimation of Warburg Coefficient

Warburg impedance is defined mathematically as

$$Z_w(j\omega) = (1 - j) \frac{\sigma}{\sqrt{\omega}} \quad (4)$$

where σ is the Warburg coefficient.

From Figure 1, it is clear that the Warburg impedance is significant only at lower frequencies ($\omega < \omega_{k1}$). In Figure 2, feature points from k_{DF1} to k_{DF2} are selected (where $k_{DF1} = 1$), considering the real part of the impedance z_r in the diffusion arc:

$$\begin{aligned} z_r(1) - z_r(k_{DF2}) &= \sigma \left(\frac{1}{\sqrt{\omega_1}} - \frac{1}{\sqrt{\omega_{k_{DF2}}}} \right) \\ z_r(2) - z_r(k_{DF2} - 1) &= \sigma \left(\frac{1}{\sqrt{\omega_2}} - \frac{1}{\sqrt{\omega_{(k_{DF2}-1)}}} \right) \\ &\vdots \\ z_r(n) - z_r(k_{DF2} - n + 1) &= \sigma \left(\frac{1}{\sqrt{\omega_n}} - \frac{1}{\sqrt{\omega_{(k_{DF2}-n+1)}}} \right) \end{aligned} \quad (5)$$

where $n = \text{floor}(\frac{k_{DF2}-k_{DF1}+1}{2})$. The expression $z_r(i) - z_i(j)$ is used to reduce the effect of noise in the measurements.

The observation model corresponding to (5) is

$$\tilde{\mathbf{z}} = \mathbf{b}\sigma \quad (6)$$

where

$$\tilde{\mathbf{z}} = \begin{bmatrix} z_r(1) - z_r(k_{DF2}) \\ z_r(2) - z_r(k_{DF2} - 1) \\ \vdots \\ z_r(n) - z_r(k_{DF2} - n + 1) \end{bmatrix}, \mathbf{b} = \begin{bmatrix} \left(\frac{1}{\sqrt{\omega_1}} - \frac{1}{\sqrt{\omega_{k_{DF2}}}} \right) \\ \left(\frac{1}{\sqrt{\omega_2}} - \frac{1}{\sqrt{\omega_{(k_{DF2}-1)}}} \right) \\ \vdots \\ \left(\frac{1}{\sqrt{\omega_n}} - \frac{1}{\sqrt{\omega_{(k_{DF2}-n+1)}}} \right) \end{bmatrix}$$

The LS estimate of σ is

$$\hat{\sigma} = (\mathbf{b}^T \mathbf{b})^{-1} (\mathbf{b}^T \tilde{\mathbf{z}}) \quad (7)$$

2.3. Estimation of R_{SEI} and C_{SEI}

The impedance for frequencies $\omega_{k_{SEI1}} \leq \omega \leq \omega_{k_{SEI2}}$ is in a practical Nyquist plot as shown in Figure 2; to fit the SEI arc precisely, we select feature points that lie between k_{SEI1} and k_{SEI2} . Therefore, the impedance of the SEI arc between $\omega_{k_{SEI1}} \leq \omega \leq \omega_{k_{SEI2}}$ is given as

$$Z_{SEI} = \frac{1}{\frac{1}{R_{SEI}} + j\omega C_{SEI}} \quad (8)$$

The impedance measurements in the SEI arc can be denoted as:

$$\begin{aligned} s_r &\triangleq z_r(k) \quad \text{s.t. } k_{SEI1} \leq k \leq k_{SEI2} \\ s_i &\triangleq z_i(k) \quad \text{s.t. } k_{SEI2} \leq k \leq k_{SEI2} \end{aligned} \quad (9)$$

where $z_r(k) = \text{Re}(Z(\omega_k))$ and $z_i(k) = \text{Im}(Z(\omega_k))$.

Estimation of the SEI arc is essentially the problem of fitting a semicircle with its center lying on the real axis; the coordinates of this semicircle's center can be noted as $(x_s, 0)$; the radius of the semicircle can be noted as R_s ; therefore, the measurements in (9) should satisfy the equation of the semicircle, which are given by

$$(s_r - x_s)^2 + (s_i - 0)^2 = R_s^2 \quad (10)$$

$$s_r^2 - 2x_s s_r + x_s^2 + s_i^2 = R_s^2 \quad (11)$$

Let $c = -2x_s$ and $d = x_s^2 - R_s^2$, thus

$$R_s^2 = \frac{c^2}{4} - d \quad (12)$$

$$R_s = \sqrt{\frac{c^2}{4} - d} \quad (13)$$

In addition, (11) can be rewritten as

$$s_r^2 + s_i^2 + cs_r + d = 0 \quad (14)$$

In the matrix form, (14) can be written as

$$\underbrace{\begin{bmatrix} -(s_r(k_{SEI1})^2 + s_i(k_{SEI1})^2) \\ -(s_r(k_{SEI1} + 1)^2 + s_i(k_{SEI1} + 1)^2) \\ -(s_r(k_{SEI1} + 2)^2 + s_i(k_{SEI1} + 2)^2) \\ \vdots \\ -(s_r(k_{SEI2})^2 + s_i(k_{SEI2})^2) \end{bmatrix}}_{\mathbf{z}} = \underbrace{\begin{bmatrix} s_r(k_{SEI1}) & 1 \\ s_r(k_{SEI1} + 1) & 1 \\ s_r(k_{SEI1} + 2) & 1 \\ \vdots \\ s_r(k_{SEI2}) & 1 \end{bmatrix}}_{\mathbf{B}} \underbrace{\begin{bmatrix} c \\ d \end{bmatrix}}_{\mathbf{x}_{SEI}} + \underbrace{\begin{bmatrix} n_v(1) \\ n_v(2) \\ \vdots \\ n_v(n) \end{bmatrix}}_{\mathbf{n}} \quad (15)$$

Using the LS algorithm, the estimate of $\hat{\mathbf{x}}_{SEI}$ will be given by

$$\hat{\mathbf{x}}_{SEI} = (\mathbf{B}^T \mathbf{B})^{-1} (\mathbf{B}^T \mathbf{z}) \quad (16)$$

The estimates of c and d are:

$$\hat{c} = \hat{\mathbf{x}}_{SEI}(1), \quad \hat{d} = \hat{\mathbf{x}}_{SEI}(2) \quad (17)$$

From Figure 2.1(b) in [27], the solid electrolyte interface resistance R_{SEI} is the diameter of the SEI arc; thus, by substituting the values of c and d in (13), the estimate of R_{SEI} is

$$\hat{R}_{SEI} = 2R_s = 2\sqrt{\frac{\hat{c}^2}{4} - \hat{d}} \quad (18)$$

In (1), when the frequency is very high, we assume the impedance in the CT arc and Diffusion arc will be very small so that it is negligible; thus, the $Z_{CT\&DF}$ term will become zero, that is

$$Z = Z_{RL} + Z_{SEI} + 0 \quad (19)$$

Therefore, the impedance in the SEI arc can be expressed as:

$$Z_{SEI} = Z - Z_{RL} \quad (20)$$

$$\frac{R_{SEI}}{1 + j\omega R_{SEI} C_{SEI}} = Z(\omega) - j\omega L - R_{\Omega} \quad (21)$$

$$1 + j\omega R_{SEI} C_{SEI} = \frac{R_{SEI}}{Z(\omega) - j\omega L - R_{\Omega}} \quad (22)$$

$$j\omega R_{SEI} C_{SEI} = \frac{R_{SEI}}{Z(\omega) - j\omega L - R_{\Omega}} - 1 \quad (23)$$

Taking the imaginary part on both sides of the above equation,

$$C_{SEI} = \left(\frac{1}{\omega R_{SEI}} \right) \text{Im} \left(\frac{R_{SEI}}{Z(\omega) - j\omega L - R_{\Omega}} - 1 \right) \quad (24)$$

Substituting the expression for R_{SEI} , R_Ω , and L from (18), (2), and (3), respectively, in (24) at $\omega = \omega_k$ ($k_{SEI1} \leq k \leq k_{SEI2}$):

$$\tilde{C}_{SEI}(k) = \left(\frac{1}{\omega_k \hat{R}_{SEI}} \right) \text{Im} \left(\frac{\hat{R}_{SEI}}{Z(\omega_k) - j\omega_k \hat{L} - \hat{R}_\Omega} - 1 \right) \quad (25)$$

Finally, we average all the estimates $\tilde{C}_{SEI}(k)$ to obtain the final estimate

$$\hat{C}_{SEI} = \frac{1}{k_{SEI2} - k_{SEI1} + 1} \sum_{k=k_{SEI1}}^{k_{SEI2}} \tilde{C}_{SEI}(k) \quad (26)$$

2.4. Estimation of R_{CT} and C_{DL}

The practical Nyquist plot is shown in Figure 2; to fit the CT arc precisely, we select feature points that lie between k_{CT1} and k_{CT2} ; therefore, the impedance of the CT arc between $\omega_{k_{CT1}} \leq \omega \leq \omega_{k_{CT2}}$ is given as

$$Z_{CT} = \frac{1}{\frac{1}{R_{CT} + Z_w(j\omega)} + j\omega C_{DL}} \quad (27)$$

The impedance measurements in the CT arc can be denoted as:

$$\begin{aligned} c_r &\triangleq z_r(k) \quad \text{s.t. } k_{CT1} \leq k \leq k_{CT2} \\ c_i &\triangleq z_i(k) \quad \text{s.t. } k_{CT1} \leq k \leq k_{CT2} \end{aligned} \quad (28)$$

where $z_r(k) = \text{Re}(Z(\omega_k))$ and $z_i(k) = \text{Im}(Z(\omega_k))$.

Similar to the estimation of R_{SEI} , R_{CT} can be estimated by fitting a semicircle to the CT arc. Assuming that the center of the semicircle lies on the real axis, which is noted as $(x_c, 0)$, the radius of the semicircle can be noted as R_c ; therefore, the measurements in (28) should satisfy the equation of the semicircle, which is given by

$$(c_r - x_c)^2 + (c_i - 0)^2 = R_c^2 \quad (29)$$

$$c_r^2 - 2x_c c_r + x_c^2 + c_i^2 = R_c^2 \quad (30)$$

Let $a = -2x_c$ and $b = x_c^2 - R_c^2$; thus,

$$R_c^2 = \frac{a^2}{4} - b \quad (31)$$

$$R_c = \sqrt{\frac{a^2}{4} - b} \quad (32)$$

Now, (30) can be rewritten as

$$c_r^2 + c_i^2 + ac_r + b = 0 \quad (33)$$

In the matrix form, (33) can be written as

$$\underbrace{\begin{bmatrix} -(c_r(k_{CT1})^2 + c_i(k_{CT1})^2) \\ -(c_r(k_{CT1} + 1)^2 + c_i(k_{CT1} + 1)^2) \\ -(c_r(k_{CT1} + 2)^2 + c_i(k_{CT1} + 2)^2) \\ \vdots \\ -(c_r(k_{CT2})^2 + c_i(k_{CT2})^2) \end{bmatrix}}_{\mathbf{p}} = \underbrace{\begin{bmatrix} c_r(k_{CT1}) & 1 \\ c_r(k_{CT1} + 1) & 1 \\ c_r(k_{CT1} + 2) & 1 \\ \vdots & \vdots \\ c_r(k_{CT2}) & 1 \end{bmatrix}}_{\mathbf{C}} \underbrace{\begin{bmatrix} a \\ b \end{bmatrix}}_{\mathbf{x}_{CT}} + \underbrace{\begin{bmatrix} n_v(1) \\ n_v(2) \\ \vdots \\ n_v(n) \end{bmatrix}}_{\mathbf{n}} \quad (34)$$

From (34), x_{CT} can be estimated using the LS algorithm

$$\hat{x}_{CT} = (C^T C)^{-1} (C^T p) \quad (35)$$

Thus, the estimates of a and b are:

$$\hat{a} = \hat{x}_{CT}(1), \quad \hat{b} = \hat{x}_{CT}(2) \quad (36)$$

From Figure 2.1(b) in [27], the charge transfer resistance R_{CT} is the diameter of the CT arc; thus, by substituting the values of a and b in (32), the estimate of R_{CT} is

$$\hat{R}_{CT} = 2R_c = 2\sqrt{\frac{\hat{a}^2}{4} - \hat{b}} \quad (37)$$

From (1),

$$Z = Z_{RL} + Z_{SEI} + Z_{CT\&DF} \quad (38)$$

Therefore, the impedance in the CT arc and Diffusion arc can be expressed as:

$$Z_{CT\&DF} = Z - Z_{RL} - Z_{SEI} \quad (39)$$

$$\frac{R_{CT} + Z_w(j\omega)}{1 + j\omega(R_{CT} + Z_w(j\omega))C_{DL}} = Z(\omega) - j\omega L - R_{\Omega} - \frac{R_{SEI}}{1 + j\omega R_{SEI}C_{SEI}} \quad (40)$$

$$j\omega(R_{CT} + Z_w(j\omega))C_{DL} = \frac{R_{CT} + Z_w(j\omega)}{Z(\omega) - j\omega L - R_{\Omega} - \frac{R_{SEI}}{1 + j\omega R_{SEI}C_{SEI}}} - 1 \quad (41)$$

$$j\omega C_{DL} = \frac{1}{Z(\omega) - j\omega L - R_{\Omega} - \frac{R_{SEI}}{1 + j\omega R_{SEI}C_{SEI}}} - \frac{1}{R_{CT} + Z_w(j\omega)} \quad (42)$$

Taking the imaginary part on both sides of the above equation, and substituting $Z_w(j\omega)$ with the expression given in (5), we obtain

$$C_{DL} = \left(\frac{1}{\omega}\right) \text{Im} \left(\frac{1}{Z(\omega) - j\omega L - R_{\Omega} - \frac{R_{SEI}}{1 + j\omega R_{SEI}C_{SEI}}} - \frac{1}{R_{CT} + (1-j)\frac{\sigma}{\sqrt{\omega}}} \right) \quad (43)$$

Substituting L , R_{Ω} , R_{SEI} , C_{SEI} , R_{CT} and σ with the estimations given in (3), (2), (18), (26), (37), and (7), respectively, in (24) at $\omega = \omega_k$ ($k_{CT1} \leq k \leq k_{CT2}$):

$$\tilde{C}_{DL}(k) = \left(\frac{1}{\omega_k}\right) \text{Im} \left(\frac{1}{Z(\omega_k) - j\omega_k \hat{L} - \hat{R}_{\Omega} - \frac{\hat{R}_{SEI}}{1 + j\omega_k \hat{R}_{SEI} \hat{C}_{SEI}}} - \frac{1}{\hat{R}_{CT} + (1-j)\frac{\hat{\sigma}}{\sqrt{\omega_k}}} \right) \quad (44)$$

Finally, we average all the estimates $\tilde{C}_{DL}(k)$ to obtain the final estimate

$$\hat{C}_{DL} = \frac{1}{k_{CT2} - k_{CT1} + 1} \sum_{k=k_{CT1}}^{k_{CT2}} \tilde{C}_{DL}(k) \quad (45)$$

3. Time Domain Approach to ECM Parameter Estimation

Time domain approaches are widely used to estimate the internal resistance of the battery. Due to requiring less time consumption for its implementation, this approach is more suitable for real-time applications [7,8,29]. One of the methods is to use the pulse stream current profile [28], as shown in Figure 3, to estimate the internal resistance of the battery.

In Figure 4, considering a simple R-int model: when current $i(k)$ is supplied to the battery, voltage $z_v(k)$ across its terminal is given by

$$z_v(k) = E + i(k)R_0 \quad (46)$$

where E denotes the open circuit voltage, and R_0 is the internal resistance of the battery.

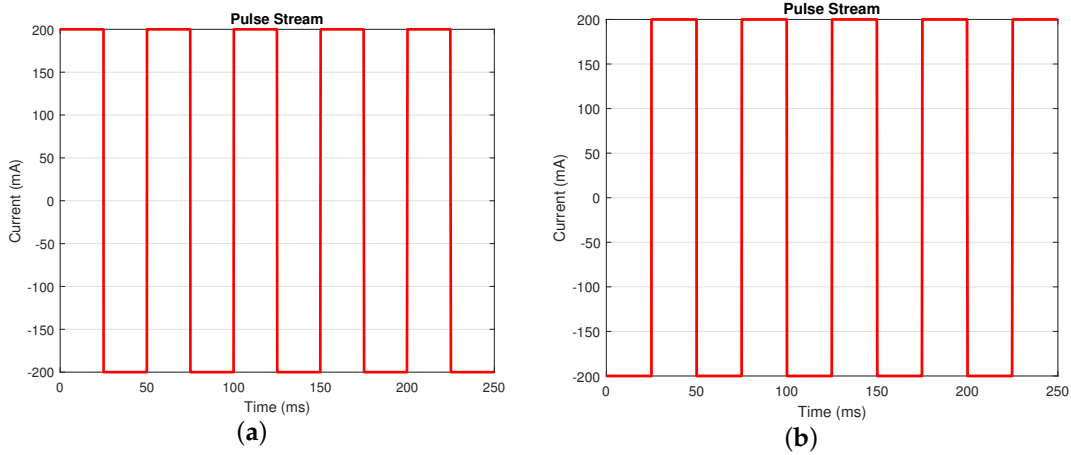


Figure 3. Current profile for pulse stream test. Use pulse stream A when the battery's SOC is between 0% and 90%; use pulse stream B when the battery's SOC is 100%. (a) Pulse stream A (frequency: 20 Hz; Duty Cycle: 50%). (b) Pulse stream B (frequency: 20 Hz; Duty Cycle: 50%).

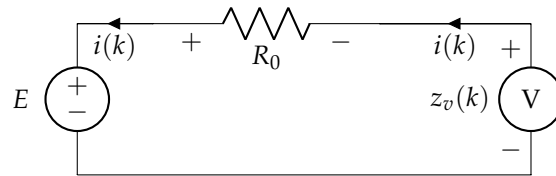


Figure 4. R-int model of battery.

Considering the presence of noise in measured voltage $z_v(k)$, (46) can be rewritten as

$$z_v(k) = E + i(k)R_0 + n_v(k) \quad (47)$$

Assuming there are n measurements in (47), the following can be written

$$\begin{aligned} z_v(1) &= E + i(1)R_0 + n_v(1) \\ &\vdots \\ z_v(n) &= E + i(n)R_0 + n_v(n) \end{aligned} \quad (48)$$

Equation (48) can be written in the matrix form

$$\underbrace{\begin{bmatrix} z_v(1) \\ z_v(2) \\ \vdots \\ z_v(n) \end{bmatrix}}_{\mathbf{z}} = \underbrace{\begin{bmatrix} 1 & i(1) \\ 1 & i(2) \\ \vdots & \vdots \\ 1 & i(n) \end{bmatrix}}_{\mathbf{P}} \underbrace{\begin{bmatrix} E \\ R_0 \end{bmatrix}}_{\mathbf{k}} + \underbrace{\begin{bmatrix} n_v(1) \\ n_v(2) \\ \vdots \\ n_v(n) \end{bmatrix}}_{\mathbf{n}} \quad (49)$$

E and R_0 can be estimated using the LS approach:

$$\hat{\mathbf{k}} = (\mathbf{P}^T \mathbf{P})^{-1} (\mathbf{P}^T \mathbf{z}) \quad (50)$$

$$\hat{E} = \hat{k}(1), \quad \hat{R}_0 = \hat{k}(2) \quad (51)$$

4. Experimental Procedure

This section explains the experimental procedure for data collection. The specifications of LG and Molicel batteries are shown in Table 1; four LG batteries are labeled as LG01, LG02, LG03, and LG04; and four Molicel batteries are labeled as MCL01, MCL02, MCL03, and MCL04. The data are collected using the Arbin battery cycler (Model: LBT21084UC). The Arbin cycler has 16 channels that can operate in parallel; eight channels were used to collect data simultaneously at room temperature (23 °C).

The EIS data are collected by the EIS device (Gamry interface 5000P). A Gamry EIS device and Arbin battery cycler are operated using the software named MITS Pro provided by Arbin. The voltage measurement error of the Gamry EIS device, as specified, is 0.2 mV [31].

All experiments presented in this paper started with a fully charged battery (SOC = 100%) and the SOC is reduced by 10% at a time until the SOC reached 0%; after that, the SOC is increased by 10% at a time until the SOC returned to 100%. In this paper, discharging the battery with $C_d/10$ A constant current or charging the battery with $C_c/10$ A constant current for 1 hour will decrease/increase the SOC by 10%; here, C_d is the discharge capacity and C_c is the charge capacity of the battery, which are given in Table 2.

At each of these SOC levels except for 100% and 0%, an EIS experiment is performed; additionally, a time-domain experiment is also performed. For the time-domain experiment, the current profile detailed in Figure 3 is applied right after the EIS experiment is conducted at the corresponding SOC. The detailed procedure is shown as follows:

- Find the cut-off voltage V_c
To ensure the maximum current in the CC-CV charging process below the safety limit, we need to set a conditional voltage, which should be greater than the cut-off voltage to decide when to start the CC or CV charging; the cut-off voltage can be written as:

$$V_c = V_{\max} - I_{\max}R_0 \quad (52)$$

From Table 1, the internal resistance of the LG battery is less than 40 mΩ, and the internal resistance of the Molicel battery is less than 15 mΩ. The maximum current $I_{\max} = 4.2$ A, and the maximum voltage $V_{\max} = 4.2$ V. Therefore, in the OCV test, we set the conditional voltage $V_{\text{con}} = 4.1$ V for LG batteries and $V_{\text{con}} = 4.15$ V for Molicel batteries.

Table 1. Specifications of LG and Molicel battery [32,33].

Specification	Value	
	Molicel INR-21700-P42A	LG INR-18650-MJ1
Nominal voltage	3.6 V	3.635 V
Nominal capacity	4200 mAh	3500 mAh
End of charge voltage	4.2 V	4.2 V
End of discharge voltage	2.5 V	2.5 V
Internal resistance	≤15 mΩ	≤40 mΩ
Height	70.2 mm	65 mm
Diameter	21.7 mm	18 mm
Weight	70 g	49 g

- OCV Test
 - Figure 5 shows the detailed test procedure.
 - Table 2 shows the actual discharge and charge capacity of the LG batteries and Molicel batteries, which are computed after the OCV test.

- EIS Test
 - The experimental procedure is shown in Figure 6a.
 - The experimental setup is shown in Figure 6b.

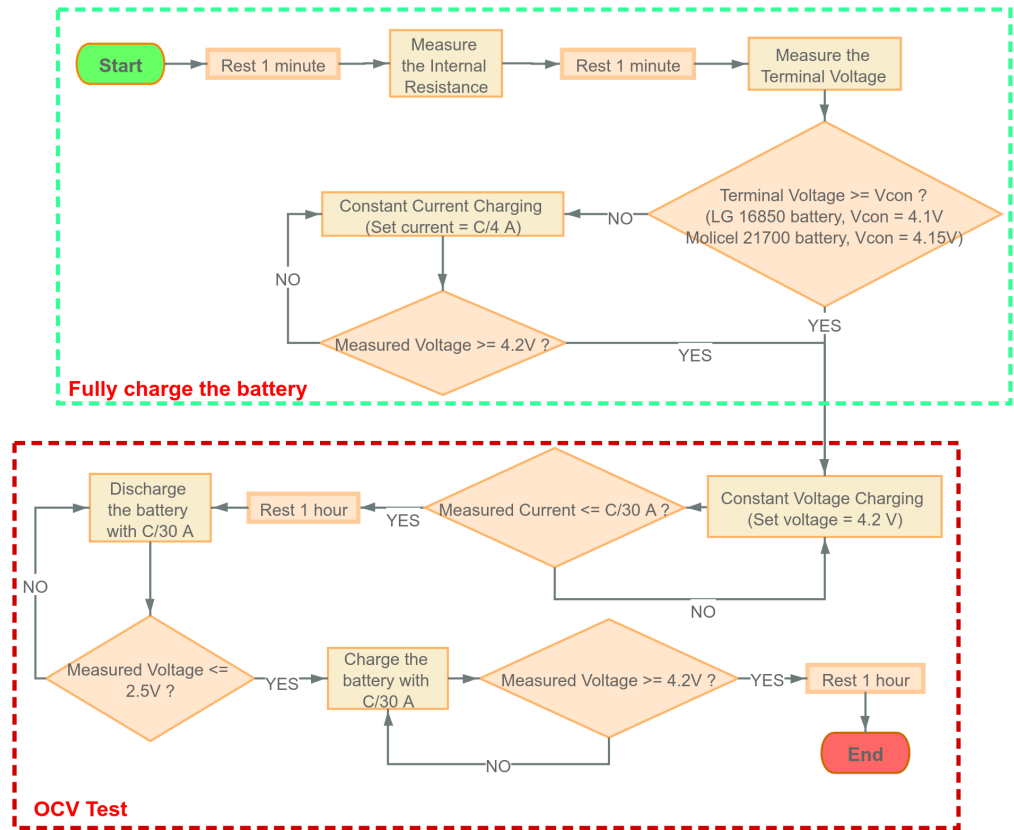
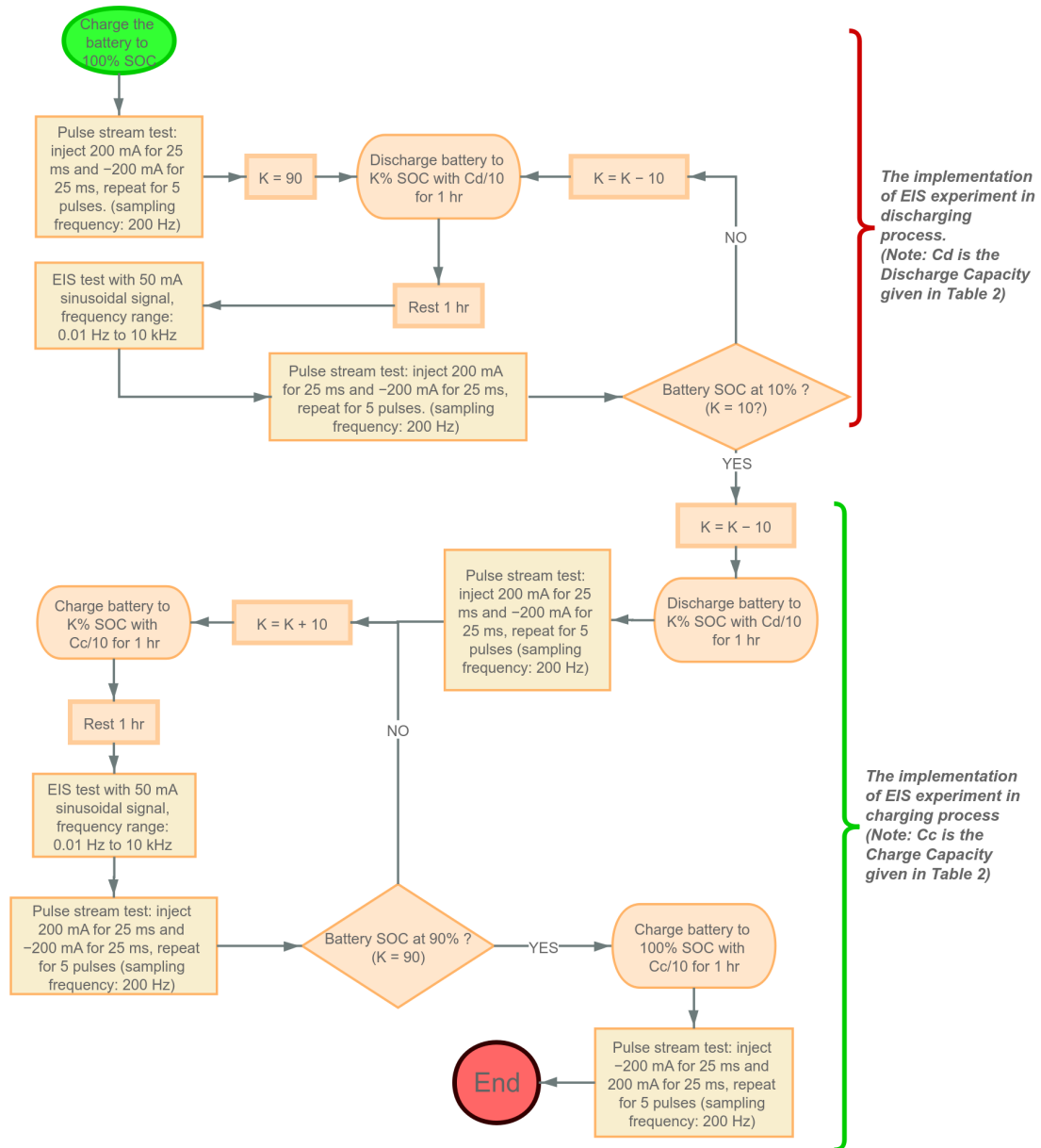


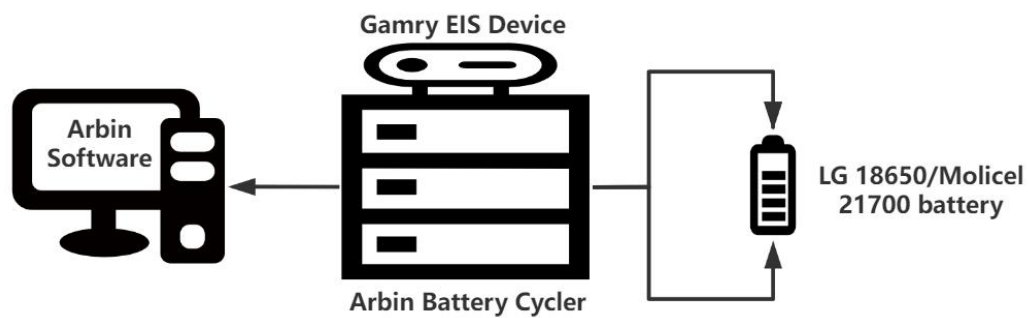
Figure 5. Procedure of OCV test.

Table 2. Discharge and charge capacity of different batteries. Models LG01/02/03/04 use the LG INR 18650 MJ1 battery, models MCL01/02/03/04 use the Molicel INR 21700-P42A battery.

Battery	Discharge Capacity (Ah)	Charge Capacity (Ah)
LG01	3.4063	3.3918
LG02	3.4272	3.4228
LG03	3.493	3.4972
LG04	3.4853	3.4912
MCL01	3.9867	3.98
MCL02	4.0105	3.9953
MCL03	4.0115	4.0249
MCL04	3.9889	4.0025



(a) EIS test procedure.



(b) Experimental setup.

Figure 6. Experimental procedure and setup.

5. Results

In this section, the results obtained from the experiment are shown and discussed.

Nyquist plots of eight batteries at different SOC levels are shown in Figures 7 and 8, where the SEI effect can be seen clearly in the Nyquist plot corresponding to 10% SOC while batteries are in the discharging or charging process.

In Tables 3–6, the estimated ECM parameters for LG and Molice batteries are obtained using the algorithms explained in Section 2. We can observe that the internal resistance R_i measured by Arbin is quite close to the ohmic resistance R_Ω . Furthermore, Figure 9a shows the fitted Nyquist plot of LG01 battery at 10% SOC while discharging, and Figure 9b shows the fitted Nyquist plot of MCL01 battery at 10% SOC while discharging.

From Figures 10 and 11, it can be observed that the ohmic resistance R_Ω , charge transfer resistance R_{CT} and double-layer capacitance C_{DL} all reached the highest value at 10% SOC; this phenomenon applies to both LG and Molice batteries. The Warburg coefficient σ of LG batteries reached the highest value at 10% SOC; as for Molice batteries, the highest σ occurred at 80% while discharging and 60% while charging. In addition, no regularity can be found in LG and Molice batteries with respect to the variations of L , R_{SEI} and C_{SEI} at the 10% SOC level; also, the variations of all ECM parameters between 20% and 90% SOC are not significant in general.

Figure 12 shows all the estimated internal resistance R_0 using the time domain approaches presented in Section 3. It can be seen that at 0%, both LG and Molice batteries' internal resistance R_0 declined to the lowest value, whereas at 10% SOC, all the Molice batteries' internal resistance R_0 reached the highest value.

Table 3. Estimated ECM parameters of LG batteries at each SOC while discharging. (Note: R_i is the internal resistance measured by Arbin.)

Battery	SOC (%)	R_i (m Ω)	R_Ω (m Ω)	L (nH)	R_{SEI} (m Ω)	C_{SEI} (F)	R_{CT} (m Ω)	C_{DL} (F)	σ ($\times 10^{-3}$)
LG01	90	33.82	34.12	467.72	3.04	0.22279	4.91	1.7651	2.12
	80		34.09	464.57	3.2	0.2151	4.29	1.6712	2.28
	70		34.11	470.99	2.33	0.21431	4.04	1.0928	2.24
	60		34.08	466.42	2.88	0.21156	4.01	1.4976	2.05
	50		34.21	473.66	2.82	0.23089	3.62	1.7077	1.54
	40		34.22	468.48	2.72	0.21218	3.84	1.3592	1.50
	30		34.17	465.74	3.22	0.20842	4.38	1.6185	1.47
	20		34.28	473.25	3.36	0.23364	5.35	2.1996	1.54
	10		34.55	465.79	3.4	0.20285	15.04	3.7892	3.12
LG02	90	33	33.33	448.08	3.35	0.22329	4.82	1.926	2.04
	80		33.3	444.73	2.84	0.20036	4.46	1.2474	2.31
	70		33.29	449.46	3.14	0.21614	3.89	1.7315	2.26
	60		33.3	442.35	2.3	0.18748	4.38	0.84849	1.96
	50		33.35	451.24	2.34	0.21002	3.75	1.0752	1.54
	40		33.38	444	3.21	0.20429	3.93	1.6539	1.50
	30		33.33	444.65	3.58	0.20997	4.21	1.9187	1.47
	20		33.46	451.29	3.91	0.24557	5.12	2.7591	1.68
	10		33.75	457.08	3.90	0.1923	16.51	4.1721	2.80
LG03	90	30.88	30.41	491.69	4.07	0.17069	4.8	1.6651	2.07
	80		30.37	496.55	3.82	0.17129	3.92	1.5633	2.26
	70		30.41	480.42	3.61	0.17819	3.71	1.5579	2.35
	60		30.44	480.88	3.43	0.17851	3.62	1.4463	2.33
	50		30.48	495.02	3.76	0.16739	3.85	1.5345	1.65
	40		30.54	492.51	3.86	0.16338	3.95	1.5042	1.53
	30		30.6	493.95	4.14	0.16388	4.2	1.6635	1.58
	20		30.73	497.38	4.95	0.19313	4.96	2.5082	1.65
	10		31.18	486.93	4.52	0.14924	14.1	2.7819	2.65
LG04	90	31.8	31.25	459.39	4.21	0.1715	4.76	1.7413	2.10
	80		31.22	461.43	3.36	0.1601	4.37	1.0751	2.37
	70		31.21	467.46	3.48	0.17395	3.74	1.4256	2.27
	60		31.22	466.49	3.53	0.1736	3.76	1.4251	2.28
	50		31.24	462.1	4.02	0.17255	3.76	1.8098	1.67
	40		31.27	461.36	4.01	0.16519	3.94	1.6283	1.53
	30		31.30	462.34	3.20	0.1527	4.79	0.93301	1.57
	20		31.40	463.75	4.65	0.18473	5.21	2.1757	1.64
	10		31.82	469.83	4.23	0.13732	14.01	2.9987	2.64

Figures 13 and 14 show the comparison of estimated total resistance $R_\Omega + R_{SEI} + R_{CT}$ and the estimated internal resistance R_0 of LG batteries and Molice batteries, respectively. As for LG and Molice batteries, $R_\Omega + R_{SEI} + R_{CT}$ is slightly higher than R_0 at all SOC, and it reached the highest value at 10% SOC.

Furthermore, Figure 15 shows the percent error of the estimated resistive elements $R_\Omega + R_{SEI} + R_{CT}$ with respect to the internal resistance R_0 in the charging and discharging

process. As for LG batteries, it can be seen that the percent errors are within 5% when the batteries' SOC is between 30% and 80% while charging or discharging; at 10% SOC, the percent errors are between 28% and 38% in the discharging process, and they are between 25% and 43% in the charging process. As for Molicel batteries, when the SOC is between 20% and 90%, the percentage errors are within 8% while discharging and are within 11% while charging; at 10% SOC, the percentage errors are between 6.8% and 9.5% in the discharging process, and they are between 12% and 15% in the charging process.

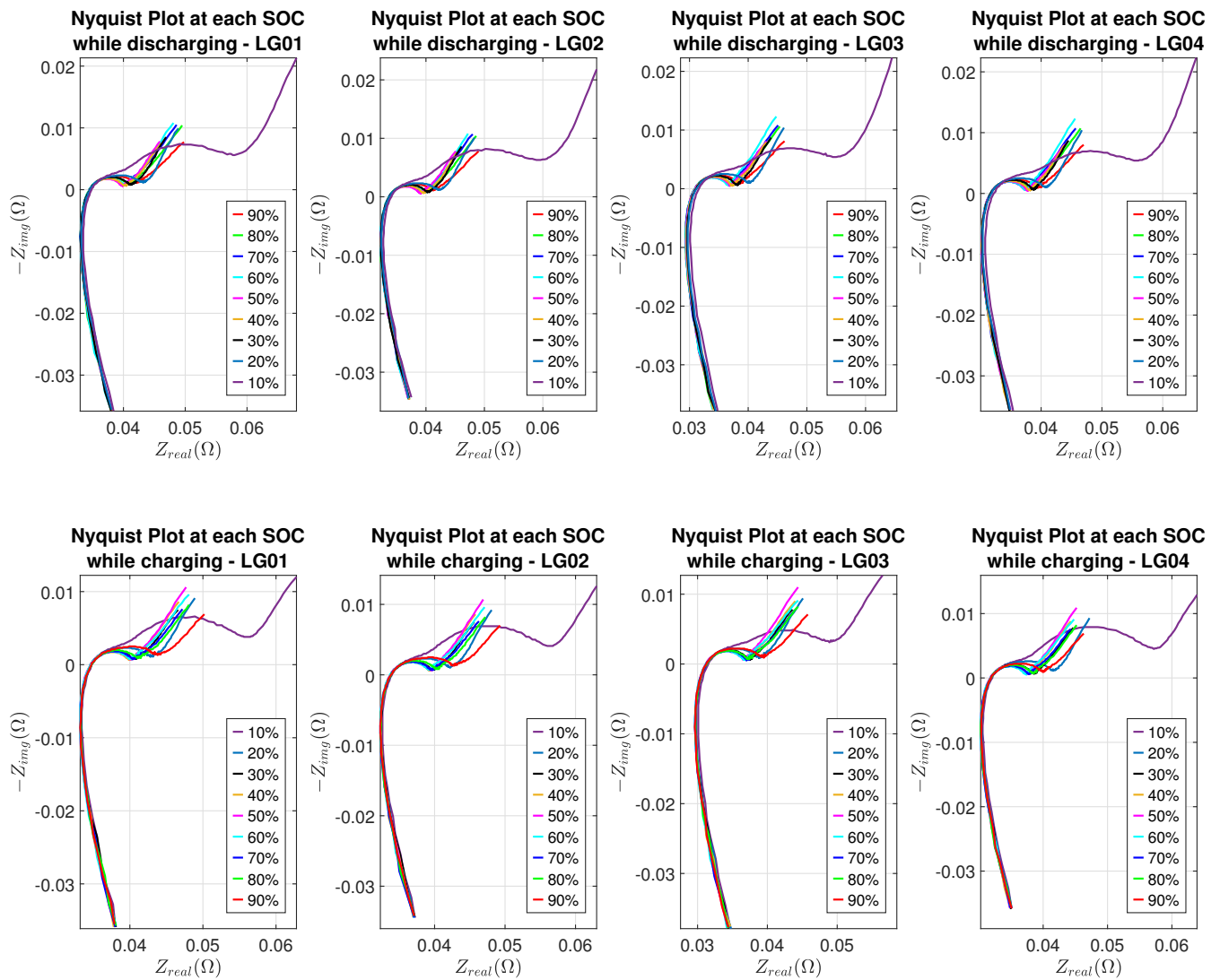


Figure 7. Nyquist plots of LG batteries.

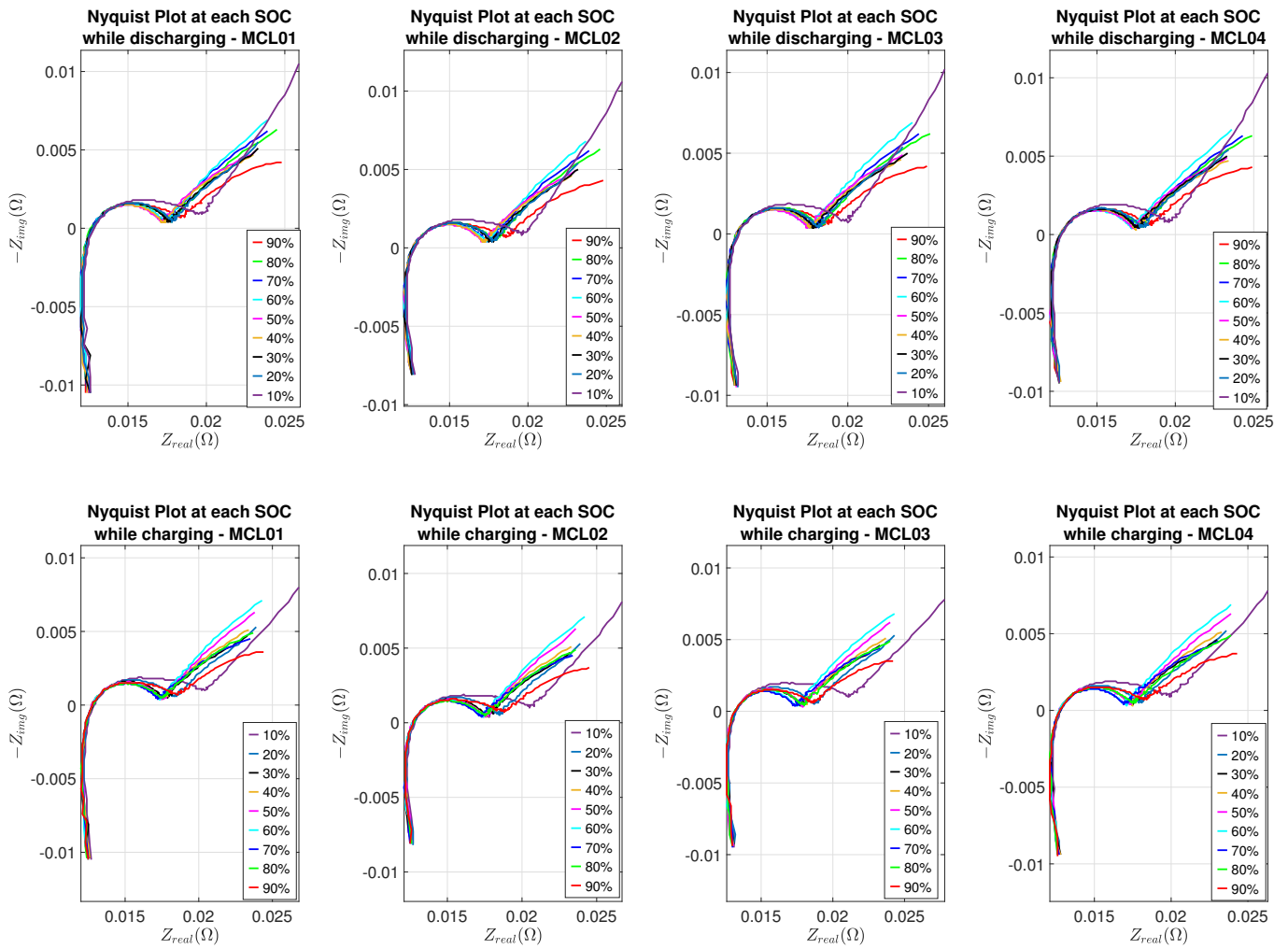


Figure 8. Nyquist plots of Molicel batteries.

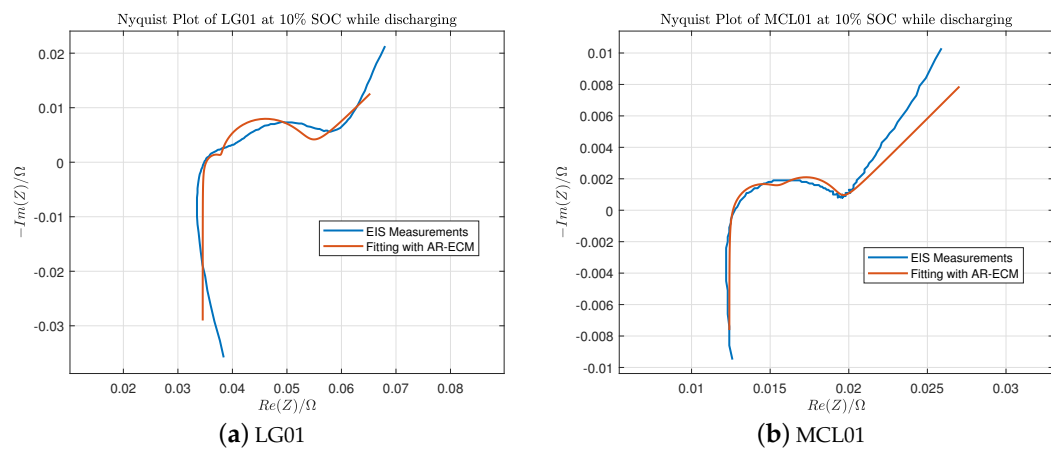


Figure 9. EIS fitting of LG01 and MCL01 batteries at 10% SOC while discharging.

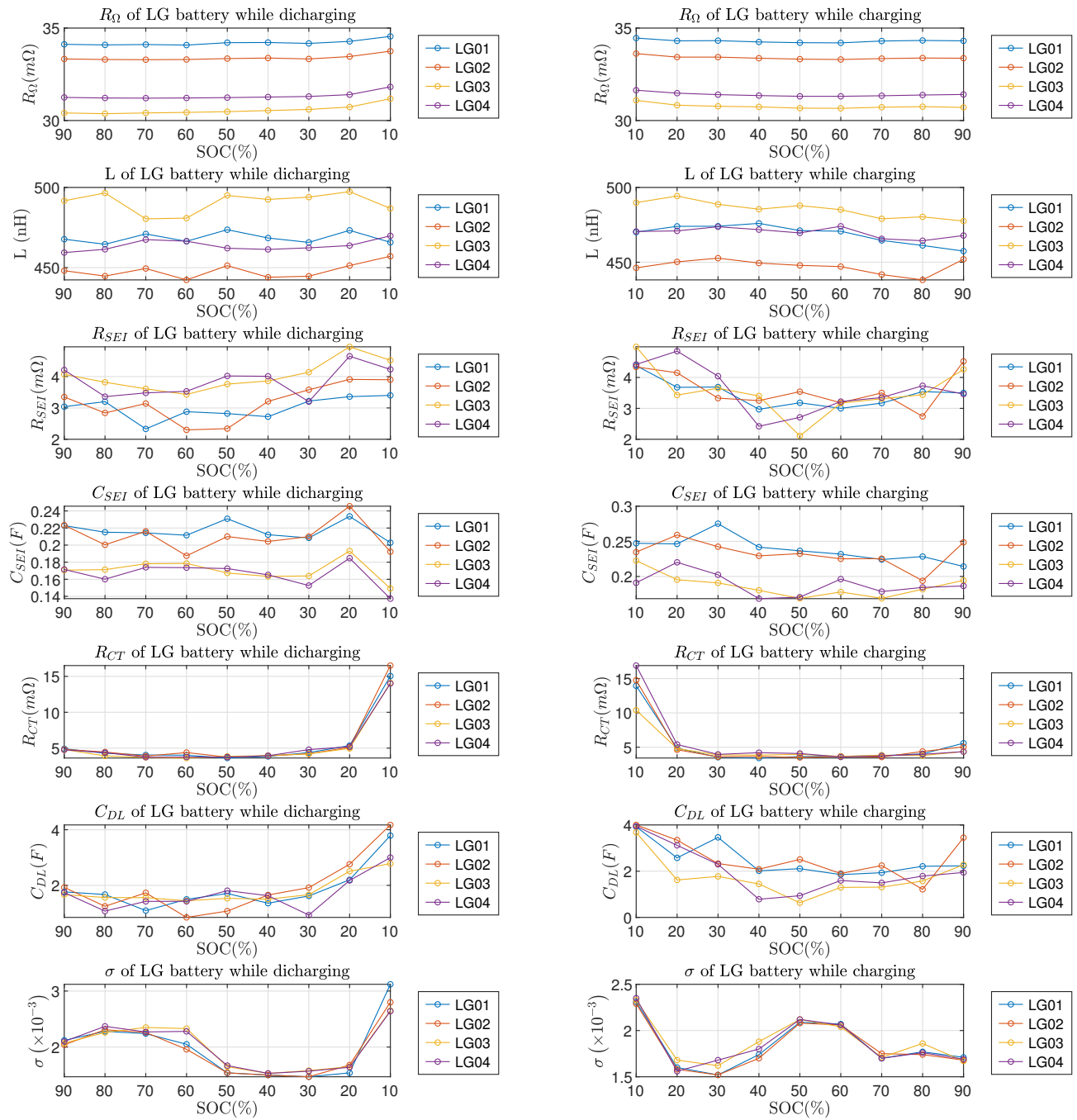


Figure 10. ECM parameters of LG batteries vs. SOC. Left column is for discharging and right column is for charging.

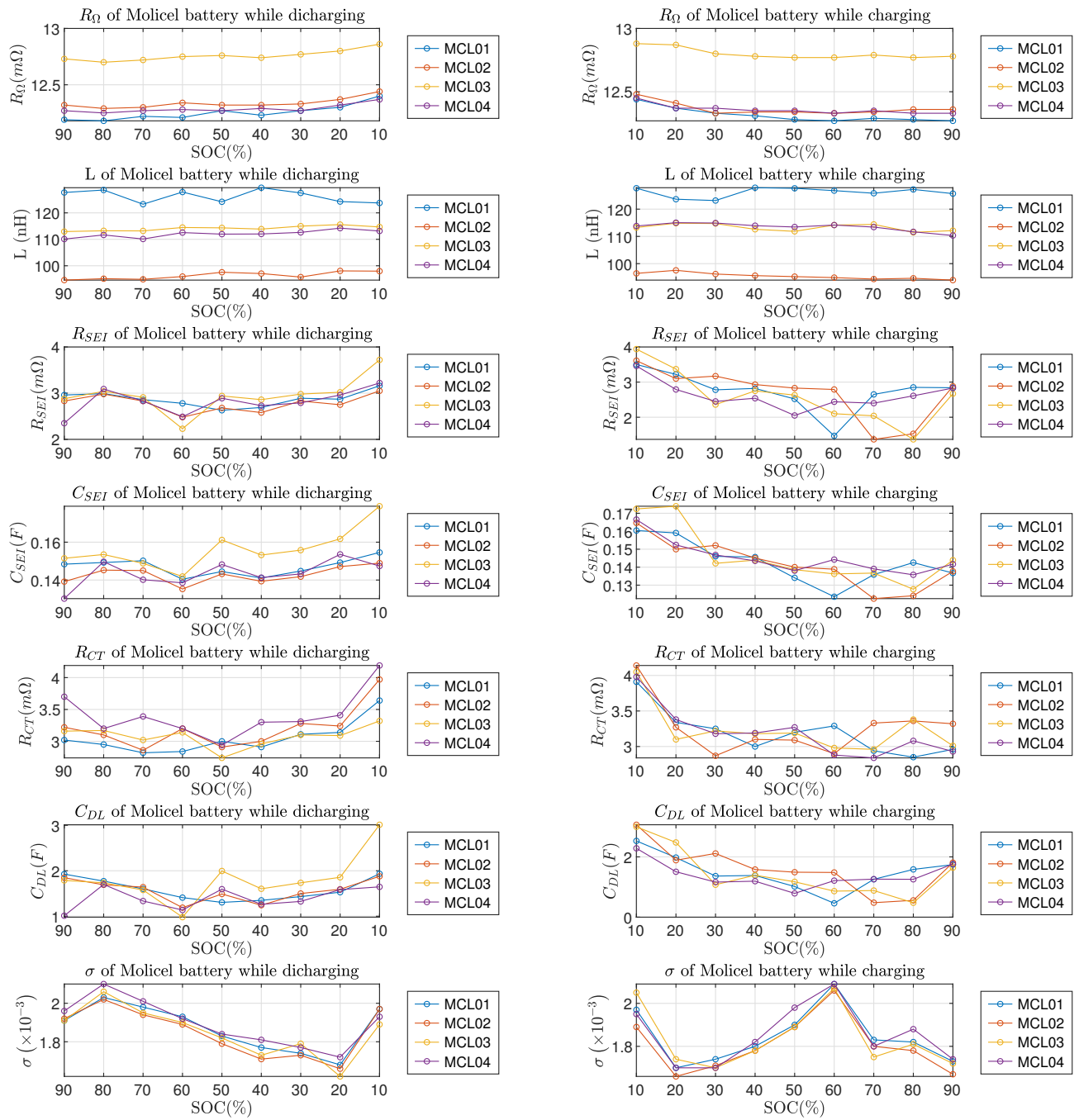


Figure 11. ECM parameters of Molicel batteries vs. SOC. Left column is for discharging and right column is for charging.

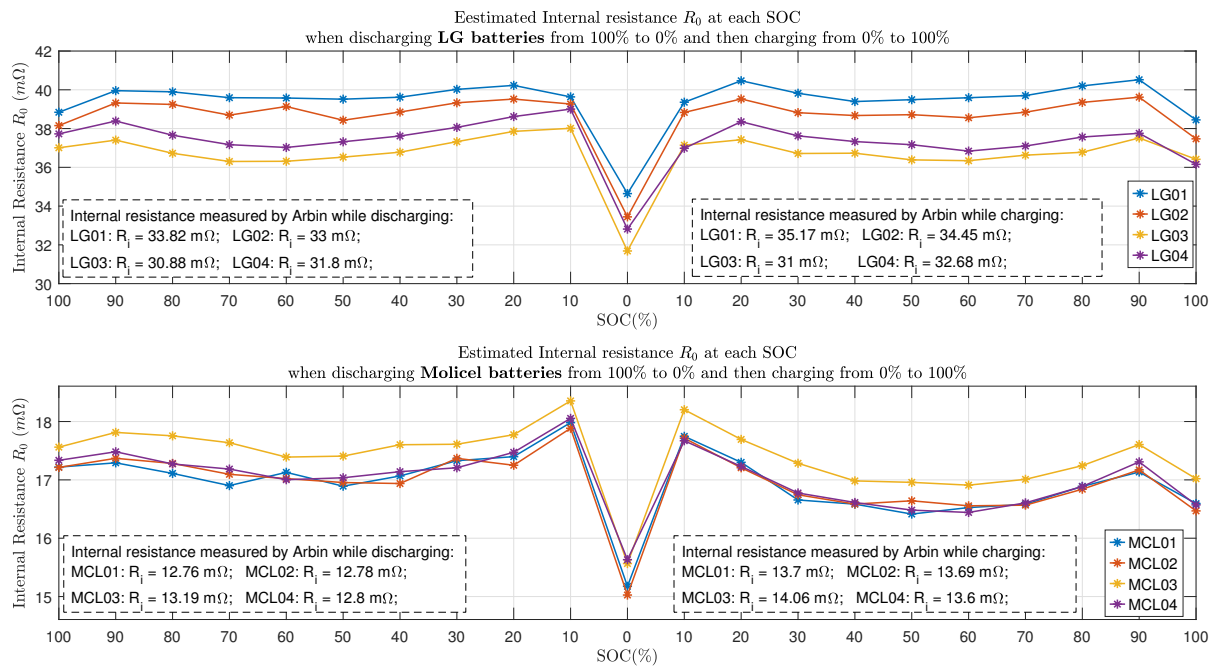


Figure 12. Internal resistance R_0 at each SOC.

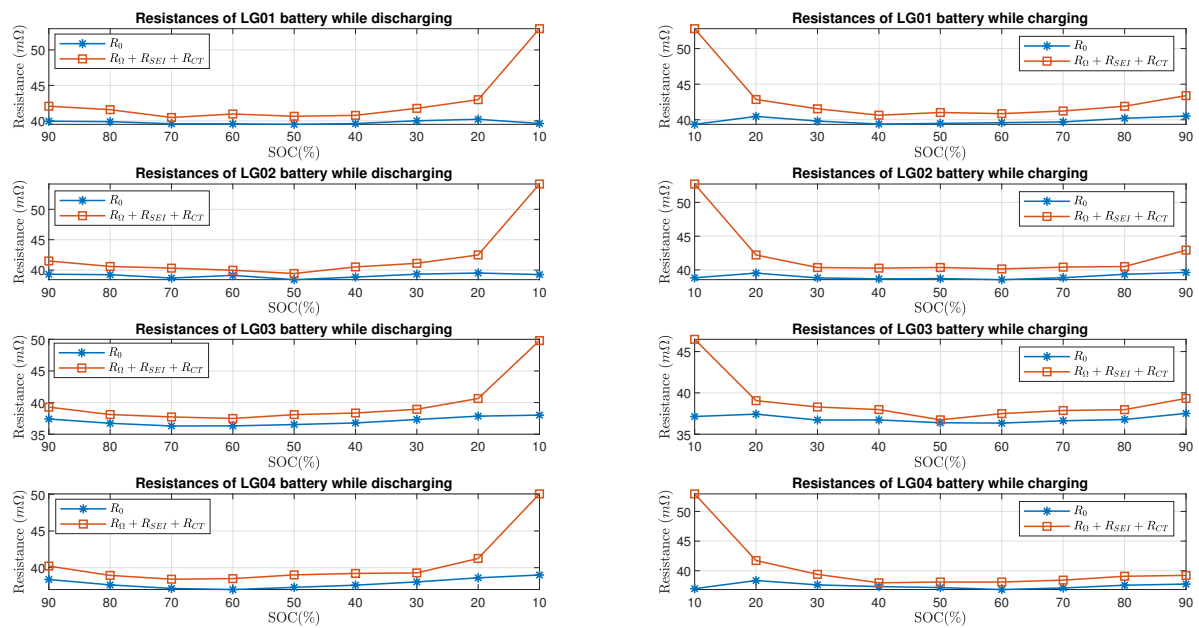


Figure 13. LG batteries' resistance estimate in time domain and frequency domain.

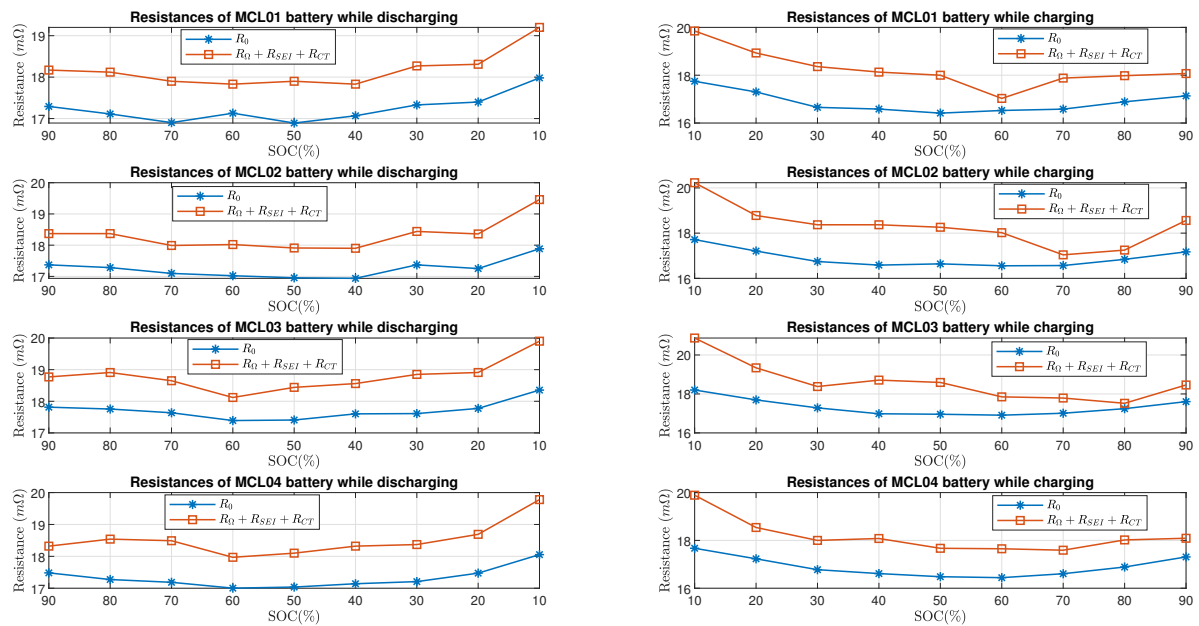


Figure 14. Molcel batteries' resistance estimate in time domain and frequency domain.

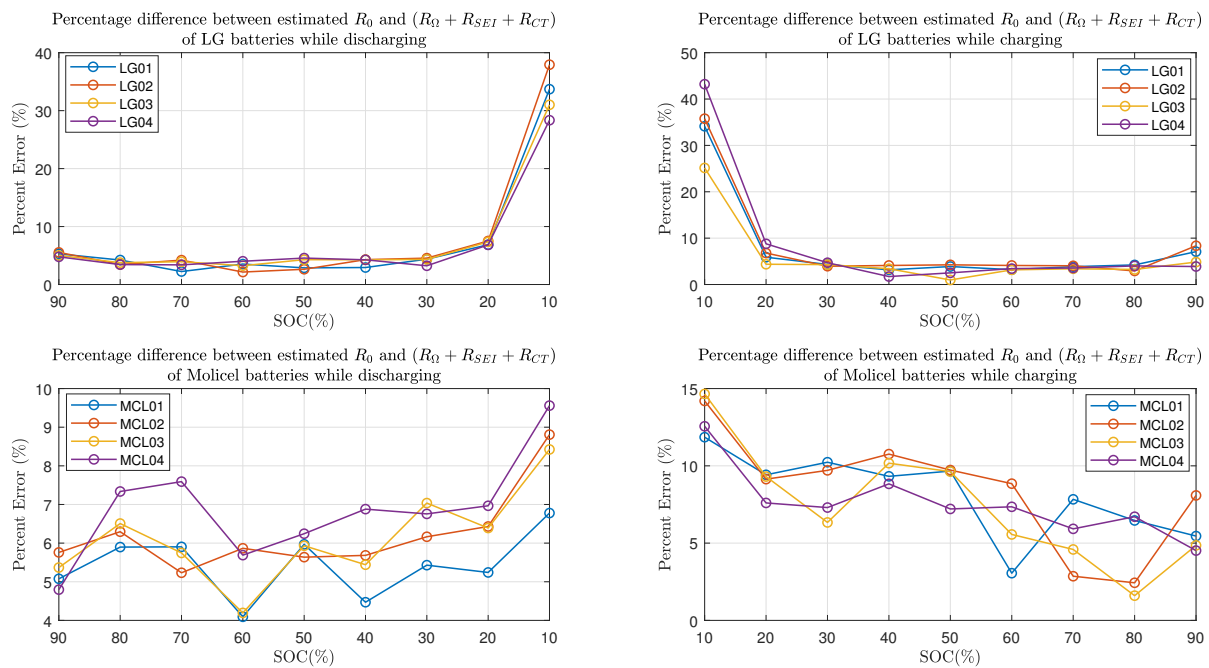


Figure 15. Percent error between time domain and frequency domain estimates.

Table 4. Estimated ECM parameters of LG batteries at each SOC while charging. (Note: R_i is the internal resistance measured by Arbin.)

Battery	SOC (%)	R_i (m Ω)	R_Ω (m Ω)	L (nH)	R_{SEI} (m Ω)	C_{SEI} (F)	R_{CT} (m Ω)	C_{DL} (F)	σ ($\times 10^{-3}$)
LG01	10	35.17	34.46	470.15	4.38	0.24722	13.95	3.9242	2.31
	20		34.31	474	3.68	0.24631	4.86	2.5783	1.6
	30		34.32	474.07	3.69	0.2751	3.53	3.4651	1.52
	40		34.25	475.98	2.97	0.24166	3.42	2.0166	1.74
	50		34.21	471.19	3.18	0.23648	3.63	2.1106	2.09
	60		34.2	470.72	3	0.23176	3.66	1.8533	2.07
	70		34.3	464.58	3.17	0.22409	3.76	1.9357	1.7
	80		34.33	461.21	3.54	0.22834	4.03	2.2135	1.77
	90		34.31	457.45	3.5	0.21421	5.58	2.2336	1.71
LG02	10	34.45	33.62	446.24	4.34	0.23464	14.76	4.0039	2.29
	20		33.43	450.27	4.15	0.25904	4.63	3.3461	1.58
	30		33.43	452.72	3.33	0.24237	3.59	2.3318	1.52
	40		33.37	449.45	3.25	0.22934	3.64	2.087	1.7
	50		33.32	447.91	3.54	0.23246	3.5	2.5096	2.08
	60		33.3	447.1	3.18	0.22511	3.66	1.8996	2.06
	70		33.35	441.77	3.5	0.22536	3.56	2.2455	1.75
	80		33.38	438.19	2.74	0.19386	4.38	1.2153	1.74
	90		33.37	451.99	4.52	0.24856	5.04	3.4536	1.68
LG03	10	31	31.09	489.85	4.99	0.22245	10.4	3.6818	2.33
	20		30.83	494.27	3.43	0.19534	4.8	1.6213	1.68
	30		30.77	488.72	3.65	0.19079	3.87	1.7747	1.62
	40		30.74	485.46	3.4	0.18028	3.84	1.4483	1.88
	50		30.67	487.89	2.11	0.16878	3.96	0.63426	2.12
	60		30.66	485.13	3.17	0.17787	3.66	1.2994	2.04
	70		30.72	479.05	3.31	0.16892	3.84	1.3108	1.71
	80		30.75	480.36	3.44	0.18174	3.78	1.5759	1.86
	90		30.71	477.52	4.26	0.19437	4.36	2.2802	1.67
LG04	10	32.68	31.64	470.56	4.42	0.19099	16.9	3.9463	2.35
	20		31.48	470.95	4.85	0.2201	5.39	3.1217	1.56
	30		31.4	473.72	4.04	0.20236	3.95	2.2992	1.68
	40		31.35	471.8	2.42	0.16841	4.2	0.78514	1.8
	50		31.31	469.59	2.71	0.17051	4.08	0.9391	2.12
	60		31.31	474.04	3.22	0.19627	3.57	1.5973	2.06
	70		31.34	465.67	3.35	0.1785	3.73	1.4949	1.7
	80		31.38	464.39	3.73	0.1844	3.96	1.7888	1.76
	90		31.41	467.86	3.46	0.18651	4.35	1.9457	1.69

Table 5. Estimated ECM parameters of Molice batteries at each SOC while discharging. (Note: R_i is the internal resistance measured by Arbin.)

Battery	SOC (%)	R_i (m Ω)	R_Ω (m Ω)	L (nH)	R_{SEI} (m Ω)	C_{SEI} (F)	R_{CT} (m Ω)	C_{DL} (F)	σ ($\times 10^{-3}$)
MCL01	90	12.76	12.19	127.7	2.96	0.14838	3.02	1.9264	1.91
	80		12.18	128.64	2.99	0.14925	2.95	1.7723	2.03
	70		12.22	123.27	2.86	0.15021	2.82	1.6021	1.98
	60		12.21	127.87	2.78	0.14041	2.84	1.4092	1.93
	50		12.27	124.19	2.63	0.14448	3	1.3045	1.83
	40		12.23	129.51	2.69	0.14108	2.91	1.349	1.77
	30		12.27	127.53	2.89	0.14477	3.11	1.4313	1.74
	20		12.3	124.27	2.87	0.14921	3.14	1.5283	1.68
	10		12.4	123.74	3.16	0.15457	3.64	1.9338	1.97
MCL02	90	12.78	12.32	94.58	2.83	0.13917	3.22	1.8474	1.92
	80		12.29	95.12	2.98	0.14524	3.1	1.6911	2.02
	70		12.3	94.88	2.83	0.14501	2.86	1.6404	1.94
	60		12.34	95.93	2.48	0.13526	3.2	1.1881	1.89
	50		12.32	97.55	2.68	0.14322	2.91	1.4888	1.79
	40		12.32	97.06	2.58	0.13936	3	1.2418	1.71
	30		12.33	95.73	2.83	0.14179	3.28	1.499	1.73
	20		12.37	98.06	2.75	0.1471	3.24	1.5932	1.66
	10		12.44	97.97	3.05	0.14893	3.97	1.8782	1.97
MCL03	90	13.19	12.73	112.93	2.88	0.15149	3.16	1.7869	1.91
	80		12.7	113.23	2.55	0.14004	3.45	1.1063	2.06
	70		12.72	113.18	2.76	0.14458	3.24	1.3804	1.96
	60		12.75	114.47	2.23	0.14188	3.14	0.97923	1.9
	50		12.76	114.33	2.94	0.16119	2.74	1.9954	1.82
	40		12.74	113.87	2.86	0.15321	2.96	1.6035	1.73
	30		12.77	114.98	2.98	0.1558	3.1	1.7348	1.79
	20		12.8	115.57	3.02	0.16174	3.09	1.8559	1.62
	10		12.86	114.67	3.72	0.17899	3.32	3.0123	1.89
MCL04	90	12.8	12.27	110.09	2.35	0.13018	3.7	1.0107	1.96
	80		12.25	111.65	3.09	0.1497	3.2	1.6986	2.1
	70		12.27	110.12	2.83	0.14016	3.39	1.334	2.01
	60		12.28	112.54	2.49	0.13854	3.2	1.1365	1.92
	50		12.27	111.96	2.89	0.1482	2.94	1.5953	1.84
	40		12.29	112.02	2.73	0.14128	3.3	1.2619	1.81
	30		12.27	112.62	2.79	0.14323	3.31	1.3253	1.77
	20		12.32	114.22	2.96	0.15357	3.41	1.5857	1.72
	10		12.37	113.14	3.22	0.1474	4.19	1.6458	1.93

Table 6. Estimated ECM parameters of MoliceL batteries at each SOC while charging. (Note: R_i is the internal resistance measured by Arbin.)

Battery	SOC (%)	R_i (m Ω)	R_Ω (m Ω)	L (nH)	R_{SEI} (m Ω)	C_{SEI} (F)	R_{CT} (m Ω)	C_{DL} (F)	σ ($\times 10^{-3}$)
MCL01	10	13.7	12.44	127.69	3.5	0.16041	3.91	2.5303	1.97
	20		12.37	123.65	3.22	0.15903	3.34	1.9775	1.7
	30		12.33	123.16	2.78	0.14601	3.25	1.3636	1.74
	40		12.31	127.87	2.82	0.14565	3	1.3831	1.8
	50		12.28	127.65	2.52	0.13408	3.2	1.0172	1.9
	60		12.27	126.8	1.47	0.12357	3.29	0.45992	2.09
	70		12.29	125.84	2.65	0.13586	2.94	1.2557	1.83
	80		12.28	127.24	2.85	0.14256	2.85	1.5845	1.82
	90		12.27	125.7	2.84	0.13672	2.96	1.7427	1.73
MCL02	10	13.69	12.48	96.43	3.61	0.16464	4.14	3.0663	1.89
	20		12.41	97.55	3.1	0.15	3.27	1.8899	1.66
	30		12.33	96.18	3.17	0.15212	2.87	2.1141	1.71
	40		12.34	95.6	2.93	0.14508	3.1	1.5808	1.78
	50		12.34	95.24	2.83	0.14004	3.09	1.4919	1.89
	60		12.33	94.88	2.79	0.13887	2.9	1.4831	2.06
	70		12.34	94.34	1.37	0.1225	3.33	0.48037	1.8
	80		12.36	94.63	1.53	0.1241	3.36	0.5577	1.78
	90		12.36	93.96	2.88	0.13771	3.32	1.8098	1.67
MCL03	10	14.06	12.88	113.27	3.94	0.17241	4.05	2.9983	2.05
	20		12.87	114.83	3.37	0.17392	3.1	2.4794	1.74
	30		12.8	114.72	2.36	0.14214	3.22	1.0772	1.7
	40		12.78	112.61	2.75	0.14392	3.18	1.3912	1.78
	50		12.77	111.85	2.63	0.13862	3.19	1.1738	1.89
	60		12.77	114.16	2.1	0.13627	2.98	0.86353	2.07
	70		12.79	114.4	2.04	0.13671	2.96	0.88326	1.75
	80		12.77	111.48	1.37	0.12773	3.38	0.47767	1.81
	90		12.78	112.13	2.67	0.1439	3.01	1.6431	1.72
MCL04	10	13.6	12.45	113.81	3.46	0.16651	3.98	2.2854	1.95
	20		12.37	115.03	2.79	0.15239	3.38	1.5069	1.7
	30		12.37	114.91	2.45	0.14681	3.18	1.1633	1.7
	40		12.35	113.93	2.54	0.14354	3.19	1.1937	1.82
	50		12.35	113.45	2.05	0.13807	3.27	0.78896	1.98
	60		12.33	114.16	2.44	0.14425	2.88	1.2123	2.09
	70		12.35	113.42	2.4	0.13905	2.84	1.2617	1.8
	80		12.33	111.68	2.61	0.13576	3.08	1.2558	1.88
	90		12.33	110.33	2.83	0.14168	2.93	1.7636	1.74

6. Conclusions and Discussions

This paper demonstrates the parameter estimation to identify the resistive and inductive components in an AR-ECM based on the battery's EIS.

The ECM parameter estimation approach is applied to the EIS data collected from LG 16850 and MoliceL 21700 batteries at multiple SOC levels. The proposed approach is implemented via the manual selection of feature points from actual Nyquist plot; this relies on the precise separation of SEI arc, CT arc, and Diffusion arc from the real Nyquist plot, which has a low signal-to-noise ratio.

From the experiment, it is clear that the internal resistance measured by Arbin is actually the ohmic resistance R_Ω from the AR-ECM; besides, whether it is an LG or MoliceL battery, the variation of all estimated ECM parameters is very small when the SOC ranges from 20% to 90%; furthermore, R_Ω , R_{CT} and C_{DL} reached the highest value at 10% SOC, whereas the variation of L , R_{SEI} , and C_{SEI} show irregularity at 10% SOC; moreover, the total resistance $R_\Omega + R_{SEI} + R_{CT}$ reaches the highest value at 10% SOC.

In addition, a time domain approach is developed to check the validity of the estimated ECM parameters; the validation is performed by using data collected from eight different batteries at nine different SOC levels both in the discharging and charging process, which shows good agreement between the time domain and frequency domain approaches when the battery's SOC is between 20% and 90%. It must be noted that this approach is well suited to estimate resistive components only. When the RC effect increases, the accuracy of resistance estimation is expected to drop. The prominent error observed at 10% SOC is due to the significant RC effect; this makes sense, since there are two RC elements in the AR-ECM. As a result, it can be concluded that there exists an inadequacy in the time domain approach for modeling all resistive elements at low SOC.

In future works, the automatic detection of feature points will be developed to improve the efficiency of ECM parameter estimation. Another limitation of the present work is that all the experiments were conducted at room temperature. Future studies will repeat these

experiments at various temperatures to investigate whether the variation of temperature has an impact on ECM parameters.

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