



Article

Power Losses Investigation in Direct 3×5 Matrix Converter Using MATLAB Simulink

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Abstract: This article addressed the problem of matrix converters (MxC), specifically the investigation of power losses and matrix converter efficiency in a 3×5 arrangement. In today's modern world, efficiency is very important; hence, power loss and efficiency analysis are important throughout the design process of modern semiconductor converters. The ability to evaluate power losses more quickly using the simulation approach can greatly reduce the amount of time necessary for the design, in comparison with numerical analysis. The described model employed contemporary SiC semiconductors, which offer substantial benefits over IGBT transistors. The 3×5 converter model was shown, along with a study of power losses in various elements of the converter, such as the power circuit, input filter, and so on. A summary of the simulated findings was offered at the end of the study, along with the benefits and drawbacks of employing SiC semiconductors in bidirectional switches for matrix converters.

Keywords: matrix converter; SiC semiconductors; power losses; efficiency; MATLAB Simulink



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1. Introduction

Matrix converters gained considerable interest in the sphere of research and universities in recent years [1–4]. In high power density applications [4,5] or applications with large temperature variations, the lack of the DC-Link capacitor or inductor is beneficial over the normal VSI design.

Direct matrix converters (DMCs) were long viewed as an appealing AC/AC choice due to their sinusoidal input/output currents, bidirectional power flow, and customizable input power factor. As a result, it is a competitive topology that may be used in a wide range of electrical equipment, including industrial pumps, cooling, refrigeration, elevators, belt transportation systems, and avionic applications [6,7].

Direct matrix converters (DMCs) and the bidirectional switches (BDSs) have changed throughout time. Each BDS, in an instance, can be achieved by a single monolithic device [7], which is not yet accessible, or by some combination devices [8,9] to offer bidirectional current conduction when activated and bidirectional voltage blocking when deactivated. Because a bidirectional switch constructed in a single monolithic semiconductor that could conduct and block current and voltages in both directions is not available, bidirectional switches must be designed utilizing discrete components such as IGBTs, MOSFETs, or RB-IGBTs. However, recent news from new GaN technology may overcome this problem, and researchers recently focused their efforts on this area as well [10–12].

When a high-power density is required, the power loss analysis is an important aspect of the converter design approach. If power losses are not examined under various operating situations, the cooling solution design may be insufficient. The analytical technique is a common procedure for calculating losses. This method can be time-demanding due to the extensive analysis of the matrix converter increased number of semiconductors [13–19]. Another method is to use numerical analysis with semiconductor models. If transistor models are available, this technique is more efficient [20].

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If any operating circumstances, such as converter start-up, fault conditions, and others, must be evaluated, numerical analysis is particularly helpful. The goal of this study is to analyze the potential benefits of SiC transistors in matrix converter applications, as stated in the switch analysis part of this paper. The transistor and diode models were used to mimic the power component of the matrix converter in a 3×5 arrangement suited for multiphase drives [21]. In addition, all of the power components of the matrix converter's building parts, such as the protection network, current direction detecting circuit, and input filter, were simulated to determine the entire efficiency of the converter.

2. Bidirectional Switch Analysis

The IGBT transistor is used to provide a bidirectional switch in the majority of matrix converters [6,22–24]. Even some manufacturers, such as SEMIKRON, produce modules with IGBT switches suitable for use in matrix converters, such as the SKM150GN12T4G or SKM400GM17E4. The switches mentioned are only available in high-power designs, which are not suitable for low or mid-power applications due to their high cost, possibly large power losses, and low power density. However, IGBT switches are well established, dependable, and can even survive a short circuit current for a short period, which can be useful in matrix converter applications. The significant drawback, on the other hand, is the current flow distribution in the switch during positive or negative flow, as seen in Figure 1.

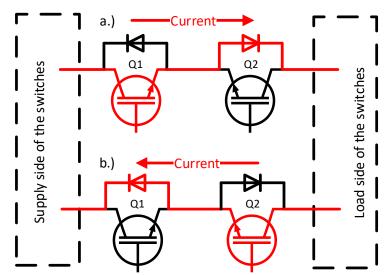


Figure 1. Current flow in IGBT-based bidirectional switch (a) Positive current flow, (b) Negative current flow.

As shown in Figure 1a, the current travels in a positive direction (from the power source to the load) via Q1 and then, through the internal diode of Q2. Conversely, the negative current (from the load to the power supply) flows via Q2 and then through Q1 internal diode. As previously established, current will always flow via one transistor and one diode even if both transistors are fully open. This is due to the technology utilized in IGBT transistors. The resulting conducting power losses in this sort of bidirectional switch may be represented as:

$$P_{LOSSight} = I_{AV} \cdot V_{SAT} + I_{AV} \cdot V_{F} \tag{1}$$

where I_{AV} denotes the average current flowing through the bidirectional switch and V_{SAT} and V_F denote the IGBT saturation voltage and internal diode forward voltage, respectively. The following characteristics can be noticed while using a random average 1200 V IGBT, such as the STGW15H120DF2. The voltage drop at the separate sections of the IGBT is shown in Table 1.

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Table 1. Parameters of the IGBT STGW15H120DF2.

Parameter	V _{SAT} [V]@10A	V _F [V]@10A
STGW15H120DF2	2.6	3

As can be observed, the diode voltage drop is quite substantial, which can result in high power losses, particularly at low power outputs, lowering the matrix converter's efficiency dramatically. SiC technology, on the other hand, is now quite popular in power electronics due to its benefits. They provide a very high blocking voltage while also having a low RDSon of the transistor. Because the driving circuits are simple and SiC semiconductors can function at high frequencies, the overall volume of the converter's passive components may be kept to a minimum.

Another feature of MOSFET-based SiC semiconductors is the channel ability to conduct current in both directions. This mode of operation is known as inverse conduction, and most manufacturers include a description of it in their product datasheet. The reverse conducting capability in matrix converter applications can have a significant impact on power losses and converter efficiency. If a negative voltage is given to the Drain-Source channel and the transistor is positively biased (VGS is positive), the channel will conduct current from Source to Drain if the following equation is true:

$$V_F > I_{RMS} \cdot R_{DSon} \tag{2}$$

The current will pass through both the SiC channel and the intrinsic diode in the circumstance when the right side of Equation (2) is somewhat higher than the left side. If the voltage drop on the channel is less than the internal diode threshold voltage VF, current flows exclusively via the MOSFET channel. This scenario is depicted in Figure 2.

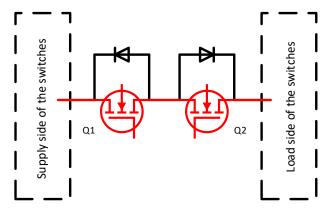


Figure 2. Current flow in SiC-based bidirectional switch.

If both transistors are positively biased and the voltage drop in the channel is less than the threshold voltage of the internal diode, Figure 2 represents both current directions (positive and negative). We can express the power losses in this type of switch using this assumption as follows:

$$P_{LOSSmos} = 2 \cdot \left(I_{RMS}^2 \cdot R_{DSon} \right) \tag{3}$$

Because the RDSon values of SiC semiconductors can range from 20 to 110 m Ω , the power losses created in the matrix converter based on the MOSFET can be greatly decreased according to Equation (3) when compared to Equation (1) for the IGBT switch.

3. Analytical Power Losses Calculation in Matrix Converter

Due to the system symmetries, the global conduction power losses can be easily derived. In the 3×5 matrix converter, every output phase has three switches connected to the input phases U, V, and W. Thus, output current determines power losses in all three

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bidirectional switches. For the IGBT-based matrix converter, the output phase current must be split to the positive and negative components, because due to the analysis in Figure 1, positive current flows through transistor Q1 and the internal diode of Q2, and negative current flows through transistor Q2 and the internal diode of Q1. Then, we can calculate average and rms current as follows [15]:

$$I_{a(AV)} = \frac{I_{pk}}{3\pi} \tag{4}$$

$$I_{a(RMS)} = \frac{I_{pk}^2}{12} \tag{5}$$

where I_{PK} represents the peak value of the output current of the matrix converter. Losses in one bidirectional switch can be then calculated using:

$$P_{IGBT} = U_F I_{a(AV)} + r I_{a(RMS)}^2 \tag{6}$$

Then, global power losses of one semiconductor can be calculated as follows [15]:

$$U_F = 30(U_{F,Transistor} + U_{F,Diode})$$
 (7)

$$r = 30(r_{Transistor} + r_{Diode}) \tag{8}$$

With the use of formula, we can calculate the conducting power losses in the 3 \times 5 IGBT-based matrix converter.

In the SiC (MOSFET)-based bidirectional switch, the situation is slightly different. Because the MOSFET transistor has channel with resistive character when conducting, bidirectional switch has only resistive power losses. Then, Equation (6) must be adjusted, and power losses in one MOSFET transistors can be calculated:

$$P_{MOSFET} = \frac{\left(I_{pk}\sqrt{2}\right)^2}{12}r\tag{9}$$

where I_{PK} is the peak value of the output current and r represents $R_{DS(on)}$ of one MOSFET transistor in the bidirectional switch. For the global power losses in the 3 × 5 matrix converter, r can be substituted as follows:

$$r = 30\left(R_{DS(on)}\right) \tag{10}$$

The components parameters were used to calculate power losses using this analytical approach and results can be seen in comparison chapter of this paper.

4. Model of the MxC Converter in MATLAB Simulink

The matrix converter simulation was carried out using the Simulink Simscape environment. For the power loss investigation, three models were simulated and investigated.

The first model used SiC transistors in the bidirectional switch. Additionally, for the proper current commutation, the direction of the current of every output phase must be known. For this purpose, additional antiparallel diodes were connected at the output of every phase of the matrix converter to reliably detect the current direction.

The second model used the IGBT transistor in bidirectional switches to compare losses to the SiC one. The current direction diodes were left in the circuit.

Finally, the third model bidirectional switches were based on IGBT transistors too, but direction diodes were removed. Instead of bidirectional diodes, the voltage drop at the transistor of the bidirectional switch was measured and evaluated. If the value was higher than 2.8 V, according to Table 1, the current was reportedly flowing through the internal diode of the IGBT; thus, current direction was negative. If the voltage drop was below 2.8 V, the current was flowing through IGBT itself and the current was positive.

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This approach requires additional circuits and comparators, but the losses generated at the direction detection diodes can be eliminated, which can lead to higher efficiency.

For the simulation, indirect control using vector modulation was used. The matrix converter is virtually split into two parts, a virtual rectifier and a virtual inverter. Both parts can be controlled separately with their gains, respectively. The resultant switching pulses are then transferred from the indirect to the direct topology using the following matrix [25]:

$$\begin{bmatrix} S_{aA} & S_{bA} & S_{cA} \\ S_{aB} & S_{bB} & S_{cB} \\ S_{aC} & S_{bC} & S_{cC} \\ S_{aD} & S_{bD} & S_{cD} \\ S_{aE} & S_{bE} & S_{cE} \end{bmatrix} = \begin{bmatrix} S_7 & S_8 \\ S_9 & S_{10} \\ S_{11} & S_{12} \\ S_{13} & S_{14} \\ S_{15} & S_{16} \end{bmatrix} \begin{bmatrix} S_1 & S_3 & S_5 \\ S_2 & S_4 & S_6 \end{bmatrix}$$
(11)

where individual switches correspond to the switches in the indirect and direct matrix topology, as shown in Figure 3.

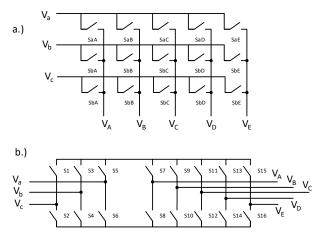


Figure 3. (a) Direct matrix converter, (b) Indirect matric converter.

Additionally, the matrix converter requires an input filter for the proper function and for the current drawn from the grid to be sinusoidal. The filter will have additional losses; thus, the filter was modeled to the simulation too. The chosen filter was the LC damped filter due to its relatively low component count and good performance. The LC filter is unstable around its resonant frequency, which can cause problems during the matrix converter operation, especially during low output powers and step load changes. Multiple damping solutions are known for the LC filter, and for this application, the resistor parallel to the inductor as a damping component was chosen, due to its good damping, low cost, and simplicity. The parameters of the used filter are summarized in Table 2.

Table 2. Parameters of the input filter in the simulation.

Part	Value	Unit
Inductor	1.11	mH
Inductor resistance	160	${ m m}\Omega$
Capacitor	7	μF
Capacitor resistance	7	${ m m}\Omega$
Damping resistor	15	Ω

5. Simulation Results

5.1. Simulation of Power Losses in IGBT-Based Bi-Switch with External Current Direction Detection Diode

During the simulations, the constant gain of the virtual rectifier q_{RECT} was maintained at its maximum value of 1. The gain of the virtual inverter was changed from 0.1 to its

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maximum value of 1.6. The load for the matrix converter was represented with a five-phase RL circuit with values of R = $7.8~\Omega$ and L = 30~mH. The input power supply was simulated by three phase voltage sources with voltages set to 90~V RMS and frequency of 50~Hz. Three simulations were conducted with devices and parameters shown in Table 3.

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Table 3	Parameters	Ot.	the semicond	11Ctors 11sec	1 1n	the simulations.

Device	V _{CE} [V] at 10 A	V _F [V] at 10 A	R_{DSon} [m Ω] *
IGBT STGW15H120DF2	2.6	-	-
Internal diode of IGBT	-	3	-
Direction Diode V20PW15	=	0.9	-
MOSFET NTBG080N120SC1	-	-	110

 $[\]overline{}$ Value of R_{DSon} is stated for V_{GS} = 18 V and I_{DS} = 20 A.

The simulation parameters of the devices used in the simulation from Table 3 were acquired from the datasheets of the mentioned parts. Direction diode and the MOSFET were also used in the experimental verification of the power losses. First, the simulation using IGBTs as components of the bidirectional switch was simulated. The results can be seen in Figure 4.

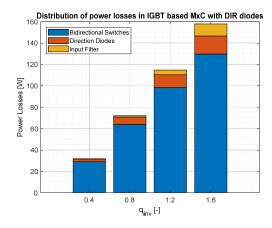


Figure 4. Distribution of power losses.

As can be seen, most of the power losses were represented by the bidirectional switches. This is because current is always flowing through the IGBT/Diode pair, which can be seen in Figure 5.

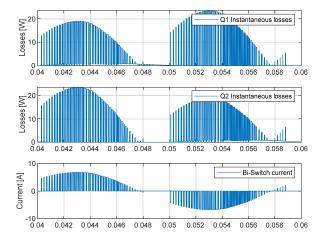


Figure 5. Instantaneous power losses in bidirectional switch.

The upper subplot in Figure 5 shows power losses at the Q1, according to Figure 1. The current flowed from the Source to the Load according to the current direction. The

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power losses in Q1 were generated at the IGBT itself, and in Q2, the power losses were generated at the internal diode. The internal diode losses were higher due to the higher barrier voltage and higher internal resistance of the component. Similarly, when the current flowed from the Load to the Source, the losses were turned around, the losses in Q1 were generated in the diode, and losses in Q2 were generated by the IGBT itself. Other losses generated in the MxC were in the current direction diodes as well as in the input filter. At the value of the $q_{\rm INV} = 1.6$, the bidirectional switches losses were 130 W, direction diodes losses were 16.8 W and input filter losses were 11.25 W. The total output power at the $q_{\rm INV} = 1.6$ was 860.78 W.

5.2. Simulation of Power Losses in IGBT-Based Bi-Switch without External Current Direction Detection Diode

However, the direction of the current in the IGBT-based bidirectional switch can be detected using one of the IGBTs, as described earlier, the model was redesigned, and the power losses without direction-detection diodes are shown in Figure 6.

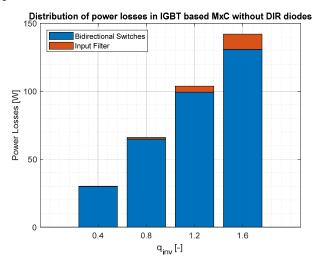


Figure 6. Distribution of power losses.

As can be seen, the power losses at higher output powers dropped significantly due to the absence of the detection diodes. The efficiency of both models is shown in Figure 7:

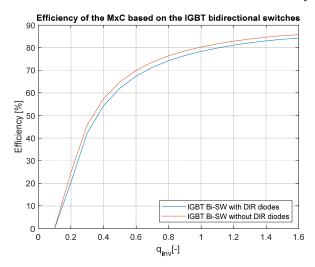


Figure 7. Efficiency comparison of IGBT simulations.

The peak efficiency of the IGBT-based matrix converter with direction diodes was 84.1% at the output power of 860 W and the model without direction detection diodes reached an efficiency of 85.7% at the 874 W of output power.

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5.3. Simulation of Power Losses in SiC-Based Bidirectional Switch

In the next simulation, the matrix converter with SiC bidirectional switches was investigated. The simulation parameters and conditions were the same as for previous models. The distribution of the power losses in the SiC MxC is shown in Figure 8.

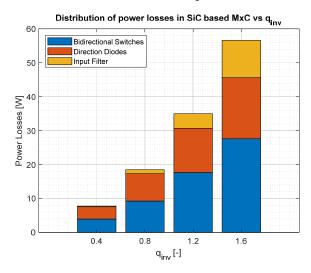


Figure 8. Distribution of power losses in SiC-based MxC.

The columns in Figure 8 show a significant reduction in the power losses of the bidirectional switches because MOSFET can conduct current in the reverse direction, thus effectively eliminating internal body diode losses, which were significantly higher than losses in the conducting channel. The total power losses at maximum output power were 56.6 W, from which switch losses formed 27.6 W, direction diodes were 18 W, and filter losses were 11 W. The total output power of the simulation was 945 W. The output power was higher due to the lower power losses in the power part of the matrix converter. The Simscape library was used to properly implement power losses models of the used semiconductors. Subsequently, m-file script was used to extract all data from the simulation and calculate average values of power losses used in Figures 4, 6 and 8. The total output power with every type of switch is shown in Figure 9.

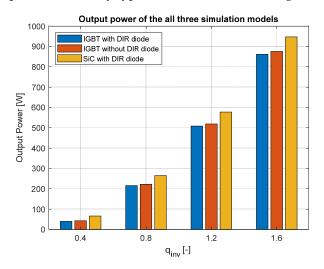


Figure 9. Output powers of the simulation models.

As we can see, the total output power was very similar, but the output power was higher with the SiC simulation model, due to the lower power losses. This is because the power losses were lowest in this configuration, and were transferred to the output. The efficiency of the simulation model is shown in Figure 10.

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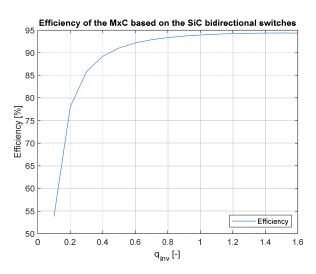


Figure 10. Simulated efficiency of the SiC-based MxC.

As can be seen in Figure 10, the highest efficiency of 94.35% was again reached at the maximum value of the $q_{\rm INV}$.

6. Comparison with the MxC Prototype

Based on assumptions in the introduction of the paper and the simulation results, the practical prototype of the matrix converter was built. The sample was based on the SiC semiconductors to create a power part of the MxC. Due to the possible comparison with the simulation model, the same SiC and Direction diode as in the simulation was used, as can be seen in Table 3. Every module contained power transistors together with direction diodes designed at the IMS (insulated metal substrate) board for easy mounting and good cooling. The other part of the module contained drivers for the transistors, as well as the isolated power supplies for the drivers. Every module contained six SiC transistors forming the three inputs and one output configuration. Because of this arrangement, a total of five modules were needed to create a power part of the 3×5 matrix converter investigated in this article. The final prototype of the converter is shown in Figure 11.

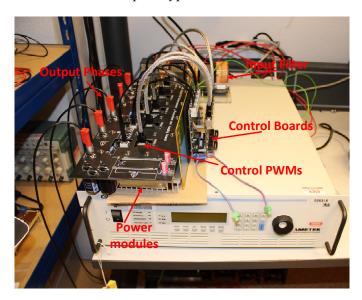


Figure 11. Prototype of the 3×5 matrix converter.

Further important parts of the converter were the input filter, control boards, and measurement boards. Control boards are divided into two separate parts: the first is DSP board, which calculates duty cycles, measures currents and voltages, and communicates

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with the superior system. The second part is FPGA board, which works with vectors and generates switching pulses with commutation delays [26]. The second board was implemented due to the high computation requirements of the vector implementation and commutation times calculations.

The California instruments three-phase power supply was used to supply power to the prototype of the matrix converter. For the output power measurement and evaluation, the YOKOGAWA precision power analyzer was used, which can measure six channels in total. The measured output currents at the $q_{\rm INV}=1.6$ are shown in Figure 12.

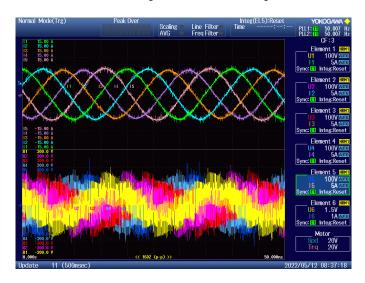


Figure 12. Measured five phase output of the MxC prototype (phase currents—top and phase voltages—bottom).

The input power was measured using the input California power supply, and the output was measured using the mentioned YOKOGAVA analyzer. To phase voltages, the software filter in the YOKOGAWA analyzer was used to better observe the switched voltages and currents. The cut-out frequency of the filter was set to 1 kHz. The results can be seen in Figure 13.

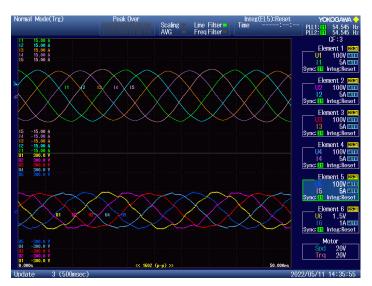


Figure 13. Measured five phase output of the MxC prototype (phase currents—top and phase voltages—bottom)—Software Filtered.

For a better view of the individual quantities at the output of the matrix converter, the measurement at the oscilloscope is presented in Figure 14.

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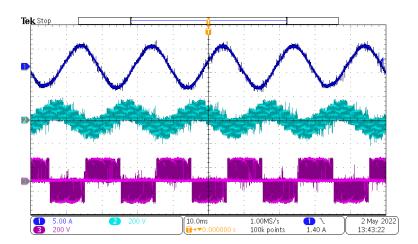


Figure 14. Waveforms at the output of the 3×5 matrix converter (output phase current—blue, phase to neutral voltage—cyan, phase to phase voltage—purple).

The waveform in Figure 14 shows the output waveforms at the five-phase load. The voltages and current matched the theoretical assumptions presented in Section 3 and simulations results in Section 5 of this paper. With the use of the YOKOGAWA analyzer, the efficiency of the converter was measured and compared to the simulation model. The results of the comparison are shown in Figure 15.

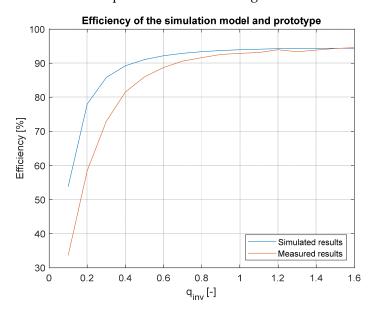


Figure 15. Compared efficiency (simulation vs. measurement).

As can be seen in Figure 15, the simulation and prototype of the matrix converter had a very good match at the higher output powers. At the maximum output power, the difference was only 0.2%. The prototype of the matrix converter reached lower efficiency at the lower output powers because the output current was very noisy, which resulted in the lower efficiency. The simulated efficiency was 94.3% and the measured efficiency was 94.5%.

Finally, the input current and voltage waveforms were compared between the simulation and prototype. The result is shown in Figure 16.

The match between simulation and the prototype was very good, as can be seen in Figure 16. The current waveform matched the simulation with its shape and amplitude. This confirmed that the prototype of the MxC worked identically to the simulation model (Table 4).

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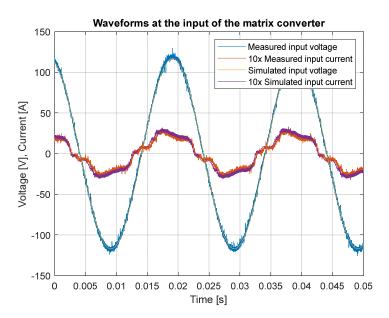


Figure 16. Compared input waveforms.

Table 4. Calculated and simulated power losses in bidirectional switches.

Type/Loss per Switch	Analytical [W]	Simulation [W]
IGBT	4.37	4.32
SiC	1.76	1.79

7. Conclusions

This paper focused on the investigation of power losses in matrix converters. The introduction section presented IGBT- and MOSFET-based bidirectional switches and analyzed power losses generated in every type of switch. Anylytical simulation was conducted in Section 3 of this paper, where mathematical calculations of power losses were presented. Parameters of the used components were used in these calculations, where results are shown in Table 3 and compared to the simulation results from MATLAB Simulink environment, described in Section 4. These simulation models were created with IGBT and SiC switch to simulate and investigate power losses in a 3×5 matrix converter. Three modes were presented, one with a SiC switch and two with a IGBT switch, where the difference was only the methodology of the current direction sensing.

As can be seen in Figure 7, the efficiency of the IGBT-based MxC was around 85%, whereas the model without direction detection diodes had slightly higher efficiency. Figures 4 and 6 show that the majority of the power losses were generated in the IGBT/Diode pair, which significantly decreased available output power and generated the power losses which lowered the efficiency of the solution. The SiC-based MxC showed very high improvement due to the possibility of the inverse conduction of the MOSFETs, and the total efficiency reached with this type of switch was 94.3% which was almost a 10% improvement compared to the IGBT-based MxC.

Based on the simulation, the prototype of the matrix converter was built using the SiC MOSFET due to the lower power losses resulting from the simulations.

The efficiency of the prototype was lower at the lower output powers due to the noisy output power, but at the output powers from 350 W and higher, the results from the simulation and measurement showed a very good match. At the maximum output power, the error between the simulation and prototype was only 0.2%, as shown in Figure 15.

As shown in the paper, the SiC transistors were a very good option for application in the matrix converter due to the low power losses. Even though, nowadays, the price of the SiC transistors is higher than IGBTs, if the application requires the advantages of the matrix Appl. Sci. 2023, 13, 4049 13 of 14

converter as adjustable input power factor and unity power factor, the SiC transistors are a great choice in MxC application. If higher efficiency is required, the transistors in the same package but with lower RDS-ON can be used to lower power losses even more.

In the future work, the practical verification of the five-phase matrix converter on asynchronous machine will be conducted, where dynamic responses of the matrix converter can be investigated.

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