

Article

Effects of Wall Properties on Temperature-Control Effectiveness of Heating Section in a Thermosiphon Containing PCM Suspensions

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Abstract: This article considers the problem of natural heat transfer in a rectangular thermosiphon to investigate the effects of wall properties (thickness and thermal conductivity) on the heat-transfer characteristics of phase-change-material (PCM) suspension flow. The following parameter ranges were investigated: dimensionless loop-wall thickness, 0–0.5; wall-to-fluid thermal-conductivity ratio, 0.1–100; modified Rayleigh number, 10¹⁰–10¹¹; and volumetric fraction of PCM particles, 0–10%. From numerical simulations via the finite-volume approach, it was found that using a pipe with appropriate wall thickness and thermal conductivity containing PCM suspensions for the heating section of a rectangular thermosiphon can effectively control the maximal temperature.

Keywords: phase-change material; heat-transfer enhancement; latent heat; thermosiphon

1. Introduction

The thermosiphon is a natural circulation loop. With proper arrangement of the heating and cooling sections, the resulting thermal buoyancy can drive the working fluid in the loop to achieve thermal-energy transportation. The cooling and heating sections are usually positioned at the left and right or upper and lower sides of the loop, respectively. The increase in working-fluid temperature in the heating section decreases fluid density. The working fluid flows upwards by thermal buoyancy, which dissipates heat in the cooling section. Gravity opposes the upward flow of working-fluid flows, and promotes the downward flow of the working fluid. The absence of external driving forces results in considerable operational reliability for the thermosiphon. The self-adjusting mechanism and stability of the thermosiphon have resulted in wide application, such as in solar heating or cooling [1,2], nuclear thermal coolers [3,4], geothermal systems [5], waste-heat recovery [6], and electronic cooling devices [7]. There are many considerations in the design of thermally efficient thermosiphons, such as the selection of the working fluid, pipe-wall material, the locations of the heating and cooling sections, and geometric loop parameters [1,8–10].

Phase-change material (PCM) can effectively store and release a large amount of latent heat during phase transition; therefore, is a promising material choice for applications of energy storage, heat-transfer enhancement [11,12], thermal-environment control [13], boiling-heat-transfer enhancement with nanofluids [14], etc. Comprehensive literature studies on thermophysical properties, impregnation methods, thermal-performance analyses, numerical simulations, and other applications can be found



in the review articles [15,16]. Attinger et al. [17] reviewed the techniques and challenges of engineering surfaces for phase-change heat transfer.

Fine solid–liquid PCM particles can be dispersed in a carrier or a suspending working fluid to form PCM slurries or suspensions. The absorption and release of latent heat of the PCM at designated locations of the loop decreases the maximal temperature and increases heat transfer. Methods for manufacturing PCM particles can be categorized into microencapsulation [18–21] and emulsification [22,23]. In microencapsulation, PCMs are encapsulated by polymer materials, separating the disperse phase (PCM) from the dispersion media (such as water and glycerol) and suspending in the dispersion media. The advantages of microencapsulation are that the size and shape of the particles are fixed, and the physical properties of the particles are stable. The disadvantages of this method are a complex manufacturing process, high cost, and that the polymer layer on the PCM particle surface can reduce the heat-transfer efficiency, and may expand and break after repeated heating–cooling. In emulsification, the surface tension between a dispersed phase and a dispersion medium is reduced via the addition of an appropriate emulsifier. PCM particles can be homogeneously suspended in a dispersion medium as a stable emulsion.

The heat-transfer enhancement obtained by using PCM suspensions as a working fluid was widely demonstrated for forced convection [24,25]. By contrast, limited studies have been carried out on the heat-transfer characteristics for PCM suspensions in a thermosiphon.

Ho et al. [26] numerically simulated the heat transfer of a rectangular thermosiphon containing PCM suspensions. A flow regime was identified where the latent heat absorption/release of the PCM suspension effectively enhanced heat transfer. Ho et al. [27] performed more extensive parametric simulations to investigate the effects of heating-section ratio, cooling-section height, and loop size on the heat-transfer characteristics of a rectangular thermosiphon containing PCM suspensions. The highest heating and the cooling efficiencies were obtained for a certain combination of the aspect ratio of the loop, the dimensionless length of the heating section, and the dimensionless elevation of the cooling section relative to the heating section. However, the wall properties of the thermosiphon were not considered.

As inspired from the literature on conjugate heat transfer in single-phase and phase-change [26,28] pipe flows, heat conduction in the duct wall of a certain thickness can significantly affect the forced and natural convection in a PCM suspension flow, respectively. The wall effects lead to technical gaps between predictions and experiment results for pipe-flow studies. Therefore, in this study, a rectangular thermosiphon containing PCM suspensions with an optimal loop configuration was used to investigate the effects of wall thickness and thermal conductivity on loop heat transfer, for which little information is available.

2. Material and Methods

In this study, the physical model (shown in Figure 1) was a rectangular natural circulation loop (aspect ratio $AR = l_H^+/l_V^+$) containing the PCM suspension fluid. l_H^+ and l_V^+ were the horizontal length (width) and the vertical length (height) of the loop, respectively. The inner radius of the circular pipe in the loop was r_i^+ . The loop consisted of a heating and a cooling section separated by adiabatic sections. The lower horizontal section had a heating section with a length of l_h^+ that provided uniformly distributed heat flux q_h'' . The upper portion of the vertical section (right) had a cooling section with length l_c^+ that provided isothermal boundary T_c . The height from the center of the cooling section to the lower horizontal section is l_z^+ . The geometric configuration that maximized the heat-transfer efficiency of a heating section of a rectangular thermosiphon containing PCM suspensions, obtained in our previous study [27], was used: AR = 11; the dimensionless length of the heating section ($l_z=l_z^+/l_t^+$) = 0.4, and the dimensionless elevation of the cooling section relative to the heating section ($l_z=l_z^+/l_t^-$) = 0.75.



Figure 1. Schematic of rectangular thermosiphon loop and coordinate system.

Consider a binary mixture system of continuous fluid (water) dispersed with small PCM particles, as shown in Figure 1 (upper-left A–A section). PCM particles can absorb/release thermal energy from/to fluid, undergoing solid–liquid phase change so that they can be solid, liquid, or both. Continuum formulation was applied to model the buoyancy-driven circulation flow of the PCM suspensions under the following assumptions.

- (1) PCM suspension was regarded as incompressible Newtonian fluid and in steady-state, two-dimensional, axisymmetric, and fully developed laminar flow.
- (2) Viscous dissipation in the loop flow was neglected.
- (3) All other physical properties did not vary with temperature, except that the Boussinesq approximation was used to describe working-fluid density.
- (4) PCM particles were evenly distributed in the loop.
- (5) Heat-conduction heat transfer inside the pipe wall was axisymmetric. The thermal conductivity of the pipe wall was constant.
- (6) There was negligible variation in the density of the PCM particles during the solid–liquid phase transition.
- (7) The relative velocity between PCM particles and base fluid was substantially smaller than the total velocity and could be neglected.
- (8) The supercooling effect of the PCMs was negligible, i.e., the melting and freezing points of the PCMs were the same.

The following dimensionless variables were defined:

$$r = \frac{r^+}{r_i^+}, \ s = \frac{s^+}{l_c^+}, \ \theta = \frac{T - T_M}{(q_h'' \ r_i^+ / k_b)}, \ u = \frac{u^+}{(Ra^{*1/4}\alpha_b / r_i^+)}$$

The assumptions and dimensionless variables given above were used to obtain the dimensionless governing equations below.

Continuity equation:

$$\frac{\partial u}{\partial s} = 0. \tag{1}$$

Momentum equation integrated over the entire loop length (l_L):

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial u}{\partial r}\right) + \frac{\left(Ra^{*1/4}R_L\right)^3}{\gamma_L l_L}\int_0^{l_L}\theta\phi ds = 0,$$
(2)

where $\phi = 1$ for $l_H < s < (l_L/2)$; $\phi = -1$ for $(l_L/2 + l_H) < s < l_L$; and $\phi = 0$ for $0 \le s \le l_H$ or $(l_L/2) < s < (l_L/2 + l_H)$. The correction factor for loop length $\gamma_L (\ge 1)$ is embodied in the buoyancy force term of Equation (2) to specify minor losses in the loop [29].

Energy equation:

$$\frac{\partial^2 \theta}{\partial s^2} + \frac{1}{\left(R_L l_L\right)^2} \left(\frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} \right) = 0 \tag{3}$$

$$u\frac{\partial\theta}{\partial s} = \left(\frac{R_L l_L}{Ra^{*1/4}}\right)\left[\frac{\partial^2\theta}{\partial s^2} + \frac{1}{\left(R_L l_L\right)^2}\left(\frac{\partial^2\theta}{\partial r^2} + \frac{1}{r}\frac{\partial\theta}{\partial r}\right)\right] - \left(\frac{\rho_{pf}^*}{\rho_{bf}^*}\right)\frac{c_v}{Ste^*}u\frac{\partial\xi_\ell}{\partial s}$$
(4)

The last term on the right-hand side of Equation (4) represents the transport of latent-heat absorption and the release of PCM particles, and requires closure in terms of liquid-phase volume fraction of particles ξ_l . The approximate enthalpy model [26,30] was utilized to characterize the phase change of the PCM particles, as well as ξ_l :

$$u\frac{\partial\xi_{\ell}}{\partial s} = (\frac{3Bi_{p}}{r_{p}^{2}})(\frac{k_{pf}^{*}}{k_{bf}^{*}})(\frac{\rho_{bf}^{*}}{\rho_{pf}^{*}})(\frac{Ste^{*}}{R_{L}l_{L}Ra^{*1/4}})\theta$$
(5)

Particle Biot number Bi_p is obtained using the relationships given by Charunyakorn et al. [31]. During the phase-change process, particle temperature was assumed to be the same as the phase-change temperature. The time lag of the PCM particles, which was related to the diffusion time scale of the particles and the heat-capacity difference between particles and mixture, was assumed to be 0. The effect of PCM supercooling was not considered in this study. Incorporation of the time lag of PCM particles during the phase-change process and PCM supercooling is very important. This is not what we explore in this study, but worthy of further consideration. Readers can refer to [30] for details.

Dimensionless boundary conditions:

(1) Outer wall boundary, $r = 1 + t_w$

$$\frac{\partial \theta}{\partial r} = \frac{k_{bf}^*}{k_{wf}^*}; \ l_a \le s < (l_H - l_a) \tag{6}$$

$$\frac{\partial \theta}{\partial r} = 0; \ 0 \le s < l_a, \ (l_H - l_a) \le s < (2l_H + l_v + l_a), \ (2l_H + l_v + l_a + 1) \le s < l_L$$
(7)

$$\theta = -Sb^*; \ (2l_H + l_v + l_a) \le s < (2l_H + l_v + l_a + 1) \tag{8}$$

(2) Inner wall boundary, r = 1

$$u = 0; \ \theta_{w,i} = \theta_b; \left(\frac{\partial \theta}{\partial r}\right)_{w,i} = \frac{k_{bf}^*}{k_{wf}^*} \left(\frac{\partial \theta}{\partial r}\right)_b \tag{9}$$

(3) Center of pipe, r = 0

$$\frac{\partial u}{\partial r} = 0, \ \frac{\partial \theta}{\partial r} = 0, \ \frac{\partial \xi_l}{\partial r} = 0 \tag{10}$$

Dimensionless bulk temperature of the PCM suspension θ_b and mean liquid-phase fraction of PCM suspension ξ_b at a specified cross-section of the loop are determined as follows:

$$\theta_b(s) = \int_0^1 u(r)\theta(r,s) \ rdr / \int_0^1 u(r) \ rdr \tag{11}$$

$$\xi_b(s) = \int_0^1 u(r)\xi_\ell(r,s) \ rdr / \int_0^1 u(r) \ rdr.$$
(12)

The dimensionless local heat flux of the inner wall $(q_i''^*)$ is

$$q_i^{''*} = \frac{q_i^{''}}{q_h^{''}} = \frac{k_b \left(\frac{\partial T}{\partial r^+}\right)_{r^+ = r_i^+}}{q_h^{''}} = \left(\frac{\partial \theta}{\partial r}\right)_{r=1}.$$
(13)

Neglecting axial fluid conduction, an integral energy balance was incorporated to derive the heat-transfer rate over the heating section between $s = l_a$ and $s = l_H - l_a$:

$$q_{h}^{*} = \frac{1}{l_{h}} \int_{l_{a}}^{(l_{H}-l_{a})} \left(\frac{\partial \theta}{\partial r}\right)_{r=1} ds$$

$$\approx \frac{u_{b}}{2} (Ra^{*1/4}R_{L}) (\frac{l_{L}}{l_{h}}) [\theta_{b}(s = (l_{H} - l_{a})) - \theta_{b}(s = l_{a})]$$

$$+ \frac{u_{b}}{2} (Ra^{*1/4}R_{L}) (\frac{l_{L}}{l_{h}}) (\frac{\rho_{pf}^{*}}{\rho_{bf}^{*}}) (\frac{c_{v}}{Ste^{*}}) [(\xi_{b}(s = (l_{H} - l_{a})) - \xi_{b}(s = l_{a})].$$
(14)

Equation (14) relates θ_b to ξ_b for convection heat-transfer rate q_h^* . That is, the convective heat transfer by the PCM suspension flow in the loop arose from the transport of sensible and latent heat, which are given as follows:

$$(q_h^*)_{sen} = \frac{u_b}{2} (Ra^{*1/4} R_L) (\frac{l_L}{l_h}) [(\theta_b (s = (l_H - l_a)) - \theta_b (s = l_a)]$$
(15)

$$(q_h^*)_{lat} = \frac{u_b}{2} (Ra^{*1/4} R_L) (\frac{l_L}{l_h}) (\frac{\rho_{pf}^*}{\rho_{bf}^*}) (\frac{c_v}{Ste^*}) [(\xi_b(s = (l_H - l_a)) - \xi_b(s = l_a)].$$
(16)

Latent-heat contribution to the overall heat transfer of the heating section $(\Phi_h^*)_{lat}$ is

$$(\Phi_h^*)_{lat} = (q_h^*)_{lat} / q_h^*.$$
(17)

To estimate the efficacy of the PCM suspension for heat-transfer enhancement, the effectiveness of maximal temperature control $\varepsilon_{T_{\text{max}}}$ for the heating section is defined as follows:

$$\varepsilon_{T_{\max}} = (\theta_{w,h,\max,f} / \theta_{w,h,\max,b})(k_{bf}^*) = (T_{w,h,\max,f} - T_M) / (T_{w,h,\max,b} - T_M).$$
(18)

3. Numerical Method

The differential equations were spatially discretized on a uniform mesh. Second-order centraldifference and QUICK [32] schemes were used for the diffusion terms and convective terms, respectively. In this paper, line-successive over-relaxation (SOR) was used to solve the unknown terms, and the tridiagonal-matrix algorithm (TDMA) to solve the problem, where the solution was initiated at $s^+ = 0$ and iterated along main flow direction s^+ (Figure 1). The ratios of the maximal variations to the maximal values of the temperature, the volumetric proportion of the liquid phase of the PCM suspension, and velocity were monitored to determine the convergence of these parameters, where the convergence condition for each parameter was 10^{-5} .

To test grid independence, the mean Nusselt numbers of the inner pipe walls in both the heating and the cooling section were used to calculate the deviation percentages. Numerical errors were estimated using the grid-convergence-index (GCI) method for the local Nusselt numbers of the heating and cooling sections. Deviation percentages and numerical errors were used to determine suitable grid points for our calculations. In our previous study [27], a grid of 2001×201 points was sufficient for zero wall thickness ($t_w = 0$). Therefore, in this study, a grid of 2001×201 points was used as the baseline, and the number of grid points was increased along the radial direction. The following loop configuration was used to test grids with different numbers of points, and AR = 1; $l_H^* = 0.8$; $l_z = 2$; $Ste^* = 0.1$; $Sb^* = 0.6$; $Ra^* = 10^{11}$; $c_v = 10\%$; and $t_w = 0.5$. A grid of 2001×701 resulted in less than 1% deviation in the mean Nusselt number, and less than 1% error in the energy-balance conditions (data not shown) of the walls in the heating and cooling sections. Therefore, a grid of 2001×701 was used in all simulations.

The developed formulation and the incorporated numerical method were verified by simulating selected cases of heat transfer in a single-phase toroidal loop [33] and forced convection of the PCM suspension fluid in a straight circular pipe [34], as shown in Figure 2 [27]. No significant difference was found among the results of the different studies, confirming the reliability of the simulation results in this study.



Figure 2. Simulation-result comparison with (a) Mertol et al., and(b) Goel et al. [27].

4. Results and Discussion

Figure 3 shows the axial distributions of the loop temperatures and ξ_b versus t_w , where $\theta_{w,o}$ represents the temperature of the outer pipe wall, $\theta_{w,i}$ represents the temperature of the inner pipe wall, and θ_b represents the local mean temperature of the suspension fluid at a given cross section of the pipe, and s^* is the modified dimensionless axial coordinate ($=s^+/l_L^+$). The dotted lines partition the figure into five blocks, and the point with dimensionless distance s^* of 0 was set at the lower-right

corner of the loop system (Figure 1). Except for the heating and cooling sections, all other parts in the figure are adiabatic sections. The s^* range of 0–0.073 corresponds to the adiabatic section before the inlet of the heating section, the range of 0.073–0.174 corresponds to the heating section, the range of 0.174–0.748 corresponds to the adiabatic section between the outlet of the heating section and the inlet of the cooling section, the range of 0.748–0.948 corresponds to the cooling section, the range of 0.948–1 corresponds to the adiabatic section after the cooling section, and s^* of 1 indicates the return to the starting point of the loop.



Figure 3. Axial distributions of different temperature levels (a) $\theta_{w,o}$, (b) $\theta_{w,i}$, and (c) θ_b and (d) ξ_b for different wall-thickness levels t_w (AR = 1, $l_h^* = 0.4$, $l_z = 0.75$, $Sb^* = 0.6$, $Ste^* = 0.1$, $Ra^* = 10^{10}$, $c_v = 10\%$, and $k_{wf}^* = 1$.

Results showed that, after the fluid entered the heating section, it was heated by a constant heat flux, and temperatures started to rise. When entering the adiabatic section, temperatures decreased. After that, it remained approximately isothermal until entering the cooling section. Then, the temperatures decreased due to the cooling effect. After leaving the cooling section, it entered the adiabatic section, and the temperatures rose because the wall of the adiabatic section receives axial heat transfer from the heating section. Figure 3a–c shows that, the thicker the pipe wall was, the higher the temperatures were because thermal resistance increased with pipe-wall thickness. The distribution of the liquid fraction of PCM suspension (Figure 3d) shows that, for $t_w = 0.5$, the thicker pipe wall caused overall temperature to increase, which delayed the solidification of the PCM particles after complete cooling, as shown by the red arrow in the figure.

In this paper, the thermal-conductivity ratio of the pipe wall $k_{wf}^* = k_w/k_f$ is defined as the ratio of the wall's heat conductivity to that of the pure fluid (water), and reflects the heat-conduction capability of the wall. Figure 4 shows the effects of k_{wf}^* on the loop heat-transfer characteristics for fixed wall thickness ($t_w = 0.1$). The smaller that k_{wf}^* was, the higher the thermal resistance of the pipe wall was, and the higher the wall temperature was. However, a large k_{wf}^* increased the heat transfer of the pipe wall, which caused preheating or precooling of the walls of the adiabatic sections near the heating and cooling sections, respectively. For $k_{wf}^* = 0.1-10$, the temperature at each point near the heating section caused axial heat transfer to increase the temperature at each point before the heating section, as shown by the red arrow. Similarly, the points after the adiabatic section before the cooling section were precooled, and the temperature of each point decreased, as shown by the blue arrow.



Figure 4. Axial distributions of temperatures ((a) $\theta_{w,o}$, (b) $\theta_{w,i}$, (c) θ_b) and (d) ξ_b for different k_{wf}^* s (*AR* = 1, l_b^* = 0.4, l_z = 0.75, *Sb*^{*} = 0.6, *Ste*^{*} = 0.1, *Ra*^{*} = 10¹⁰, c_v = 10%, and t_w = 0.1).

 ξ_b distribution shows that, for $k_{wf}^* = 0.1$, $t_w = 0.1$, the fluid was overheated upon leaving the adiabatic section and entering the cooling section. The fluid could only be cooled to melting point for PCM solidification T_M after passing approximately 1/3 of the cooling section (as shown by the red circle in Figure 4d), leading to $\xi_b < 1$ (where fluid temperature = T_M , $\theta_b = 0$). After the fluid left the cooling section and entered the adiabatic section, the PCM could completely solidify, leading to $\xi_b = 0$ (as indicated by the blue circle). Compared with other cases (as shown by the solid red arrow), the lack of supercooling for $k_{wf}^* = 0.1$, $t_w = 0.1$ facilitated early PCM melting in the heating section (as indicated by the dotted red arrow). The rapid completion of the melting process resulted in $\xi_b = 1$. For $k_{wf}^* = 0.1$, $t_w = 0.2$ –0.5 (i.e., a slightly thicker pipe with poor thermal conductivity), $\xi_b = 1$ in all the parts of the loop, showing the utilization of latent heat in the loop (Please also refer to Figure 5a, $(\Phi_h^*)_{lot} = 0$: yellow area).



Figure 5. Latent-heat contribution of heating section $(\Phi_h^*)_{lat}$ versus wall thickness t_w for different k_{wf}^* s: (a) $Ra^* = 10^{10}$ and (b) $Ra^* = 10^{11}$ (AR = 1, $l_h^* = 0.4$, $l_z = 0.75$, $Sb^* = 0.6$, $Ste^* = 0.1$, and $c_v = 10\%$).

Figure 5 shows latent heat contribution versus wall thickness, where $(\Phi_h^*)_{lat}$ represents latent heat contribution to the overall heat transfer of the heating section $(=(q_h^*)_{lat}/q_h^*)$. For $Ra^* = 10^{10}$ (Figure 5a), increasing the wall thickness from theoretical condition $t_w = 0$ (shown by \blacktriangleright in the figure) to $t_w = 0.1$ did not result in significant change in $(\Phi_h^*)_{lat}$ (as indicated by the area enclosed by the dotted red line), because the final wall thickness was not large. However, increasing wall thickness affected $(\Phi_h^*)_{lat}$ differently for different pipe-wall materials (corresponding to different thermal-conductivity levels). For $k_{wf}^* = 0.1$, $t_w \ge 0.2$, loop wall temperature was too high because the wall had low thermal conductivity and was relatively thick. Thus, the PCM particles did not solidify in the cooling section (as indicated by the dotted red circle in the insert of Figure 5a), and latent heat did not play a role in the heating section. For $k_{wf}^* = 100$, increasing wall thickness (0.1–0.5) increased $(\Phi_h^*)_{lat}$ in the heating section, effectively using latent heat. Figure 5b shows that, for $k_{wf}^* = 0.1$, $t_w \ge 0.2$, the $Ra^* = 10^{11}$ and

 $Ra^* = 10^{10}$ cases were similar, and latent heat was not utilized. For $k_{wf}^* \ge 1$, increasing wall thickness (0.1–0.5) increased $(\Phi_h^*)_{lat}$ in the heating section, and latent PCM heat was effectively utilized.

Figure 6 shows that, the thicker the pipe wall was, the higher the heat flux in the heating section was, as shown by the red arrow. At the entrance to the cooling section, the thicker the pipe wall was, the lower the maximal heat flux was, which reduced the peak heat flux (yellow area). However, the thicker wall also increased the heat flux in the cooling section outside the above-mentioned (dotted-red) area. For a relatively large k_{wf}^* s, the heat-flux curve was modified earlier because of preheating the heating section and precooling section, as shown by the dotted blue area. This precooling phenomenon was more marked for $k_{wf}^* = 100$ (Figure 6b).



Figure 6. Effect of wall thickness t_w on distribution of local dimensionless heat flux $q_i^{"*}$ for different k_{wf}^* s: (a) $k_{wf}^* = 1$ and (b) $k_{wf}^* = 100$ (*AR* = 1, $l_h^* = 0.4$, $l_z = 0.75$, *Sb*^{*} = 0.6, *Ste*^{*} = 0.1, *Ra*^{*} = 10¹⁰, and $c_v = 10\%$).

Figure 7 shows the $\varepsilon_{T\max}$ of the heating section versus t_w , where $\varepsilon_{T\max}$, defined in Equation (16), represents the effectiveness of the maximal temperature control for the heating section. A high $\varepsilon_{T\max}$ shows low maximal wall temperature in the heating section. In Figure 7a, for $Ra^* = 10^{10}$, $\varepsilon_{T\max}$ increased with k_{wf}^* . $\varepsilon_{T\max}$ was higher than the theoretical value ($t_w = 0$; shown by \blacktriangleright) for the following cases: $k_{wf}^* = 10$, $t_w = 0.1$ and $k_{wf}^* = 100$, $t_w = 0.1$ –0.5. The highest $\varepsilon_{T\max}$ of 1.21 was obtained for $k_{wf}^* = 100$,

 $t_w = 0.4$. On the basis of the design parameters provided here ($k_{wf}^* = 100$, $t_w = 0.4$), an optimized practical system could be designed and manufactured by readers. Figure 7b shows that, for $Ra^* = 10^{11}$, thinner walls and higher k_{wf}^* s increased ε_{Tmax} in the heating section, where the highest ε_{Tmax} of 1.92 was obtained for $t_w = 0$, a theoretical condition. In this case, the optimized design parameters (k_{wf}^* and t_w) are not possible; however, using a thicker pipe with a high thermal conductivity is recommended. For $k_{wf}^* = 100$, $t_w = 0.1$, $\varepsilon_{Tmax} = 1.83$, which represented a reduction of only 4.8% with respect to the highest theoretical ε_{Tmax} (1.92).



Figure 7. $\varepsilon_{T \max}$ of heating section versus t_w : (**a**) $Ra^* = 10^{10}$ and (**b**) $Ra^* = 10^{11}$ (AR = 1, $l_h^* = 0.4$, $l_z = 0.75$, $Sb^* = 0.6$, $Ste^* = 0.1$, and $c_v = 10\%$).

When water was used as the working fluid, $\varepsilon_{T\max} = 1$ in the loop (dotted red line in Figure 7). The working fluid was changed from pure water to a 10% PCM suspension (by volume fraction of PCM particles), and the simulations were again performed using the same parameter values. For $Ra^* = 10^{10}$, the pipe with $k_{wf}^* \ge 1$ enhanced temperature-control effectiveness (indicated by $\varepsilon_{T\max}$) in the heating section: for $k_{wf}^* = 100$, $t_w = 0.4$, $\varepsilon_{T\max}$ was enhanced by up to 21.5% over that of pure water. For $Ra^* = 10^{11}$ and a thin pipe ($t_w \le 0.2$), $k_{wf}^* \ge 1$ enhanced temperature-control effectiveness in the heating section, whereas for a thick pipe ($t_w > 0.2$), $k_{wf}^* \ge 10$, i.e., high thermal conductivity, is recommended.

5. Conclusions

In our previous study, the following geometric configuration was found to maximize the heat-transfer efficiency of a heating section: loop aspect ratio = 1, dimensionless heating-section length = 0.4, and dimensionless relative elevation between cooling and heating sections = 0.75. In this study, this configuration was used for a rectangular thermosiphon containing PCM suspensions to investigate the effects of the wall properties (thickness and thermal conductivity) on heat transfer.

Results showed that selecting a pipe with appropriate wall thickness and thermal conductivity improved temperature control in the heating section for rectangular thermosiphons containing PCM suspensions. For preselected parameters $Sb^* = 0.6$, $Ste^* = 0.1$, $c_v = 10\%$, and $Ra^* = 10^{10}$, temperature control in the heating section was improved using a pipe with a high thermal conductivity: the highest ε_{Tmax} (effectiveness of maximal temperature control) of 1.21 was obtained for $k_{wf}^* = 100$, $t_w = 0.4$, which was 7.5% higher than that for the theoretical condition ($t_w = 0$). Using a 10% PCM suspension (by volume fraction) as the working fluid increased ε_{Tmax} for the heating section by 21.5% over that of pure water.

For $Ra^* = 10^{11}$, using a thin pipe with a high thermal conductivity increased the ε_{Tmax} of the heating section. For example, for $k_{wf}^* = 100$, $t_w = 0.1$, $\varepsilon_{Tmax} = 1.83$, which represented a reduction of only 4.8% compared to the highest ε_{Tmax} of 1.92 obtained for $t_w = 0$. Using a 10% PCM suspension as the working fluid increased ε_{Tmax} of the heating section by 83% compared with using pure water.

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Nomenclature

AR	aspect ratio of rectangular loop, l_H^+/l_V^+
Bip	Biot number of a PCM particle, $\frac{k_f}{k_p} \frac{2(1-c_v)}{(2-3c_p^{1/2}+c_p)}$
<i>c</i> _p	specific heat
c_v	volumetric fraction of PCM particles
g	acceleration due to gravity
h_{ls}	latent heat of fusion
k	thermal conductivity
k_{bf}^{*}	thermal-conductivity ratio, k_b/k_f
k_{pf}^{*}	thermal-conductivity ratio, k_p/k_f
k_{wf}^{*}	thermal-conductivity ratio, k_w/k_f
l_a^+	length of left and right adiabatic sections of lower leg of loop
la	dimensionless length of left and right adiabatic sections of lower leg of loop, l_a^+/l_c^+
l_c^+	cooling-section length
l_h^*	dimensionless length of heating section, l_h^+ / l_H^+
l_h^+	heating-section length
l_h	dimensionless length of heating section, l_h^+ / l_c^+
l_H^+	rectangular-loop width
l_H	dimensionless rectangular-loop width, l_H^+/l_c^+ or $(1+2l_z)AR/2$
l_I^+	total length of rectangular loop, $2(l_V^+ + l_H^+)$
$l_{L,eff}^{\mp}$	correction factor for loop length [29]
l_L	dimensionless total length of rectangular loop, $2(l_V + l_H)$ or $(1 + 2l_z)(1 + AR)$
l_V^+	rectangular-loop height
l_V	dimensionless height of rectangular loop, l_V^+/l_c^+ or $(1+2l_z)/2$
l_z^+	elevation of cooling section relative to heating section

Nomenclature

- l_z dimensionless mean elevation of cooling section relative to heating section, l_z^+/l_c^+
- $\begin{array}{c} q''_{n} \\ q_{i}^{''*} \\ q_{h}^{*} \\ R_{L} \end{array}$ local heat flux
- local dimensionless heat flux, $q_i^{''*} = q_i^{''} / q_h^{''}$
- total convection heat-transfer rate
- dimensionless pipe radius, r_i^+ / l_L^+ modified Rayleigh number, $(g\beta q_h^" r_i^+ l_L^{+3}) / (\alpha_b v_b k_b)$ Ra*
- radial coordinate
- r^+ r^+_i r^+_0 r^+_p rinner radius of loop pipe
- outer radius of loop pipe
- PCM particle radius
- dimensionless radial coordinate, r^+/r_i^+
- dimensionless particle radius, r_p^+/r_i^+ rp
- s^+ axial coordinate
- dimensionless axial coordinate, s^+/l_c^+ S
- s^* modified dimensionless axial coordinate, s^+/l_I^+
- Sb^* modified subcooling factor, $(T_M - T_c)/(q_h'' r_i^+/k_b)$
- Ste* modified Stefan number, $c_{p,b}(q_h'' r_i^+ / k_b) / h_{ls}$
- t_w^+ pipe-wall thickness $(r_o^+ - r_i^+)$
- dimensionless pipe-wall thickness $(=t_w^+/r_i^+)$ t_w
- Τ temperature
- u^+ axial velocity
- dimensionless axial velocity, $u^+/(Ra^{*1/4}\alpha_b/r_i^+)$ и

Greek symbols

- thermal diffusivity α
- β thermal-expansion coefficient
- effectiveness of maximal wall temperature control, $(T_{w,h,\max,f} T_M)/(T_{w,h,\max,b} T_M)$ or $\mathcal{E}_{T_{\max}}$ $(\theta_{w,h,\max,f}/\theta_{w,h,\max,b})(k_{bf}^*)$
- correction factor for loop length, $l_{L,eff}^+/l_L^+$ γ_L
- ν kinematic viscosity
- dimensionless temperature, $(T T_M) / (q''_h r_i^+ / k_b)$ θ
- density ρ
- base fluid-density ratio, ρ_b/ρ_f ρ_{bf}^*
- ρ_{pf}^{*} particle-density ratio, ρ_p / ρ_f
- ξ_b mean liquid fraction of PCM suspension
- ξ_{ℓ} liquid-phase volume fraction of PCM particles
- Φ latent-heat contribution

Subscripts

- bulk fluid b bulk-to-base-fluid ratio bf
- cooling section С
- base fluid (water) f h
- heating section
- i inner
- l PCM liquid phase
- latent heat lat
- М melting point
- max maximum
- particle р
- particle-to-base-fluid ratio pf
- sen sensible heat
- pipe wall w
- pipe-wall-to-base-fluid ratio wf
- *Superscripts*
- * ratio of quantities
- + dimensional quantity

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