



Article Investigating the Influence of a Pre-Existing Shear Band on the Seismic Response of Ideal Step-like Slopes Subjected to Weak Motions: Preliminary Results

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Abstract: The assessment of slope susceptibility to seismically-induced displacements receives wide attention in the geotechnical earthquake engineering field, but the alteration of the seismic wave inside the slope and at the ground surface due to the presence of a shear band confining a quiescent landslide body is rarely investigated. This paper describes the preliminary results of the numerical analysis of two step-like FE models, reproducing a gentle slope and steep cutting subjected to weak earthquakes, thus focusing on seismic wave amplification processes only. The results show that the higher the thickness of the weakened zone, the higher the maximum value of the amplification factors predicted at the ground surface. For gentle slopes affected by a landslide body confined by a thick shear band, the highest amplification factors are expected in the longer period range of 0.7–1.1 s, while the highest level of amplification is achieved in the intermediate period interval of 0.4-0.8 s in the case of steep slopes. In addition, the parasitic vertical component of acceleration can be considerably amplified beyond the crest and at the toe of the slope for increasing band thickness, especially in the case of steep topography, for which the effects of the shear band morphology enhance those related to the topographic profile. Finally, the fundamental frequency of the sloping deposit is not particularly affected by the presence of the shear band, while the amplitude of the amplification function at the fundamental frequency is clearly related to its thickness.

Keywords: seismic slope analysis; pre-existing shear bands; amplification factors; seismic hazard; FE numerical modelling

1. Introduction

Ground response analysis is a key tool in seismic hazard assessment, as the reference ground motion (i.e., at the outcropping bedrock with a flat surface) can be different from that recorded at a nearby site in terms of frequency content, amplitude, duration and polarisation due to local topographic and stratigraphic conditions (e.g., [1]). Previous seismic site response investigations have focused on: (i) the heterogeneity of the deposit with depth and the soil nonlinearity (e.g., [2–7]), (ii) the variability of the soil mechanical properties and input motion characteristics (e.g., [8–17]), (iii) the ground surface topography (e.g., [18–27]), (iv) the buried morphologies (e.g., [28–30]) and (v) the numerical code and approach employed in the simulations (e.g., [31–38]).

When studying the seismic behaviour of a slope affected by a landslide mechanism, most researchers have investigated the interaction between seismic waves and fully-developed landslide bodies, mainly focusing on the evaluation of slope susceptibility to seismically-induced displacements (e.g., [39–46]). In these studies, the entire sliding mass is assumed to be characterised by different physical and mechanical properties with respect to the surrounding stable deposit. However, in some cases, the landslide process may determine the alteration of the soil mechanical properties only at the shear band location as an effect of the shear strain localisation, inducing the degradation of both strength



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Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). and stiffness in a narrow zone confining the landslide body (e.g., [47–50]). Therefore, the propagation of seismic waves into a slope could be potentially affected by the presence of a weakened shear band, which may modify the response at the ground surface even during weak earthquake motions. Furthermore, some studies have shown the characteristic directivity of the slope dynamic response to seismic shaking on the basis of geological, geophysical and in situ investigations (e.g., [51–55]). Moreover, a sloping surface can generate a parasitic vertical component of acceleration even for input motions characterised by horizontally polarised waves due to the reflection of the incoming waves from the inclined slope surface [19,56].

Within this framework, the paper presents a set of two-dimensional (2D) finite element (FE) dynamic analyses of ideal slopes in soft soils, including a landslide body confined by a pre-existing weakened shear band. The main purpose is to evaluate the effect of the presence of the disturbed material in the shear band on the seismic response of step-like slope models, mainly focusing on aspects merely related to the seismic wave amplification processes. Indeed, the interactions between the seismic motion and the landslide body, in terms of earthquake-induced displacements causing the activation or the reactivation of the existing landslide mechanism, are beyond the scope of this paper. For this reason, providing that the earthquake loading is expected not to re-activate the sliding mechanism, weak input motions are adopted in the simulations by scaling them to very low peak acceleration. This assumption reasonably allows the adoption of a simple linear visco-elastic constitutive model to simulate the behaviour of the slope soils implemented in the analysis.

For each slope model, the results of the numerical simulations are described in terms of (i) 2D contours of the peak ground acceleration (PGA) of both horizontal and vertical components, to assess the effect of the weakened zone at ground surface and within the slope; (ii) profiles of amplification factors (Afs) (i.e., the ratio between quantities referred to the free-field and the outcrop signals, as described later on), at the ground surface, commonly used as a supporting tool for urban, emergency planning and seismic risk mitigation studies [14,57,58]; (iii) ground motion polarisation plots, to highlight the effect of the pre-existing shear band on the directivity of the surface motion in the vertical plane; (iv) response spectra of the ground surface pseudo-acceleration, typically employed for the design of above-surface structures and infrastructures, in comparison to the 1D response to highlight the influence of the shear band morphology; (v) amplification functions in the frequency domain, widely used in geotechnical earthquake engineering to identify the main characteristics of the wave propagation process in slope models; (vi) profiles of the maximum amplitude of the amplification functions at the fundamental frequency of the slope (Af_0) with the aim of illustrating the effect of the shear band on the amplification amplitude along the slope surface.

2. Description of the Ideal Case Studies

In this section, the selected case studies focus on the topography of the step-like slopes and the morphology of the weakened shear band implemented in the numerical FE models, as well as the soil properties, the adopted constitutive assumptions and the selected input motions.

2.1. Site Conditions

Numerical investigations have been performed with reference to two ideal slopes, characterised by different step-like geometries, shown in Figure 1, reproducing a gentle natural slope (Case I) and steep natural cutting (Case II). With reference to Case I, the considered geometry is: SH = 80 m, SL = 1000 m, L1 = L2 = 800 m and MH = 161 m, where SH is the slope height, SL is the slope length, L1 and L2 are, respectively, the left- and right-side extension of the slope and MH is the total height of the model. For Case II, the slope geometry is characterised by SH = 40 m, SL = 1000 m, L1 = L2 = 400 m and MH = 81 m. In detail, a soft deposit overlying seismic bedrock was considered, as shown in Figure 2. The soft deposit thickness was implemented equally to 80 m and 40 m for the gentle slope

and steep cutting, respectively. Consequently, the soft soil-bedrock interface was assumed parallel to the ground surface.



Figure 1. Geometrical scheme implemented in the FE simulations.



Figure 2. Details of the FE model with reference to (**a**) Case I and (**b**) Case II. Only the polyline representing the middle of the shear bands is sketched for the sake of simplicity.

For each step-like geometry, five numerical models were generated: one assuming the soil to be undisturbed in the whole slope (i.e., without the shear band) and four implementing a pre-existing weakened zone of thickness equal to 2.5%, 5%, 10% and 20% of the slope height. Hence, the thickness of the shear band was assumed equal to 2, 4, 8 and 16 m for Case I, while a weakened zone of 1, 2, 4 and 8 m was considered for Case II models. The location and the morphology of the shear bands, implemented in each numerical model, were defined by performing preliminary shear strength reduction analyses (i.e., c-phi reduction analyses) available in the FE code [59]. Realistic strength parameters representative of soils typically found in gentle natural slopes and steep cutting cases were assumed for the slope soils. Once the morphology of the potential slip surface was obtained from the c-phi reduction analyses, the shear band implemented in the dynamic simulations was drawn as a polyline connecting the points characterised by the highest shear strain. Thus, a weak zone of specific thickness around the shear band was modelled by offsetting the polylines sketched in Figure 2.

The choice of thickness should be governed by the geometrical extension and inclination of the slope, considering that in gentle natural slopes in soft soils (i.e., Case I), the band associated with a pre-existing roto-translation failure mechanism can be thicker, while in steep natural cuttings (i.e., Case II), the shear strains should be proportionally more localised in a thinner zone. Indeed, previous works have shown that the thickness of the weakened zone may range between centimetres and a few metres (e.g., [47–49,60–63]), and several contributions can be found in the literature where this feature has been specifically implemented in the numerical model of the slope [59,64–68]. It is interesting to note that Griffiths and Lane [59] introduced a weaker layer with a thickness equal to 20% of the slope height in the stability analysis of a clay slope in undrained conditions. Therefore, the inclusion of a 16 m thick shear band into an 80 m high slope (as assumed in Case I) or of an 8 m thick shear band into a 40 m high slope (as implemented in Case II) should not be considered unreasonable.

2.2. FE Models

Numerical analyses have been performed using the FE code PLAXIS 2D [69]. A preliminary study on the boundary conditions, not shown herein for the sake of brevity, was carried out to appropriately create the numerical models aimed at avoiding spurious reflections of the seismic waves and obtaining reliable numerical results. The adopted dynamic boundary conditions are (i) free-field boundaries along the vertical sides of the FE models with the addition of fixed vertical displacements and (ii) a compliant base, i.e., adsorbing boundaries, at the bottom of the mesh to simulate the dissipation of the waves into the deep soil layers with minimum reflection at the bottom boundary [69–71]. The compliant base option implies applying, as input motion at the base of the FE models, only the upward propagating component of the ground motion recorded at the outcropping bedrock. Moreover, the FE meshes were laterally extended by five times the height of the model (i.e., $L1 = L2 = 5 \cdot MH$, see Figure 1) in order to avoid any interference of the vertical boundaries with the slope area. The coarseness of the FE mesh was refined to obtain a distance between two consecutive nodes smaller than approximately one-eighth of the wavelength associated with the maximum frequency content, f_{max} , of the input wave [72,73]. In particular, a frequency cut-off equal to 15 Hz was used to filter the input signals. The gravity loading procedure was employed to generate the initial stress state before the application of earthquake loading.

The details of the slope area are sketched in Figure 2a,b with reference to Cases I and II, respectively. Three control points at the ground surface have been selected in both cases which are near the crest, in the middle of the slope and at its toe. Defining a relative normalised distance as $x_r = (x - L1)/SL$, the three nodes have been selected at x_r equal to 0.2, 0.5 and 0.8 for both Cases I and Case II. The results of the simulations are shown for these three points to highlight the differences for each case study varying the shear band thickness. Amplification functions, response spectra and ground motion polarisation plots are also shown in the following with reference to the three control points. Additionally, profiles of Af_0 and amplification factors, AF_s , along the slope have been retrieved from all the FE nodes located at the ground surface of the slope, from above its crest to the area beyond its toe.

2.3. Constitutive Assumptions

The slope soils behaviour has been described by the linear visco-elastic constitutive model, selected to explicitly avoid plasticity-induced effects on the wave propagation process (e.g., earthquake-induced sliding movements). The mechanical properties of the considered materials are reported in Table 1. In particular, the shear wave velocity value, V_S , adopted for the soft soils is representative of the cover materials typically emerging on the Italian territory [74–76], while the V_S value of the shear band has been reduced to account for the stiffness degradation due to shear strain localisation. A typical value of 800 m/s was assigned to the seismic bedrock. Viscous damping was implemented through the standard Rayleigh formulation [70], selecting 1 and 10 Hz as controlling frequencies for its calibration on the basis of the prevailing frequency content of the input signals (e.g., [21,23,35,36]). A value of 5% was assumed for the target damping ratio, being representative of the dissipative capacity of both the intact soft soil and the disturbed material in the weakened band; a smaller value equal to 1% was adopted for the seismic bedrock, as it is supposed to provide a lower amount of energy dissipation.

It is worth noting that these constitutive assumptions are in line with those adopted in previous studies, where fundamental aspects of the slope seismic response have been numerically investigated (e.g., [19,20]). The use of more advanced constitutive models would allow us to better describe the cyclic behaviour of soils during strong earthquakes; however, at the same time, it would unnecessarily complicate the interpretation of the numerical results by introducing nonlinear effects associated with soil plasticity, which is beyond the scope of the work.

Table 1. Properties of the slope soils implemented in the FE simulations.

Material	Soil Unit Weight γ _{soil} (kN/m ³)	Poisson's Ratio ν	Shear Wave Velocity V _S (m/s)	Damping Ratio D (%)	
Soft soil	20	0.25	400	5	
Seismic bedrock	22	0.25	800	1	
Weakened shear band	18	0.25	200	5	

2.4. Input Motions

Two reference seismic signals, considerably different in terms of frequency content, have been selected [77,78]. Specifically, the north–south component recorded by the Lauria station (LRS) during the 1998 Southern Italy earthquake and the east–west component recorded by the Arquata del Tronto station (RQT) during the 2016 Central Italy earthquake (named RM1 and RM2 in Figure 3, respectively) were chosen for the numerical investigation. The main features of the seismic events are listed in Table 2 in terms of magnitude, distance from the fault, PGA, PGV (peak ground velocity) and PGD (peak ground displacement). The acceleration time histories and the pseudo-acceleration response spectra are shown in Figure 3a,b, respectively, highlighting the different frequency content of the input motions, characterised by predominant periods equal to 0.5 s for RM1 and 0.1 s for RM2. The signal duration is 20 s and 40 s for RM1 and RM2, respectively.



Figure 3. Reference input motions RM1 and RM2 presented in terms of (**a**) acceleration time history and (**b**) pseudo-acceleration response spectrum (5% damping) scaled at the same PGA.

Table 2. Main features of the reference motions selected from the Italian strong motion netwo
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Station ID	Date	$\mathbf{M}_{\mathbf{w}}$	R (km)	PGA (g)	PGV (m/s)	PGD (m)	Name
LRS	9 September 1998	5.6	18.0	0.165	0.125	0.127	RM1
RQT	26 October 2016	5.4	16.7	0.222	0.04947	0.00495	RM2

Since the main objective of the work is to investigate the slope response in the linear elastic field, both signals have been scaled to a PGA of 0.02 g, being representative of weak earthquake motions. The acceleration time histories with a sampling time of 0.005 s have been re-sampled with a time step of 0.01 s to minimise the hard disk storage required for the FE output data files. This time step is lower than the critical value [72], equal to 0.02 s as derived from $1/(3 \cdot f_{max})$, where $f_{max} = 15$ Hz.

The signals have been properly selected with the aim of enlightening the expected topographic effects for each case study. In the work of Bouckovalas and Papadimitriou [19], the criteria for considering topographic aggravation were provided in terms of two main

variables, i.e., the normalised slope height H/λ (where H is the slope height and $\lambda = V_S \cdot T$ is the predominant wavelength of the input motion) and the normalised slope angle $i/90^{\circ}$. Through the contours reported in Figure 4, the authors identified the limits of the normalised slope height and slope angle for which topographic effects become significant. Thus, at least 10% topographic aggravation of the horizontal ground motion is expected if $H/\lambda > 0.03$ and i > 10° (Low aggravation (AG) in Figure 4), while topographic effects become important (at least 20% aggravation of the horizontal ground motion) for $H/\lambda > 0.16$ and $i > 17^{\circ}$ (high AG in Figure 4). Within this framework, negligible topographic effects were expected for the Case I model excited by the RM1 signal (characterised by H/ λ equal to 0.4 for $i/90^{\circ}$ equal to 0.05), while high topographic effects were expected for the Case II model subjected to the RM2 motion, for which H/λ is equal to 1 for $i/90^\circ = 0.24$ (Figure 4). Since the higher the fundamental period of the signal, the lower the normalised slope height, the adoption of the RM1 signal to the steep slope of Case II, corresponding to $H/\lambda = 0.2$, provides lower topographic amplification. Conversely, the RM2 signal applied to the gentle slope of Case I, i.e., H/λ equal to 2, provides a condition outside the case studies analysed by Bouckovalas and Papadimitriou [19]. For the above reasons, the analysed scenarios are the Case I model subjected to the RM1 signal and the Case II model excited by the RM2 signal.



Figure 4. Comparison between the examined case studies and the limits of normalised slope height H/λ and slope angle $i/90^{\circ}$ for which topographic effects become significant [19], with respect to the (**a**) horizontal and (**b**) vertical motion.

3. Interpretation of the Numerical Results

The results of the 2D simulations are firstly illustrated in terms of the contours of the maximum values of PGA attained by the horizontal and vertical motion during the earthquake. As already recalled, a parasitic vertical component of the seismic motion might be generated into slopes due to the wave reflection from the inclined topographic surface and/or at the shear band. Figures 5 and 6 show the contours of the horizontal and vertical PGA values for the Case I models, including or not including the shear bands. With reference to the intact soil case (i.e., no shear band), the PGA contours of the horizontal component (Figure 5) are approximately parallel to the ground surface in the central zone of the slope, thus indicating a prevalent 1D behaviour expected due to the correlation between the predominant wavelength of the input motion and the geometry of the model. Instead, the presence of the shear band clearly affects the distribution of the PGA at the ground surface and inside the entire slope. Indeed, high values of the PGA might be detected at depth for the higher thickness of the weakened material; additionally, the highest PGA values are located close to the crest and beyond the toe downslope for increasing the thickness of the shear band. Figure 6 gives evidence of the existence of a significant component of the vertical motion (maximum value of 0.012 g), already in the case without a shear band, due to the inclined surface of the slope. This parasitic vertical component may become significantly high in the presence of a shear band due to the wave reflections at the contact between the soft soil and the weakened material. In particular, the higher

the shear band thickness, the higher the PGA values, which concentrate at the crest of the slope. For example, for the 16 m thick shear band, a maximum PGA of 0.300 g is observed at 850 m, where the shear band outcrops.



Figure 5. Contours of the PGA of the horizontal component for Case I. The dashed line refers to the polyline in the middle of the shear bands.



Figure 6. Contours of the PGA of the vertical component for Case I. The dashed line refers to the polyline in the middle of the shear bands.

The PGA contours of the horizontal and vertical acceleration components obtained for the steep slope (Case II) are presented in Figures 7 and 8, respectively. As for the gentle slope, the thicker the shear band, the higher the PGA values recorded within the FE model. However, for the steep slope cases, it is more evident how the PGA distribution in the upslope and downslope areas (i.e., above the crest and beyond the toe) depends on the coupling between the shear band and topography effects. In particular, the amplification of the vertical motion appears to propagate above the crest with the increasing thickness of the weakened band (see x = 350 m in Figure 8).



Figure 7. Contours of the PGA of the horizontal component for Case II. The dashed line refers to the polyline in the middle of the shear bands.

The 2D results are then interpreted in terms of amplification factors at the surface, which provide the quantification of ground motion modification with reference to different period intervals and allow us to display the site effects in an easy-to-read fashion within a seismic hazard perspective (e.g., [58,79–81]). The amplification factors are defined as the ratio between a quantity describing the seismic motion recorded at the ground surface and the same quantity describing the input motion:

$$AF_{PGA} = \frac{PGA_o}{PGA_i}$$
(1)

$$AF_{T1-T2} = \frac{\int_{T1}^{12} Sa_o dT}{\int_{T2}^{T2} Sa_i dT}$$
(2)

where Sa is the pseudo-spectral acceleration, and T is the period. The subscripts "i" and "o" refer, respectively, to the input and output motions, the latter recorded at the ground surface. The AF_{T1-T2} are evaluated as the ratio of the integral of the pseudo-acceleration response



spectra (5% structural damping) over predefined period ranges, T1–T2. Specifically, the period intervals adopted in this study are 0.1–0.5, 0.4–0.8 and 0.7–1.1 s.

Figure 8. Contours of the PGA of the vertical component for Case II. The dashed line refers to the polyline in the middle of the shear bands.

The profiles along the slope ground surface of the amplification factors (AF) are shown in Figure 9 for Case I. The AFs relative to the vertical component of the surface motion (presented on the right side of the figure) have been calculated with respect to the horizontal component of the input motion. As expected, the profiles of the amplification factors in the shear band area (highlighted in the upper part of the figure) are strongly influenced by its presence. Indeed, depending on the period range, the weakened shear bands may be responsible for the amplification of the input motion in some locations but also for its de-amplification in other parts of the slope. In particular, the higher the thickness of the weakened zone, the higher the maximum absolute value of the amplification factors in the shear band area. For example, for the 16 m thick shear band slope model, the AF_{PGA} profile of the horizontal component of the motion is characterised by a minimum of 0.7 and a maximum of 1.6; the AF_{0.1-0.5} profile shows a minimum value of 0.9 and a maximum of 1.7, while in the long period range of 0.7-1.1 s, the AF_{0.7-1.1} profile gives evidence for the amplification of the motion along the entire slope surface. Additionally, it might be observed that the AFs profiles for the cases with the shear band are characterised by fluctuations around the profile obtained for the intact soil case, showing minimum values in the upper portion of the slope and maximum values in the lower portion of the slope. The location of the maximum values of the horizontal and vertical AFs tend to move toward the toe of the slope for increasing thickness of the weakened zone. Conversely, only the amplification factor of the horizontal motion in terms of PGA considerably increases at the crest with respect to the case of intact soil. Additionally, it might be remarked that, for all the examined cases, the parasitic vertical component is always lower than the horizontal component of the input motion (i.e., AFs less than 1). The highest amplification of the



vertical component is observed in the 0.7–1.1 s interval of the period for the thickest shear band case.

Figure 9. Profiles of amplification factors relative to Case I obtained with or without the shear band.

Figure 10 presents the profiles of the AFs for Case II. The amplification factors calculated for both the horizontal and vertical components in the mid and higher period ranges are slightly affected by the presence of the weakened zone in the FE model. Instead, the AFs in terms of PGA and in the lower period range (i.e., 0.1–0.5 s) are considerably altered by the shear band, showing numerous oscillations between the minimum and maximum values. Peaks of the amplification factor profiles are detected in different locations of the

slope surface, with the maximum around the toe of the slope. Additionally, in this case, the presence of the weakened zone may generate a de-amplification of the horizontal component of the motion, which is more significant the thicker the shear band is. Moreover, the parasitic vertical component induced by the topography and the morphology of the shear band is significantly higher in the low period range and considerably amplified for the increased thickness of the shear band: for thicker shear bands, i.e., 4 m and 8 m, the vertical component could be even higher than the horizontal component of the input motion (see the right side of Figure 10).



Figure 10. Profiles of amplification factors relative to Case II, obtained with or without the shear band.

Table 3 shows the amplification factors (Afs) at control point locations $x_r = 0.2$, 0.5 and 0.8 for both Cases I and II, considering or not considering the presence of the shear bands. It should be noted that the amplitudes of the AFs over different period ranges are strongly dependent on both the shear band thickness and the position of the point of interest.

Shear Band Thickness	AF _{PGA}	AF _{0.1-0.5}	AF _{0.4-0.8}	AF _{0.7-1.1}	AF _{PGA}	AF _{0.1-0.5}	AF _{0.4-0.8}	AF _{0.7-1.1}	AF _{PGA}	AF _{0.1-0.5}	AF _{0.4-0.8}	AF _{0.7-1.1}
(m)	(-)	(-)	(-)	(-)	(-)	(-)	(-)	(-)	(-)	(-)	(-)	(-)
Control point x _r	0.2	0.2	0.2	0.2	0.5	0.5	0.5	0.5	0.8	0.8	0.8	0.8
Case I												
-	1.24	1.28	1.42	1.66	1.24	1.28	1.45	1.72	1.32	1.30	1.50	1.72
2	1.16	1.24	1.40	1.66	1.16	1.32	1.51	1.78	1.33	1.30	1.52	1.74
4	1.12	1.17	1.37	1.63	1.19	1.32	1.55	1.83	1.34	1.31	1.54	1.75
6	1.24	1.12	1.30	1.51	1.40	1.31	1.60	1.93	1.36	1.32	1.56	1.76
8	1.14	1.03	1.18	1.37	1.25	1.20	1.58	2.01	1.38	1.38	1.61	1.81
Case II												
-	1.11	1.22	1.57	1.30	1.32	1.36	1.40	1.22	1.08	1.25	1.26	1.12
1	1.36	1.22	1.61	1.29	1.26	1.31	1.43	1.21	1.08	1.21	1.27	1.11
2	1.16	1.20	1.64	1.30	1.15	1.24	1.45	1.21	1.05	1.20	1.29	1.12
4	0.93	1.13	1.68	1.31	1.13	1.21	1.52	1.24	1.05	1.17	1.32	1.14
8	0.69	1.09	1.78	1.37	0.98	1.21	1.66	1.31	1.30	1.27	1.42	1.21

Table 3. Amplification factors at $x_r = 0.2$, 0.5, and 0.8 for Case I and II with and without a shear band.

Figures 11 and 12 show the plots of the horizontal and vertical components of the surface motions recorded at three control nodes on the ground surface for Case I and Case II, respectively. The relative normalised distance of the nodes (i.e., x_r) is shown in the figures. It might be noted that, for the intact soil slope (i.e., figures entitled "no s.b."), the directivity of the surface motion is in accordance with the slope inclination, both for Case I and Case II. The presence of the weakened zone causes an increase in the earthquake's vertical components, while the horizontal ones tend to reduce. This is more evident for the accelerations recorded at the ground surface of the Case I model at $x_r = 0.2$ and 0.5 when the thickness of the shear band is 8 m and 16 m (Figure 11) and at the ground surface of the Case II model at $x_r = 0.2$ and 0.5 for a shear band thickness of 4 m and 8 m (Figure 12). Moreover, the acceleration seems to be orthogonal to the ground surface in Case II at $x_r = 0.2$ for a shear band thickness of 8 m, thus showing a prevailing effect on the ground motion modification of the weak zone presence on the topographic effect. Therefore, the ground motion polarisation in the vertical plane is somehow influenced by the presence of a thick shear band, thus confirming what has been observed, for example, by Del Gaudio and co-workers [52,54,55], through HVSR measurements on quiescent landslide bodies. Nevertheless, the 2D numerical simulations performed in this work do not allow us to estimate the polarisation of the motion induced in the horizontal plane by the landslide body (e.g., [41,82]). This effect could only be captured through a comprehensive study based on 3D numerical simulations [83], which is out of the scope of the paper.

The percentage difference between the AFs calculated for slope models with and without shear band can be quantified through the following expression:

$$\Delta_{AF} = \frac{AF_{\text{with shear band}} - AF_{\text{without shear band}}}{AF_{\text{without shear band}}} \cdot 100$$
(3)



Figure 11. Surface motions recorded in the control nodes at the ground surface for Case I.

90

80

50 40

0.030

0.015

0.000

-0.015

-0.030 0.030

0.015

0.000

-0.015

-0.030 0.030

0.015

0.000

-0.015

-0.030

 $a_{\rm Z}\left(g\right)$

 $a_{\rm Z}\left(g\right)$

 $a_{\rm Z}\left(g\right)$

(≘ ⁷⁰ ≈ 60





Figure 12. Surface motions recorded in the control nodes at the ground surface for Case II.

Figures 13 and 14 illustrate the Δ_{AF} profiles relative to Case I and II, respectively. For Case I, the Δ_{AF} referring to the horizontal component are in the range ±40%, while the percentage differences in the AFs of the vertical motion are much higher, especially above the crest and at the toe of the slope, reaching a maximum value of about 150% in the case of the Δ_{AF} calculated in the period range 0.1–0.5 s. Considering Case II, the presence of the shear band affects the amplification factors calculated in the low period ranges and the Δ_{AF} referring to the PGA of the vertical component attains its maximum of 200% at the crest of the slope when a weakened zone of 8 m is considered. In general, the effect of the pre-existing shear band seems to be more pronounced on the vertical motion rather than on the horizontal one.



Figure 13. Profiles of the percentage difference between the AFs calculated with and without shear band relative to Case I.



Figure 14. Profiles of the percentage difference between the AFs calculated with and without shear band relative to Case II.

With the purpose of separating and distinguishing the geometric effects (i.e., ground motion modifications induced by the uneven topography and by the buried morphology) from the stratigraphic effects, the latter related to the presence of different soft materials in the subsoil, additional 1D FE seismic analyses were performed with reference to 1D soil columns characterised by the same soil stratigraphy and depth as that extracted from the 2D FE models along the vertical passing through the observation points at $x_r = 0.2$. Figure 15 shows the surface response spectra of the horizontal accelerations obtained at $x_r = 0.2$ by means of 1D and 2D numerical schemes for Case I, while Figure 16 presents the same comparison for Case II. The 2D results are different from those obtained with the 1D models, with higher spectral accelerations predicted by the 1D scheme in almost all the investigated cases. Greater differences are observed for the gentle slope case with respect to the steep slope case. The comparison between 2D and 1D response spectra in the case without a shear band gives evidence to solely the topographic effects. The discrepancies between 1D and 2D response spectra predicted by the models, including the shear bands,

are, instead, related not only to the sloping topography but also to the morphology of the weakened area. This confirms that the site response at the surface is affected by both the geometrical shape and thickness of the weakened zone. Moreover, it is worth noting that 1D models cannot predict the vertical motion induced by the geometric effect, which is related to topography and buried morphology, while the 1D horizontal ground motion seems to be consistent with the 2D horizontal response.



Figure 15. Case I surface response spectra of the horizontal accelerations obtained at $x_r = 0.2$ by means of 1D and 2D numerical models.

Finally, the numerical results are illustrated in terms of amplification functions determined as the ratio of the Fourier spectra obtained at the ground surface and at the interface between the soft soil and the bedrock. The amplification functions, shown in Figure 17, are referred to as the control points at $x_r = 0.2$, 0.5 and 0.8 for the two analysed case studies.



Figure 16. Case II surface response spectra of the horizontal accelerations obtained at $x_r = 0.2$ by means of 1D and 2D numerical models.

With reference to Case I, it might be observed that the fundamental frequency, f_0 , is not particularly affected by the presence of the shear band, attaining a value of about 1 Hz independently of the shear band thickness, while all the other natural frequencies reduce for the increased thickness of the band, apart from $x_r = 0.8$ (i.e., near the toe). The f_0 for 1D and 2D models can be evaluated through Equations (4) and (5), respectively, according to [1,84]:

$$f_{0_{-1}D} = \frac{V_S}{4 \cdot H} \tag{4}$$

$$f_{0_2D} = \frac{V_S}{5 \cdot H}$$
(5)

where H is the thickness and V_S is the shear wave velocity of the soft soil layer. Hence, considering V_S = 400 m/s and H = 80 m for Case I, $f_{0_{1D}}$ and $f_{0_{2D}}$ are equal to 1.00 Hz and 1.25 Hz, respectively. The f_0 values obtained by means of the numerical simulations range between 1.00 and 1.25 Hz. In particular, the second and the third natural frequencies reduce

to about 40% when considering the 16 m thick shear band with respect to the case of intact soil (i.e., no shear band) for $x_r = 0.2$ and 0.5. A similar pattern might be recognised for Case II simulations. Indeed, for the three selected nodes on the ground surface, the fundamental frequency f_0 remains in the range of 2.00–2.50 Hz, while the higher natural frequencies seem to undergo a reduction dependent on the shear band thickness. In this case, the second natural frequency, equal to 8.5 Hz in the absence of the shear band, decreases to 6.5 Hz at $x_r = 0.2$ when the weakened zone is 8 m thick. The other natural frequencies at $x_r = 0.5$ and 0.8 are, instead, not easy to detect. Furthermore, the amplification peak amplitude Af₀ corresponding to the fundamental frequency f₀ is strongly dependent on the thickness of the weakened zone (e.g., [83,85]). As an example, a significant reduction from a value of 10 in the case of the intact soil to about 7 for the thickest shear band was recognised at $x_r = 0.5$ in Case I, while at $x_r = 0.8$, the Af₀ was about 10 disregarding the presence of the shear band.



Figure 17. Amplification functions referred to $x_r = 0.2$, 0.5, and 0.8 for Case I and Case II.

The profiles of Af_0 along the slope surface are depicted in Figure 18, revealing the complex correlation between the thickness of the shear band and the amplification response. For Case I, the Af_0 profiles for the higher thicknesses of the weakened zone (i.e., 8 and 16 m) are much lower than those achieved with the thinner bands, indicating a damping effect on the fundamental frequency, which increases with the thickness of the weakened zone. Shear bands of 2 m and 4 m thickness generate higher Af_0 in the middle–top part of the slope (between 800 m and 1300 m) with respect to the case of no shear band. Additionally, in Case II, a more pronounced amplification of the first natural frequency can be observed near and beyond the crest area when weakened zones of 1 and 2 m are included in the numerical model, while the 8 m thick shear band causes a peak in the Af_0 profile just above the crest.



Figure 18. Profiles of the amplification amplitude Af_0 at the fundamental frequency f_0 for Case I and Case II.

Referring to slopes without a pre-existing shear band or, in general, without a quiescent landslide body, other researchers (e.g., [83,84,86,87]) have proved that the profiles of Af₀ from numerical analysis are in satisfactory agreement with the Af_0 profiles obtained through ambient noise measurements (e.g., HVSR). On the other hand, no example of Af₀ profiles for slopes with a pre-existing shear band has been provided by other authors who, instead, have focused their attention on the directivity effect on the HVSR measurement induced by a buried morphology [52,54,55,82,88]. Furthermore, Figure 18 shows that the Af₀ profiles are correlated to the slope inclination and to the presence of a shear band. In detail, the Af_0 profiles are correlated to the thickness of the shear band. Moreover, for a fixed thickness of the weakened zone and a fixed slope inclination, different geometries of the shear band are expected to provide different Af_0 profiles. In this context, bearing in mind that rapid population growth often forces the urbanisation of quiescent or unstable areas, the comparison between ambient noise measurements (e.g., HVSR) and preliminary slope modelling results (such as those presented in Figure 18) could support and guide the design of site-specific investigations with depth, aimed at better constraining the buried morphology of the landslide body (e.g., [82,88–90]). The following working flow could be considered in these cases:

- (1) geomorphological analysis of the area of interest;
- (2) collection of soil data (physical and mechanical properties) from available archives;
- (3) definition of a preliminary site model including the buried morphology (i.e., shape and thickness of the shear band);
- (4) ambient noise measurements aimed at providing Af_0 profiles;
- (5) performing a parametric analysis by means of numerical simulations based on the preliminary site model and varying the shape and the thickness of the shear band;

- (6) comparison between numerical results and site data in terms of Af_0 profiles;
- (7) selection of the most suitable site model which gives comparable results with site data;
- (8) design and execution of site-specific investigations (e.g., continuous coring borehole, inclinometers, etc.) in order to verify the site model selected at the previous point;
- (9) release of the definitive subsoil geotechnical model.

4. Conclusions

This paper presents some preliminary results on the influence of pre-existing shear bands, confining a landslide body, on the seismic wave propagation processes of two steplike ideal slopes subjected to weak earthquakes, performed through a 2D finite element approach. Two ground surface configurations, representing gentle and steep natural slopes, were analysed, whose geometry was appropriately selected to consider the occurrence of negligible and high topographic amplification effects. The pre-existing shear bands were implemented in the numerical models as weakened zones of reduced mechanical properties with respect to the surrounding soil, characterised by different thicknesses. Since the plasticity-induced effects are beyond the scope of the paper, the bedrock input motions were scaled to a very low peak acceleration, while the slope soils were modelled as a linear visco-elastic material.

The results of the numerical simulations indicate that the presence of a pre-existing shear band may significantly affect the dynamic response inside the slope and at the ground surface. In the case of a gentle natural slope (i.e., Case I), for which negligible topographic amplification was expected, a higher thickness of the weakened zone and higher peak values of the amplification factors were recorded. For steep slopes (i.e., Case II, for which high topographic effects are predictable), instead, only the AFs calculated in terms of PGA and in the lower period range are influenced by the presence of the shear band. In particular, for gentle slopes affected by a landslide body confined by a thick shear band, the highest amplification factors are expected in the longer period range of 0.7–1.1 s, while the highest level of amplification is achieved in the intermediate period interval of 0.4–0.8 s in the case of steep slopes. Moreover, the parasitic vertical component may be pronounced, especially in the case of steep topography, for which the effects of the shear band morphology enhance those related to the topographic profile. Indeed, the presence of a thick shear band may force the polarization of the ground motion in the direction normal to the slope surface. Finally, it is shown that the fundamental frequency of the deposit is not particularly affected by the presence of the shear band along the slope for the analysed case studies, while the amplitude of the amplification function at the fundamental frequency is clearly related to the thickness of the shear band. As a matter of fact, more complex shear band geometries or thicker weakened zones are expected to modify also the f_0 values with respect to the case of the intact soil (i.e., without the shear band).

The numerical study highlights the importance of considering the actual position, shape and thickness of a pre-existing shear band in the site response analysis of natural slopes performed from a seismic risk mitigation perspective (e.g., microzonation studies). Therefore, the subsoil geotechnical model should be based on detailed site investigations aimed at identifying and geometrically locating the possible weakened zone, even if the slope area of interest is characterised by a non-active sliding mechanism. Conversely, bearing in mind that site investigations in unstable areas are generally expensive, the numerical results of seismic site response based on preliminary slope modelling could be compared to ambient noise measurements in order to support the design of invasive investigations with depth tailored at better constraining the buried morphologies of the body of the landslide.

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