



# Article Runoff Estimation Using Advanced Soft Computing Techniques: A Case Study of Mangla Watershed Pakistan

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Abstract: A precise rainfall-runoff prediction is crucial for hydrology and the management of water resources. Rainfall-runoff prediction is a nonlinear method influenced by simulation model inputs. Previously employed methods have some limitations in predicting rainfall-runoff, such as low learning speed, overfitting issues, stopping criteria, and back-propagation issues. Therefore, this study uses distinctive soft computing approaches to overcome these issues for modeling rainfallrunoff for the Mangla watershed in Pakistan. Rainfall-runoff data for 29 years from 1978–2007 is used in the study to estimate runoff. The soft computing approaches used in the study are Tree Boost (TB), decision tree forests (DTFs), and single decision trees (SDTs). Using various combinations of past rainfall datasets, these soft computing techniques are validated and tested for the security of efficient results. The evaluation criteria for the models are some statistical measures consisting of root means square error (RMSE), mean absolute error (MAE), coefficient of determination (R<sup>2</sup>), and Nash-Sutcliffe efficiency (NSE). The outcomes of these computing techniques were evaluated with the multilayer perceptron (MLP). DTF was found to be a more accurate soft computing approach with the average evaluation parameters R<sup>2</sup>, NSE, RMSE, and MAE being 0.9, 0.8, 1000, and 7000 cumecs. Regarding  $\mathbb{R}^2$  and RMSE, there are about 57% and 17% of improvement in the results of DTF compared to other techniques. Flow duration curves (FDCs) were employed and revealed that DTF performed better than other techniques. This assessment revealed that DTF has potential; researchers may consider it an alternative approach for rainfall-runoff estimations in the Mangla watershed.

Keywords: artificial intelligence; forecasting; rainfall-runoff; Indus basin; modelling

# 1. Introduction

Rainfall is the most prominent feature among all variables while dealing with hydrological issues because it varies temporally and spatially [1]. It is the primary source of runoff that helps mitigate the impact of droughts and floods on the water resource system. Pakistan and all other developing countries are facing drought and flooding more frequently [2]. So, to address these drought and flood issues, the estimation of runoff generated from the rainfall event is vital. In the transition of precipitation into a runoff, precipitation finally transforms into a runoff after fulfilling various losses such as interception, depression storage, infiltration, and evaporation [3,4]. Runoff is a complex and nonlinear outcome of rainfall and watershed properties. There are numerous modeling methodologies for the rainfall-runoff process [5]. This complicated and nonlinear relationship between rainfall



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**Copyright:** © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). and runoff has been modeled in various ways. These methods can be separated into two categories: data-driven models and theory-based models [6]. Theory-based models include conceptual and physically based models, whereas data-driven models include empirical and black-box models. The sub-processes and physical mechanisms of the hydrological cycle are elaborated through conceptual models. In conceptual models, geographical variability and stochastic properties of rainfall-runoff processes are disregarded. Using differential equations, physically based models estimated the various components of the hydrological cycle. In contrast, data-driven models treated the hydrological system as a black box and established a link between rainfall-runoff and desired parameters [7,8]. Therefore, these data-driven approaches are preferred over theory-driven models. These models have great importance because less data is required, the area of expertise is superior, and a massive amount of data can be modeled efficiently and quickly [9]. Artificial neural network (ANN) [10], adaptive neuro-fuzzy inference system (ANFIS) [11], genetic programming (GP) [12], gene expression programming (GEP) [13], and support vector machine (SVM) are the most prevalent data-driven techniques used in hydrology [14]. Multilayer perceptron neural network (MLPNN)-a variation of ANN-is utilized most frequently in the literature to represent the rainfall-runoff process [15]. ANN was used to determine the daily watershed runoff of Cahaba River, Alabama [16]. For the estimation of runoff, [17] used three data-driven methodologies including ANN with a back-propagation algorithm (BPA), a real coded genetic algorithm (RGA), and a self-organizing map (SOM). In the rainfall-runoff investigation, BPA yielded poor performance, whereas RGA and SOM yielded comparable outcomes. [18] performed a study on modeling the discharge of the Bah Bolon Watershed in Indonesia and determined that ANN with two to three hidden layers for twelve months is optimal. An artificial neural network was used successfully to model daily and monthly runoff computations in several hydrological studies [3,9,19–27]. SVM is the statistical learning technique used for water table depth estimation and streamflow forecasting [4,28–33]. Gene expression programming (GEP) and ANFIS examine hydrological concerns such as flood and river flow forecasting [34,35]. Although different data-driven models are utilized for rainfall-runoff analysis modeling, as stated previously, some data-driven approaches have not yet been used. Among these methods are decision trees. A DT is a method for extracting valuable information from raw data. [36] employed four techniques to reduce the decision trees for classifying hypothyroid disorders. [37] introduced a coupled tree model for predicting water flow and quality. The model has been applied to the Meshushim watershed, a sub-basin watershed inside Lake Kinneret in Israel and Lebanon. [38] compares the ANN and M5 model trees for estimating the wave height of a superior lake. Wind velocity and wave height output are the input variables for data-driven models. The results demonstrate that the M5 model tree is superior to ANN. Using remote sensing data, [39] developed a decision tree to estimate land cover. Comparing the multivariate regression spline, support vector machine (SVM), and M5 tree model based on statistical parameters, [40] conclude that the M5 tree model is the most effective. [41] studied the structural dependability of data. The study concluded that Monte Carlo simulation (MCS) and the M5 tree model are preferable for reducing the probability of failure. These data-driven models, including decision trees, DTFs, and TB, are less dataintensive solutions for successful networking than the other options that are now available. A data mining method known as DTs is used for an entire dataset to extract important information from it. These data mining techniques are beneficial for determining runoff because tree pruning reduces entropy and misclassification mistakes, thereby increasing the findings. As a result, these strategies are quite beneficial. Estimating runoff is accomplished using SDTs, TB, and DTFs; three different data mining methodologies. The computation of runoff is carried out in an effective manner once these three methods have been applied. After the runoff has been computed, the results are then compared to MLP. The term "back propagation neural networking" more commonly refers to MLP, which is a mathematical framework of neurons that creates outcomes by making use of mathematical functions.

As far as the authors are aware, no work has been performed on the SDTs, DTFs, and TB to simulate the rainfall-runoff process in the Mangla watershed. This study is designed and executed to evaluate SDTs, DTFs, and TB approaches for rainfall-runoff modeling capability. This study seeks to compute the runoff resulting from recent and past precipitation in the Mangla basin of Pakistan. The main objective of this study is to estimate the potential of data mining approaches to estimate runoff and compare SDTs, DTFs, and TB with the MLP.

## 2. Materials and Methods

DTREG [42] is used as the predictive software in this study. DTREG (pronounced D-T-Reg) develops neural networks, classification, and regression decision trees. DTREG receives a data set with any number of rows and one column per variable. The "target variable," whose value is to be modeled and forecasted as a function of the "predictor variables," is one of the variables. DTREG examines the information and develops a model that predicts the target variable's values based on the predictor variable's values. DTREG can generate traditional SDTs and TB and DTF models comprised of ensembles of many trees [43].

## 2.1. Single Decision Trees (SDTs)

There are three main components of SDTs: edges, leaves, and terminals. Edges proceed toward the child node. Leaves entail connecting nodes to another node; the terminal node represents the output value following tree construction [43]. SDTs comprise two phases for tree generation. The first phase involves tree growth, whereas the second part involves tree pruning. The data will be constructed in ascending order during tree construction. Tree trimming eliminates or adjusts data that cause noise or have a high entropy level; after pruning the data tree, a regression or classification tree is constructed depending on the given data (continuous or categorical). DTREG [42] will use a variety of variables in a class of variables, including target, predicted, and weight variables. The association between the goal and predicted variables is created in tree building; the weight variable establishes the weight between nodes via edges. The data variables are assigned equal weights if no weight variable is supplied to the data row. If the data variables are continuous, DTREG separates the data based on petal length after randomly selecting data. If the data variables are categorical, the petal width will be used to split the data. The node represents the predicted and desired variables. The splitting variable will be shifted to the child node to continue building the tree. Random data will be separated using regression analysis and the tree technique, as well as misclassification error and probability [22]. Figure 1 depicts the complete schematic diagram of SDTs.

No. of splits = 
$$2^{(k-1)-1}$$
 (1)

No. of terminal nodes = 
$$2^k$$
 (2)



Figure 1. Basic structure of decision tree.

#### 2.2. Decision Tree Forests (DTFs)

The DTFs assign data of desired continuous or categorical variables to the model. Numeric values represent continuous data and alphabetic or character variables represent categorical data. The data are going to be partitioned according to the misclassification error. A misunderstanding of the classification led to the initiation of the investigation into structural dependability. The Monte Carlo simulation, the simplified order reliability method (SORM), and the first-order reliability method (FORM) are examples of strategies or approaches that can be used to estimate the likelihood of a failure occurring. These methods are utilized to determine how successful reliability analysis truly is. A tree will be built for each attribute to show how the attributes are related to one another. The node with the lowest rate of incorrect classification will be the root node, and logarithms incorporating the C 4.5 algorithm will be used to produce splitting from the note node [36].

In Figure 2, the data splitting and error elimination process will continue until either the terminal node is reached or the data misclassification error (ME) at the end of the terminal node becomes zero, at which time further data splitting will end. The output value can be seen on the terminal node generation's display.



Figure 2. Flow sheet diagram of decision tree forests.

Figure 3 depicts the entire working principle of DTFs.



Figure 3. Working principle of decision tree.

# 2.3. Tree Boost (TB)

Jerome H. Friedman is the pioneer stakeholder of this technique [44]. Another name for TB is stochastic gradient boosting and multiple regression trees. The algorithm or working principle is the same as tree forests. The only difference between TB and DTFs is the mode of construction. TB generates trees in a series pattern, whereas DTFs consist of a forest of trees in parallel. It is a technique that enhances accuracy by weighing output values to reduce total prediction error. The general working mechanism of the is shown in Figure 4.



Figure 4. Flow sheet diagram of Tree Boost technique.

# 2.4. Multi-Layer Perceptron (MLP)

Most hydrologists and researchers compute rainfall and runoff using artificial neural networks, the most well-known method. ANN consists of three layers: the input layer, the hidden layer, and the output layer. The input layer receives the information. The subsequent layer generates a beautiful link between rainfall data using algorithmic functions and other mathematical techniques. The final layer provides the output value. Jang introduced ANFIS in 1993 [11], consisting of five output interpretation layers. In layer 1, the membership function is used to associate variables with membership while layer 2 consists of nodes that establish a relationship with incoming signals. The third layer locks every node, the fourth layer computes each node's contribution to the output value, and the last layer provides the result. There are numerous varieties of ANN. MLPNN (multi-layer perceptron neural network) is utilized in hydrology [45]. In Figures 5 and 6, MLPNN is depicted as a network of input; hidden and neuronal output layers are all present. A layer comprises many neurons, each in the preceding layer linked to those in the next layer. Consider the input layer's output value as the hidden layer's input value.



Figure 5. Flow sheet diagram of MLP.



Figure 6. Multi-layer perceptron neural networks.

Similarly, the hidden layer's output value will be the output layer's input value. The neuron transfer function sends neurons between the hidden and output layers. There is no point link between the input and output layers.

The input layer receives the data. All neurons in this layer are linked and use mathematical functions to process data in the buried layer. The output layer receives input from the concealed layer and returns the anticipated value [22,35]. Six external inputs are supplied in the input layer of Figure 6. Each neuron in the input layer interacts with neurons in the layers beneath it. These values can be transmitted using mathematical functions, with the output layer being responsible for interpreting the resulting value.

#### 2.5. Study Area

This study focused on daily precipitation and runoff in the Mangla basin. The Mangla watershed is located at a latitude 33–35° N and longitude 73.62° E. As seen in Figure 7, the Mangla catchment's demographical borders are in Pakistan and India. It has a drainage area of 165,499.15 km<sup>2</sup>, making it the second-largest tributary in the world after the Indus basin [22]. The Mangla watershed is situated on the Jhelum River and has a storage capacity of 7.475 MAF and a drainage area of 33,333.15 km<sup>2</sup>. The runoff of the Jhelum River basin drains into the Mangla watershed. This catchment supplies irrigation and hydropower with water. Six million hectares of land are irrigated from this reservoir as part of a 1000 MW hydroelectric power-producing capability. The Jhelum and its tributaries, Neelam, Poonch, Kanshi, and Naran, make up the Mangla watershed. In the catchment area, precipitation and snowmelt generated runoff, representing the reservoir's intake. The water stored in various basins, such as the Neelam, Poonch, Kanshi, Jhelum, and Naran basin, will flow to the river Jhelum as runoff at the Mangla catchment.



Figure 7. Mangla catchment study area.

# 2.6. Dataset

There are twelve rain gauge stations in the boundary of the Mangla reservoir, as shown in Figure 7. Nine stations are in Pakistan while the remaining are in India. Table 1 contains information about these stations and Figure 7 depicts their location. These rain gauge stations allow us to mimic the runoff generated and dropping into the Jhelum River at the Mangla. The four rain gauge stations are in the Indian territory and cover a broad region for the contribution of runoff from the Mangla basin above the Jhelum River. Data on daily rainfall for 29 years from January 1978 to Dec 2007 from nine stations located in Pakistan is obtained in the Pakistan Metrological Department. The daily rainfall data of four stations outside of Pakistan are obtained from [46]. The rainfall data of these thirteen stations are averaged arithmetically to calculate the point of rainfall over the Basin. The corresponding discharge is the inflow to the Mangla reservoir used in this study.

Table 1. Statistics of rainfall stations in the Mangla catchment.

Name of Station	Elevation (MSL) in Meters	Latitude	Longitude	Mean Yearly Precipitation (Inches)	Mean Yearly Tem- perature (°C)	Country
Naran	2409	34.909° N	73.6507° E	1.83	19	Pakistan
Balakot	975	34.548° N	73.3532° E	48.7	25.1	Pakistan
Muzaffarabad	679	34.359° N	73.47105° E	45.67	27.6	Pakistan
Gharidopatta	817	34.225° N	73.6154° E	3.85	25.9	Pakistan
Murree	2291.2	33.907° N	73.3943° E	5.91	17.7	Pakistan
Plandri	1400	33.715° N	73.6861° E	5.91	21.8	Pakistan
Kotli	3000	33.518° N	73.9022° E	5.48	28.5	Pakistan
Rawlakot	1638	33.866° N	73.7666° E	19.99	24.7	Pakistan
Kupwaara	1522	34.033° N	74.266° E	42.00	13.9	India
Qazigund	1670	33.624° N	75.145° E	3.30	27.0	India
Gulmerg	2650	34.05° N	74.38° E	67.1	4.1	India
Sirinagar	5000	34.083° N	74.797° E	32.5	11.8	India

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#### 2.7. Performance Evaluation

While dealing with some hydrological processes, determining the model's goodness depends upon various statistical parameters, such as rainfall-runoff modeling. The current study employs four statistical evaluation metrics to determine the model's goodness. The basic formulas of these four statistical parameters are:

$$R^{2} = \frac{n(\sum xy) - (\sum x)(\sum y)}{\sqrt{n[\sum_{x} 2 - (\sum_{x} 2)][\sum_{y} 2 - \sum_{(y} 2)]}}$$
(3)

$$RMSE = \sqrt{\sum \frac{(Qobs - Qpre)^2}{N}}$$
(4)

$$MAE = \sum \frac{(Qpre - Qobs)}{N}$$
(5)

$$NSE = 1 - \sum \frac{(Qobs - Qmod)^2}{(Qobs - Qave)^2}$$
(6)

$$AIC = mln(RMSE) + 2n$$
(7)

For an efficient correlation between expected and observed values, R<sup>2</sup> is between 0 and 1. The model will be considered the most efficient when the correlation coefficient value approaches 1 or is equal to 1. The range of model efficiency RMSE values is between 0 and 1. The better the model, the lower the RMSE number, while the worse the model or data, the higher the RMSE value. Most hydrological studies provide NSE values as percentages [24,47]. In Equation (7), where m is the number of input–output training patterns, n is the number of parameters to be detected and RMSE is the root-mean-square error between the network output and target. The RMSE statistics are predicted to improve when more parameters are introduced to a model, whereas the AIC statistics punish the model for having more parameters and, as a result, tend to produce more parsimonious models [48].

# 3. Results

The current work aims to simulate the rainfall-runoff process using several methodologies, such as SDTs, TB, and DTFs, and then compare the findings of these models with MLP. This rainfall-runoff modeling uses several rainfall combinations to obtain statistically significant results. The input data employed in this study are the lagging rainfall data, whereas the desired output is the observed inflow into the Mangla reservoir. To forecast current runoff Q(t), the eleven input combinations of lagged precipitation are given in Table 2. Selecting a suitable collection of inputs is essential for accurate data-driven rainfall and runoff forecasting. We employed Akaike's information criterion (AIC) for the analysis inputs combination and the AIC values of selected input combinations shown in Table 2.

This study uses daily rainfall-runoff data spanning 29 years, beginning in January 1978 and ending in December 2007. The remaining data is utilized for validation and testing, while the first fifteen years of data, beginning in January 1978 and ending in December 1993, are used for training purposes. Lagged rainfall was used as the input data for the rainfall-runoff models, while present discharge served as the model's desired output. Prediction models were constructed utilizing the four applied approaches of SDTs, DTFs, TB, and MLP. The models' statistical evaluation is presented in Tables 3–10. During the training and testing of the models, it was observed that the error rate was acceptable and improved from the training to the test process with different input combinations. The error rate was improved as an acceptable value when input combinations were changed from a 1-day lag to a 10-day lag. Overall, the percent of improvement for DTFs in terms of R<sup>2</sup> was 57%; for RMSE, it was found to be a 17% improvement.

Input Combinations	AIC
P(t)	4.5432
P(t), P(t-1)	4.2015
P(t), P(t-1), P(t-2)	4.1534
P(t), P(t-1), P(t-2), P(t-3)	3.9812
P(t), P(t-1), P(t-2), P(t-3), P(t-4)	3.9678
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5)	3.9561
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5), P(t-6)	3.8911
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5), P(t-6), P(t-7)	3.6582
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5), P(t-6), P(t-7), P(t-8)	3.5121
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5), P(t-6), P(t-7), P(t-8), P(t-9)	3.3140
P(t), P(t-1), P(t-2), P(t-3), P(t-4), P(t-5), P(t-6), P(t-7), P(t-8), P(t-9), P(t-10)	3.1480

Table 2. The information criteria statistics of input combinations are used for runoff estimation.

**Table 3.** Training and testing results with Q(t) of different data mining techniques.

	Traini	vith P(t)		Testing Results with P(t)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.329	0.322	25,905.668	20,441.804	DTFs	0.247	0.245	23,431.452	18,356.359
SDTs	0.072	1.000	30,319.632	21,709.896	SDTs	0.116	0.116	25,354.221	19,403.642
TB	0.169	0.164	28,804.129	20,771.767	TB	0.118	0.093	25,975.933	18,769.243
MLP	0.145	0.144	29,107.893	21,653.686	MLP	0.163	0.163	24,671.509	19,676.838

Table 4. Training and testing results with Q(t-1) of different data mining techniques.

	Trainin	ith P(t-1)		Testing Results with P(t-1)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.607	0.573	20,552.859	16,087.144	DTFs	0.555	0.517	18,743.686	14,051.887
SDTs	0.283	0.283	26,655.355	20,296.326	SDTs	0.143	0.143	24,957.492	18,966.122
TB	0.247	0.234	27,574.589	19,787.896	TB	0.179	0.157	24,902.517	17,934.826
MLP	0.202	0.201	28,125.942	21,264.919	MLP	0.150	0.149	24,873.708	19,182.440

Table 5. Training and testing results with Q(t-2) of different data mining techniques.

	Trainin	ith P(t-2)		Testing Results with P(t-2)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.721	0.670	18,066.618	13,873.521	DTFs	0.684	0.625	16,512.014	12,073.647
SDTs	0.307	0.307	26,196.097	19,778.782	SDTs	0.180	0.180	24,422.021	18,304.985
TB	0.254	0.242	27,432.893	19,339.867	TB	0.185	0.159	24,930.989	17,685.465
MLP	0.214	0.214	27,899.405	20,915.020	MLP	0.138	0.137	25,058.222	19,672.974

Table 6. Training and testing results with Q(t-3) of different data mining techniques.

	Trainin	g Results w	ith P(t-3)		Testing Results with P(t-3)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE	
DTFs	0.861	0.812	13,654.807	9663.240	DTFs	0.829	0.776	12,776.157	8996.971	
SDTs	0.312	0.312	26,105.991	19,558.401	SDTs	0.184	0.184	24,360.689	18,264.990	
TB	0.257	0.246	27,367.762	19,095.066	TB	0.203	0.167	24,850.153	17,518.771	
MLP	0.217	0.217	27,850.550	20,693.155	MLP	0.164	0.160	24,717.335	19,418.675	

	Trainin	ith P(t-4)		Testing Results with P(t-4)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.892	0.838	12,669.483	8868.312	DTFs	0.863	0.803	11,980.313	8415.763
SDTs	0.294	0.294	26,447.197	19,776.773	SDTs	0.200	0.200	24,118.012	18,123.016
TB	0.267	0.257	27,152.242	18,731.501	TB	0.298	0.288	22,771.702	16,219.624
MLP	0.214	0.214	27,906.102	20,439.615	MLP	0.144	0.144	24,957.346	19,268.403

Table 7. Training and testing results with Q(t-4) of different data mining techniques.

Table 8. Training and testing results with Q(t-5) of different data mining techniques.

	Trainin	ith P(t-5)		Testing Results with P(t-5)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.910	0.859	11,802.909	8361.152	DTFs	0.886	0.822	11,381.253	8046.244
SDTs	0.296	0.296	26,405.846	19 <i>,</i> 680.738	SDTs	0.201	0.201	24,107.606	18,224.162
TB	0.317	0.310	26,148.224	18,184.550	TB	0.281	0.267	23,123.848	16,485.957
MLP	0.234	0.234	27,556.290	20,657.409	MLP	0.161	0.160	24,719.766	19,027.579

Table 9. Training and testing results with Q(t-8) of different data mining techniques.

	Trainin	ith P(t-9)		Testing Results with P(t-9)					
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.943	0.884	10,728.798	7399.087	DTFs	0.934	0.871	9672.249	6975.412
SDTs	0.302	0.302	26,299.122	19 <i>,</i> 562.380	SDTs	0.216	0.216	23,882.899	17,811.067
TB	0.293	0.274	26,855.594	18,116.157	TB	0.375	0.359	21,614.152	15,211.614
MLP	0.230	0.230	27,622.395	19,999.241	MLP	0.117	0.089	25,938.759	20,903.000

Table 10. Training and testing results with Q(t-10) of different data mining techniques.

	th P(t-10)	Testing Results with P(t-10)							
Model	R2	NSE	RMSE	MAE	Model	R2	NSE	RMSE	MAE
DTFs	0.945	0.885	10,671.543	7273.468	DTFs	0.940	0.876	9511.740	6840.659
SDTs	0.325	0.325	25,870.455	19,120.118	SDTs	0.217	0.217	23,867.600	17,791.516
TB	0.351	0.339	25,613.232	17,437.303	TB	0.325	0.308	22,469.118	15,777.656
MLP	0.215	0.214	27,903.246	20,319.296	MLP	0.145	0.144	24,965.553	19,058.321

Table 3 demonstrates that DTF was superior to the other three methods. The  $R^2$  and NSE values for DTF training and testing range between 0.24 to 0.32. The RMSE and MAE are approximately 24,000 and 19,000 cumecs.  $R^2$  and NSE values for SDT are between 0.10 and 0.11 to 1 for training and testing. The figures for RMSE and MAE range between 27,000 and 20,000 cumecs.  $R^2$  and NSE range between 0.15 and 0.10 for TB, whereas the other statistical measures, RMSE, and MAE, range between 26,000 and 19,000 cumecs. The typical technique MLP has a training and testing value of 0.15 for both  $R^2$  and NSE.

RMSE and MAE performance for MLP ranges between 25,000 and 20,000 cumecs. In addition, Table 3 demonstrates that the performance parameters of TB and MLP are nearly identical. SDT's performance is underrated in comparison to the other three approaches. The bold results from Tables 3–10 shows the best overall outputs of models applied in rainfall runoff prediction. In a manner analogous to Table 3, the performance of the DTFs is superior to that of the other three applied models, while the performance of the TB and MLP is comparable. Table 4 reveals that the values for R<sup>2</sup> and NSE for the DTFs fall in the range of 0.5 to 0.6, while the values calculated for RMSE and MAE are approximately 14,000 to 20,000 cumecs. The values of R<sup>2</sup> and NSE for SDTs are both 0.20, regardless of whether the model is being trained or tested, whereas the values of RMSE and MAE range between 25,000 and

19,000 cumecs. The TB values for R<sup>2</sup> and NSE are 0.20 and 0.18, respectively. RMSE and MAE both perform at a level of 25,000 to 18,000 cumecs. Both the training and testing phases of the MLP have  $R^2$  and NSE values of 0.17 and 0.18, respectively. In the case of MLP, the performance evaluation of RMSE and MAE ranges from around 26,000 to 20,000 cumecs. All these results from Table 4 indicate that MLP is less efficient for analyzing runoff when a combination of the three is used. Table 5 shows that the values of  $R^2$  and NSE are determined within the range of 0.6 to 0.7 for both training and validation for the DTFs. RMSE and MAE both have values that range between 16,000 and 12,000 cumecs. The values of  $\mathbb{R}^2$  and NSE are the same, with a value of 0.20, for both the training and the testing phases. RMSE and MAE both have performances that fall somewhere in the range of 25,000 to 18,000 cumecs. For TB, the values for  $\mathbb{R}^2$  and NSE range from 0.21 to 0.19 for training and testing analyses, whereas the values range from around 25,000 to 20,000 cumecs for RMSE and MAE. Table 8 shows that the values of  $R^2$  and NSE for DTFs range from 0.86 to 0.81, while RMSE and MAE are between 13,000 and 9000 cumecs. SDTs show 0.25 for  $R^2$  and NSE, but 25,000 and 19,000 cumecs for RMSE and MAE. TB's training and testing NSE and  $R^2$  are 0.23 and 0.18, respectively. RMSE and MAE for TB ranges from 25,000 and 18,000 cumecs. MLP has the same values, 0.19 for R<sup>2,</sup> NSE, and 25,000 and 19,000 cumecs for RMSE and MAE. The findings in Table 7 indicate that the DTF is a more effective solution than SDT, TB, and MLP. The training and testing stages produce  $R^2$  and NSE values for the DTF in the range of 0.89 and 0.83, while the RMSE and MSE values produce 13,000 and 9000 cumecs, respectively. In the SDT, 0.25 is specified for  $R^2$ , and the exact value is specified for NSE. RMSE and MAE are between 25,000 and 19,000 cumecs. R<sup>2</sup> is found to be 0.26 using the TB technique, and NSE is 0.27. The final RMSE and MAE values fall somewhere in a range that goes from 24,000 to 17,000 cumecs. The exact value of 0.17 is shown for MLP's  $R^2$ and NSE. In contrast, RMSE and MAE range from 20,000 and 25,000 cumecs, respectively. Table 8 shows that R<sup>2</sup> and NSE for DTFs are between 0.90 and 0.80. RMSE and MAE are 12,000 and 9000 cumecs. SDTs and TB have a 0.25 square correlation and NSE. RMSE and MAE are 250,000 and 180,000 cumecs. 0.20 is MLP's R<sup>2</sup> and NSE. RMSE and MAE range from 25,000 to 19,000 cumecs. MLP is underestimated compared to DTFs, TB, and SDTs. MLP has a lower potential than other techniques. Table 9 reveals that the  $R^2$  and NSE values for DTFs are in the region of 0.9 to 0.8, giving it an advantage over TB, SDTs, and MLP. It is evidenced by the fact that DTFs come out on top. The results for RMSE and MAE range between 10,000 and 8000 cumecs. R<sup>2</sup> and NSE have 0.25 and 0.27 for SDTs, whereas RMSE and MAE have 25,000 and 17,000 cumecs, respectively. TB has an  $R^2$  value of 0.35 and an NSE value of 0.30. Its RMSE value is 24,000 cumecs and its MAE value is 16,000 cumecs. The minimum likelihood proportionate has the lowest value of any statistical parameter. These are the results for R<sup>2</sup>, NSE, RMSE, and MAE: 0.20, 0.18, 26,000, and 18,000 cumecs, respectively. The DTFs models were the most accurate based on the  $R^2$ , and NSE values lie between 0.9 and 0.8, as shown in Table 10. The RMSE and the MAE come in at 10,000 cumecs and 7000 cumecs, respectively. R<sup>2</sup> values of 0.30 and NSE values of 0.27 are comparable for SDTs and TB, whereas RMSE values of 24,000 cumecs and MAE values of 17,000 cumecs are reported for each. The MLP model has a value of 0.19 for R<sup>2</sup> and a comparable amount for NSE. However, the RMSE value is 25,000 cumecs and the MAE value is 19,000 cumecs.

Figure 8a,b depicts the performance parameters R<sup>2</sup>, NSE, MAE, and RMSE for each input combination for the best DTFs model to examine the effect of the previously mentioned input combinations.

Figure 8a demonstrates the variation in R<sup>2</sup> across input combinations. Figure 8a shows an increase in R<sup>2</sup> values from input combination 1 with a single P(t) precipitation value to input combination 4, which has P(t), P(t-1), P(t-2), and P(t-3) precipitation data, followed by a constant value. Figure 8b shows a similar pattern for NSE fluctuations. Similarly, Figure 8a,b illustrates the fluctuation of RMSE and MAE, respectively, with selected input combination changes. (c) depicts the overall RMSE and MAE values. Figure 8a,b demonstrates a significant reduction in error values from input combinations up to the input

combination, which is consistent with the R<sup>2</sup> and NSE values (4). According to the findings, it is possible to assert that the precipitation P(t), P(t-1), P(t-2), and P(t-3) contain complete data about the watershed's hydrological signature and that there is no vital information hidden in the lag precipitation data. This assertion can be supported by stating that the lag precipitation data do not contain any relevant information.



Figure 8. (a,b) Impact of input combinations on the performance.

The flow duration curves (FDC) in Figure 9 were developed to test the efficacy of developed models in projecting low, medium, and high flows. Figure 9a-d are FDCs generated with various combinations of precipitation and lag precipitation series, such as 1-day precipitation, lag-3-day precipitation, lag-5-day precipitation, lag-8-day precipitation, and lag-10-day precipitation, respectively. The flows on these FDCs can be classed as low, medium, or high. If the flow range with exceedance probability is between 0 and 10, the flow is classified as high. If it is from 11 to 89, the flow is classified as medium, which further separates into two classes: low-medium if the flow ranges from 11 to 49, and high-medium if the flow runs between 50 and 89. The discharge is below the 50th percentile when it exceeds 89 [15]. It can be shown from Figure 9a that DTFs and MLP both underestimate the observed discharge for all three high, medium, and low flows. Figure 9b illustrates that MLP and DTFs tie for high and high medium flow with observed discharge. Figure 9c represents DTFs and MLP, which are comparable for high and medium flow. MLP underestimates the observed discharge in the region of low flow and low, medium flow. Figure 9d shows that DTFs capture the high, medium, and low flow with observed discharge better than MLP, and the last Figure 9e directs the best relationship with observed discharge for DTFs, including high, medium, and low flow.



**Figure 9.** (a) FDCs between DTF, MLP and Qobs with input combination R(t). (b) FDCs between DTF, MLP and Qobs with input combination R(t-3). (c) FDCs between DTF, MLP and Qobs with input combination R(t-5). (d) FDCs between DTF, MLP and Qobs with input combination R(t-8). (e) FDCs between DTF, MLP and Qobs with input combination R(t-10).

# 4. Discussion

The DTF was the best technique in the training and testing applied soft computing techniques, such as MLP, SDTs, DTFs, and TB. The average values of R<sup>2</sup> and NSE discovered during the training and testing of models were found to be more than other techniques, as shown in Tables 5–10. The percent of improvement in terms of  $R^2$  and RMSE in the outputs of DTFs up to the maximum value of 57% and 17%, respectively, compared to other techniques. Many researchers quoted that results from DTFs are generally equal to 1 and many others [22,49,50]. R<sup>2</sup> is one of the most significant model evaluation criteria that many hydrologists and researchers have found and utilized for predicting and forecasting the behavior of various hydrological cycle components [30]. The RMSE findings of all the different input combinations demonstrated that the DTFs have a higher ability to predict rainfall and runoff than SDTs and TB while the models are being trained and tested. The reduced value of the root-mean-square error (RMSE) demonstrates that the model is accurate [51]. DTFs and SDTs were previously used for streamflow forecasting and showed good potential [22]. In Figure 8a,b, TB and SDTs demonstrated the most effective results of 1.00 in training modeling techniques at all stations, according to the NSE results for both train and test cases of soft computing techniques. SDTs, TB, and MLP showed less efficient results. The higher NSE value shows the models' efficiency [52]. Figure 8a,b shows that the DTF has better runoff prediction than SDT and TB, according to RMSE values. DTF is a more effective MLP than the conventional one [22]. A smaller value of the RMSE indicates the model's fitness [53]. So, the DTFs are the most effective technique for rainfall and runoff prediction for the Mangla watershed, according to NSE results previously mentioned by [54]. Figure 9 shows that hydrographs of the low, medium, and high streams were made using soft computing techniques such as SDTs, DTFs, and MLP to analyze their capability. These techniques were used to create the hydrographs. DTFs have good potential for predicting runoff. For the evaluation of catchment features, the lower and upper regions of the FDCs are essential parts. The low flow component of the FDC indicates how well the catchment can support itself during hot and dry weather. The catchment is likely to have the flood regime indicated by the high flow portion [7,15].

In contrast to the considerably smoother curves towards the upper portion, which are due to floods caused by snowmelt, steep curves show floods mostly driven by rain in small catchments. The flat curves in the low flow region represent flows resulting from either natural or artificial streamflow [15]. SDTs, DTFs, TB, and MLP were tested in the observed hydrographs with high, medium, and low flows. Numerous investigations from the past have shown that the FDCs' demonstrations of exceedance probability versus the simulated and observed flows that represent the specified discharges were surpassed during the designated period [55,56]. When the flow is between or equal to 1 and 10 percent of the time, it is deemed to be high. The flow rate is deemed high when it falls within 1 to 10 percent of the period.

Similarly, flows are considered medium flows from the 11th to the 89th percentile and low flows from the 90th to the 100th percentile. The flow from the 11th to the 49th percentile is considered a high-medium flow, while the flow from the 50th to the 89th percentile is considered a low-medium flow [56]. Compared to other FDCs of SDTs, TB, and MLP, DTFs are a better method for medium-high and high percentile flows and correlate with the observed flow duration curve. The FDCs of TB bond with observed flow FDCs superior to others for low and medium-low percentile flows. The FDCs of all Mangla watershed stations observed and predicted by various soft computing approaches revealed that DTFs outperformed. DTFs are better than other techniques in forecasting medium-high and high discharges, while TB is better at estimating low and medium-low discharges over the long term. SDTs can predict high-flow runoffs.

#### 5. Conclusions

This study evaluates the performance of SDTs, DTFs, TB, and MLP for rainfall-runoff analysis. The analysis and observations show that DTFs are superior to all other data-

driven approaches, including SDTs, TB, and MLP. In contrast, based on the outcomes of performance evaluation criteria, DTFs are assessed as the most successful advanced soft computing approach among other applied approaches. In addition, SDTs and TB have fared better in yearly streamflow forecasts. However, the SDTs were deemed the most effective approach for the Mangla catchment. The accuracy between observed and forecast runoff in the current catchment was evaluated using FDCs. The results of FDCs revealed that the DTFs was a superior method for medium-high and high-percentile flows and had stronger correlations with the FDC of observed flow than other methods. MLP is frequently compared to DTFs because both methods model data with nonlinear connections between variables and manage interactions. However, neural networks have certain disadvantages in comparison to DTFs. The MLP model is not easily comprehensible. When examining DTFs, TB, and SDTs, it is straightforward to observe that an initial variable splits the data into two categories, and subsequently, further variables separate the following child groups. This information is quite helpful for the researcher attempting to comprehend the data's nature.

Soft computing approaches have limitations that focus on data and strive to extract variables and relations from raw data, yielding more accurate answers without using analytical laws and equations. Many issues remain; in some cases, physical principles are not fulfilled. It can be utilized in the forecasting of numerous different hydrological processes, including evapotranspiration, rainfall-runoff, and sediment transport. This study further investigates that DTFs have a higher potential for rainfall-runoff analysis.

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#### Abbreviations

ТВ	Tree Boost
DTFs	Decision tree forests
SDTs	Single decision trees
MLP	Multilayer perceptron
RMSE	Root means square error
MAE	Mean absolute error
R <sup>2</sup>	Coefficient of determination
NSE	Nash–Sutcliffe efficiency
FDCs	Flow duration curves
ANN	Artificial neural network
ANFIS	Adaptive neuro-fuzzy inference system
GP	Genetic programming
GEP	Gene expression programming
SVM	Support vector machine

BPA	Back-propagation algorithm
RGA	Real-coded genetic algorithm
SOM	Self-organizing map
MCS	Monte Carlo simulation
SORM	Simplified order reliability method
FORM	First-order reliability method
ME	misclassification error
km <sup>2</sup>	Square kilometers (area)
MAF	Million acre feet (storage capacity)
MW	Megawatts (electric power)
°C	Degrees Celsius (temperature)
Inches	Precipitation

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