

Article

Tower-Based Validation and Improvement of MODIS Gross Primary Production in an Alpine Swamp Meadow on the Tibetan Plateau

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Abstract: Alpine swamp meadow on the Tibetan Plateau is among the most sensitive areas to climate change. Accurate quantification of the GPP in alpine swamp meadow can benefit our understanding of the global carbon cycle. The 8-day MODerate resolution Imaging Spectroradiometer (MODIS) gross primary production (GPP) products (GPP_MOD) provide a pathway to estimate GPP in this remote ecosystem. However, the accuracy of the GPP_MOD estimation in this representative alpine swamp meadow is still unknown. Here five years GPP_MOD was validated using GPP derived from the eddy covariance flux measurements (GPP_EC) from 2009 to 2013. Our results indicated that the GPP_EC was strongly underestimated by GPP_MOD with a daily mean less than 40% of EC measurements. To reduce this error, the ground meteorological and vegetation leaf area index (LAI_G) measurements were used to revise the key inputs, the maximum light use efficiency (ϵ_{\max}) and the fractional photosynthetically active radiation (FPAR_M) in the MOD17 algorithm. Using two approaches to determine the site-specific ϵ_{\max} value, we suggested that the suitable ϵ_{\max} was about 1.61 g C MJ⁻¹ for this alpine swamp meadow which was considerably larger than the default 0.68 g C MJ⁻¹ for grassland. The FPAR_M underestimated 22.2% of the actual FPAR (FPAR_G) simulated from the LAI_G during the whole study period. Model comparisons showed that the large inaccuracies of GPP_MOD were mainly caused by the underestimation of the ϵ_{\max} and followed by that of the undervalued FPAR. However, the DAO meteorology data in the MOD17 algorithm did not exert a significant affection in the MODIS GPP underestimations. Therefore, site-specific optimized parameters inputs, especially the ϵ_{\max} and FPAR_G, are necessary to improve the performance of the MOD17 algorithm in GPP estimation, in which the calibrated MOD17A2 algorithm (GPP_MODR3) could explain 91.6% of GPP_EC variance for the alpine swamp meadow.

Keywords: alpine swamp meadow; MOD17A2 algorithm; eddy covariance (EC); light use efficiency (LUE); gross primary production (GPP); Tibetan Plateau

1. Introduction

Alpine swamp meadows cover about 50,000 km² of the Qinghai-Tibetan plateau, and hold the highest soil organic carbon content among all the plateau ecosystems in the world [1]. One reason for this is the low temperature and water-logged ambient circumstance caused a relative

moderate decomposition rates [2]. Another more important reason is the most effectively productive capacity in this ecosystem [1,3]. Gross primary production (GPP), a key component for carbon fixation through vegetative photosynthesis in carbon biogeochemical cycle between the biosphere and the atmosphere [4–6], represents the productive capacity of ecosystem [7]. Besides, the alpine swamp meadow is always considered as a symbol of global change [8]. Therefore, accurate quantification of the GPP in alpine swamp meadow can benefit our understanding of the global carbon cycle.

MODerate resolution Imaging Spectroradiometer (MODIS) GPP algorithm, based on the light use efficiency (LUE) model [9], provides a pathway to document the logical spatial patterns and temporal variabilities of GPP across a diverse range of biomes and climate regimes [7,10,11]. The LUE model assumes that GPP of well-watered and fertilized crops is linearly related to the amount of solar energy they absorbed (APAR) which could be calculated from the PAR and the fraction of PAR absorbed (FPAR) by vegetation [7,12]. Consequently, in the last few decades, the LUE approach has been used to estimate GPP at various spatial and temporal scales [7,13–15]. However, significant discrepancies were often found between this approach and other terrestrial ecosystems models [16]. Therefore, we need to effectively validate these products to establish their utility in regional and global GPP estimation [17], which is full of challenge because of the large uncertainties in parameters inputs of the maximum LUE (ϵ_{\max}) and FPAR in different ecosystems [18,19].

Eddy covariance (EC) technique is the most efficient micrometeorological method to observe CO₂ exchange between the biosphere and the atmosphere [20,21] thus is increasingly used for ecosystem model calibration and validation [22–24]. Recent many researches tend to concentrate on the evaluation and validation of MODIS GPP products (GPP_MOD) using GPP partitioned from the net ecosystem CO₂ exchange (NEE) of EC measurements [10,17,19,25–35]. Most studies suggested that GPP_MOD were able to capture seasonal and spatial GPP patterns across biomes except croplands because of human disturbances [30,31]. However, the accuracy of GPP_MOD varied with different ecosystem and spatial-temporal scale [17,28,29]. For example, Turner et al. (2006) proposed that GPP_MOD tended to be overestimated at low productivity site, in contrast, that tended to be underestimated in high productivity sites. Zhang et al. (2008) revealed that GPP_MOD accounted for 1/2–2/3 of GPP_EC for the alpine meadow, but only about 1/5–1/3 for the cropland. He et al. (2012) demonstrated GPP_MOD was seriously underestimated in the forest ecosystems of East Asia, especially at northern sites. Verma et al. (2014 and 2015) concluded that GPP_MOD had a low confidence to track inter-annual GPP variation patterns despite of their better performances in intra-annual GPP patterns. Tang et al. (2015) discovered that the current MODIS product works more significantly for deciduous broadleaf forest and mixed forest, less for evergreen needle leaf forest, and least for evergreen broadleaf forest. Overall, all of these studies mainly attributed the discrepancies between GPP_MOD and GPP_EC to the quality of different upstream inputs. Further, with the vigorous development of international flux networks [36,37], they appealed that the next efforts should have a site-specific refinement of MOD17 parameters inputs, especially the ϵ_{\max} and FPAR, which directly affected GPP estimation based on the LUE model [11,38,39]. Then many tower-based site-level validation studies on GPP_MOD increasingly arise in recent years [25,27,32,34,38,40,41]. However, the validation of GPP_MOD estimation in alpine swamp meadow is still absent.

Lhasa River Basin is one typical area dominated by alpine swamp on the central Tibetan Plateau [8] and the dominant (65.45%) wetland landscape types is *Kobresia littledalei* swamp meadow [42]. Our EC flux tower was established at Damxung, a county located at the Lhasa River Basin, surrounded by more than 30 high mountains (>6000 m a.s.l) and a dense river networks, which provided favorable conditions for development of alpine wetlands due to a constant water supply from abundant snow melt in growing season [43]. 26% of the area was alpine wetland, of which has the largest patches area ($\sim 15.7 \times 10^3 \text{ hm}^2$) of the *K. littledalei*-*B. sinocompressus* swamp meadow [8]. Therefore, EC measurements in this alpine swamp provided the representative and effective insitu data for validation and revision of the MOD17 GPP products. Based on five years MODIS data products and GPP_EC measurements from 2009 to 2013, the main objectives of our study are: (1) to evaluate the validity of GPP_MOD in

temporal patterns and absolute amounts; (2) to quantify the uncertainty sources of GPP_MOD caused by inaccurate parameters inputs in the MOD17 algorithm; (3) to identify the optimized parameters inputs in the MOD17 algorithm for this alpine swamp meadow.

2. Materials and Methods

2.1. Site Description

The experimental site is a typical alpine *K. littledalei*-*B. sinocompressus* swamp meadow (30°28′08.50″N, 91°03′44.50″E, elevation 4286 m) that is located at Majilukuo village, approximately 5 km from the Damxung county, Tibet Autonomous Region. The local area is categorized as plateau monsoon climate with characteristics of strong radiation, low air temperature, and short cool summers. Climatic records from 1963 to 2008 show that the average annual air temperature is 1.8 °C, with coldest monthly mean of −9.1 °C in January and the warmest of 11.1 °C in July. Average annual precipitation is 475.6 mm, over 90% of which concentrated between May and September. Flat terrain (less than 2 degree-slope) and different microtopographies, hummocks (0.1–0.2 m above the ground) and hollows (0.1–0.3 m below the ground) with similar proportions (about 50% each), covered in this wetland. The dominant species (Over 90%) are *K. littledalei* in hummocks and *B. sinocompressus* in hollows, and the canopy heights are 35–45 cm and 20–30 cm, respectively. Other genera, such as *Potentilla*, *Pteridophyta*, and *Pedicularis* mixed in hummocks. The soil is gravelly sandy loam, and often is called alpine swamp meadow soil [44]. Water depth is about 10–45 cm during growth season from May to September. In general, this alpine swamp becomes frozen at the beginning of November and gradually thaws in the following March.

2.2. Ground Measurements

EC flux measurements were conducted at a height of 2.0 m in the central of a fetch of at least 200 m in all directions by open-path EC method from 12 May 2009 to 31 August 2013. The EC system consisted of one three-dimensional sonic anemometer (Model CSAT3, Campbell Scientific Inc., Logan, UT, USA) and an open-path fast-response infrared gas analyzer (IRGA, Model LI7500, LI-Cor Inc., Lincoln, NE, USA), which provides a digital output of fluctuations in three wind components, sonic temperature, water vapor, and CO₂ density at a rate of 10 Hz. Calculations were carried out for each 30 min period by a data-logger (Model CR1000, Campbell Scientific Inc.). Calibrations of CO₂ and H₂O flux were performed annually.

Standard meteorological and soil parameters were measured using an array of sensors. A Li-cor quantum sensor (Model LI190SB, LI-Cor) was mounted at a height of 1.5 m with the EC system to measure photosynthetically active radiation (PAR). The radiation balance of solar and far-infrared radiation was measured by a Net Radiometer (Model CNR1, Kipp & Zonen, Utrecht, The Netherlands) at a height of 2 m, providing total solar radiation (SR), reflected solar radiation (SRR), far-infrared radiation (LR), and reflected far-infrared radiation (LRR), to allow calculation of net radiation (R_n). Air temperature (T_a) and relative humidity (RH_a) were measured with shielded and aspirated sensors (Model HMP45C, Vaisala, Finland) at 2 m (T_{a2}/RH_{a2}). Vapor pressure deficit (VPD) was calculated as the difference between the saturation and actual vapor pressures at the given temperature based on the measured relative humidity and air temperature. Soil temperature at depths of 5 cm was measured with the thermocouple sensor (Model 107-L, Campbell Scientific Inc.). All channels from meteorological sensors were recorded as 30 min averages with a data-logger (Model CR10X and AM25T, Campbell Scientific Inc.). The data were retrieved by a laptop computer every three weeks.

The vegetation leaf area index (LAI_G) was regularly measured by a leaf area meter (Model AM200, ADC BioScientific Ltd., Hertfordshire, UK) approximately every two weeks during the growing season (May to September). Five sampling quadrants (0.5 m × 0.5 m) were randomly measured both in hummocks and hollows, the biomass samples were oven-dried at 65 °C till that the weight did not change and then recorded.

2.3. MODIS Data Products

MODIS collection 5.1 land products are available from the Land Processes DAAC [45]. Using the flux tower position (30°28′08.50″N, 91°03′44.50″E) as the center pixel, we extracted the MODIS LAI/FPAR (LAI_M/FPAR_M) from MOD15A2 and GPP (GPP_{MOD}) products from MOD17A2 at 1 km spatial resolution and 8-day time step from 1 January 2009 to 31 December 2013 [45]. Here we didn't use the MODIS collection 6 land products because we have no access, so far, to these data at our site. Thus, we used the MOD17A2 Collection 5.1 that is more complete and accessible to our study area. The GPP_{MOD} (Kg C day^{−1}) were calculated from the MOD17A2 algorithm [11] based on a light energy use efficiency (LUE) model (Equation (1)) [7,11,46].

$$GPP = \varepsilon \times APAR \quad (1)$$

where ε is the PAR conversion efficiency (Kg C MJ^{−1}) [47]. The two parameters for Tmin and the two parameters for VPD are used to calculate the scalars that attenuate ε_{\max} to produce the final ε (Equation (2)) [11].

$$\varepsilon = \varepsilon_{\max} \times Tmin_scalar \times VPD_scalar \quad (2)$$

where the value of ε_{\max} is obtained from the Biome Properties Look-Up Table (BPLUT) [7,11]. The attenuation scalars (Tmin_scalar and VPD_scalar) are simple linear ramp functions of the daily minimum air temperature (Tmin) and daytime average VPD (Equations (3) and (4)), which range from 0 to 1 [23,48].

$$Tmin_scalar = \begin{cases} 0, & Tmin \in (-\infty, Tmin_min] \\ \frac{Tmin - Tmin_min}{Tmin_max - Tmin_min}, & Tmin \in (Tmin_min, Tmin_max) \\ 1, & Tmin \in [Tmin_max, +\infty) \end{cases} \quad (3)$$

$$VPD_scalar = \begin{cases} 0, & VPD \in [VPDmax, +\infty) \\ \frac{VPDmax - VPD}{VPDmax - VPDmin}, & VPD \in (VPDmin, VPDmax) \\ 1, & VPD \in (-\infty, VPDmin] \end{cases} \quad (4)$$

where Tmin and VPD are obtained from the NASA Data Assimilation Office (DAO) dataset [49].

APAR is the absorbed PAR (MJ m^{−2} day^{−1}) by vegetation canopy, which can be calculated as Equation (5).

$$APAR = FPAR \times PAR \quad (5)$$

where FPAR is the fraction of absorbed PAR by vegetation canopy, and derived from the MOD15A2 product (FPAR_M). PAR is PAR incident on the vegetative surface, which estimated from incident shortwave radiation (SWRad, provided in the DAO dataset) as Equation (6).

$$PAR = 0.45 \times SWRad \quad (6)$$

2.4. EC-Based GPP Estimation

EC flux data processing and gap filling procedure were carried out according to the ChinaFLUX method [37,50]. Here we only give a brief description. Data processing included the despiking to exclude extreme abnormal observations [50], coordinate rotation to eliminate anomalies resulting from tilt of the anemometer [51,52], air density corrections to correct density fluctuations induced by temperature and water vapor (WPL corrections) [53–55], outlier rejection to filter data uncertainty ($|NEE| > 3 \text{ mg CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) [56,57], and friction velocity threshold (u^*) corrections to correct the underestimate flux in weak turbulence [50,58].

Due to sensor failures, unsuitable weather conditions, and data processing above, EC flux observational data generate discontinuous gaps [59]. We need to fill them in order to contrast with MODIS data products. Linear interpolation was used to fill the small gaps (less than 2 h). For the gaps

more than 2 h, two nonlinear empirical models were separately applied for daytime and nighttime data [50]. The daytime ($R_n > 10 \text{ W m}^{-2}$) CO_2 fluxes were estimated using the Michaelis-Menten equation [59,60].

$$NEE = -\frac{a \times A_{max} \times PAR}{a \times PAR + A_{max}} + Re \quad (7)$$

where NEE ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) and Re ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) are the day time net ecosystem exchange and ecosystem respiration, respectively. P_{max} ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) is the maximum ecosystem photosynthesis rate, and α ($\mu\text{mol CO}_2 \mu\text{mol photons}^{-1}$) is the apparent quantum yield and the maximum light use efficiency, which are taken as indicators of plant photosynthetic capacity [57,60].

The nighttime missing NEE data (Re) were filled with the exponential relationship between Re and soil temperature at 5 cm due to GPP is assumed to be zero during the night [61,62].

$$Re = a \times e^{(b \times Ts5)} \quad (8)$$

where Re ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) is nighttime ecosystem respiration. $Ts5$ ($^{\circ}\text{C}$) is the soil temperature at 5 cm. a (The reference respiration when $Ts5 = 0^{\circ}\text{C}$) and b are the regression parameters.

The gap-filled daytime NEE were partitioned into EC-based GPP (GPP_{EC}) as CO_2 assimilation and Re as CO_2 emission [57,63].

$$GPP_{EC} = Re - NEE \quad (9)$$

2.5. FPAR Estimation

FPAR, the fraction of absorbed PAR by vegetation canopy, can also be calculated using the LAI_G measurements based on the Beer-Lambert law ($FPAR_G$) as Equation (10) [16] except for the direct acquisition from $FPAR_M$.

$$FPAR_G = 0.95 \times (1 - \exp(-k \times LAI_{MG})) \quad (10)$$

where k is the light extinction coefficient with a value of 0.5 for herbaceous crops in this study [25,64]. The LAI_G is discontinuous that is only available in measurement days, while the LAI_M is consecutive an 8-day time step. To document a consecutive LAI_{MG} , a linear regression between the LAI_G and the LAI_M was trained.

2.6. ϵ_{max} Estimation

ϵ_{max} , the maximum light use efficiency, is 0.68 g C MJ^{-1} in the default (collection 5.1, hereafter the same) MOD17A2 algorithm for grassland biome [11]. However, wide variation in ϵ_{max} is reasonable because both vegetation types and suboptimal climatic conditions have potential impact on it [11,25]. In this study, we determined the ϵ_{max} values using two approaches. One is the MOD17A2 algorithm based on LAI_G and EC_GPP measurements data [25]. In brief, we only used the LAI_G in measurement days to calculate $FPAR_G$ in Equation (10). Actually, all parameters, $APAR_G$, $Tmin_scalar$, and VPD_scalar , could be directly estimated from the existing ground measurement data, PAR , $Tmin$, and VPD in the MOD17A2 algorithm as mentioned above, respectively. Therefore, the ϵ_{max} value for this alpine wetland ecosystem is the linear regression slope between the EC_GPP and the multiplicative of two attenuation scalars ($Tmin_scalar$ and VPD_scalar) in the LAI_G measurement days [4,25].

Another is using light response curve derived from the Michaelis-Menten equation based on EC measurement data [59,60]. As Equation (7) illustrated, the α ($\mu\text{mol CO}_2 \mu\text{mol photons}^{-1}$) can be taken as the maximum light use efficiency (ϵ_{max} , g C MJ^{-1}) [57,60] just after unit conversion [65].

$$\epsilon_{max} = \lambda \times Mc \times \alpha \quad (11)$$

where λ is the conversion ratio with α value of 4.43 because 1 J energy of PAR is equivalent to $4.43 \mu\text{mol quantum}$ [65]. Mc (12 g mol^{-1}) is the molar quantity of carbon. Therefore, we extracted the daytime NEE and PAR observational data in growing season from 2009 to 2012 to estimate the ϵ_{max} values.

2.7. Revised GPP Estimation

Based on the MOD17A2 algorithm and ground measurements, we introduced four approaches in revising GPP_MOD (GPP_MODR1, GPP_MODR2, GPP_MODR3, and GPP_MODR4) according to parameters selection (Table 1). As EC is the most direct and efficient micrometeorological method to research carbon dynamics between the biosphere and the atmosphere [20], in this study, the 8 days composited GPP_EC was used to determine the fitting capacity of the four revised GPP models.

Table 1. Parameterization schemes for estimating gross primary production (GPP) in this alpine wetland based on the MOD17A2 algorithm.

GPP *	$\varepsilon_{\max}^{\dagger}$ (g C MJ ⁻¹)	Tmin_max *	Tmin_min *	VPDmax *	VPDmin *	FPAR *	Meteorology Data
GPP_MOD	0.68	12.02	−8.00	3.50	0.65	FPAR _M	DAO ‡
GPP_MODR1	0.68	12.02	−8.00	3.50	0.65	FPAR _M	Ground measurements
GPP_MODR2	0.68	12.02	−8.00	3.50	0.65	FPAR _G	Ground measurements
GPP_MODR3	1.61 (1.33–1.80) †	12.02	−8.00	3.50	0.65	FPAR _G	Ground measurements
GPP_MODR4	1.61 (1.33–1.80) †	12.02	−8.00	3.50	0.65	FPAR _M	Ground measurements

* GPP list represents the diverse GPP values from different models based on the MOD17A2 algorithm according to data source showed in this table; * Tmin_max, Tmin_min, VPDmax, and VPDmin are the upper limit, the lower of daily minimum temperature, the upper, and the lower of daily minimum vapor pressure difference, respectively. All of them are extracted from the Biome Properties Look-Up Table (BPLUT) in grassland biome; * FPAR is the fraction of absorbed PAR by vegetation canopy from the MOD15A2 product (FPAR_M) and estimation based on ground measurements (FPAR_G); † The ε_{\max} is the maximum light use efficiency. The default of the collection 5.1 MOD17A2 algorithm for grassland is 0.68 g C MJ⁻¹. Based on ground measurements, the mean ε_{\max} value for this alpine wetland we calculated using two methods is 1.61, which ranges from 1.33 to 1.80 due to the vegetation condition in different observational years; ‡ DAO is the NASA Data Assimilation Office, which provided the meteorology data for the MODIS data product.

2.8. Statistical Analysis

All daily and annual-scale GPP estimations derived from diverse methods, GPP_EC, GPP_MOD, GPP_MODR1, GPP_MODR2, GPP_MODR3, and GPP_MODR4, passed the normality (Shapiro-Wilk test) and homogeneity of variance test (Bartlett test) ($p > 0.05$). Thus, we employed the one-way analysis of variance (ANOVA) and Tukey's honest significant difference (HSD) to investigate GPP estimations differences among those different methods and among temporal series at $\alpha = 0.05$. In this study, we employed the linear regression analysis and the following two indices, RMSE and RPE (Equations (12) and (13)), to adequately compare the performance of MODIS-based GPP with GPP_EC.

$$RMSE = \sqrt{\frac{\sum_{i=1}^n (x_i - y_i)^2}{n}} \quad (12)$$

$$RPE = \left(\frac{\bar{y} - \bar{x}}{\bar{x}} \right) \times 100\% \quad (13)$$

where the x_i are the GPP_EC data, the y_i are the MODIS-based GPP estimations depending on different parameterization schemes (Table 1), and \bar{x} and \bar{y} are the averages of corresponding data, respectively. The n is the number of samples. The root mean square error (RMSE) is used to measure the bias from the simulated data compared to tower measurements. The relative predictive error (RPE) is used to quantify the percentage of mean difference between MODIS-based GPP estimations and GPP_EC, which provides the direct effectiveness (underestimation as negative, or overestimation as positive)

in predicted values compared to measured values [27]. All statistical and modeling procedures were performed in the R statistical computing package (Version 3.2.0).

3. Results

3.1. Ground Measurements and Parameters Estimation

All ground measurements data were integrated into 8-day time step for the comparability in temporal resolution with the MODIS data products (Figure 1). Daily Tmin, range from -20.4°C to 8.9°C , which was much lower than the default upper limit (Tmin_max, 12.02°C) in the BPLUT (Table 1 and Figure 1a). In general, VPD fluctuated around 0.15 ± 0.10 (mean \pm SD) Kpa except for a few measurement days accessible to the VPDmin (0.65 Kpa) (Table 1 and Figure 1b). The supreme PAR appeared on July and August (DOY120–240) that the seasonal average could reach $18.6 \pm 4.2 \mu\text{mol photons}^{-1} \text{ m}^{-2} \text{ day}^{-1}$ (equal to $4.2 \pm 0.9 \text{ MJ m}^{-2} \text{ day}^{-1}$) (Figure 1c).

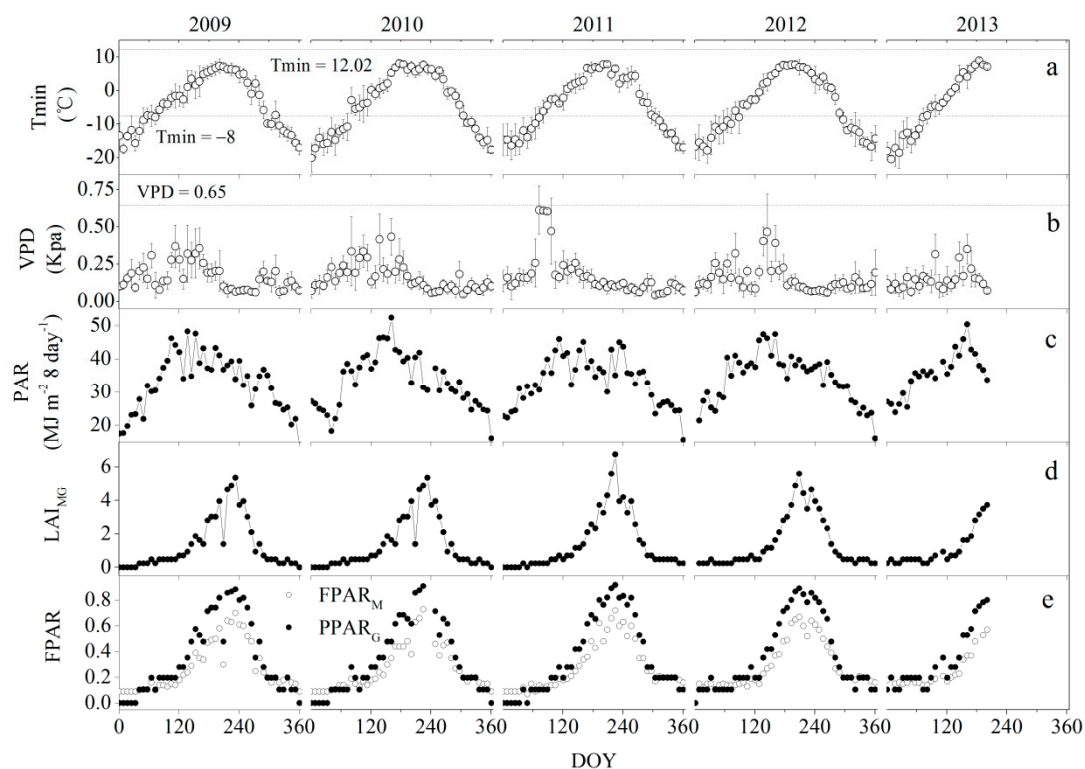


Figure 1. Seasonal variation of ground meteorological measurements data and the FPAR from 2009 to 2013. All data are integrated into 8-day time step and showed with the first day of each 8-day interval, the error bars in (a) and (b) are standard deviation for corresponding mean values. (a), Tmin is the daily minimum temperature; (b), VPD is the daily vapor pressure deficit; (c), PAR is photosynthetically active radiation; (d), the consecutive LAI_{MG} is derived from linear regression between ground LAI_{G} measurements and MODIS LAI (LAI_{M}) in LAI_{G} measurement days ($n = 23$); (e), FPAR_{M} is directly obtained from MODIS products, while FPAR_{G} is calculated from LAI_{G} in e based on Beer-Lambert law.

The consecutive LAI_{MG} was stimulated from the linear regression between the consecutive 8-day time step LAI_{M} and field measurement LAI (LAI_{G}) in measurement days ($\text{LAI}_{\text{MG}} = 2.33 \times \text{LAI}_{\text{M}} - 0.23$, $R^2 = 0.84$, $p < 0.001$, $n = 23$) (Figure 1d). The LAI_{M} underestimated the vegetation condition in this alpine swamp meadow by an average 39.2% except a few days during the non-growing season. The LAI_{MG} reached its maximum on the August with multi-years average $5.99 \text{ m}^2 \text{ m}^{-2}$ (± 0.64 SD) from 2009 to 2012 (Figure 1d). As Figure 1e illustrated, the FPAR_{M} also generally underestimated the

FPAR_G by an average 22.2% during the whole study period. Seasonal FPAR trend was similar to LAI (Figure 1d,e).

The MOD17A2 algorithm carried out an integrated ϵ_{\max} estimation of 1.78 g C MJ⁻¹ for this alpine wetland from 2009 to 2013 ($R^2 = 0.78$, $p < 0.01$, $n = 23$). Alternatively, the light response curve derived from the Michaelis-Menten equation provided annual-scale ϵ_{\max} estimation for 1.70, 1.80, 1.33, and 1.59 g C MJ⁻¹ from 2009 to 2012, respectively (Figure 2a–d and Table 1). Two ϵ_{\max} estimate methods failed to generate significant difference in ϵ_{\max} values (paired t -test, $t_{0.025} = 2.2$, $df = 4$, $p = 0.1$) during study period. Therefore, we assumed the ϵ_{\max} value in 2013 was 1.78 g C MJ⁻¹ when calculated GPP_MODR3 and GPP_MODR4 (Table 1).

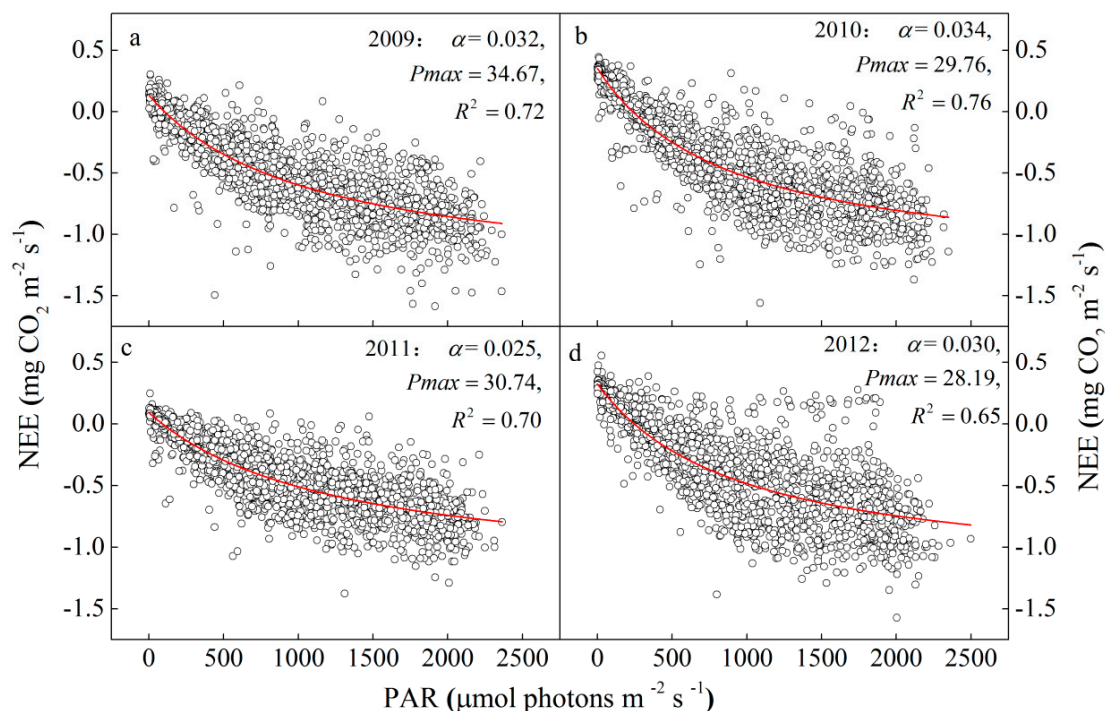


Figure 2. The maximum light use efficiency estimation using the light response curve derived from the Michaelis-Menten equation based on daytime EC measurement data from 2009 to 2012 (a–d). The P_{\max} (μmol CO₂ m⁻² s⁻¹) is the maximum ecosystem photosynthesis rate. α (μmol CO₂ μmol photons⁻¹) is the maximum light use efficiency.

3.2. Seasonal-Scale Contrast of GPP Estimations

Seasonal variation of the field GPP measurement (GPP_{EC}) and five MODIS-based GPP estimations (GPP_{MOD}, GPP_{MODR1}, GPP_{MODR2}, GPP_{MODR3}, and GPP_{MODR4}) showed similar tendency but with different quantities in all observational years, especially in growing season (Figure 3a–e). GPP_{EC} was generally greater than any other GPP estimation from the MOD17A2 algorithm, which indicated that all MODIS-based GPP estimations in this site were underestimated in predicting GPP. GPP_{MODR3} got the closest agreement with GPP_{EC} estimation, GPP_{MODR4} took the second place, and the rest MODIS-based GPP estimations (GPP_{MOD}, GPP_{MODR1}, and GPP_{MODR2}) strongly underestimated GPP in this alpine wetland with corresponding values less than half of GPP_{EC} estimation (Figure 3).

In growing season, statistical results showed that the mean GPP estimation from the same method, either the EC-based or the MODIS-based, had no significant differences ($p > 0.1$) amid different observational years (Table 2). However, diverse estimation methods significantly affected the mean GPP values ($p < 0.01$) in all observational years (Table 2). In contrast, the GPP_{MOD} and GPP_{MODR1} showed the worst underestimation (less than 35% of GPP_{EC}), and the GPP_{MODR2} came the second

(about 40% of GPP_EC). There also existed a significant underestimation (about 64% of GPP_EC) from the GPP_MODR4 despite of significant promotion compared to the former MODIS-based GPP estimation. However, GPP_MODR3 did not show significant difference with GPP_EC (Table 2) thus provided an instrumental approach in daily GPP estimation for this alpine wetland.

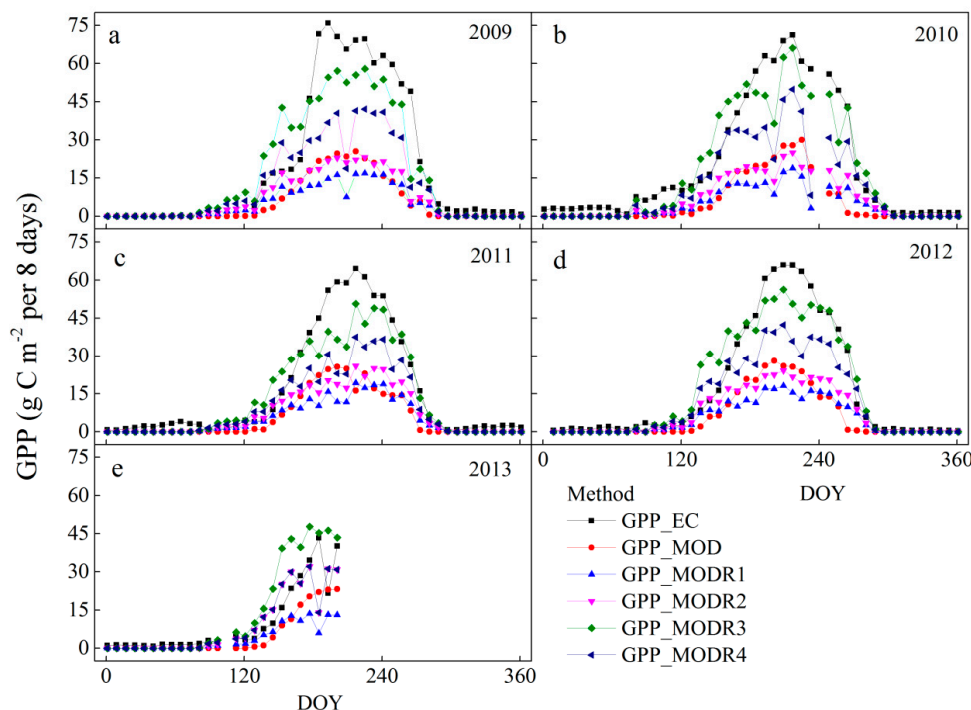


Figure 3. Seasonal variation of gross primary production (GPP) estimation from different methods from 2009 to 2013 (a–e). GPP_EC is from NEE partitioned of EC measurement data, while GPP estimations based on the MOD17A2 algorithm are showed in Table 1. Data are 8 days composited GPP estimation showed in the first day.

Table 2. GPP estimation differences among diverse estimation methods and inter-annual differences during growing season in different years *.

	2009 (<i>n</i> = 19)	2010 (<i>n</i> = 18)	2011 (<i>n</i> = 19)	2012 (<i>n</i> = 19)	All (<i>n</i> = 75)
GPP_EC	46.91 (±24.45) Da	45.60 (±19.41) Ca	37.93 (±20.52) Ca	40.89 (±20.50) Ca	40.74 (±22.39) C
GPP_MOD	13.62 (±8.91) Aa	13.90 (±9.91) Aa	13.75 (±8.49) Aa	14.17 (±9.67) Aa	13.86 (±9.06) A
GPP_MODR1	10.88 (±4.84) Aa	10.18 (±4.79) Aa	11.47 (±5.09) Aa	11.66 (±4.65) Aa	10.06 (±4.78) A
GPP_MODR2	15.94 (±6.55) ABa	15.40 (±5.83) ABa	16.18 (±6.65) Aa	16.49 (±6.12) ABa	16.01 (±6.19) A
GPP_MODR3	39.84 (±16.39) CDa	40.77 (±15.43) Ca	31.65 (±13.00) BCa	38.56 (±14.31) Ca	37.67 (±14.96) C
GPP_MODR4	27.21 (±12.11) BCa	26.95 (±12.69) Ba	22.43 (±9.96) ABa	27.26 (±10.86) BCa	25.99 (±11.46) B

* GPP estimation methods are similar to Table 1. Data is the mean (±1 standard deviation) of 8 days composited GPP estimations. * All raw data of this table passed the normality (Shapiro-Wilk test) and homogeneity of variance test (Bartlett test) ($p > 0.05$). Statistical analysis is based on the 95% family-wise confidence level ($\alpha = 0.05$). Rows with the same lowercase indicate no significant difference in different years ($p > 0.1$), and columns with the different uppercase indicate that a significant difference exist among diverse GPP estimation methods ($p < 0.01$).

The significant linear regression between EC-based GPP estimation (GPP_EC) and MODIS-based GPP estimation indicated that temporal variation of GPP could be well explained by MODIS-based GPP estimation ($R^2 > 0.83$, $p < 0.0001$, $n = 190$) (Figure 4). However, the absolute magnitudes of GPP were undervalued with a attenuation coefficient (slope in the Figure 4) range from 13.0% (GPP_MODR3) even to 75.0% (GPP_MODR1) depending on the methodology we used (Table 1). In contrast with the GPP_MOD estimation, GPP_MODR1 reduced the capacity in the GPP estimation about 10.0%

of GPP_EC (Figure 4). However, the GPP_MODR2, GPP_MODR3, and GPP_MODR4 improved the accuracy of the GPP estimations by 3.0%, 53.0%, and 25.0%, respectively. Therefore, GPP_MODR3 presented a superior performance in daily GPP estimation compared to other MODIS-based models (Table 2, Figures 3 and 4).

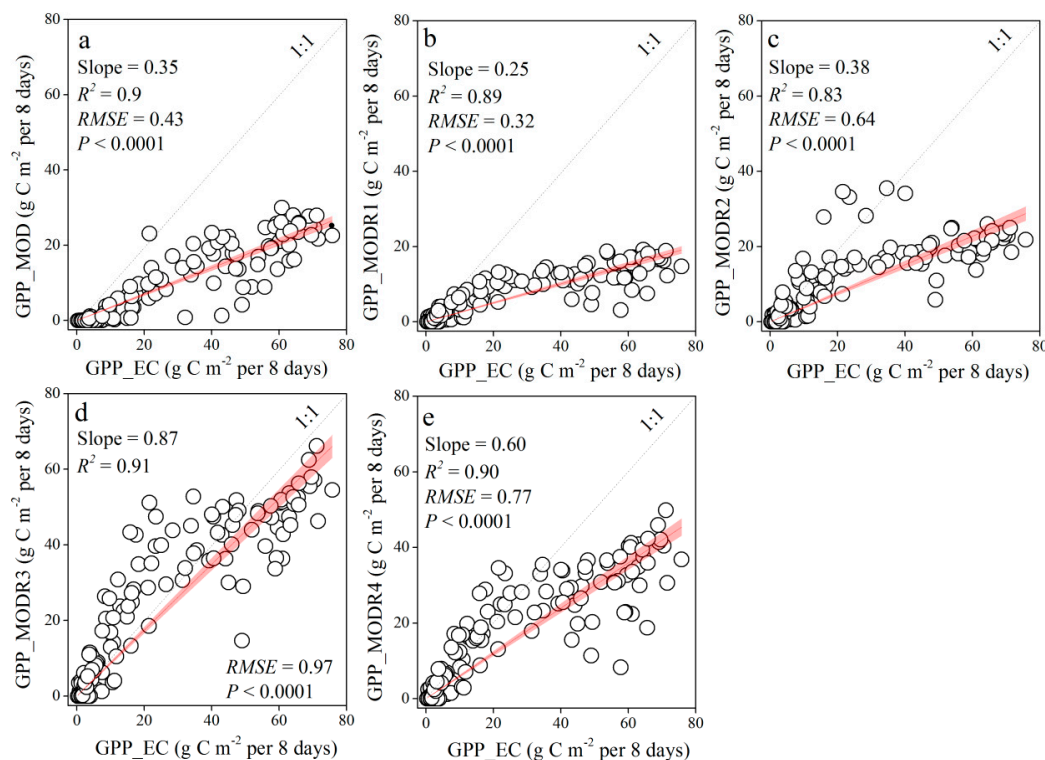


Figure 4. Linear regression between EC-based GPP estimation (GPP_EC) and MODIS-based GPP estimation. GPP estimations based on the MOD17A2 algorithm are showed in Table 1. (a), GPP_MOD; (b), GPP_MODR1; (c), GPP_MODR2; (d), GPP_MODR3; (e), GPP_MODR4. Data are the 8 days composited GPP values. The solid lines are the regression curves, the coverages are 95% confidence interval of linear regressions. Dash lines are the 1:1 reference lines.

3.3. Annual-Scale Contrast of GPP Estimations

Annual GPP_EC in this alpine wetland was range from the minimum 755.02 g C m⁻² in 2011 to the maximum 901.37 g C m⁻² in 2010 (Figure 5a). The GPP_MOD had strong underestimation in annual GPP accumulation that was only 27.98% in 2010 to 34.69% in 2011 of GPP_EC measurements. The GPP_MODR1 not only had no improvement in GPP estimation but showed a slight decrease with mean 6.6% of GPP_EC compared with GPP_MOD (Figure 5b). The GPP_MODR1 improved 7.2% predictive capacity compared to the GPP_MOD, actually the impact was not significant (Figure 5b). In contrast with the GPP_MOD, the GPP_MODR4 had a significant, 31.3% of GPP_EC, promotion in GPP estimation, but there still existed significant difference between GPP_MODR4 and GPP_EC (Figure 5b). Statistical results showed that there was no significant difference between GPP_MODR3 and GPP_EC, which indicated that the GPP_MODR3 was the most instrumental estimation methods in annual GPP accumulation.

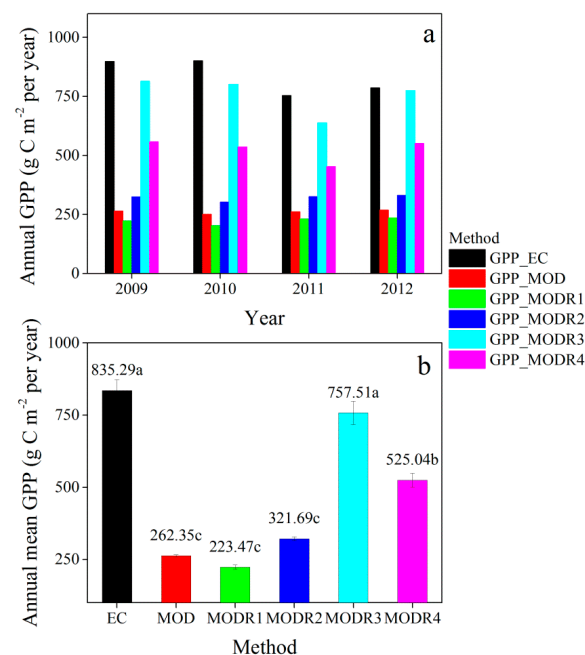


Figure 5. Inter-annual GPP variations from the field GPP measurement (GPP_EC) and five MODIS-based GPP estimations (GPP_MOD, GPP_MODR1, GPP_MODR2, GPP_MODR3, and GPP_MODR4) (a) and the difference among different estimation methods (b). The error bars in b are the standard deviation of the mean annual GPP estimation from 2009 to 2012. The bar with the same lowercase indicates no significant difference among diverse GPP estimation methods ($p > 0.05$).

4. Discussion

This study utilized the MOD17A2 algorithm and tower-based ground measurements to reconcile MODIS default GPP estimation (GPP_MOD) in four GPP estimation models, GPP_MODR1 to GPP_MODR4, depending on the diverse parameterization schemes (Table 1). We assessed the performance of these models on GPP estimations as compared to in situ flux tower GPP (GPP_EC).

4.1. Impacts of Meteorology Data on GPP Estimations

In this study, GPP_MOD strongly underestimated (68.0%) daily mean GPP compared to GPP_EC (Table 3 and Figure 5). The difference between GPP_MOD and the GPP_MODR1 was only the meteorology data inputs in GPP estimations (Table 1). Unexpectedly, ground meteorology data (Tmin, VPD, and PAR) used in GPP_MODR1 generated a slightly higher underestimation (RPE of 73.0%) with mean daily RMSE of 2.8 g C m^{-2} than the default DAO data with mean daily RMSE of -2.47 g C m^{-2} that caused 6.6% of less integrated estimations in annual mean GPP (Table 2 and Figure 5). Bulks of previous studies demonstrated that the DAO meteorology data was coarse in the GPP algorithm [25–27,66] that stems from the inaccurate observations on three meteorological factors of Tmin, VPD, and net surface solar radiation [33,67,68]. Turner et al. (2003) concluded that the VPD and minimum temperature data in the DAO performs well when compared to flux tower measurements whereas PAR has a large positive bias, which might be a reason for the deteriorate of GPP_MODR1. However, similar to Zhang et al. (2008), our study also revealed that the coarse meteorology data in the MOD17 algorithm did not exert a significant affection in the MODIS GPP products.

Table 3. Performances of MODIS-based GPP estimations methods on daily GPP estimations as compared to the insitu flux tower GPP (GPP_EC).

Methods *	RMSE (g C m ⁻²) [†]					RPE (%) [†]				
	2009 (n = 46)	2010 (n = 45)	2011 (n = 46)	2012 (n = 45)	Mean	2009	2010	2011	2012	Mean
GPP_MOD	2.90	2.59	2.14	2.26	2.47	−70.4	−72.0	−63.7	−65.7	−68.0
GPP_MODR1	3.24	2.97	2.41	2.59	2.80	−75.1	−77.5	−69.3	−70.0	−73.0
GPP_MODR2	2.84	2.55	2.04	2.21	2.41	−63.8	−66.4	−56.7	−57.8	−61.2
GPP_MODR3	1.30	0.95	0.97	0.86	1.02	−9.4	−11.3	−15.4	−1.4	−9.4
GPP_MODR4	2.01	1.75	1.55	1.37	1.67	−37.9	−40.4	−39.9	−29.9	−37.0

* The MODIS-based GPP estimation methods are similar to Table 1; [†] The RMSE and RPE are the root mean square error and the relative predictive error between MODIS-based daily GPP estimations and GPP_EC, respectively. The negative RPE represents the underestimation of MODIS-based daily GPP estimations compared to GPP_EC.

4.2. Impacts of ϵ_{\max} on GPP Estimations

The default ϵ_{\max} value for grassland in the BPLUT was less than half of the optimized ϵ_{\max} estimations from field observations in this specific biome (Table 1). Validations in parameters of LUE model in most recent studies revealed that the realistic ϵ_{\max} values were undervalued in the MODIS default GPP algorithms [12,25,27,34] with a few exceptions [26], which emphasized the urgent need to reconcile the optimized ϵ_{\max} for more extensive biomes [17,29,35,38,69]. The global look-up table of ϵ_{\max} in the MOD17A2 GPP algorithm is hard to satisfy all vegetation properties due to various biomes with complex climatic, soil types, and associated stand structures and ages [25,28]. Actually, these uncertainties in ϵ_{\max} estimations might also attribute to the practice that LUE is alterable against different cloudiness, generally highest on overcast days and decreases on clear sky days [17], whereas the overcast conditions are not considered in the MOD17 default ϵ_{\max} list and they are assumed to change only with vegetation types [11]. Optimized ϵ_{\max} inputs directly caused that no significant difference was existed between GPP_MODR3 and GPP_EC in daily and annual GPP estimations (Figure 5b and Table 2), which indicated that GPP_MODR3 was an alternative estimation method to evaluate seasonal and annual GPP on this alpine wetland on the Tibetan Plateau. Contrast to GPP_MOD, GPP_MODR3 improved approximately 60% of RPE in the agreements of the model for the insitu flux tower GPP with the lowest RMSE from −0.86 to −1.3 g C m⁻² (Table 3 and Figure 6). Therefore, refinements of MOD17 ϵ_{\max} may be beneficial to have a more agreeable fit between GPP_EC and MODIS products because optimized ϵ_{\max} inputs directly improve the LUE model for GPP estimation [11,38,39].

4.3. Impacts of FPAR on GPP Estimations

FPAR is an important input variable in light use efficiency model that directly modulates the essential energy source input to photosynthetic systems [9,13,16]. However, FPAR_M often produce misleading signals in GPP estimations due to the contamination by atmospheric characteristics [28,70]. Thus, compared with FPAR_M among diverse seasons and different spatial biomes, realistic ground FPAR_G could be either undervalued [34,71], overvalued [25,29,72], or had a closest agreement [17,34]. In this study, 22.2% (20.4% in 2011 to 23.8% in 2010) of the FPAR_G derived from ground LAI_{MG} was underestimated by the FPAR_M (Figure 1d,e). A near study in an alpine meadow, however, demonstrated that the MODIS-based FPAR was about 14.70% higher than the FPAR_G, which could be attributed that the vegetation canopies in alpine meadow was much less than in this alpine wetland [25,71,73].

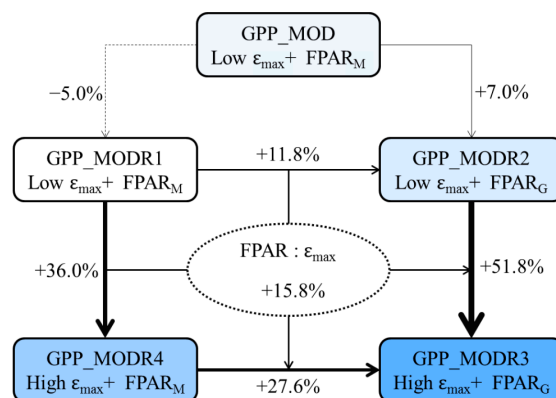


Figure 6. Performances of gross primary production (GPP) estimation models based on the MOD17A2 algorithm compared to in situ flux tower GPP (GPP_EC). The parameterization schemes of these models are showed in Table 1. The positive percentages indicate the improvement of relative predictive error (RPE) between MODIS-based daily GPP estimations and GPP_EC and vice versa. The solid arrows represent algorithm improvements while dashed arrows represent algorithm deterioration. Both the thickness of the arrow and the intensity of the color in model boxes, which are proportional to the percentages above, represent the degree of the model performances changes. The “Low ϵ_{\max} ” represents default ϵ_{\max} value for grassland in MODIS product, while the “High ϵ_{\max} ” represents the natural ϵ_{\max} estimations form ground measurements. The “FPAR: ϵ_{\max} ” in the central dashed ellipse shows the interaction of FPAR and ϵ_{\max} in GPP estimation models in this alpine swamp.

The improving performance of FPAR_G inputs, instead of FPAR_M , into GPP estimation model was different at distinct ϵ_{\max} levels (Figure 6 and Table 3). With the default ϵ_{\max} inputs, although GPP_MODR2 improved the agreement of GPP_MODR1 in daily GPP estimation by 11.8% of RPE with 0.38 g C m^{-2} decrease in RMSE, the promoting effects was still not significant (Table 3). Nevertheless, when we used the optimized ϵ_{\max} values from our estimation for this specific ecosystem, the effect of the introduction of FPAR_G (GPP_MODR3) instead of FPAR_M (GPP_MODR4) would generate an appreciable close to GPP_EC estimation by 27.6% of RPE with 0.58 g C m^{-2} decrease in RMSE (Table 3). Therefore, the discrepancies of FPAR changes in GPP estimation models among two distinct ϵ_{\max} levels implied that 15.8% of RPE would be related to the interaction of FPAR and ϵ_{\max} (FPAR: ϵ_{\max}) in GPP estimation models in this alpine swamp [74] (Figure 6). In addition, we also found the same discrepancies (15.8% of RPE) of ϵ_{\max} caused changes in GPP estimation models among two distinct FPAR levels through comparing changes of GPP estimation models from GPP_MODR1 to GPP_MODR4 (36.0% of RPE) and from GPP_MODR2 to GPP_MODR3 (51.8% of RPE) (Figure 6 and Table 3), which confirmed that the FPAR: ϵ_{\max} caused 15.8% of RPE in GPP estimation based on the MOD17A2 algorithm compared to in situ flux tower GPP (GPP_EC) in this alpine swamp meadow.

4.4. Algorithm Evaluation and Uncertainty

In this study, we found the revised MODIS GPP algorithms inordinately improved the GPP estimation quality except for the GPP_MODR1, in which the order of model improvements showed revised ϵ_{\max} (+36.0% of RPE) > FPAR: ϵ_{\max} (+15.8% of RPE) > FPAR_G (+11.8% of RPE) > meteorology data (−5% of RPE) through the comparisons of model performances (Figures 3–6 and Tables 1–3). Our results coincided with a comparative study in the forest ecosystems of the East Asia that demonstrated the errors of MODIS GPP were mainly caused by uncertainties in ϵ_{\max} and followed by those in FPAR and meteorological data [26]. Meanwhile, many studies pointed out that the improper parameterization of light use efficiency was the most significant limitation of the MOD17 algorithm [14,38,39]. Over an irrigated cropland and an alpine meadow ecosystem, research also confirmed that the underestimation of ϵ_{\max} was the main reason, and the followed was undervalued LAI-caused FPAR, for the considerable underestimation of GPP calculated using the MOD17 algorithm [34]. However, researches in a tropical

savanna show that the main reason for the differences between MODIS and tower derived GPP is FPAR, followed by LUE and meteorological inputs [27]. This could be attributed to the different upstream inputs across multiple biomes, artificially high values of MODIS FPAR at low productivity site and relatively low default ϵ_{\max} values at high productivity sites [17], in the LUE estimation procedure [28].

Although GPP_MODR3 predicted the seasonal and annual GPP patterns well and could be treated as an alternative GPP estimation method on this alpine swamp, an approximate 10% of RPE offset in daily GPP estimations still existed (Figures 3–5 and Table 3). Three kinds of reasons could explain this offset and the larger offsets in other MODIS-based GPP estimation models in this study. One is the parameter inputs in MOD17A2 algorithm [34]. First, many relevant researches proposed that the VPD only represents part of the atmospheric evaporative demand but is not entirely representative indicator of water availability condition thus it does not adequately reflect the observational GPP [25,26,35]. Therefore, they advised that soil moisture [17], remote water index [4,15], or precipitation [25] should be added as a stress factor in the MOD17 algorithm to improve GPP simulation [26]. However, in this study, the alpine swamp is waterlogged during the growing season thus the water limitation should not be the main reason for underestimation of MODIS-based GPP. Second, different cloudiness regulated the ϵ_{\max} value changes due to the change of solar radiation intensity, especially the diffuse radiation [75], which have direct or indirect influences on GPP estimation [17]. Moreover, previous studies suggested that light use efficiency should be different between sunlit and shaded leaf due to the distinct acceptance of direct and diffuse radiation [26,35]. Whereas we assumed a constant ϵ_{\max} value for this alpine swamp throughout the year, it also may be a reason for the current offsets in MODIS-based GPP estimation.

Another is the uncertainties in temporal-spatial matching between MODIS-based and ground measurements [19]. In the DAO with a spatial resolution of $1^\circ \times 1.25^\circ$ is hard to perfectly match a 1 km pixel of MODIS products, which may cause large inaccuracies in GPP estimation at spatial scales [19,28]. Besides, the footprint of GPP_EC is not the regular geographical pixel what the MODIS products provide, which implied the inconformity in GPP estimation [29]. In addition, MODIS products outputs an average LAI_M with an 8-day time step while LAI_G reflects the specific vegetation state in the measurement day, thus the errors of temporal match is also inevitable due to the vegetation activity [11].

The rest is the estimation errors of GPP_EC themselves. The EC measurement exist certain uncertainties caused by instrument malfunction, rainfall, dew formation, and human disturbances [76,77]. Additionally, both the gap filling and NEE partitioning are based on the assumption that the relationship between ecosystem respiration and temperature is similar in all day, daytime and nighttime [57,59,63,78], which may actually produce GPP_EC estimation error [21].

5. Conclusions

In this study, tower-based measurements were used to validate and improve the MODIS-based GPP products in an alpine swamp on the central Tibetan Plateau. Our results indicated that the MOD17 GPP strongly underestimated GPP_EC with a daily mean less than 40% of EC measurements. The large inaccuracies of MODIS GPP were mainly caused by the underestimation of ϵ_{\max} and followed by that of FPAR. The interaction of FPAR: ϵ_{\max} also affected the GPP estimation. We suggested that the suitable ϵ_{\max} for this alpine swamp was about 1.61 g C MJ^{-1} which was considerably larger than the default 0.68 g C MJ^{-1} for grassland. The FPAR_M underestimated 22.2% of the FPAR_G during the whole study period. However, the DAO meteorology data in the MOD17 algorithm did not exert a significant affection in the MODIS GPP underestimations. Therefore, site-specific optimized parameters inputs, especially ϵ_{\max} and FPAR_G, are necessary to improve the performance of MOD17 algorithm in GPP estimation, in which the calibrated MOD17A2 algorithm (GPP_MODR3) could explain 91.6% of GPP_EC variance for the alpine swamp meadow. Our results not only improved the accuracy of the site-specific MODIS GPP estimation greatly, but provide a simple approach to quantify GPP more accurately in other similar alpine swamp meadow on the Tibetan Plateau whose

field observation was still scanty despite of their extensive lands area and significant position in the winter rangeland for the local livestock.

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