



Retraction

Retraction: Jang et al. Lateral Handling Improvement with Dynamic Curvature Control for an Independent Rear Wheel Drive EV. *World Electr. Veh. J.* 2015, 7, 238–243

World Electric Vehicle Association

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The journal retracts the article, “Lateral handling improvement with dynamic curvature control for an independent rear wheel drive EV” [1], cited above, due to redundant publication with “Lateral handling improvement with dynamic curvature control for an independent rear wheel drive EV” by Jang, Y.-J., et al. [2] in the *International Journal of Automotive Technology*, where the authors submitted their work in 2016 after submitting to 28th International Electric Vehicle Symposium Exhibition (EVS28) as a conference paper in 2015.

The article is retracted from the *World Electric Vehicle Journal* and can henceforth be found under reference [2].

This retraction was approved by the Editor in Chief of the journal. The authors agreed to this retraction.



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1. Jang, Y.-J.; Lee, M.-Y.; Suh, I.-S.; Nam, K.H. Lateral handling improvement with dynamic curvature control for an independent rear wheel drive EV. *World Electr. Veh. J.* **2015**, 7, 238–243. [[CrossRef](#)]
2. Jang, Y.-J.; Lee, M.-Y.; Suh, I.-S.; Nam, K.H. Lateral handling improvement with dynamic curvature control for an independent rear wheel drive EV. *Int. J. Automot. Technol.* **2017**, 18, 505–510. [[CrossRef](#)]