

## Article

# Numerical Study on Pool Film Boiling of Liquid Hydrogen over Horizontal Cylinders

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**Abstract:** Due to the low boiling point of hydrogen, the boiling phenomenon is usually encountered in the applications of liquid hydrogen. The underlying mechanism as well as the physical performance of film boiling over horizontal cylinders are not yet fully understood, especially for the various diameters. In this paper, pool film boiling of hydrogen over horizontal cylinders with diameters ranging from 0.2 to 30 mm is investigated based on the volume-of-fluid method. By the analysis of the gas–liquid interface evolution and the heat transfer mechanism, the cylinders are divided into wire heaters, transition heaters, and tube heaters. The results show that the heat transfer of the wire is affected by the evolution of a single bubble, while the heat transfer of the tube is mainly affected by the movement of multiple crescent-shaped gas structures along the surface. Besides, with the increase in cylinder diameter, the bubble detachment diameter increases, the heat flux decreases correspondingly, and the bubble growth period experiences a complicated principle.

**Keywords:** film boiling; bubble dynamics; heat transfer characteristics; numerical simulation; wire heater; tube heater



**Citation:** Wang, J.; Li, Y.; Wang, L. Numerical Study on Pool Film Boiling of Liquid Hydrogen over Horizontal Cylinders. *Energies* **2022**, *15*, 1044. <https://doi.org/10.3390/en15031044>

Academic Editors: Alon Kuperman and Alessandro Lampasi

Received: 15 December 2021

Accepted: 20 January 2022

Published: 30 January 2022

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## 1. Introduction

Boiling is a highly energy-intensive vaporization process, frequently arising in many applications, such as the petroleum and petrochemical industry, nuclear power plants, spacecraft, and fusion systems. The fundamental understanding of the boiling phenomenon can be described by the Nukiyama curve [1], which represents the function of heat flux and wall superheat temperature (wall temperature minus saturation temperature). As shown in Figure 1, film boiling is observed when it comes to the case of large wall superheat temperature, such as metal chill-down [2], nuclear reactor accident analysis [3], and a superconducting environment [4]. In the film boiling regime, the heater is completely covered by the vapor layer from the surrounding liquid and continuous bubble generation and release happens at the liquid–vapor interface. Since the liquid hydrogen with a low boiling temperature is widely used in the spacecraft and fusion fields, knowledge of film boiling heat transfer from a horizontal cylinder surface is of great significance in both academic and industrial views.

Film boiling on the horizontal cylinder surface has been studied extensively both experimentally and analytically since the 1950s, with the focus on the diameter of the horizontal cylinder, the pressure of the system, subcooling, and wall superheat. Bromley et al. [5] first presented the analytical correlation for stable film boiling over a horizontal tube, which provided a basis for the following research. Banchemo et al. [6] performed a series of experiments with liquid oxygen for various diameters and pointed out that Bromley's equation failed to predict film boiling in a certain range of diameters. Breen and Westwater [7]

proposed a semi-empirical correlation of film boiling through extensive experiments using Freon 113 and isopropanol for a wide range of diameters. Flanigan [8] compared their experimental data with Bromley's equation as well as Breen and Westwater's equation and found that both correlations were inadequate for predicting film boiling of nitrogen and argon. Capone [9] investigated the variables of diameter, pressure, and wall superheat and also concluded that the deviations of both Bromley's equation and Breen and Westwater's equation from their experimental data were large. Wang et al. [10] collected a lot of experimental data about film boiling on horizontal cylinders to study Bromley's equation and Breen and Westwater's equation. The results showed that Bromley's equation had a better performance when the diameter of the heater was larger than 0.5–1 mm and Breen and Westwater's equation showed a better predictive ability with the diameter smaller than 0.5–1 mm. The Laplace reference length was defined as the characteristic length to distinguish tube and wire conditions. Gorenflo et al. [11] obtained the experimental data of film boiling over a horizontal tube with methane over the range of pressure between atmosphere and critical pressure. Pomerantz [12] performed film boiling experiments over a horizontal tube in an increased gravitation field and proved the validity of Bromley's equation within a certain range. Sakurai et al. [13,14] carried out extensive experiments and proposed a general correlation of film boiling on a horizontal cylinder based on laminar boundary layer theory [15,16]. Sarma et al. [17,18] developed a turbulence film boiling correlation with a horizontal cylinder under isothermal conditions, which was similar to Frederking and Clark's equation [19] within related conditions. For wire heaters, many studies [20–27] have been conducted to explore the influencing factors of pressure, subcooling, and superheat. Simonequ and Baurneister [20] combined visual and thermal experiments of film boiling under a wide range of pressure conditions, which verified that the heat transfer coefficient increased with a decrease in the wire diameter as well as an increase in the subcooling. Horie et al. [21] confirmed that the film boiling of hydrogen on horizontal wire was predicted well by Sakurai's correlation. Moreover, Rousselet et al. [22] and Siviour and Ede [23] extended the experimental data for subcooled film boiling and presented correlations for subcooled film boiling.

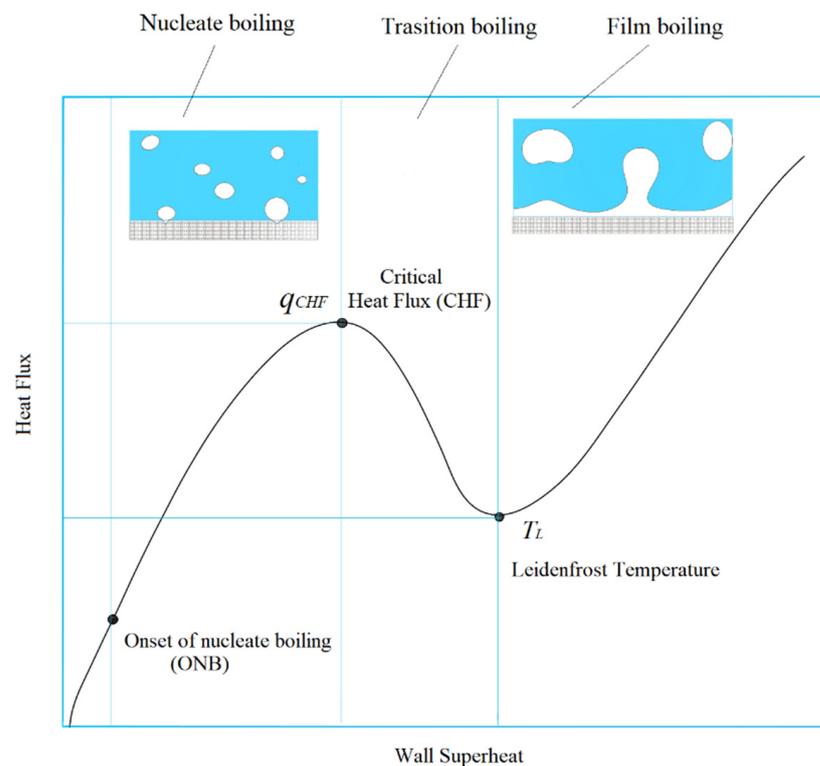


Figure 1. Nukiyama curve of pool boiling heat transfer.

Various methods were presented to track the interfacial profiles in the numerical study, including the Lagrangian moving-mesh method, the Eulerian volume-of-fluid (VOF) method, the Eulerian level-set (LS) method, the Lagrangian–Eulerian interface front-tracking (FT) method, and the Lattice Boltzmann method (LBM). The pioneering work of direct simulations of pool film boiling on a horizontal surface was conducted by Son and Dhir [24], who used the Lagrangian moving-mesh method to capture the interface but did not obtain the whole interfacial motion. Juric and Tryggvason [25] extended the front-tracking method using source terms in the continuity energy equation to simulate horizontal film boiling. Esmaeeli and Tryggvason [26,27] performed numerical simulations of film boiling over a large surface and observed multiple bubble formation and release from the vapor film using a model similar to the one used by Juric and Tryggvason. Son and Dhir [28] applied the level-set method to investigate the details about the bubble release pattern during horizontal film boiling. The volume-of-fluid method as a popular approach is reported by many studies [29–31] to simulate the two-phase phenomenon of hydrogen. The two-dimensional geometries were adapted, and the results showed good agreements [32–34]. Saha and Das [35] carried out the numerical simulation of boiling over wires with the VOF model in a three-dimensional domain. In addition, Tomar et al. [36], Ninge Gowda et al. [37], and Singh et al. [38] used the coupled level-set and volume-of-fluid (CLVOF) method to model the film boiling on a horizontal flat surface. In recent years, the Lattice Boltzmann method has drawn great attention in the simulating of multiphase fluids. A three-dimensional LBM model was developed by Sadeghi et al. [39] to simulate the film boiling over single and multimode horizontal zones. Ma and Cheng [40] pointed that the results from 2D and 3D simulations are identical to those from the Lattice Boltzmann method.

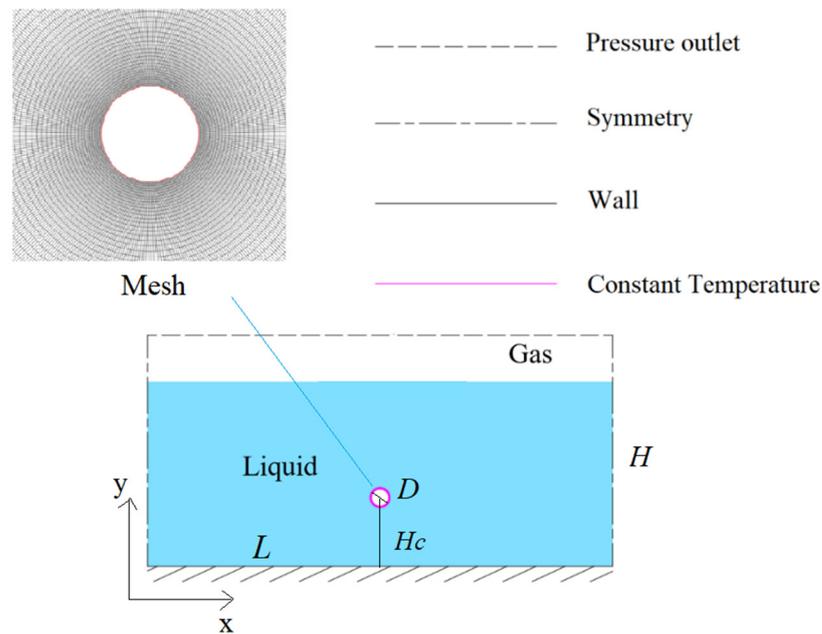
Although many experimental and numerical investigations have been carried out, the underlying mechanism as well as physical performance of the film boiling over horizontal cylinders is not fully understood, especially for the cases of various diameters of cylinders. Experimental studies provide the basis for theoretical models, but the empirical correlation is only applicable to a certain range of specific conditions. Due to the diversity of hydrogen applications, the study of film pool boiling over horizontal cylinders is complicated. The purpose of this paper is to analyze the physical and thermal characteristics of film boiling over horizontal cylinders and distinguish the heat transfer principles of wire and tube heaters, which can provide a theoretical basis for efficient utilization of liquid hydrogen.

## 2. Simulation Method and Modeling

A two-dimensional numerical model is developed to simulate the physical and thermal performance of subcooled film boiling of liquid hydrogen on horizontal cylinders. The diameters of the cylinders are changed from 0.2 to 30 mm to identify detailed principles of film boiling from wire and tube surfaces.

### 2.1. Physical Model

As shown in Figure 2, a cylinder heater is immersed horizontally in the liquid hydrogen pool of 18.324 K at atmosphere pressure. The heater surface is considered to be at a constant wall temperature of 80 K, the upper boundary of calculated region is the pressure outlet condition, and the sides of the liquid pool adopt symmetry boundary conditions. The two-dimensional model is divided into a fully structured grid and is encrypted near the surface of the cylinder heater, as shown in the figure. The diameter of the cylinder is changed from 0.2 to 30 mm, and the length of the liquid pool  $L$  is correspondingly set to 10 times the diameter of the cylinder.



**Figure 2.** The geometric diagram and boundary conditions (Adapted from Ref. [2]).

## 2.2. Governing Equations

The volume-of-fluid (VOF) multiphase method is adopted, and the continuity equations for the volume fraction are

$$\frac{\partial}{\partial t}(\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{v}_l) = S_l \quad (1)$$

$$\frac{\partial}{\partial t}(\alpha_g \rho_g) + \nabla \cdot (\alpha_g \rho_g \vec{v}_g) = S_g \quad (2)$$

For each control cell, the volumes of liquid and vapor sum up to unity.

$$\alpha_g + \alpha_l = 1 \quad (3)$$

The volume fraction weighted average method is used to calculate the fluid properties in each cell.

$$\varnothing_m = a_g \varnothing_g + a_l \varnothing_l \quad (4)$$

The momentum equation can be written as Equation (5), which is solved throughout the whole domain and shared by the two phases.

$$\frac{\partial}{\partial t}(\rho_m \vec{v}) + \nabla \cdot (\rho_m \vec{v} \vec{v}) = -\nabla p + \nabla \cdot \left[ \mu_m \left( \nabla \vec{v} + \nabla \vec{v}^T \right) \right] + \rho_m \vec{g} + \vec{F}_{vol} \quad (5)$$

The volume force  $\vec{F}_{vol}$  is transformed from surface tension and added as a source term to the momentum equation. The continuum surface force (CSF) model proposed by Brackbill et al. [41] is chosen to express the surface tension.

$$\vec{F}_{vol} = \sigma \frac{\alpha_l \rho_l \kappa_l \nabla \alpha_l + \alpha_g \rho_g \kappa_g \nabla \alpha_g}{0.5(\rho_l + \rho_g)} \quad (6)$$

where  $\kappa_l$  and  $\kappa_g$  are the surface curvatures.

$$\kappa_l = -\kappa_g = \nabla \cdot \left( \frac{\nabla \alpha_l}{|\nabla \alpha_l|} \right) \quad (7)$$

The energy equation can be written as

$$\frac{\partial}{\partial t}(\rho_m E) + \nabla \cdot [\vec{v}(\rho_m E + p)] = \nabla \cdot (\lambda_{eff} \nabla T) + S_h \quad (8)$$

The energy term  $E$  is computed as mass-averaged variables.

$$E = \frac{\alpha_g \rho_g E_g + \alpha_l \rho_l E_l}{\alpha_g \rho_g + \alpha_l \rho_l} \quad (9)$$

The effective thermal conductivity  $\lambda_{eff}$  is calculated as follows:

$$\lambda_{eff} = \lambda + \frac{c_p \mu_t}{Pr_t} \quad (10)$$

where  $c_p$  is the specific heat,  $\mu_t$  is the turbulent viscosity, and  $Pr_t$  represents the turbulent Prandtl number. The energy source term  $S_h$  is calculated as

$$S_h = S_m h_{fg} \quad (11)$$

Lee's model is selected in this paper, and the mass transfer rate per unit volume is calculated according to the following relations:

$$S_g = -S_l = r_i a_g \rho_g \frac{(T - T_{sat})}{T_{sat}} \text{ for condensation } (T < T_{sat}) \quad (12)$$

$$S_g = -S_l = r_i a_l \rho_l \frac{(T - T_{sat})}{T_{sat}} \text{ for evaporation } (T > T_{sat}) \quad (13)$$

where  $r_i$  is the mass transfer intensity factor with the unit of  $s^{-1}$ .

The upper boundary of the fluid is an open condition, described as follows:

$$y = H, p = p_0, \frac{\partial v}{\partial y} = 0, \frac{\partial T}{\partial y} = 0 \quad (14)$$

The symmetry boundaries of the sides of the liquid pool are expressed as

$$x = 0, x = L, \frac{\partial v}{\partial x} = 0, \frac{\partial T}{\partial x} = 0 \quad (15)$$

The boundaries for the solid surface are described as

$$y = 0, \frac{\partial T}{\partial y} = 0 \quad (16)$$

$$(x - L/2)^2 + (x - H_w)^2 = (D/2)^2, T = T_w \quad (17)$$

### 2.3. Turbulence Model

The combination of the  $k - \epsilon$  model and the wall function is a common method for turbulence calculation in the heat transfer process for the good convergence rate as well as low memory requirements. The low- $Re$   $k - \epsilon$  model proposed by Launder et al. [42] is a reasonable supplement to the  $k - \epsilon$  model that improves the calculation of the nearby wall area by modifying the damping function and additional terms. Due to the high calculation accuracy for heat flux, the low- $Re$   $k - \epsilon$  model is selected in this paper. The turbulent kinetic energy  $k$  and the turbulent energy dissipation rate  $\epsilon$  are calculated from the transport equations.

$$\frac{\partial}{\partial t}(\rho_m k) + \nabla \cdot (\rho_m k \vec{v}) = \nabla \cdot \left[ \left( \mu_m + \frac{f_\mu \mu_t}{\sigma_k} \right) \nabla k \right] + G_k - \rho_m \epsilon - D_k \quad (18)$$

$$\frac{\partial}{\partial t}(\rho_m \varepsilon) + \nabla \cdot (\rho_m \varepsilon \vec{v}) = \nabla \cdot \left[ \left( \mu_m + \frac{f_\mu \mu_t}{\sigma_\varepsilon} \right) \nabla \varepsilon \right] + f_1 C_{1\varepsilon} \frac{\varepsilon}{k} G_k - f_2 C_{2\varepsilon} \rho_m \frac{\varepsilon^2}{k} \quad (19)$$

where the  $f_\mu$ ,  $f_1$ , and  $f_2$  are the damping functions considering the effect of the turbulent Reynolds number  $Re_t$ .

$$f_\mu = \exp\left(-\frac{2.5}{1 + Re_t/50}\right) \quad (20)$$

$$f_1 = 1 \quad (21)$$

$$f_2 = 1 - 0.3 \exp(-Re_t^2) \quad (22)$$

$$Re_t = \frac{\rho_m k^2}{\varepsilon \mu_m} \quad (23)$$

$G_k$  represents the generation of turbulent kinetic energy due to the mean velocity gradients, and  $D_k$  represents the anisotropic dissipation effect of turbulent kinetic energy in the viscous sublayer.

$$G_k = f_\mu \mu_t \nabla \vec{v} \cdot (\nabla \vec{v} + \nabla \vec{v}^T) \quad (24)$$

$$D_k = 2\mu_m \left( \frac{\partial \sqrt{k}}{\partial r} \right)^2 \quad (25)$$

The equation includes five adjustable constants  $C_{1\varepsilon}$ ,  $C_{2\varepsilon}$ ,  $C_\mu$ ,  $\sigma_k$ , and  $\sigma_\varepsilon$ . The values in the simulation are as follows according to Launder et al. [42]:

$$C_{1\varepsilon} = 1.44, C_{2\varepsilon} = 1.92, C_\mu = 0.09, \sigma_k = 1.0, \sigma_\varepsilon = 1.3 \quad (26)$$

#### 2.4. Numerical Approaches

The numerical simulation in this paper selects the SIMPLE algorithm for the pressure and velocity equations based on pressure-based transient solver in commercial software Fluent. The second-order upwind scheme is used to discretize density, momentum, and energy equations; the geo-reconstruct scheme is chosen as volume fraction discretization; and the Green–Gauss Cell-Based and PRESTO schemes are applied for gradient and pressure discretization, respectively. The physical properties of the fluid are acquired according to Reference Fluid Properties Database (REFPROP). The time step is varied from  $10^{-6}$  s to  $10^{-4}$  s in the calculation process, and the convergence criterion of energy equation is  $10^{-6}$ .

### 3. Model Validation

#### 3.1. Phase Change Verification

The key problem in the application of the Lee phase change model is to find the appropriate coefficient  $r_i$ . The value of the mass transfer intensity factor  $r_i$  covers a wide range, from 0.1 to  $10^7$  s $^{-1}$  [43–45]. The optimum value of the empirical coefficient  $r_i$  is investigated by many studies, and the conclusions prove that a significantly low value of  $r_i$  could lead to discrepancy and an excessively high value of  $r_i$  would cause convergence problems. As shown in Figure 3, the optimum range of empirical coefficient  $r_i$  in this numerical model is from  $10^2$  to  $10^4$ .

#### 3.2. Grid Independence

Since the low- $Re$   $k - \varepsilon$  turbulence model requires a good-quality mesh near the wall, the dimensionless parameters  $y^+$  will definitely be less than 1 during the grid independence verification. To ensure calculation accuracy, three parameters are selected as the criteria. It can be seen from Figure 4 that when  $y^+$  is less than 1, the heat flux is less affected by the number of grids, but for the bubble diameter and the growth period, the grid needs to be dense enough to achieve accuracy. In the case of comprehensive consideration of heat

transfer and bubble behavior, 150,000 grids are considered to be suitable computational grids for this working condition.

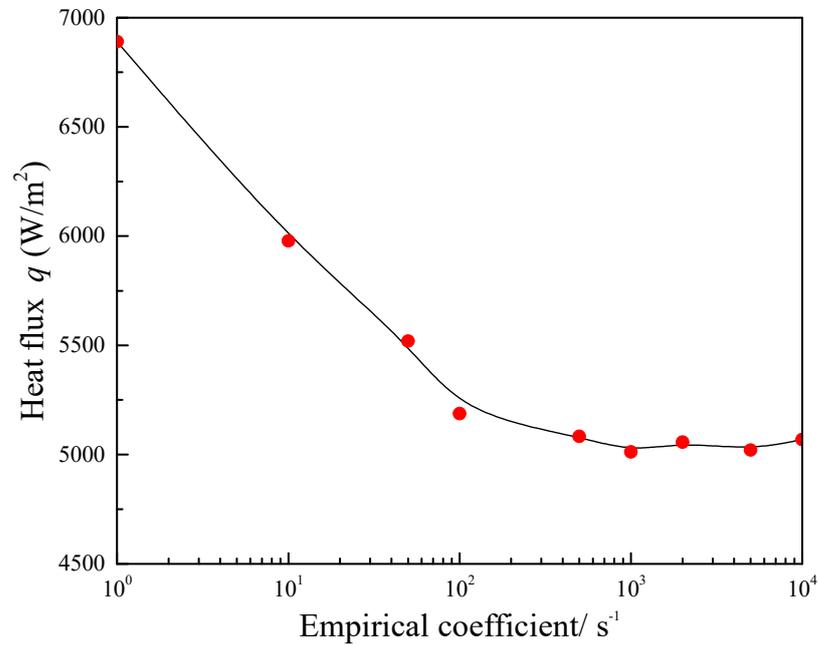


Figure 3. The calculated heat flux with different  $r_i$  values (Adapted from Ref. [2]).

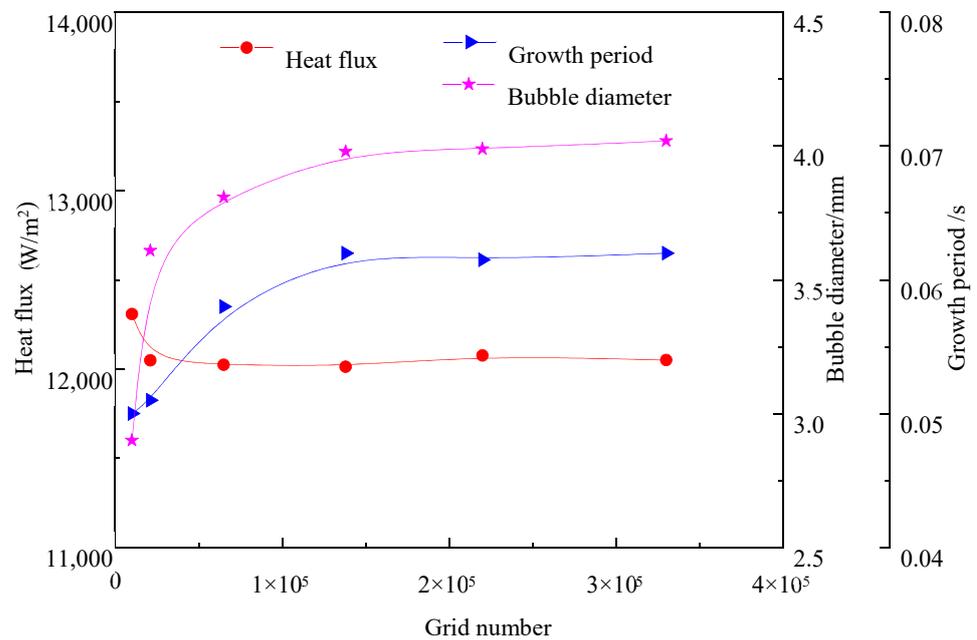


Figure 4. The results with different grid numbers.

### 3.3. Experimental Verification

Experimental verification is conducted with liquid hydrogen. The experimental data reported in Merte [46] are chosen as the verification condition, and the points in Figure 5 depict the boiling curve of hydrogen. The simulated results cover the film boiling section and agree well with the experimental data in terms of trend and value.

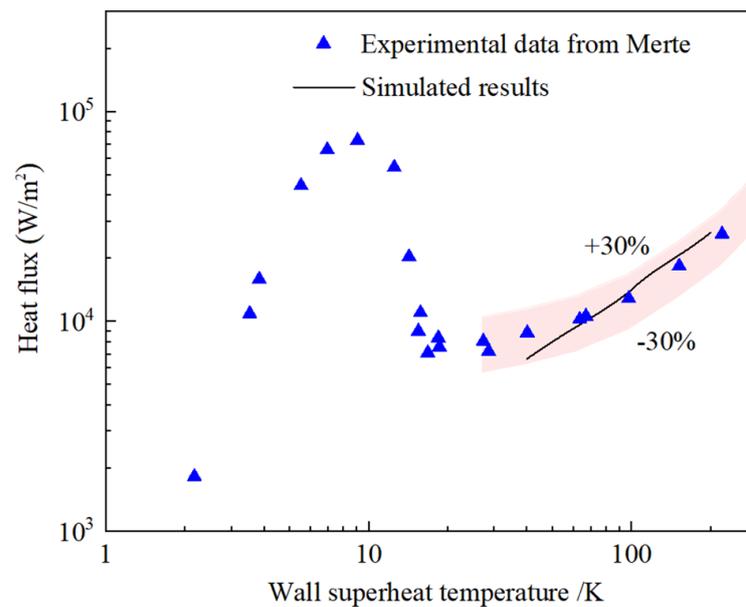


Figure 5. The comparison of calculated results and experimental data [46].

#### 4. Results and Discussion

The simulation of film boiling over cylinders of various diameters is performed based on the above model, and the physical and thermal characteristics are analyzed carefully. For the film boiling, the heater is completely covered by the gas layer and heat conduction through the gas film is the main driving energy for the phase change, so the evolution of the liquid–vapor interface is critical to the heat transfer mechanism. Periodic growth of bubbles on the horizontal cylinder and their detachment from the cylinder are observed for various conditions, and the bubble detachment shapes are illustrated in Figure 6.

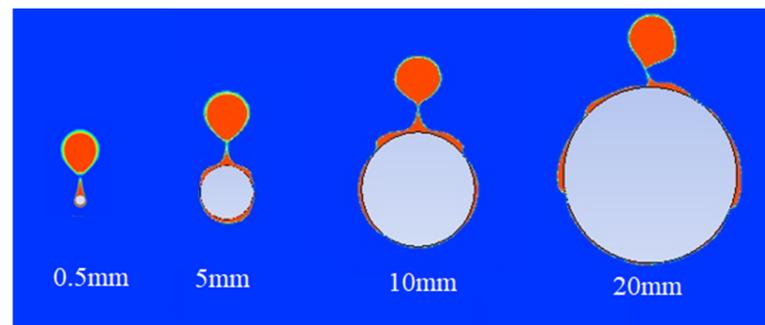
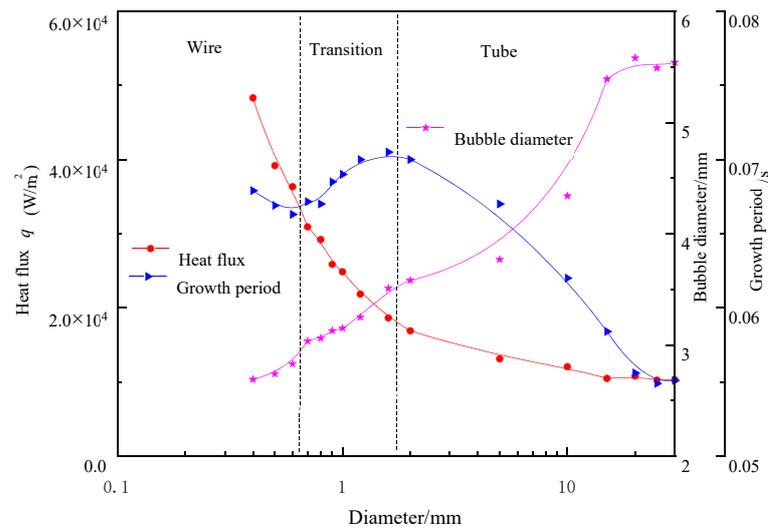


Figure 6. Bubble detachment shapes for various cylindrical diameters.

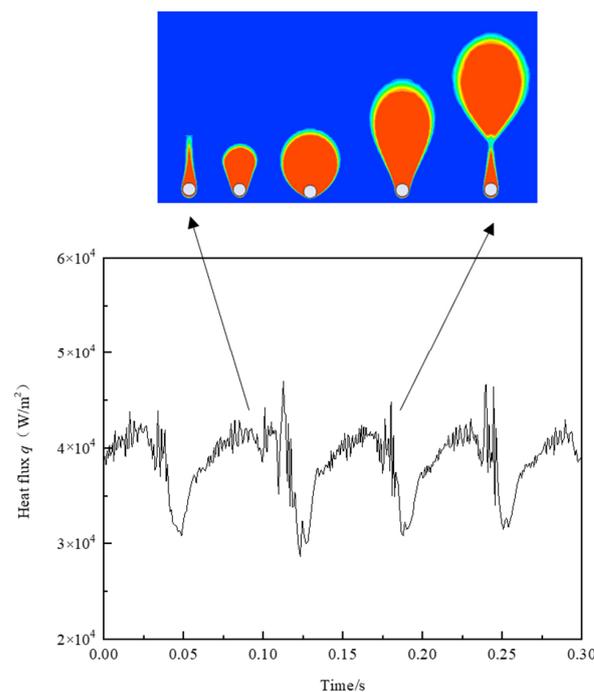
The time-averaged heat flux, the bubble detachment diameter, and the growth period for cylinders of various diameters are compared in Figure 7. As the diameter increases, the heat flux decreases and the bubble detachment diameter gradually increases. The bubble growth period shows a complicated law with the change in the diameter of the heating surface. According to the evolution of the liquid–vapor interface and the heat transfer performance, the cylinders in this paper are divided into three structures for analysis: wire heater, transition heater, and tube heater. As shown in Figure 7, the distinction between wire and transition is between 0.6 and 0.7 mm and the distinction between transition and tube is between 1.8 and 2 mm.



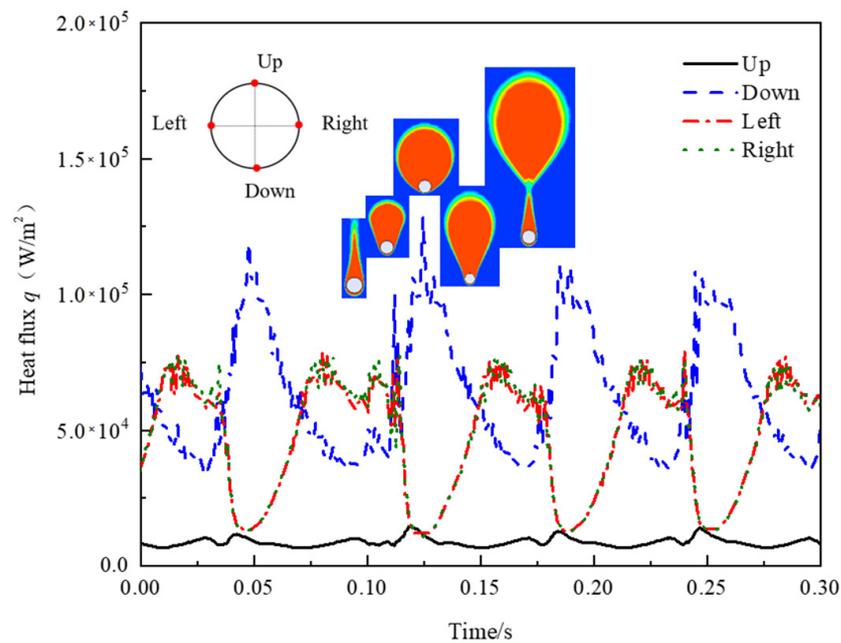
**Figure 7.** The thermal performance with different cylinder diameters.

#### 4.1. Film Boiling on a Wire Surface

Figure 8 shows the evolution of bubbles and the spatial-averaged heat flux of film boiling over the surface of the 0.5 mm wire. It can be seen that the formation and departure of bubbles correspond to the typical heat flux change cycle. When the heating surface is covered by thick gas film, the average heat flow decreases due to the increase in thermal resistance. Once the gas accumulated on the upper part of the wire under a buoyancy effect begins to form a bubble shape, the gas film covering the surface of the wire becomes thinner and the average heat flux gradually rises until the bubble leaves the wire. For a quantitative display, the heat flux at four typical positions on the wire surface over time is displayed in Figure 9. For the upper section, the heat flux remains low due to vapor accumulation for the whole process. The heat flux in the lower section of the wire changes periodically and the peak heat flux can reach the bottom of the wire. The heat flux on both left and right sides is exactly the same and also fluctuates periodically as the bubble evolves.

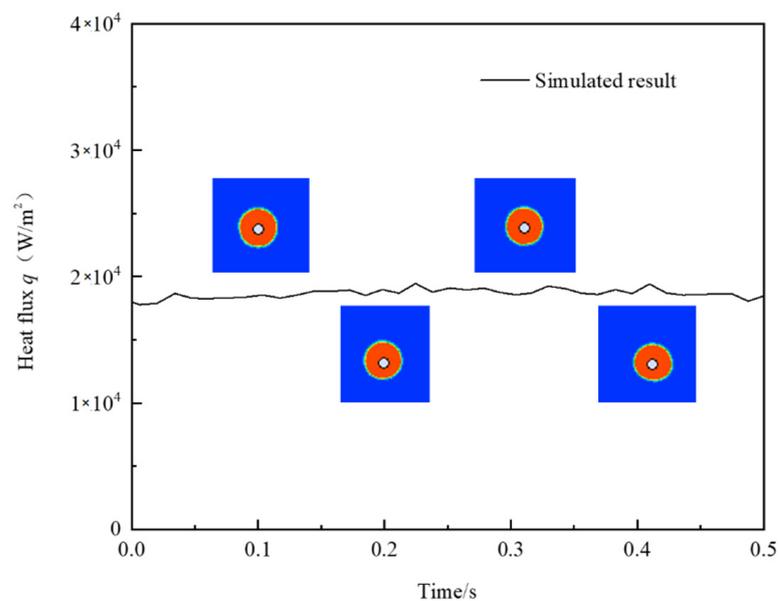


**Figure 8.** The spatial-averaged heat flux and the evolution of bubbles for the 0.5 mm wire.

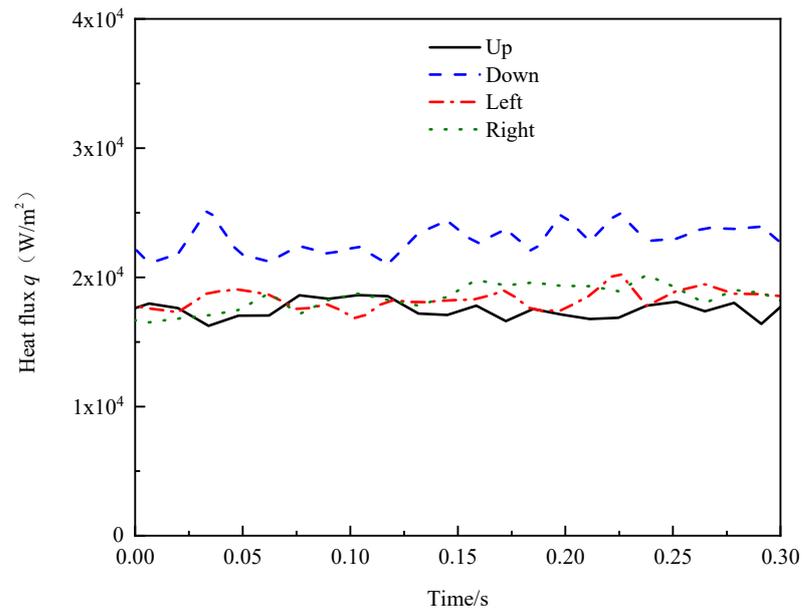


**Figure 9.** The heat flux at four typical positions of the 0.5 mm wire heater during film boiling.

Because it is a small-diameter wire, the physical behavior as well as the heat transfer mechanism of the 0.2 mm wire shows a different pattern. Figure 10 displays the spatial-averaged heat flux and the evolution of the gas–liquid interface for a 0.2 mm wire heater. The wire is wrapped by gas film, and the spatial-averaged heat flux keeps stable during the whole film boiling process. The heat flux at four typical positions is illustrated in Figure 11. It is noted that the heat flux at the bottom of the wire is higher than at the other three positions under the buoyancy effect. This phenomenon can be explained by the energy balance at the phase interface. For the small-diameter wire heater, the heat conducted through the vapor film is small and can be totally eliminated by the condensation effect driven by subcooled bulk liquid, so the gas cannot accumulate enough to form bubbles.



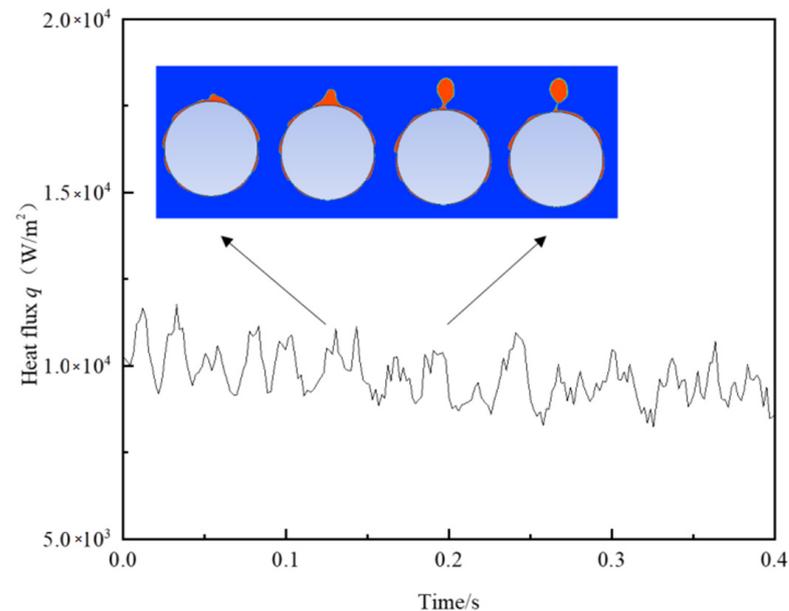
**Figure 10.** The spatial-averaged heat flux and the evolution of the gas–liquid interface for the 0.2 mm wire.



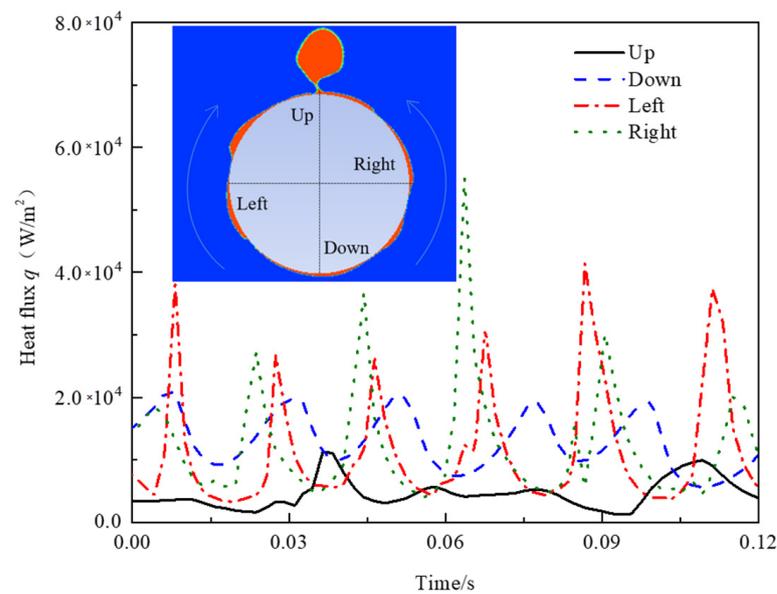
**Figure 11.** The heat flux at four typical position of the 0.2 mm wire heater during film boiling.

#### 4.2. Film Boiling on the Tube Surface

Figure 12 shows the evolution of bubbles and the spatial-averaged heat flux of film boiling over the surface of the 25 mm wire. Compared with the wire surface, the heat flux fluctuation of the tube surface is smaller and its fluctuation law does not correspond to the periodic growth of bubbles. Several crescent-shaped gas structures move slowly upward on both sides of the tube and accumulate at the top to form bubbles. Figure 13 displays the heat flux at four typical positions on the 25 mm tube surface over time. The peak heat flux happens on the left or the right, which exhibits periodic fluctuations with the movement of the crescent-shaped gas structure. The heat flux at the bottom of the tube also fluctuates cyclically, but the amplitude is smaller than that on both sides. Similar to the wire structure, the heat flux on top is the smallest and reaches a maximum when the bubble leaves.



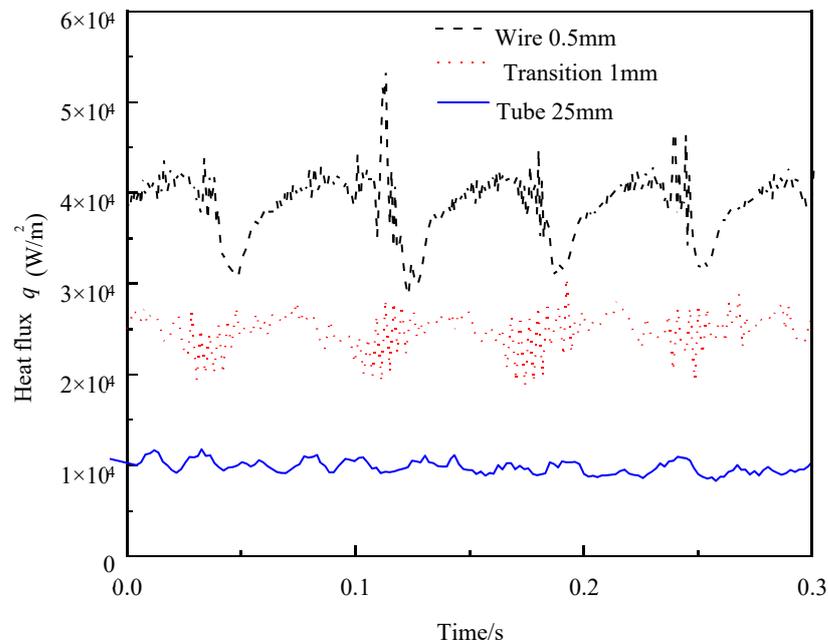
**Figure 12.** The spatial-averaged heat flux and the evolution of the gas–liquid interface for the 25 mm tube.



**Figure 13.** The heat flux at four typical positions of the 25 mm tube heater during film boiling.

#### 4.3. Analysis of Heater Diameter

The spatial-averaged heat flux comparison of three typical diameter heating surfaces (0.5 mm wire, 1 mm transition, and 25 mm tube) is shown in Figure 14. It is obvious that the fluctuation amplitude and the average value of heat flux decrease with an increase in diameter. There are similarities as well as differences between the small-diameter cylinder heater and the large-diameter cylinder heater. Combined with the above analysis, the heat transfer of the wire is affected by the evolution of a single bubble, while the heat transfer of the tube is mainly affected by the movement of multiple crescent-shaped gas structures along the surface.



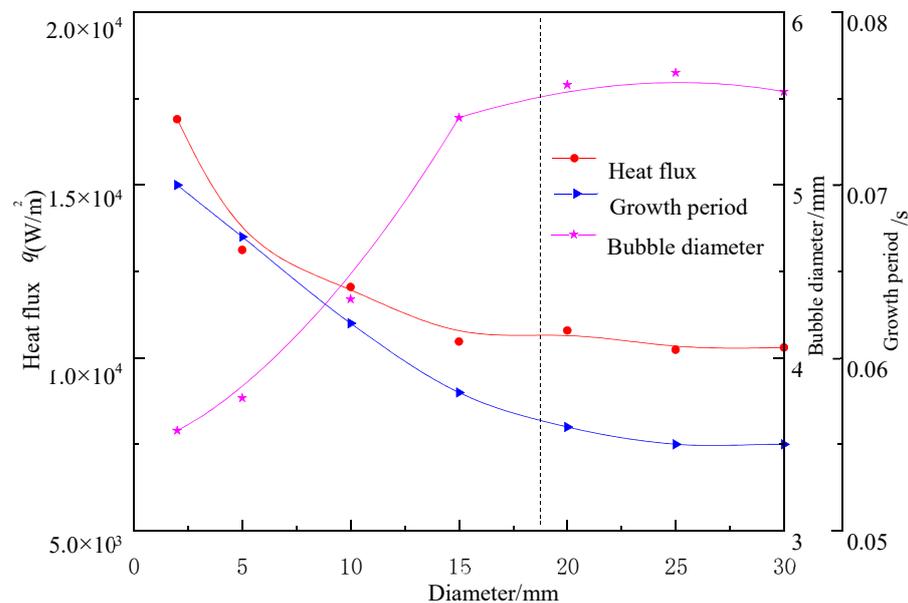
**Figure 14.** The spatial-averaged heat flux of horizontal cylinders with different diameters.

For the horizontal plate heating structure, the gas–liquid interface in the pool film boiling follows the Rayleigh–Taylor instability. The critical wavelength deduced from related instability analysis is a significant length scale for the bubble departure diameter.

The release of the bubble is mainly affected by gravity and surface tension. Therefore, if the influence of the heating surface structure is excluded, the bubble departure diameter becomes a constant parameter.

$$\lambda_c = 2\pi\sqrt{\rho/g(\rho_l - \rho_g)} \quad (27)$$

For tube heaters, the time-averaged heat flux, the bubble detachment diameter, and the growth period with various diameters are shown in Figure 15. As the diameter of the tube increases, the bubble detachment diameter gradually increases and the heat flux as well as the bubble growth period gradually decrease. There is an asymptotic value of the bubble detachment diameter with an increase in the tube diameter, which is a special feature of the tube heating surface.



**Figure 15.** The thermal performance for the tube heating surface.

For the wire heater, the thermal performance with various diameters is compared in Figure 16. There are two different gas–liquid interface patterns with the increase in the wire diameter. For the small-diameter wires, the heating surface is wrapped by thick gas film instead of the bubble evolution and the heat flux is small. For the large-diameter wires, the bubble diameter increases with the increase in the wire diameter and the bubble growth time decreases correspondingly. Poorer heat transfer performance is also observed as the diameter increases for the wire heating surface.

Figure 17 shows the gas–liquid interface pattern under different subcooling conditions for a 0.5 mm wire heater. It is shown that the bubble departure diameter decreases with an increase in the subcooling temperature. When the degree of subcooling exceeds a certain level, there is no bubble formation and departure. This is due to the fact that the enhanced condensation effect leads to a reduction in gas volume. When the condensing effect is large, the conduction heat through gas film can be removed totally, so a balance is reached and no bubble growth happens at the gas–liquid interface. Since the evolution of the liquid–gas interface has a direct effect on the heat transfer performance, the heat flux also experiences a sudden change phenomenon. Figure 18 displays the heat flux for the wire in different subcooling conditions. It is noted that the transition diameter increases with an increase in the subcooling degree. This is because for the larger subcooling liquid, more heat from the heating surface is required to balance the condensation effect.

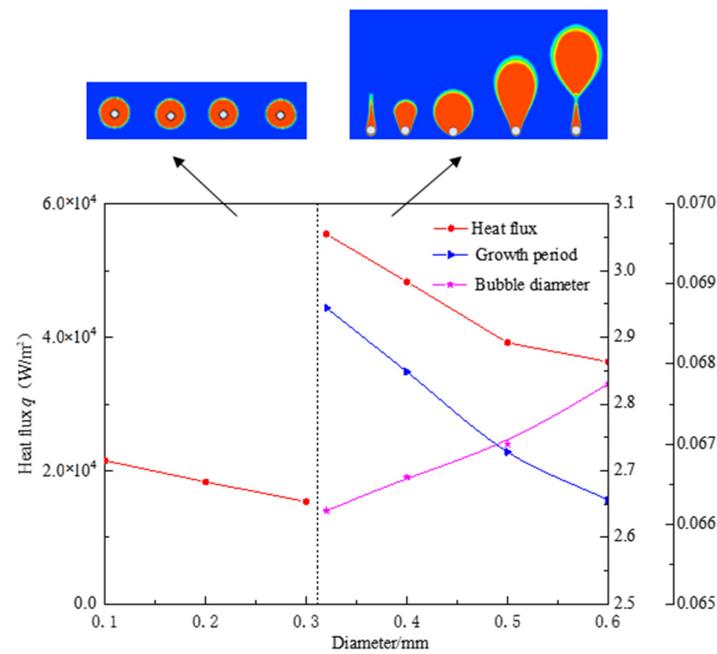


Figure 16. The thermal performance for the wire heating surface.

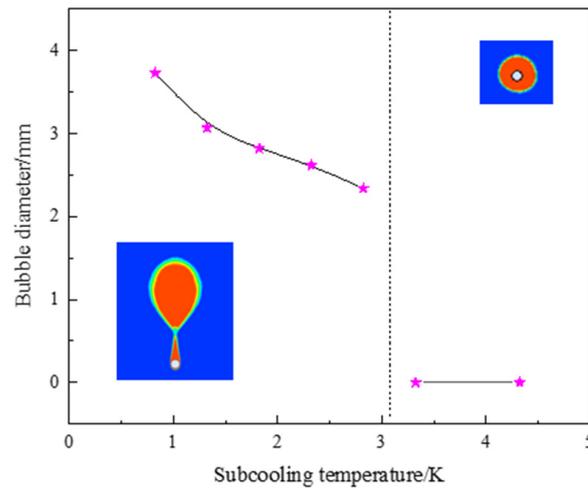


Figure 17. Bubble departure diameter for 0.5 mm wire heaters with different subcooling degrees.

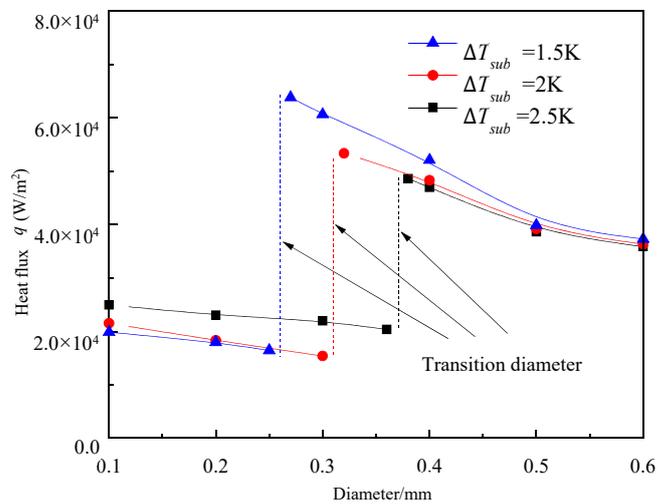


Figure 18. The time-averaged heat flux for a wire with different subcooling degrees.

## 5. Conclusions

The simulation of pool film boiling of hydrogen over a horizontal cylinder is performed, and the diameter of the horizontal cylinder ranges from 0.2 to 30 mm. The main conclusions are summarized as follows:

- (1) The diameter of the horizontal cylinder is a key factor affecting the thermal and physical performance of hydrogen pool film boiling. As the diameter increases, the bubble detachment diameter gradually increases, the heat flux decreases, and the bubble growth period experiences a complicated law.
- (2) For the wire heating surface, the heat flux is affected by the evolution of a single bubble and the formation and departure process of a bubble exactly corresponds to a typical cycle of heat flux change. Besides, the small-diameter wire is wrapped by gas film and the spatial-averaged heat flux keeps stable during the whole film boiling process.
- (3) For the tube heating surface, the heat transfer is mainly affected by the movement of multiple crescent-shaped gas structures along the surface and the heat flux fluctuation is smaller than that of the wire surface. When the diameter of the tube increases to a certain extent, the bubble detachment diameter, the heat flux, and the bubble growth period all reach stable values.
- (4) As the wire diameter increases, two different gas–liquid interface patterns are observed. The degree of subcooling and the diameter of the wire heater are two determining factors for the gas–liquid interface shape. In addition, the transition diameter of two different thermal performance patterns increases with the increase in the subcooling degree.

In conclusion, the results in this paper reveal the heat transfer behaviors of pool film boiling of hydrogen over horizontal cylinders, which provides a theoretical basis for engineering applications. When the degree of subcooling exceeds a certain level, no bubble growth happens at the gas–liquid interface and the heat flux is significantly small. The special characteristics of the thick gas film instead of the bubble evolution are analyzed and provide a possible point to avoid heat transfer deterioration.

**Author Contributions:** Software, J.W.; validation, L.W.; formal analysis, J.W.; writing—original draft preparation, J.W.; supervision, L.W.; project administration, Y.L.; funding acquisition, Y.L. All authors have read and agreed to the published version of the manuscript.

**Funding:** This work was supported by the National Natural Science Foundation of China (51876153, 51976151) and the Research Fund of State Key Laboratory of Technologies in Space Cryogenic Propellants (SKLTSCP202004). The China Scholarship Council (Grant No. 201906280355) is gratefully acknowledged.

**Institutional Review Board Statement:** Not applicable.

**Informed Consent Statement:** Not applicable.

**Data Availability Statement:** Not applicable.

**Acknowledgments:** The State Key Laboratory of Technologies in Space Cryogenic Propellants and China Scholarship Council are gratefully acknowledged.

**Conflicts of Interest:** The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

## Nomenclature

$c_p$	Specific heat, J/(kg·K)
$D$	Diameter of cylinder, m
$E$	Internal energy, J/kg
$F_{vol}$	Volume force, N/m <sup>3</sup>
$g$	Acceleration due to gravity, m/s <sup>2</sup>
$h$	Enthalpy, J/kg
$H$	Height of hydrogen pool, m
$H_c$	Height of cylinder, mm
$h_{fg}$	Latent heat, J/kg
$L$	Length of hydrogen pool, m
$Nu$	Nusselt number
$p$	Pressure, Pa
$P_0$	Atmospheric pressure, Pa
$Pr$	Prandtl number
$Pr_t$	Turbulent Prandtl number
$q$	Heat flux, W/m <sup>2</sup>
$Re$	Reynolds number
$S$	Volume mass source, kg/(m <sup>3</sup> s)
$Sh$	Energy source term, J/(m <sup>3</sup> s)
$t$	Time, s
$T$	Temperature, K
$\Delta T_{sup}$	Wall superheat, $T_W - T_{sat}$
$\Delta T_{sub}$	Liquid subcooling, $T_{sat} - T_l$
<i>Greek symbols</i>	
$\alpha$	Void fraction
$\varepsilon$	Turbulence dissipation rate, m <sup>2</sup> /s <sup>3</sup>
$\rho$	Density, kg/m <sup>3</sup>
$k$	Surface curvature, 1/m
$\lambda$	Thermal conductivity, W/(mK)
$\lambda_c$	The most dangerous wavelength, m
$\mu$	Dynamic viscosity, Pa·s
$\mu_t$	Turbulent viscosity, Pa·s
$v$	Velocity, m·s <sup>-1</sup>
$\gamma$	Enthalpy, J/kg
$\sigma$	Surface tension, N/m
$\Phi$	Generic property
<i>Subscripts</i>	
$eff$	Effective
$f$	Fluid
$g$	Gas
$l$	Liquid
$m$	Mixture property
$sat$	Saturation property
$sub$	Subcooled property
$sup$	Superheat property
$w$	Wall

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