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**Abstract:** Carbon trading is a market-based mechanism towards low-carbon electric power systems. A hy-brid game optimization model is established for deriving the optimal trading price between mi-crogrids (MGs) as well as providing the optimal pricing scheme for trading between the microgrid cluster(MC) and the upper-layer service provider (SP). At first, we propose a robust optimization model of microgrid clusters from the perspective of risk aversion, in which the uncertainty of wind and photovoltaic (PV) output is modeled with resort to the information gap decision theo-ry(IGDT). Finally, based on the Nash bargaining theory, the electric power transaction payment model between MGs is established, and the alternating direction multiplier method (ADMM) is used to solve it, thus effectively protecting the privacy of each subject. It shows that the proposed strategy is able to quantify the uncertainty of wind and PV factors on dispatching operations. At the same time, carbon emission could be effectively reduced by following the tiered carbon price scheme.

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**Copyright:** © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). **Keywords:** information gap decision theory (IGDT); Nash bargaining; microgrid cluster (MC); hybrid game; distributed optimization; tiered carbon price

## 1. Introduction

Many carbon emission trading schemes have been proposed and implemented worldwide in recent decades to slow or stop human-caused global warming [1]. The European union emissions trading system was initiated in 2005 by the EU and is still considered to be the largest single market for emission allowance trading [2]. In pursuance of the commitment to realize a carbon emissions peak in 2030 and achieve carbon neutrality in 2060, China launched the world's largest carbon trading market in Shanghai on 16 July 2021 [3,4].

The operation of the power system naturally brings about, for example, combustion of fossil fuel [5,6]. To reduce the volume of carbon emissions in the operation of the power system, smart grid technologies had been significantly introduced in the last two decades, as they possess the capability of integrating multiple low-carbon renewable energy sources, such as photovoltaic (PV) and wind [7]. In recent years, the concepts of microgrid (MG) and microgrid cluster (MC) have become more and more popular in the smart grid community [8]. MG is a small-scale electrical power grid that consists of microgeneration units, storage units, and controllable loads. Microgrid clusters refer to multiple interconnected microgrids that facilitate energy exchange among the participating prosumers, producers, and customers. For the sake of carbon reduction in a smart grid, a promising way is to formulate a carbon emission trading incorporated energy management system within the architecture of MCs [9,10].

The trading price plays a decisive role in the designing of trading systems. Regarding the energy transaction of MCs, it is a challenging task to generate a fair price that balances the demands of prosumers, producers, and customers, as the demands are often competitive and conflictive [11]. In the related literature, game theory was extensively employed to seek the promising transaction modes in a smart grid society. In [12,13], the Stackelberg game model is utilized to generate the transaction price between MC and MG, in which the relationship of MC and MG is viewed as leader and follower. In [14,15], cooperative game models are created to reveal the cooperative and competitive behaviors of MCs. Furthermore, with the aid of Nash bargaining theory, cooperative game models can also be used simultaneously for multi-objective optimization, such as maximizing both the annual profit and the energy index of reliability [16,17]. It is pointed out that the Nash bargaining technique leads to a faster convergence than the heuristic algorithms that are equipped with remedies such as greedy or linear relaxation [18]. To realize the goal of carbon emission reduction, not only interplay of MCs, but also the transaction between MCs and the other market players of the main grid should be take into consideration. This makes it a complex optimization problem with many more decision variables; at the same time, it is difficult to produce a promising carbon trading price mechanism by applying existing game theory-based methods directly.

The high-penetration rate of renewable energy such as wind and PV in MCs provide a great potential for carbon emission reduction. However, modeling of MCs becomes technically challenging due to the inherent climate-dependent uncertainty of wind and PV [19,20]. Generally speaking, commonly used mathematical tools to cope with uncertainties include but are not limited to stochastic optimization [21,22], robust optimization [23,24], interval optimization [25,26], and distributionally robust optimization [27,28], to name a few. A scenario generation scheme is used to capture the strong randomness and interdependence between wind speeds by utilizing historical wind data, which leads to reliable Microgrid scheduling results by resorting to stochastic programming [29]. In [30], the wind speed uncertainty is modeled as a colored noise via a second-order autoregressive model; on that basis, a stochastic program is solved to increase the expected value of the profit distribution and keep the risk of profit variability controllable. In [31,32], an interval optimization method was facilitated to generate robust system dispatchers for combating fluctuation of wind power and photovoltaic over pre-specified intervals. In addition to a priori knowledge of the uncertainties, the tractability and computational efficiency of the recast optimization problems also play an important role in the development of techniques and tools for dealing with the uncertainties. Information gap decision theory (IGDT) is a powerful tool converting stochastic uncertainty into a deterministic setting. In [33,34], IGDT was introduced to describe the uncertainty of wind and PV, and a bi-layer stochastic optimization model was established to solve the day-ahead dispatching of MGs.

This paper aims to solve the carbon allowance allocation and the uncertainty problem based on renewable energy (RE), which develops a hybrid game optimization of carbon emissions considering a tiered price for SP with MC. In this paper, the MC dispatch model of carbon capture system (CCS) is given, and the risk aversion strategy is used to deal with the uncertainty of wind and PV. Furthermore, it shows that the carbon emission of MC is influenced by guiding the carbon price. Finally, the effectiveness of the proposed method in the collaborative optimization of MC is verified, and the uncertainty of wind and PV and tiered price are analyzed to verify the feasibility of using the hybrid game optimization in the case study.

Briefly, the contributions of the paper can be summarized as follows:

- The MC system considering the tiered carbon price is proposed in this paper, which combines with the service provider (SP) to provide the electricity purchase/sale price for the MC to access the utility grid.
- The risk-avoidance strategy is adopted to consider the uncertainty of wind and PV, and the information gap decision theory (IGDT) is used to solve the robust dispatch model of its uncertainty.

• A new hybrid game model is adopted, which uses the stackelberg game to deal with the relationship between SP and MC and uses Nash equilibrium theory to solve the payment interests among MGs.

# 2. System Modelling

In this study, in order to evaluate the proposed method, service providers are used to dispatch the MC composed of three MGs, as shown in Figure 1. In addition, MG1 contains different units from MG2 and MG3. MG1 contains RE, combined heat and power generation (CHP), ground source heat pump (GSHP), and CCS, etc., whereas MG2 and MG3 contain GT, GB, and CCS, etc.



Figure 1. Sample MC system structure.

The following sections contain the detailed modelling of the entities.

### 2.1. System Structure

Each MG has an operator that manages its own unit and trading power simultaneously with other MGs and the SP. A discrete time model with a 24 h horizon is considered. We assume that the time interval is 1 h, so there are 24 decisions in the dispatching cycle.

### 2.2. MG Modelling

In this study, a carbon trading MG is proposed, and the objective function and related constraint operating in the inter trading mode are as follows:

• Objective function of each MG:

$$\begin{array}{ll} \min \ Z_{\mathrm{MG},i} &= \sum\limits_{t=1}^{24} \left( C_{\mathrm{grid}}^{i,t} + C_{\mathrm{fuel}}^{i,k,t} + C_{\mathrm{ES}}^{i,m,t} \right) + C_{V}^{i} \\ C_{\mathrm{grid}}^{i,t} &= p_{\mathrm{buy}}^{i,t} P_{\mathrm{buy}}^{i,t} - p_{\mathrm{sell}}^{i,t} P_{\mathrm{sell}}^{i,t} \\ C_{\mathrm{fuel}}^{i,t} &= p_{\mathrm{gas}}^{i} G_{\mathrm{gas}}^{i,t} \\ C_{\mathrm{ES}}^{i,t} &= \sum_{j} \left( p_{\mathrm{ES}}^{\mathrm{P},i,j} \left( P_{\mathrm{ES}}^{\mathrm{dis},i,j,t} + P_{\mathrm{ES}}^{\mathrm{ch},i,j,t} \right) + p_{\mathrm{HS}}^{\mathrm{H},i,j} \left( H_{\mathrm{HS}}^{\mathrm{dis},i,j,t} + H_{\mathrm{HS}}^{\mathrm{ch},i,j,t} \right) \right) \\ C_{V}^{i} &= p_{0}^{i} E_{0}^{i} + \sum\limits_{v=1}^{V-1} \left( p_{0}^{i} + (v-1)\sigma_{v}^{i} \right) E_{v}^{i} + \sum\limits_{v=V}^{N} \left( p_{0}^{i} + V\sigma_{v}^{i} \right) E_{v}^{i} \end{array}$$

where  $p_{buy}/p_{sell}$  are the prices of buying/selling electric power between each MG and the SP, respectively;  $p_{gas}$  is the price of nature gas;  $p_{FS}^{P}$  is maintenance price of the discharge/charge

electric power in ES;  $p_{\text{HS}}^{\text{H}}$  is the maintenance price of the discharge/charge heat power in HS;  $E_v$  is the price of carbon emission in CCS. *i*, *j*, and *t* are the index of MG, ES, and time, respectively.

Objective function of the *i*th MG includes four terms referred to as the cost of trading power from the utility grid, cost of natural gas combustion, maintenance cost of discharge/charge power with ES and HS, and cost of carbon trading. The tiered carbon emission price in the interval is shown in Figure 2. Note that the carbon price in the 0th and 1st interval is  $p_0$ , whereas the actual carbon emission is less than the quota quality. The carbon price is related to both the *v*th interval and the increment  $\sigma$  in the interval  $1 \le v \le V$ , and the carbon quota is less than the actual emission. When the carbon emission exceeds the *V*th interval, the carbon price is only related to the increment  $\sigma$ . There is the index for time, which is used for hourly dispatch. The constraints, which are related to each unit of the MG, are as follows:



Figure 2. Interval tiered carbon price.

• CHP operating constraints:

$$P_{\rm CHP}^{i,t} = \eta_{\rm CHP} H_{\rm CHP}^{i,t} \tag{2}$$

$$-R_{\rm CHP}^{\max,i} \le P_{\rm CHP}^{i,t-1} - P_{\rm CHP}^{i,t-1} \le R_{\rm CHP}^{\max,i}$$
(3)

$$P_{\rm CHP}^{\min,i} \le P_{\rm CHP}^{i,t} \le P_{\rm CHP}^{\max,i} \tag{4}$$

$$H_{\rm CHP}^{\min,i} \le H_{\rm CHP}^{i,t} \le H_{\rm CHP}^{\max,i} \tag{5}$$

$$P_{\rm CHP}^{i,t} = V_{\rm CHP}^{i,t} \lambda_{\rm CHP}^i L H V_{\rm CHP} \tag{6}$$

where  $P_{\text{CHP}}$  and  $H_{\text{CHP}}$  are electric/heat powers of CHP, respectively;  $\eta_{\text{CHP}}$  is the heat to electricity conversion efficiency of CHP;  $R_{\text{CHP}}$  is the ramp rate of CHP electric power;  $V_{\text{CHP}}$  is the natural gas volume of CHP;  $\lambda_{\text{CHP}}$  is power generation efficiency of CHP;  $LHV_{\text{CHP}}$  is the combustion natural gas value of CHP; and min/max is superscript for min/max amount of the variable.

Equation (2) is the operation mode of ordering electric by heat. Equation (3) refers to the ramp rate limitation. Constraints (4) and (5) express the allowable electric and heat power of CHP. Calculation of the natural gas volume required for electric power generated by CHP uses Equation (6).

GB and GT constraints:

$$P_{\rm GT}^{\min,i} \le P_{\rm GT}^{i,t} \le P_{\rm GT}^{\max,i}$$
(8)

$$P_{\rm GB}^{\min,i} \le P_{\rm GB}^{i,t} \le P_{\rm GB}^{\max,i} \tag{9}$$

$$P_{\rm GT}^{i,t} = V_{\rm GT}^{i,t} \lambda_{\rm GT}^i L H V_{\rm TB} \tag{10}$$

$$P_{\rm GB}^{i,t} = V_{\rm GB}^{i,t} \lambda_{\rm GB}^i L H V_{\rm TB} \tag{11}$$

$$V_{\rm TB}^{i,t} = V_{\rm GB}^{i,t} + V_{\rm GT}^{i,t}$$
(12)

where  $P_{\text{GT}}$  and  $P_{\text{GB}}$  are the electric powers of GT and GB, respectively;  $V_{\text{GB}}$  and  $V_{\text{GT}}$  are the natural gas volume of GB and GT, respectively;  $V_{\text{TB}}$  is the total natural gas volume;  $LHV_{\text{TB}}$  is the lower combustion natural gas value of GB and GT;  $\lambda_{\text{GB}}$  and  $\lambda_{\text{GT}}$  are the power generation efficiency of GB and GT, respectively; and  $\eta_{\text{GT}}^{\text{E}}/\eta_{\text{GT}}^{\text{H}}$  is electrical/heat efficiency of GT.

Constraint (7) is the coupling relation between electric and heat. Constraints (8) and (9) indicate the allowable electric power of GB and GT. Constraints (10) and (11) stand for electric power generated by GB and GT natural gas. Constraint (12) illustrates the total volume of natural gas between GB and GT.

• ES and HS constraints:

$$0 \le P_{\mathsf{FS}}^{\mathsf{ch},i,t} \le \mu_{\mathsf{FS}}^{\mathsf{ch},i} P_{\mathsf{FS}}^{\mathsf{ch},\mathsf{MAX},i} \tag{13}$$

$$0 \le P_{\rm ES}^{{\rm dis},i,t} \le \mu_{\rm ES}^{{\rm dis},i} P_{\rm ES}^{{\rm dis},MAX,i}$$
(14)

$$0 \le \mu_{\rm FS}^{\rm ch,i} + \mu_{\rm FS}^{\rm dis,i} \le 1 \tag{15}$$

$$SE^{\mathrm{MIN},i} \le SE^{i,t} \le SE^{\mathrm{MAX},i}$$
 (16)

$$SE^{i,t+1} = SE^{i,t} + \left(\eta_{\rm ES}^{{\rm ch},i}P_{\rm ES}^{{\rm ch},i,t} - \frac{P_{\rm ES}^{{\rm dis},i,t}}{\eta_{\rm ES}^{{\rm dis},i}}\right)\Delta t$$
(17)

$$0 \le H_{\rm HS}^{{\rm ch},i,t} \le \mu_{\rm HS}^{{\rm ch},i} H_{\rm HS}^{{\rm ch},{\rm MAX},i} \tag{18}$$

$$0 \le H_{\rm HS}^{{\rm dis},i,t} \le \mu_{\rm HS}^{{\rm dis},i} H_{\rm HS}^{{\rm dis},MAX,i}$$
(19)

$$0 \le \mu_{\rm HS}^{{\rm ch},i} + \mu_{\rm HS}^{{\rm dis},i} \le 1$$
 (20)

$$ST^{\mathrm{MIN},i} < ST^{i,t} < ST^{\mathrm{MAX},i}$$
(21)

$$ST^{i,t+1} = ST^{i,t} + \left(\eta_{\rm HS}^{{\rm ch},i}H_{\rm HS}^{{\rm dis},i,t} - \frac{H_{\rm HS}^{{\rm dis},i,t}}{\eta_{\rm HS}^{{\rm dis},i}}\right)\Delta t$$
(22)

where  $P_{\text{ES}}^{\text{dis}}$ ,  $P_{\text{ES}}^{\text{ch}}$ ,  $H_{\text{HS}}^{\text{dis}}$ , and  $H_{\text{HS}}^{\text{ch}}$  are the discharge/charge electric and heat power of ES and HS, respectively;  $\eta_{\text{ES}}^{\text{dis}}$ ,  $\eta_{\text{ES}}^{\text{ch}}$ ,  $\eta_{\text{HS}}^{\text{dis}}$ , and  $\eta_{\text{HS}}^{\text{ch}}$  are charging/discharging efficiency rate of ES and HS, respectively; *SE* and *ST* are the capacity of ES and HS; and  $\mu_{\text{ES}}^{\text{dis}}$ ,  $\mu_{\text{ES}}^{\text{ch}}$ ,  $\mu_{\text{HS}}^{\text{dis}}$ , and  $\mu_{\text{HS}}^{\text{ch}}$  are binary variables.

Constraints (13) and (14), (18) and (19) indicate the charging and discharging power limits for the ES and HS. Equations (15) and (20) are the constraints for avoiding simultaneous charging and discharging. The constraints expressing the state of charge of the ES and HS are shown in Equations (17) and (22), and constraints (16) and (21) indicate the permissible limits for the capacity of ES and HS.

• Cooperative operation of P2G-CCS constraints:

CCS and P2G are coupled to form a joint operation system, as shown in Figure 3. Carbon captured in CCS is used as raw material to supply P2G and synthesize  $CH_4$ , which can effectively reduce the operation cost. The cooperative operation constraints can be written as follows:

$$V_{P2G}^{i,t} = \frac{3.6\eta_{P2G}^{i}}{L_{P2G}^{i}}P_{P2G}^{i,t}$$
(23)

$$Q_{\rm CC}^{i,t} = \alpha_{\rm CC}^i \eta_{\rm P2G}^i P_{\rm P2G}^{i,t}$$
(24)

$$Q_{\rm CC}^{i,t} = P_{\rm CCS}^{i,t} K_{\rm CC}^i \tag{25}$$

$$0 \le P_{\text{P2G}}^{i,t} \le P_{\text{P2G}}^{\max,i} \tag{26}$$

$$0 \le P_{\text{CCS}}^{i,t} \le P_{\text{CCS}}^{\max,i} \tag{27}$$

$$Q_{\rm N}^{i,t} = K_{\rm GC}^{i} P_{\rm GT}^{i,t} + K_{\rm buy}^{i} P_{\rm buy}^{i,t} - Q_{\rm CC}^{i,t}$$
(28)

$$Q_{\rm N}^{i,t} \ge 0 \tag{29}$$

$$\begin{cases}
E_0^i \le 0, v = 0 \\
0 \le E^{v,i} \le E^{\max,i}, 1 \le v \le V \\
E^{V,i} \ge 0, v > V
\end{cases}$$
(30)

$$\sum_{t=1}^{T} Q_{\rm N}^{i,t} - \sum_{t=1}^{T} \left( \delta_{\rm CHP}^{i,t} P_{\rm CHP}^{i,t} + \delta_{\rm buy}^{i,t} P_{\rm buy}^{i,t} \right) = E_0^i + \sum_{v=1}^{V} E^{v,i}$$
(31)

where  $P_{P2G}$  and  $P_{CCS}$  are electric power consumed of P2G and CCS, respectively;  $Q_{CC}$  is the CO<sub>2</sub> quality required for P2G operation;  $\eta_{P2G}$  and  $L_{P2G}$  are electric to gas efficiency of P2G and calorific value of natural gas, respectively;  $\alpha$ CC is the CO<sub>2</sub> quality consumed per unit of P2G; and  $K_{CC}$ ,  $K_{GC}$ , and  $K_{buy}$  are carbon emission intensity of CCS, GT/CHP, and electric power purchased, respectively.



Figure 3. P2G and CCS joint operation structure.

Constraints (23)–(25) indicate the calculable relation of carbon emission and capture. Constraints (26) and (27) designate the limitations for consumption of electrical power of P2G and CCS. Equations (28) and (29) are used to calculate the total carbon emission of CHP after carbon capture.

Compared with the unified carbon price, the tiered carbon price is more suitable for the small carbon emission region and can reduce the carbon emission operating cost, for which the tiered carbon emission model is adopted [35]. The limits of carbon emission in each interval are shown in Equation (30). In particular, carbon emission trading in the 0th interval is 0. Constraint (31) refers to the balance of quota carbon trading within the whole interval. GSHP constraints:

$$H^{i,t}_{\rm HP} = K^i_{\rm HP} P^{i,t}_{\rm HP} \tag{32}$$

$$P_{\rm HP}^{\min,i} \le P_{\rm HP}^{i,t} \le P_{\rm HP}^{\max,i} \tag{33}$$

where  $P_{\text{HP}}$  and  $H_{\text{HP}}$  are electric and heat power of GSHP, respectively; and  $K_{\text{HP}}$  is the coefficient of thermoelectric power of GSHP.

The GSHP modelling for steady state in heat exchange can be derived from Equations (32) and (33) as follows.

RE constraints:

$$\begin{pmatrix}
P_{PV}^{i,t} + P_{PV}^{cut,i,t} \leq P_{PV}^{PRE,i,t} \\
P_{W}^{i,t} + P_{W}^{cut,i,t} \leq P_{W}^{PRE,i,t}
\end{cases}$$
(34)

where  $P_{PV}$  and  $P_W$  are the actual power of PV and wind, respectively;  $P_{PV}^{cut}$  and  $P_W^{cut}$  are the curtailment powers, respectively;  $P_{PV}^{PRE}$  and  $P_W^{PRE}$  are the predicted powers, respectively.

• Exchange power among MGs and with SP constraints:

$$P_{i,j}^{i,t} + P_{j,i}^{j,t} = 0, i \neq j$$
(35)

$$P_{i,j}^{\min,i,t} \le P_{i,j}^{i,t} \le P_{i,j}^{\max,i,t}$$
 (36)

$$0 \le P_{\rm buy}^{i,t} \le \omega P_{\rm buy}^{\max,i,t} \tag{37}$$

$$0 \le P_{\text{sell}}^{i,t} \le (1-\omega)P_{\text{sell}}^{\max,i,t} \tag{38}$$

where  $P_{i,j}$  is the electric power from MG<sub>i</sub> to MG<sub>j</sub>; and  $P_{sell}$  and  $P_{buy}$  are the selling and buying electric power from the SP, respectively.

Equations (35) and (36) are the constraints for exchange power among MGs. Constraint (35) ensures that the exchange power is equal between  $MG_i$  and  $MG_j$ , and constraint (36) shows the limitations for the exchange power among MGs. Constraints (37) and (38) stand for the constraints for exchange power between  $MG_i$  and SP;  $\alpha$  is a Boolean variable.

### 2.3. Service Provider of MG

As the intermediary between MGs and the upper grid, the service provider needs to set the electrical trading price with MGs. The trading of electrical power at any time is to be done in an optimal way from economical and technical perspectives and shall be realized according to the object function of the service provider.

Objective function of service provider:

$$\max Z_{SP} = \sum_{t=1}^{T} \sum_{i} \left( p_{buy}^{i,t} P_{buy}^{i,t} \right) - \sum_{t=1}^{T} \sum_{i} \left( p_{sell}^{i,t} P_{sell}^{i,t} \right) + \sum_{i} \sum_{t=1}^{T} \left( p_{S}^{i,t} P_{S}^{i,t} - p_{B}^{i,t} P_{B}^{i,t} \right)$$
(39)

where  $p_S$  and  $p_B$  respective the selling/buying price between the SP and the utility grid.  $P_S$  and  $P_B$  are the SP sell/buy the electric power from the utility grid.

Equation (39) represents the benefit maximization of the SP, which takes the benefits of all electrical power benefit minus purchase cost in a period *T*.

Transaction price between MGs and SP constraints:

$$0 \le p_{\text{sell}}^{i,t} \le p_{\text{sell}}^{\max,i} \tag{40}$$

$$0 \le p_{\text{buy}}^{i,t} \le p_{\text{buy}}^{\max,i} \tag{41}$$

$$\frac{1}{T}\sum_{t=1}^{T}p_{\text{sell}}^{i,t} \le p_{\text{sell}}^{\text{ave},i}$$
(42)

$$\frac{1}{T}\sum_{t=1}^{T} p_{\text{buy}}^{i,t} \le p_{\text{buy}}^{\text{ave},i}$$
(43)

where  $p_{\text{sell}}^{\text{ave},i}$  and  $p_{\text{buy}}^{\text{ave},i}$  are the maximum average selling/buying prices for  $p_{\text{sell}}^{i,t}$  and  $p_{\text{buy}}^{i,t}$ , respectively.  $p_{\text{sell}}^{i,t}$  and  $p_{\text{buy}}^{i,t}$  are the selling and buying price from MG<sub>i</sub> to SP.

Equations (40) and (41) show the limitations for selling/buying prices. Constraints (42) and (43) are given by the SP to limit the average price of buying/selling electrical power in a period T.

### 3. Solution Procedure

#### 3.1. The Uncertainty of Wind and PV

Due to the stochastic output power of PV and wind, their power generation depends on the environmental conditions with uncertainty. IGDT is used to establish the uncertainty dispatching model for environmental uncertainty (44):

$$\begin{cases}
U\left(\alpha_{W}, P_{W}^{PRE, i, t}\right) = \left\{P_{W}^{t}: \left|P_{W}^{t} - P_{W}^{PRE, i, t}\right| \leq \alpha_{W} P_{W}^{PRE, i, t}\right\} \\
U\left(\alpha_{PV}, P_{PV}^{PRE, i, t}\right) = \left\{P_{W}^{t}: \left|P_{PV}^{t} - P_{PV}^{PRE, i, t}\right| \leq \alpha_{PV} P_{PV}^{PRE, i, t}\right\} \\
\alpha_{W} \geq 0, \alpha_{PV} \geq 0
\end{cases}$$
(44)

where  $\alpha_{W/}\alpha_{PV}$  is the uncertain radius of wind/PV output; and  $P_W^{PRE}/P_{PV}^{PRE}$  is the predicted power out of wind/PV.

$$\Psi = \beta_{\rm PV} \alpha_{\rm PV} + \beta_{\rm W} \alpha_{\rm W} \tag{45}$$

Equation (45) shows the comprehensive uncertainty radius of PV and wind.  $\beta_{PV}$  and  $\beta_{W}$  can be determined by using the judgment matrix method according to the demand of PV and wind uncertainty.

The risk avoidance strategy is to seek the maximum uncertainty radius of the uncertain quantity under the condition that the optimization target is within an acceptable range. The larger the uncertainty radius is, the less sensitive the scheme is to the fluctuation of the uncertain quantity, the better the robustness of the model, and the stronger the ability of the system to avoid risks.

$$\begin{cases} \max \Psi = \beta_{\rm PV} \alpha_{\rm PV} + \beta_{\rm W} \alpha_{\rm W} \\ & \left\{ \begin{array}{l} \max \sum_{i} Z_{\rm MG,i} \leq (1+\kappa) \sum_{i} Z_{\rm MG,i}^{B} \\ [P_{\rm w}^{t} \in U(\alpha_{\rm w}, P_{\rm W}^{\rm PRE,i,t}), P_{\rm PV}^{t} \in U(\alpha_{\rm PV}, P_{\rm PV}^{\rm PRE,i,t})] ] \\ s.t. \\ \{(7) - (31), (33) - (38) and (44) \\ \sum_{i} Z_{\rm MG,i}^{B} = \sum_{i} Z_{\rm MG,i} \Big|_{P_{\rm w}^{t} = P_{\rm W}^{\rm PRE,i,t}, P_{\rm PV}^{t} = P_{\rm PV}^{\rm PRE,i,t}} \end{cases} \end{cases}$$

$$(46)$$

Equation (46) refers to the maximum radius of uncertainty;  $\kappa$  is the robustness level factor, and the greater its value, the greater the degree of risk avoidance and the stronger the robustness of the dispatching scheme. It can be seen that the above IGDT robust dispatch model belongs to a two-layer optimization model. The lower layer represents that when the PV and wind output fluctuates in the uncertain set, the operating cost of the system

cannot exceed the expected cost value. In order to improve the solving efficiency, Equation (46) is simplified into a single-layer optimization model, as shown in Equation (47).

$$\begin{cases} \min & -\Psi \\ \sum_{i} Z_{MG,i} \leq (1+\kappa)\sum_{i} Z_{MG,i}^{B} \\ (7) - (31), (33) - (38)and(44) \\ P_{w}^{t} = (1-\alpha_{W})P_{W}^{PRE,i,t} \\ P_{PV}^{t} = (1-\alpha_{PV})P_{PV}^{PRE,i,t} \\ \sum_{i} Z_{MG,i}^{B} = \sum_{i} Z_{MG,i} \Big|_{P_{w}^{t}} = P_{W}^{PRE,i,t} - P_{PV}^{PRE,i,t} \\ \end{cases}$$
(47)

The joint IGDT dispatching strategy of MC considering the uncertainty of PV and wind is shown in Figure 4. First, the MC dispatch model with PV and wind certainty was constructed, and the base operating cost was solved. Next, IGDT is applied to model the uncertainty of PV and wind, and the MC joint robust dispatch model is established and solved according to the risk avoidance strategy.



Figure 4. Flow chart of IGDT multi-source joint dispatching strategy of MC.

## 3.2. The Bisection Method for MC with Service Provider

Because the stackelberg game means that the participants are in different positions, the leader can occupy the first opportunity or favorable position in the game, so that the follower can make decisions. SP (leaders) and MC (followers) are considered as two types

of interested subjects in this paper. SP order buy/sell electricity prices with the goal of maximizing their profits. Each MG receives the decision from service providers and adjusts its own operation strategies.

For the MC considering the service provider, the higher the selling price, the less electricity the MG purchased. The relationship between the two is monotonically decreasing, so the bisection method is adopted to solve it. Considering the restriction of purchase/sale price, the SP sets the central point (48) in an interval and substitutes it into the IGDT problem.

$$X^k = \frac{X^{k-1} + X^{k-2}}{2} \tag{48}$$

where *X* is a set of buying and selling prices between SP and MGs; and *k* is the iteration.

Similarly, the upper bound or the lower bound is updated by [min ( $X^k$ ,  $X^{k-1}$ ), max ( $X^k$ ,  $X^{k-1}$ )]. When the algorithm satisfies Equation (49), it converges.

$$\frac{\Sigma\left(\left|\boldsymbol{X}^{k+1} - \boldsymbol{X}^{k}\right|\right)}{\Sigma\left(\boldsymbol{X}^{k}\right)} \leq \zeta \tag{49}$$

Finally, the dispatching result of IGDT is compared with the objective function, so as to take the buying/selling price interval in half. The specific solution algorithm is shown in Appendix A.

#### 3.3. Nash Solves for Allocating Benefits among MGs

The product of the difference between the maximum benefit obtained by each player in the game and the benefit when the negotiation breaks down (i.e., the lowest benefit) is the Nash negotiation. At this time, the stackelberg equilibrium solution is the optimal solution, and it can also ensure that the interests of all participants are balanced [36]. In this paper, the cooperative game model of MC is given as

$$\max \prod_{i=1}^{N} (U_{\text{MG},i} - U^*_{\text{MG},i})$$
(50)

where  $U_{MG}$  is the profit from MG.

MGs with different interests need to maintain independence and rationality when conducting electricity trading. Using a Nash distributed solution can effectively ensure their own the overall profits; (\*) is the breaking point of negotiations.

Taking the logarithm of model (50) and transforming the product problem into a summation problem, the objective function can be transformed into:

$$\begin{cases} \min \sum_{i=1}^{N} \left[ -\ln \left( U_{\mathrm{MG},i} - U_{\mathrm{MG},i}^{*} \right) \right] \\ s.t. \begin{cases} U_{\mathrm{MG},i} \ge U_{\mathrm{MG},i}^{*} \\ p_{i,j}^{t} \ge p_{i,j}^{\min,t} \end{cases} \end{cases}$$
(51)

$$U_{\text{MG},i} = -Z_{\text{MG},i} + \sum_{j=1,i\neq j}^{N} \sum_{t=1}^{T} \left( p_{i,j}^{t} P_{i,j}^{t} \right)$$
(52)

For the convenience of solving, the optimal solutions  $(Z^0_{MG,i}, P^{0,t}_{i,j})$  in model (47) is substituted into Equation (51):

$$\begin{cases} \min \sum_{i=1}^{N} \left[ -\ln \left( -Z_{MG,i}^{0} + \sum_{j=1,i\neq j}^{N} \sum_{t=1}^{T} \left( p_{i,j}^{t} P_{i,j}^{0,t} \right) - U_{MG,i}^{*} \right) \right] \\ s.t. \begin{cases} -Z_{MG,i}^{0} + \sum_{j=1,i\neq j}^{N} \sum_{t=1}^{T} \left( p_{i,j}^{t} P_{i,j}^{0,t} \right) \ge U_{MG,i}^{*} \\ p_{i,j}^{t} \ge p_{i,j}^{\min,t} \end{cases}$$
(53)

The objective function of model (53) is the natural logarithm, which is a monotonically increasing convex optimization problem. ADMM is used to solve the electricity trading price of MC, so as to ensure the maximum benefit. Therefore, the auxiliary variables  $p_{i,j}^t$  and  $p_{j,i}^t$  are introduced to decouple the electricity price of MC.

$$p_{i,j}^t = p_{j,i}^t, i \neq j \tag{54}$$

Considering the consistency constraint (54), the augmented Lagrange function (55) is established.

$$\begin{cases} \min L_{\mathrm{MG},i} = -\ln\left(-Z_{\mathrm{MG},i}^{0} + \sum_{j=1,i\neq j}^{N} \sum_{t=1}^{T} \left(p_{i,j}^{t} P_{i,j}^{0,t}\right) + Z_{\mathrm{MG},i}^{*}\right) + \sum_{t=1}^{T} \lambda_{i} \left(p_{i,j}^{t} - p_{j,i}^{t}\right) + \frac{\rho_{i}}{2} \sum_{t=1}^{T} \left\|p_{i,j}^{t} - p_{j,i}^{t}\right\|_{2}^{2} \\ s.t. \begin{cases} -Z_{\mathrm{MG},i}^{0} + \sum_{j=1,i\neq j}^{N} \sum_{t=1}^{T} \left(p_{i,j}^{t} P_{i,j}^{0,t}\right) \ge -Z_{\mathrm{MG},i}^{*} \\ p_{i,j}^{t} \ge p_{i,j}^{\min,t} \end{cases}$$
(55)

The distributed solution steps of the Nash bargaining game are as follows:

Step1: Initialization parameters:  $\lambda_i^k = 0$ ,  $p_{i,j}^{t,k} = p_j^{k+1} = 0$ ,  $\rho_i = 10$ ,  $\varepsilon = 0.001$ , k = 0;

Step2: Each MG calculates its own trading price strategy locally, and only the updated price  $p_{i,j}^k$  is exchanged among MGs. In each iteration, the following steps need to be performed:

MG<sub>*i*</sub> updates its decision  $p_{i,i}^{k+1}$ 

$$p_{i,j}^{t,k+1} = \operatorname{argmin} L_{\mathrm{MG},i} \left( \lambda_i^k, p_{i,j}^{t,k}, p_{j,i}^{t,k} \right)$$
(56)

MG<sub>*j*</sub> receives the updated decision  $p_{i,i}^{k+1}$ , to update its decisions  $p_{i,i}^{k+1}$ 

$$p_{j,i}^{t,k+1} = \operatorname{argmin} L_{\mathrm{MG},i} \left( \lambda_i^k, p_{i,j}^{t,k+1}, p_{j,i}^{t,k} \right)$$
(57)

Step3: Update Lagrange multiplier  $\lambda_i^{k+1}$ ;

$$\lambda_{i}^{k+1} = \lambda_{i}^{k} + \rho_{i} \left( p_{i,j}^{t,k+1} - p_{j,i}^{t,k+1} \right)$$
(58)

Step4: *k* = *k* + 1; Step5: Judge convergence;

$$\begin{cases} \sum_{t=1}^{T} \sum_{i} \left\| p_{i,j}^{t,k+1} - p_{j,i}^{t,k+1} \right\|_{2}^{2} \le \varepsilon, \text{ the } k \text{th convergence} \\ k \ge k_{\max}, \text{ otherwise} \end{cases}$$
(59)

The iteration terminates if Equation (59) is satisfied. Otherwise, it will go back to Step2 to recalculate until convergence or the set maximum number of iterations is reached.

# 4. Case Study

In this section, simulations in a test system are done to demonstrate the changes of the MC optimum energy management using the proposed hybrid game model. The system architecture of the calculation example is shown in Figure 1, and the specific dispatching model of each MG is shown in Appendix B. For the specific parameters of each unit of MGs1–3, refer to Appendices Tables A1 and A2. The power of RE in MC is shown in Figure 5. The Solver CPLEX in the MATLA2020a environment is employed to perform the energy management.





4.1. Day-Ahead Dispatching Analysis

Figures 6–8 illustrate the dispatching results of the MC, and the electrical power trading among MGs is depicted in Figure 9, considering two dispatch methods of MC: (1) MG1 adopts deterministic dispatch; (2) the uncertain dispatch is used in MGs2–3. Figure 10 shows electrical power trading among MGs and between the MC and SP, respectively.



Figure 6. Output dispatch of MG1: (a) electric; (b) heat.



Figure 7. Output dispatch of MG2: (a) electric; (b) heat.



**Figure 8.** Output dispatch of MG3: (**a**) electric; (**b**) heat.



Figure 9. Electric power trading among MGs.



Figure 10. Electric trading price among MGs: (a) MG1; (b) MG2; (c) MG3.

As seen from Figure 6a, the electrical load level is relatively low at 1:00–5:00 and 17:00–24:00, and the wind power of MG1 is sufficient to sell electrical power to other MGs. The electrical load reaches the peak from 6:00–16:00; the CHP works at full power. MG1 is buying electrical power from SP and other MGs at the same time. As for the heat load in Figure 6b, the electrical power generated by CHP is relatively low during 1:00–4:00, so the heat power is also too low to meet the heat load demand. At the same time, the heat generated by the HP is sufficient to meet its own heat load demand. Due to working at full power for CHP at 8:00–22:00, the heat power production is sufficient for the heat load.

The low power output of RE in MG2 needs to rely on GT and other MGs to provide electrical power. It can be seen from Figure 7a that the electrical load is relatively low; however, the heat load demand is large, resulting in a relatively high power production of GT, and the surplus electrical power is sold to other MGs. The GT provides a considerable amount of thermal power to meet the load in a day cycle in Figure 7b, and the HS mainly meets the thermal power balance characteristics in the whole system.

In Figure 8a, from 11:00–18:00, the GT of MG3 has insufficient power generation and needs to purchase electric power from MG1. However, at 16:00–20:00, MG3 sells electric power from MG1 and MG2, as seen in Figure 9. In Figure 8b, at 10:00, 14:00–15:00, and 18:00–20:00, the heat power generated by the GT not only meets the human load demand but also charges heat power to the HS.

Under the bisection algorithm, the SP also give the selling/buying price of the electrical power transaction to each MG in Figure 10. Taking MG3 as an example, MG3 purchases less electrical power from the utility grid from 1:00–16:00, and the purchase electrical price

is also relatively low at this time, as shown in Figure 10c. However, the electrical load of MG3 is in a peak state from 17:00–22:00, and its own unit cannot meet the electrical load demand and needs to purchase power from the utility grid, and the purchase price also rises. The electrical price reaches the limits at 20:00 especially. This means that the purchase electrical price varies with purchased electrical power.

In order to verify the accuracy and speed of the bisection algorithm, compared with the golden cut algorithm, the operating cost of the bisection algorithm is (4.8%, 3.6%, 2.7%) lower than that of the golden cut algorithm in Table 1. As described below, the bisection algorithm converges after eight iterations, whereas the golden cut algorithm requires eleven convergences, showing its capability in terms of computational speed and scalability.

Table 1. Operating cost (USD) for two algorithms.

Parameter	MG1	MG2	MG3	SP	Iteration
Bisection Algorithm	24,231	43,348	33,894	13,718	8
Golden cut Algorithm	25,382	44,927	34,833	14,180	11

#### 4.2. Analysis of IGDT Dispatching Strategy Considering the Uncertainty of Wind and PV

In order to quantify the influence of each uncertainty factor on the strategy, it is assumed that the robust level factor  $\kappa = 0.1$  selects different weight coefficients to perform the calculation results of the IGDT robust dispatch model, respectively, as shown in Table 2.

Table 2. IGDT robust dispatch results with different weight coefficient combinations.

Parameter	IGD'	T Robust Dispatching R	esult
$(\beta_{\rm PV}, \beta_{\rm W})$	$\alpha_{\rm PV}$	$\alpha_{ m W}$	ψ
(1, 1)	0.7868	0.6869	1.3025
(1, 2)	0.7868	0.3279	1.4425
(1, 4)	0.7868	0.1968	1.5739
(1, 8)	0.7868	0.1182	1.7374

As can be seen from the table, due to the different sensitivities of the system to the fluctuations of various uncertain factors, different weight coefficients will affect the solution results of single uncertain factors. However, it has little influence on the solution result of the whole system. The dispatch decision maker can set each weight coefficient according to the actual situation and historical experience of the system.

In the risk avoidance model, the robust level factor  $\kappa$  is set to vary from 0 to 0.1, alongside the considered uncertain parameters in two cases studies: (1) PV and wind, and (2) PV.

With the increased operation cost for the MC,  $\alpha$  is also increasing from the perspective of overall dispatch in Figure 11. Note that  $\alpha$  and operation cost are normalized. Considering more uncertain factors, the effect of risk avoidance is more obvious at this time.

#### 4.3. Environmental Analysis of Tiered Carbon Price

The unified carbon price in all intervals is considered to be 2.9 USD/t in this paper, the tiered price given is 2.5 USD/t in sector 0, and the other intervals are calculated according to model (1). The tiered price results are shown in Table A3.

The interval price will increase with the increase of carbon emissions, but the uniform price will not. As can be seen from Figure 12, the carbon emission of the interval price is higher than with the uniform price method in intervals 0–5, but the interval price is twice as high as the uniform price in interval 6. At the same time, the carbon emission of the interval price decreases rapidly, and the carbon emission of the unified price is far more. Therefore, the use of tiered prices can effectively regulate carbon emissions in high-emission areas, which achieves a true "low carbon".



Figure 11. Comparison of IGDT result in two cases.





The total operating costs of the two prices are USD 101,473 and USD 105,810, respectively, in Table 3, and the operating cost of the uniform price is 4.28% higher than that of the tiered price. The carbon operating costs of participating are USD 9756 and USD 10,005 in the two price mechanisms, respectively, but the carbon emission of participating in the electricity market with the tiered price is 2.55% lower than that of the uniform price. It can be seen that, to a certain extent, the emission reduction task can be completed by using tiered prices.

Table 3. Operating costs in two prices.

Operating Cost (USD) –		Interval Price			Uniform Price	
	MG1	MG2	MG3	MG1	MG2	MG3
C <sub>grid</sub>	12,138	17,858	10,911	14,361	19,424	10,959
$C_{\rm fuel}$	10,354	20,978	19,377	11,383	20,167	19,389
$C_{\rm ES}$	22	45	34	23	52	47
$C_{\rm V}$	1717	4467	3572	2416	4386	3203
The total operating cost	24,231	43,348	33,894	28,183	44,029	33,598

# 4.4. Analysis of Payment Benefit among MGs

Figure 13 shows the transaction benefits among MGs and the results of the residual error iterative convergence. The ADMM algorithm requires 33 iterations to achieve convergence, the time is 53 s, and the convergence residual error is  $10^{-3}$ . Therefore, it shows that the ADMM algorithm proposed in this paper has good convergence performance and computational efficiency.



Figure 13. Convergence of the ADMM algorithm.

MG2 sells electricity to MG3 in Figure 9 from 9:00–15:00, for which the transaction price between MG2 and MG3 is relatively high at this time, as shown in Figure 14; MG2 purchases electric power from MG3 at 4:00–8:00, and the price between the two is at a low level. It can be seen that the transaction price among the MGs changes with the change in the electric power transaction.



Figure 14. Trading price among MGs.

Table 4 presents the running cost comparison of MC and multi-microgrids (MMG). MC is the model proposed in this paper; MMG is not considering constraints (35)–(36). It can be seen from the table that the operating cost of each MG in the MC are (USD 9660, USD 9628, USD 9628) less than that in MMG, which are (39.86%, 22.21%, 28.41%) lower.

This shows that MC is beneficial to reducing the operating cost of each MG. Considering the influence of errors, the cost reduction of each MG is basically equal, which is 1/3 of the overall cost. It can be seen that the fairness of benefit distribution is facilitated by the Nash equilibrium.

	Operation Cost (USD)			
	MG1	MG2	MG3	
МС	24,231	43,348	33,894	
MMG	33,891	52,976	43,522	

Table 4. Comparisons of operation costs for MC and MMG.

## 5. Conclusions

The trading of carbon emissions and the high penetration of RE lead to the complexity of multi-energy MG systems. In addition, the utilization rate of RE is increasing, and this means that the MC must also be considered. In order to solve the problem of carbon emissions in MG, a joint IGDT dispatch strategy for MC considering the uncertainty of wind and PV is proposed in this paper. The P2G-CCS joint operation mechanism is considered in a single MG, and the bisection method is used to solve the purchase/sale electrical power price between the MC and SP. In addition, the risk avoidance strategy is adopted to consider the uncertainty of RE, and a non-probabilistic method, i.e., IDGT theory, is used to solve the robustness problem for MC. Finally, Nash negotiation is used to solve the transaction price among MGs. A simulation study is carried out on the MC considering SP, for which two cases are considered, including energy management with tiered carbon price and unified carbon price, and the comparison of carbon emissions and operating costs are given in two cases. The experimental results show that: (1) a reasonable carbon price can not only effectively and reasonably regulate the carbon trading market, but can also guide carbon emissions. (2) The uncertainty of RE is considered through weight coefficients and weighted summation, by which the robustness of the system is improved. (3) Considering the transaction among MGs by means of Nash bargaining, both the profits of the respective subjects and the interests of the whole system can be considered. Compared with MMG, it can also reduce the operating cost of each. Hydrogen energy is a direction of future comprehensive energy research, and this is also an indispensable discussion for hydrogen storage and hydrogen transaction prices.

In MC, the transaction prices of other energies, i.e., heat, gas, hydrogen, etc., can be considered in the future, as can the difference of carbon emission rights due to the differences of MG generator and load.

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Figure A1. The process of solving the MC considering the SP by the bisection method.

# Appendix **B**

This test system consists of the independent SP and three MGs.

MG<sub>1</sub> consists of wind, PV, CHP, P2G-CCPP, GSHP, and ES alongside with residential loads, for which the specific dispatch model is

$$\begin{cases} \min Z_{MG,i} = \sum_{t=1}^{24} \left( C_{grid}^{i,t} + C_{ES}^{i,k,t} + C_{ES}^{i,m,t} \right) + C_{V}^{i} \\ s.t. \begin{cases} (2) - (6), (3) - (17)and(23) - (38) \\ P_{buy}^{i,t} - P_{sell}^{i,t} - P_{HP}^{i,t} + P_{ES}^{di,i,t} = P_{L}^{i,t} + P_{ES}^{ch,i,t} - P_{PV}^{i,t} - P_{W}^{i,t} + P_{CCS}^{i,t} + P_{P2G}^{i,t} + \sum_{j=1, i \neq j}^{N} P_{i,j}^{i,t} \\ H_{HP}^{i,t} + H_{CHP}^{i,t} = H_{L}^{i,t} \end{cases}$$
(A1)

Equation (A1) includes the electric power, heat power balance constraints, and i = 1.

$$G_{\text{gas}}^{i,t} = V_{\text{CHP}}^{i,t} - V_{\text{P2G}}^{i,t}, i = 1$$
 (A2)

Equation (A2) shows that the fuel volume required by the  $MG_1$  is the difference between that consumed by CHP and generated by P2G.

The structure of  $MG_2$  is the same as  $MG_3$  alongside with wind, PV, GT, GB, P2G-CCS, ES, HS, and park loads. The specific dispatch models are

Equation (A3) illustrates the RE limit and the electric and heat power balance constraints; i = 1, 2.

$$G_{\text{gas}}^{i,t} = V_{\text{GT}}^{i,t} + V_{\text{GB}}^{i,t}, i = 1,2$$
 (A4)

The sum of the fuel consumed by GT and GB is the total fuel in the  $MG_{1,2}$ , represented by Equation (A4).

Table A1. Parameters	of each unit in	MG1
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Parameter	Value	Parameter	Value	Parameter	Value
$\eta_{\mathrm{CHP}}$	0.75	$P_{i,i}^{\min}/kW$	3000	$R_{\rm CHP}^{\rm max}/{ m kW}$	300
$P_{CHP}^{min}/kW$	50	$P_{CHP}^{max}/kW$	1200	$H_{CHP}^{min}/kW$	0
$H_{CHP}^{max}/kW$	1500	$\lambda_{\text{CHP}}$	0.3	LHV <sub>CHP</sub>	10.8
$P_{\rm FS}^{\rm ch,max}/\rm kW$	150	P <sup>dis,max</sup> /kW	150	SE <sup>min</sup>	100
SEmax	800	$\eta_{\rm FS}^{\rm ch}$	0.95	$\eta_{\rm FS}^{\rm dis}$	0.95
$\eta_{P2G}$	0.85	L <sub>P2G</sub>	3.9	$\alpha_{\rm CC}$	0.78
K <sub>CC</sub>	0.269	$P_{P2G}^{max}$	500	$P_{\rm CCS}^{\rm max}$	400
K <sub>GC</sub>	0.78	K <sub>buy</sub>	0.56	$K_{\rm HP}$	3.8

Parameter	Value	Parameter	Value	Parameter	Value
$\eta_{\rm GT}^{\rm E}$	0.35	$\eta_{ m GT}^{ m H}$	0.83	P <sub>GT</sub> <sup>max</sup> /kW	5000
$P_{GT}^{min}/kW$	800	$\lambda_{\rm GT}$	0.35	$\lambda_{\rm GB}$	0.9
LHV <sub>TB</sub>	9.7	P <sub>ES</sub> <sup>ch,max</sup> /kW	300	P <sub>FS</sub> <sup>dis,max</sup> /kW	300
$\eta_{\rm FS}^{\rm ch}/\eta_{\rm FS}^{\rm dis}$	0.98/0.98	SEmax	600	ST <sup>max</sup>	500
$H_{\rm HS}^{\rm ch,max}/\rm kW$	200	H <sup>dis,max</sup> /kW	200	$\eta_{\rm HS}^{\rm ch}/\eta_{\rm HS}^{\rm dis}$	0.95
η <sub>P2G</sub>	0.35	$L_{P2G}$	3.9	$\alpha_{\rm CC}$	0.78
K <sub>CC</sub>	0.269	$P_{P2G}^{max}$	500	$P_{\rm CCS}^{\rm max}$	400
$K_{\rm GC}$	0.78	K <sub>buy</sub>	0.56		

Table A2. Parameters of each unit in MG1 and MG2.

Table A3. Tiered carbon pricing.

	Interval					
	0	1	2	3	4	5
Price $(USD/t)$	2.5	2.5	3.34	4.01	4.68	5.35

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