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Suppression Method of Partial Discharge Interferences Based on Singular Value Decomposition and Improved Empirical Mode Decomposition

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Abstract: Partial discharge detection is an important means of insulation diagnosis of electrical equipment. To effectively suppress the periodic narrowband and white noise interferences in the process of partial discharge detection, a partial discharge interference suppression method based on singular value decomposition (SVD) and improved empirical mode decomposition (IEMD) is proposed in this paper. First, the partial discharge signal with periodic narrowband interference and white noise interference x(t) is decomposed by SVD. According to the distribution characteristics of single values of periodic narrowband interference signals, the singular value corresponding to periodic narrowband interference is set to zero, and the signal is reconstructed to eliminate the periodic narrowband interference in x(t). IEMD is then performed on x(t). Intrinsic mode function (IMF) is obtained by EMD, and based on the improved 3σ criterion, the obtained IMF components are statistically processed and reconstructed to suppress the influence of white noise interference. The methods proposed in this paper, SVD and SVD + EMD, are applied to process the partial discharge simulation signal and partial discharge measurement signal, respectively. We calculated the signal-to-noise ratio, normalized correlation coefficient, and mean square error of the three methods, respectively, and the results show that the proposed method suppresses the periodic narrowband and white noise interference signals in partial discharge more effectively than the other two methods.

Keywords: partial discharge; periodic narrowband interference; white noise interference; singular value decomposition; improved empirical mode decomposition

1. Introduction

Partial discharge (PD) is one of the manifestations of electrical equipment insulation aging, and one of the main reasons for further deterioration and failure of insulation [1–3]. PD signal detection is an effective means used to evaluate and diagnose the insulation state of electrical equipment [4,5]. However, in the actual PD signal detection process, the measured PD signal is often annihilated by noise interferences due to the complex electromagnetic environment and extremely weak PD signal [6,7]. Periodic narrowband and white noise interferences impose the most serious influences on PD signal detection. Therefore, it is of great significance to suppress them effectively.

Extensive studies have been conducted on noise interference suppression in PD signals. Zhao et al. suppressed periodic narrowband interference through fast Fourier transform (FFT) without prior knowledge, but the threshold was not easily determined and there was an edge effect [8]. Luo et al. proposed that the frequency of periodic narrowband interference can be identified by combining the local energy ratio of the power spectrum and clustering algorithm [9], thus allowing the determination of the threshold. However, the residual noise was large. In [10], the white noise interference in the PD signal was effectively suppressed by using the discrete wavelet transform (DWT). Shams et al.



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Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). proposed using maximum overlap discrete wavelet transform (MODWT) to denoise the partial discharge signal, the processing object is PD signal of cable defects under different noise levels, and the noise reduction effect was superior [11]. Soltani et al. proposed that the good ability of artificial neural network (ANN) in curve fitting can be used to suppress the white noise interference of different types of measured RF signals [12].

In addition to the above methods, singular value decomposition (SVD) is an effective interference suppression method, which has been extensively used in PD signal interference suppression. This method realizes PD signal interference suppression by selecting the appropriate singular value threshold [13,14]. In [15], the PD signal was decomposed by SVD, and the singular value corresponding to the periodic narrowband interference was determined; in this way, the signal was reconstructed to achieve periodic narrowband interference suppression. Ashtiani et al. proposed an adaptive SVD method to suppress noise interference and achieved certain results [16]. Zhou et al. proposed an adaptive shorttime singular value decomposition (ASTSVD) method to denoise PD signal, this method obtains the denoised PD signal by selecting the singular value representing PD signal and removing the singular value representing the noise interference [17]. Wei et al. proposed using S-transform to process PD UHF signal, and time-frequency analysis of S-transform results to obtain the number of source signals. Singular value decomposition (SVD) is performed on the PD signal detected by a single channel to obtain the multi-channel signal. The obtained characteristic matrix is jointly approximately diagonalized, and finally the background noise in the multi-channel PD UHF signal is separated [18].

In this paper, it is found that SVD is not effective in suppressing white noise interference. To suppress white noise more effectively, a type of empirical mode decomposition (EMD) is introduced. EMD, which was proposed by Huang et al. in 1988, is used to process nonstationary and nonlinear signals, and has been applied in many fields [19]. EMD decomposes the multi-time scale component signal into multiple intrinsic mode functions (IMFs) from high to low frequencies to distinguish noise interference and the measured signal [20]. Reference [21] proposed using EMD to suppress white noise interference in the PD signal and it has exhibited good robustness. Further research showed that EMD has low efficiency on periodic narrowband interference suppression in this paper.

This paper proposes a new white noise and periodic narrowband interference suppression method based on SVD and IEMD to solve the deficiency of SVD in white noise interference suppression and the disadvantage of EMD in periodic narrowband interference suppression. First, PD and interference signals are simulated in Section 2. PD signals containing white noise and periodic narrowband interference were decomposed by SVD in Section 3, and the singular values corresponding to periodic narrowband interference were then set to zero to suppress periodic narrowband interference. Different from previous studies, this paper studies the suppression effect of SVD on white noise interference; different singular values were reserved and the signals were reconstructed. PD signals containing periodic narrowband interference and PD signals containing white noise interference are decomposed by EVD to study the suppression effect in Section 4. The signal, whose periodic narrowband interference was suppressed by SVD, was analyzed by IEMD in Section 5 to solve the modal aliasing problem in the IMF component. In a new processing method proposed in this paper, the IMF components obtained by EMD are statistically analyzed and processed based on the improved 3σ criterion. The processed IMF component was reconstructed to achieve white noise suppression. Actual measurement of PD signals interferences suppressed are discussed in Section 6. Finally, conclusions are summarized in Section 7.

The result shows the proposed method has more advantages in suppressing periodic narrowband and white noise interference in PD signal detection than SVD and SVD + EMD. However, the construction of the Hankle matrix makes the amount of calculations larger, so it is necessary to control the amount of data of the signal so as to improve the calculation efficiency.

2. PD and Interference Signals for Simulation Analysis

2.1. PD Signal Simulation

PD signal is a type of pulse signal. Based on previous studies, this paper selected the single exponential decay oscillation model D_1 and the double exponential decay oscillation model D_2 to simulate the PD signal [22]. The specific expressions are as follows:

$$D_1 = A_1 e^{-t/\tau} \sin(2\pi f_c t)$$
 (1)

$$D_2 = A_2(e^{-1.3t/\tau} - e^{-2.2t/\tau})\sin(2\pi f_c t)$$
⁽²⁾

In Equations (1) and (2), A_1 and A_2 are the amplitudes of the PD signal, τ is the attenuation coefficient, f_c is the attenuated oscillation frequency, and t is the duration of PD signal pulse [23].

In this paper, four groups of PD signal pulses are simulated in MATLAB (version 2017, MathWorks, Natick, MA, USA), and the parameters are listed in Table 1. Signals A and C are single exponential decay oscillations, and B and D are double exponential decay oscillations. The sampling frequency is 100 Msamples/s, and the sampling time is 20 μ s (number of sampling points *N* = 2000). The PD simulation signal is shown in Figure 1.

Table 1. PD Simulation signal parameters.

Partial Discharge (PD) Pulse	Α	В	С	D
Signal amplitude (A/mV)	10	20	10	20
Oscillation frequency (fc/MHz)	20	40	20	40
Attenuation coefficient ($\tau/\mu s$)	0.1	0.15	0.1	0.15



Figure 1. Partial discharge (PD) simulation signals.

2.2. Simulation of PD Signal with Noise

The periodic narrowband interference is mainly carrier communication interference, with a frequency range of 0.5~25 MHz. The periodic narrowband interference signal is generated by the superposition of sinusoidal signals with different frequencies, and its mathematical expression is

$$C(t) = \sum_{i=1}^{h} A_i \sin(2\pi f_i t)$$
(3)

In the formula: A_i is the amplitude, f_i is the frequency, and h is the number of the periodic narrowband interference signals.

Parameter values of the periodic narrowband interference simulation signal are listed in Table 2. The PD signal superimposed with the periodic narrowband interference signals is shown in Figure 2a. A gaussian white noise simulation signal is generated by MATLAB and superimposed with the PD signal, thus yielding a signal-to-noise ratio (SNR) of -2 dB. The waveform is shown in Figure 2b. Figure 2c shows the superposition of the PD signal with a white noise interference signal, where the SNR is $-2 \, dB$ and the periodic narrowband interference signals.



 Table 2. Parameters of narrowband Interference simulation signals.

Figure 2. Noising PD simulation signals. (**a**) PD signal superimposed with the periodic narrowband interference signals. (**b**) PD signal superposition with white noise interference signal. (**c**) PD signal superposition with white noise and the periodic narrowband interference signals.

3. Simulation Analysis of SVD Suppression Effect on Interference Signal *3.1. SVD of Signal*

SVD is an important matrix decomposition method, which is extensively used in signal processing. Its noise reduction principle is to use the energy separability of the measured and the noise signals [24,25]; SVD is performed on the matrix that contains signal

features according to the corresponding relationship of the singular values among the measured and noise signals. The singular value corresponding to the measured signal is retained, and the singular value corresponding to the noise signal is set to zero. An inverse SVD operation is used to reconstruct the signal, so as to suppress the noise interference.

To perform SVD of the discrete signals x(i) (i = 1, 2, ..., N) with noise interference, it is necessary to map them to an $m \times n$ dimensional phase space first, followed by the construction of the Hankel matrix. The Hankel matrix is a special matrix type with equal elements on the antidiagonal. Signal x(i) constructs the $m \times n$ Hankel matrix as shown by the following expression.

$$H = \begin{bmatrix} x(1) & x(2) & \cdots & x(n) \\ x(2) & x(3) & \cdots & x(n+1) \\ \vdots & \vdots & \vdots & \vdots \\ x(m) & x(m+1) & \cdots & x(N) \end{bmatrix}$$
(4)

In Equation (4), *m* is the embedding dimension, *N* is the signal length, and N = m + n - 1.

When constructing the Hankel matrix for signal x(i), different embedding dimensions M will lead to differences in the SVD denoising outcomes. Therefore, it is of great significance to select the optimal embedding dimension m of the Hankel matrix to improve the noise reduction performance of the SVD. To achieve full separation of the signal and noise, the product of the number of rows m and the number of columns n of the Hankel matrix should be as large as possible [26]. According to the inequality principle, when the signal length N is odd, m = (N + 1)/2. When N is even, m = N/2.

For a Hankel matrix *H* with an order $m \times n$, there exist orthogonal matrices $U \in R_{m \times m}$ and $V \in R_{n \times n}$ such that

$$H = U \sum V^T \tag{5}$$

In the equation $\Sigma = diag(\lambda_1, \lambda_2, ..., \lambda_r)$ is the r-order diagonal matrix; $\lambda_1, \lambda_2, ..., \lambda_r$ are nonzero singular values of the matrix H, and $\lambda_1 \ge \lambda_2 \ge ... \ge \lambda_r > 0$; r is the rank of matrix H, and $r \le min (m, n)$. $U = [u_1, u_2, ..., u_m]$, $V = [v_1, v_2, ..., v_n]$, where U and V are left and right singular vectors, respectively [27]. In this case, Equation (5) is the SVD of matrix H.

3.2. Signal Reconstruction Based on SVD Results

The matrix *H* can be split into the sum of several low-rank matrices H_{i} ,

$$H = \sum_{i=1}^{r} \lambda_i u_i v_i^T = \sum_{i=1}^{r} H_i$$
(6)

If signal x(i) is the superposition of the PD signal with the periodic narrowband and white noise interference signal, the matrix H can be expressed as $H = H_p + H_n + H_w$, where H_p , H_n , and H_w correspond to the PD signal, periodic narrowband, and white noise interference signals, respectively. The singular value λ_i reflects the energy concentration of each signal. According to the singular value distribution characteristics of the PD and interference signals, after the determination of the threshold interval of singular value, the reconstructed trajectory matrix H_r is obtained based on an inverse SVD operation,

$$H_{r} = \begin{bmatrix} x_{r}(1,1) & x_{r}(1,2) & \cdots & x_{r}(1,n) \\ x_{r}(2,1) & x_{r}(2,2) & \cdots & x_{r}(2,n+1) \\ \vdots & \vdots & \vdots & \vdots \\ x_{r}(m,1) & x_{r}(m,2) & \cdots & x_{r}(m,n) \end{bmatrix}$$
(7)

In Equation (7), $x_r(m, n)$ is the element of the reconstructed trajectory matrix. The elements on the diagonal of the reconstructed trajectory matrix H_r are numerically close but

not equal. The average value of the antidiagonal elements of H_r is calculated to obtain the reconstructed one-dimensional signal $X_r(i)$, and the calculation is expressed by Equation (8).

$$X_{r}(i) = \begin{cases} \frac{1}{i} \sum_{j=1}^{i} H_{r}(j, i-j+1), & 1 \le i < m \\ \frac{1}{m} \sum_{j=1}^{m} H_{r}(j, i-j+1), & m \le i \le n \\ \frac{1}{N-i+1} \sum_{j=i-n+1}^{m} H_{r}(j, i-j+1), & i > n \end{cases}$$
(8)

3.3. Singular Value Distribution Characteristics of Periodic Narrowband Interference Signals

The PD simulation signal superimposed with periodic narrowband interference in Section 2.2 is decomposed by SVD, and the singular value distribution is shown in Figure 3a. To observe the distribution of singular values, the first 100 large singular values are used, as shown in Figure 3b.



Figure 3. Singular value distribution of PD signal superimposed with the periodic narrowband interference signals. (**a**) Singular value distribution. (**b**) First 100 singular value distributions.

The energy of the periodic narrowband interference signal is larger than that of the PD signal [28]. In the singular value distribution, the periodic narrowband interference signal corresponds to a large singular value. As shown in Figure 3, the first six singular values are much larger than those of the subsequent order and appear in "pairs." The periodic narrowband interference signal corresponds to it, and the periodic narrowband interference signal of each frequency corresponds to two (a pair of) singular values. For periodic narrowband interference, the corresponding "singular value pair" contains most of its effective information. These "singular value pairs" can be set to zero to retain the singular value corresponding to the PD signal. The signal is reconstructed by an inverse SVD operation so as to realize periodic narrowband interference suppression.

3.4. Analysis on the Suppression of SVD on Periodic Narrowband Interference

The PD signal superposed with three frequencies in Section 2.2 was decomposed by SVD, the singular value corresponding to the periodic narrowband interference signal was set to zero, and the signal was reconstructed. The obtained aperiodic narrowband interference waveform is shown in Figure 4.



Figure 4. Suppression of periodic narrowband interference based on singular value decomposition (SVD).

To quantitatively analyze the effect of SVD on suppressing periodic narrowband interference, this paper introduces three evaluation indices: SNR, normalized correlation coefficient (NCC), and the mean-squared error (MSE). The specific calculation formulas are shown in Equations (9)–(11). The larger the SNR is, the closer the NCC is to unity, and the smaller the MSE is, the better the noise reduction effect is.

SNR = 10lg
$$\left(\frac{\sum_{i=1}^{N} |x(i)|^2}{\sum_{i=1}^{N} |y(i) - x(i)|^2} \right)$$
 (9)

$$NCC = \frac{\sum_{i=1}^{N} x(i)y(i)}{\sqrt{\left(\sum_{i=1}^{N} x^{2}(i)\right)\left(\sum_{i=1}^{N} y^{2}(i)\right)}}$$
(10)

$$MSE = \frac{1}{N} \sum_{i=1}^{N} |y(i) - x(i)|^2$$
(11)

In the equations above, x(i) is the PD signal, and y(i) is the signal after interference suppression.

Substitution of the PD simulation signal and signal denoised by SVD in Equations (9)–(11) yields SNR = 26.66, NCC = 99.89%, and MSE = 7.97×10^{-4} . It can be observed from the calculation results that the periodic narrowband interference is suppressed effectively.

3.5. Singular Value Distribution Characteristics of White Noise Interference Signals

Theoretically, the singular value of the PD signal is greater than that of the white noise. After determining the singular value threshold of the PD signal, the singular value corresponding to white noise interference is set to zero, so as to suppress white noise interference in the PD signal. SVD was performed on the signals in Section 3.4 without periodic narrowband interference, and the singular value distribution obtained is shown in Figure 5.



Figure 5. Singular value distribution of PD superimposed with a white noise signal.

As shown in Figure 5, there is no obvious inflection point in the distribution of singular values. Thus, it is difficult to distinguish the singular values corresponding to the PD signal and white noise interference signal, that is, it is difficult to determine the singular value threshold of the PD signal. To study the suppression effect of SVD on white noise interference, different numbers of singular values were retained. Assuming *i* (*i* = 1, 2, ..., 1000) is the number of the singular values that are retained, the first *i* singular values is retained and the remaining singular values are set to zero; the SNR, NCC, and MSE values of the reconstructed signal are then calculated. The obtained distribution curve is shown in Figure 6. Based on these results, SNR_{max} = 0.52, NCC_{max} = 65.05%, and MSE_{min} = 0.33. According to the three evaluation indices, it can be inferred that the effect of white noise interference suppression of the PD signal by SVD is not ideal.



Figure 6. Distributions of evaluation indices.

3.6. SVD Suppression Effect in the Presence of White Noise and Periodic Narrowband Interference

The PD signal superimposed with a white noise for which the SNR is -2 dB and the periodic narrowband interference signals in Section 2.2 is decomposed by SVD. The singular value distribution is shown in Figure 7 (only the first 100 singular values are drawn).



Figure 7. Singular value distribution of PD signal superimposed with white noise and periodic narrowband interference signals.

In Figure 7, the first six singular values appear in pairs and are much larger than the other singular values. The distribution of singular values in Figure 7 is similar to that in Figure 3b. Thus, it can be concluded that there is still a corresponding relationship between "singular value pairs" and periodic narrowband interference. If the "singular value pair" corresponding to periodic narrowband interference is set to zero, the reconstructed signal waveform is shown in Figure 8a. To study the effects of SVD on the suppression of periodic narrowband interference in the presence of white noise, the PD signal was superposed with a white noise signal for which the SNR is -2 dB as a whole signal, and the SNR, NCC, and MSE of the reconstructed signals were calculated. The results showed that SNR = 21.94, NCC = 99.68%, and MSE = 6.5×10^{-3} . SVD is used to suppress the white noise interference of the reconstructed signal with periodic narrowband interference, and the waveform obtained is shown in Figure 8b. By calculating the SNR, NCC, and MSE of the reconstructed signals, SNR = 0.52, NCC = 50.49%, and MSE = 0.33 were obtained.



Figure 8. Removal of periodic narrowband interference by PD signal superimposed with white noise. (a) Periodic narrowband interference suppression. (b) White noise interference suppression.

Figure 8 shows that when the PD signal contains both white noise and periodic narrowband interference, the waveform of SVD for periodic narrowband interference suppression is very close to that of Figure 2b. The calculated results of SNR, NCC, and MSE show that SVD is effective in suppressing periodic narrowband interference signals. However, compared with the original PD signal, the amplitude attenuation of the waveform after suppression of white noise interference is serious, and there are more residual interferences. The evaluation indices SNR, NCC, and MSE show that SVD has a poor suppression effect on white noise interference.

4. Simulation Analysis of Suppression Effect of EMD on Interference Signal *4.1. EMD*

EMD is used to decompose multi-time scale component signals into multiple IMF components $h_i(t)$ with high to low frequencies and a residual component $r_n(t)$ [29,30], namely,

$$x(t) = \sum_{i=1}^{n} h_i(t) + r_n(t)$$
(12)

In Equation (12), $h_i(t)$ is the IMF component of order *i* and $r_n(t)$ is the residual component of order *n*. The IMF components decomposed by EMD need to satisfy the following constraint conditions:

- (1) In the entire data sequence interval, the number of extreme points is equal to or differs by at most one unit from the number of zero crossings.
- (2) The upper envelope and the lower envelope are symmetric about the time axis, that is, the mean value m(t) = 0.

For the signal x(t), the EMD process is as follows:

- (1) Find all maximum and minimum points of signal x(t).
- (2) The upper envelope $e_{max}(t)$ and the lower envelope $e_{min}(t)$ are obtained by the cubic spline interpolation method to interpolate the maximum and minimum points, respectively.
- (3) Calculate the average value of the upper envelope $e_{max}(t)$ and the lower envelope $e_{min}(t)$ as follows:

$$m(t) = \frac{[e_{\max}(t) + e_{\min}(t)]}{2}$$
(13)

(4) Remove m(t) from x(t) and separate h(t) as follows:

$$h(t) = x(t) - m(t) \tag{14}$$

- (5) Determine whether h(t) satisfies the two constraints of the IMF. If so, $h_1(t) = h(t)$ is the first-order IMF component, and step (6) is executed. Otherwise, let x(t) = h(t) and repeat steps (1)–(5) until the condition is satisfied.
- (6) Let $r_1(t) = x(t) h_1(t)$ to determine whether $r_1(t)$ is a monotone function or the absolute value is small enough. If so, EMD ends. Otherwise, let $x(t) = r_1(t)$ and return to step (1).

4.2. Endpoint Effect

The endpoint effect is generated because extreme points need to be used in the process of EMD. However, the endpoints at both ends of the signal may not be extreme points. If the end point is directly regarded as the extreme point, there will be errors and the signal will be distorted. Therefore, the endpoint effect of EMD needs to be suppressed.

In this paper, the mean extension method is adopted to suppress the endpoint effect of EMD. First, two maximum points and two minimum points closest to the left and right endpoints are found, respectively. The average values are respectively considered as the endpoint values of the upper and the lower envelopes. As shown in Figure 9, at the left endpoint, the two nearest maximum points are x_1 and x_2 , and the average value of x_1 and x_2 is obtained as $x_{1'}$; $x_{1'}$ is then used as the left endpoint value of the upper envelope. Similarly, the average values of x_3 and x_4 are the left endpoint values of the lower envelope. The average values of x_5 and x_6 are the right endpoint values of the upper envelope. The average values of x_7 and x_8 are the right endpoint values of the lower envelope.



Figure 9. Mean continuation diagram.

4.3. Suppression Effect of EMD on Periodic Narrowband Interference

EMD is performed on the PD simulation signal superimposed with periodic narrowband interference in Section 2.2 and the IMF components obtained are shown in Figure 10.



Figure 10. Cont.



Figure 10. Cont.



Figure 10. Empirical mode decomposition (EMD) PD superimposed narrowband interference signal. (**a**) IMF₁-component. (**b**) IMF₂-component. (**c**) IMF₃-component. (**d**) IMF₄-component. (**e**) IMF₅-component. (**f**) IMF₆-component. (**g**) IMF₇-component.

The basic idea of EMD is to decompose the signal into IMF components from high to low frequencies [31] so that the characteristics of the extracted PD signal can be displayed at different resolutions. Figure 10 shows that the frequency of the IMF₁ component is the highest, and the frequency of each IMF component decreases in turn. Different IMF components represent different time scales, and the main characteristics of PD signals cannot be clearly observed in these IMF components. Therefore, EMD cannot adequately suppress the periodic narrowband interference in PD signals.

4.4. Suppression Effect of EMD on White Noise

In Section 3.4 the signal after periodic narrowband interference suppression is decomposed by EMD, and the IMF components obtained are shown in Figure 11.



Figure 11. Cont.



Figure 11. Cont.



Figure 11. EMD for PD superimposed white noise interference signal. (a) IMF₁-component. (b) IMF₂-component. (c) IMF₃-component. (d) IMF₄-component. (e) IMF₅-component. (f) IMF₆-component. (g) IMF₇-component.

Figure 11 shows the high frequency components are IMF_1 and IMF_2 , and they contain obvious partial discharge simulation signal distribution characteristics. In other words, the IMF_1 and IMF_2 components contain the main characteristics of the PD signals. The signals corresponding to the IMF_1 and IMF_2 components are reconstructed, and the waveform thus obtained is shown in Figure 12. The values SNR = 0.70, NCC = 65.89%, MSE = 0.29 are obtained by calculating the SNR, NCC, and MSE of the reconstructed signals. From the reconstructed signal waveform and calculated results, it can be observed that even though the EMD is better than the SVD method in suppressing white noise interference, there is still considerable residual noise.



Figure 12. White noise interference suppression achieved by the EMD method.

5. IEMD Method for Interference Suppression of PD Signal

5.1. IMF Component Processing Method Based on Improved 3 σ Criterion

The main reason the EMD method has more residual interference in white noise suppression is the phenomenon of mode mixing in the IMF component. As shown in Figure 11, white noise interference and PD signals are still aliased together within the IMF component. To solve this problem, this paper introduces the 3σ criterion commonly used in gross error detection [32,33]. Gross error is defined as the error which does not have a clear distribution law or follow a random distribution law in the error theory. The IMF components obtained after the EMD of white noise interference contained in the PD signal still follow a random distribution [34], whereas the PD signal does not obey this distribution rule. The PD signal can be regarded as the "gross error," and statistical processing can be conducted according to the 3σ criterion to realize the separation of white noise interference and PD signals.

As the PD signal is a damped oscillation wave, to extract the PD signal from the IMF components more accurately, this paper makes improvements on the basis of the

traditional 3σ criterion and conducts statistical processing on each IMF component based on the improved 3σ criterion. The specific process is as follows:

- (1) Estimate the absolute value of each sequence of IMF component $h_i(t)$ to obtain the absolute value sequence f(t). The standard deviation of f(t) is obtained as σ , and the threshold th = 3σ .
- (2) According to the threshold, identify the "gross error" outside the threshold range in the $h_i(t)$ component.
- (3) A new sequence f'(t) is obtained by removing the "gross error" from the f(t) sequence. The standard deviation of f'(t) is σ' , and th' = $3\sigma'$.
- (4) Assess whether a "gross error" exists in $h_i(t)$. If so, go back to Step (3). If not, end the statistical processing.

Signal reconstruction was conducted for each IMF component after statistical processing. The comparison between the obtained waveform and the original PD signal is shown in Figure 13. As shown in the figure, the PD signal was restored and the white noise interference suppression effect is good.



Figure 13. White noise interference suppression achieved by the IEMD method.

Based on these results, it can be concluded that SVD has obvious advantages in periodic narrowband interference suppression of the PD signal compared with EMD, and the EMD method based on the improved 3σ criterion can make up for the deficiency of SVD in the suppression of white noise interference of the PD signal. In summary, this paper proposes a new PD signal interference suppression method that combines SVD and EMD based on the improved 3σ criterion. The specific steps are as follows:

- (1) The PD signal with periodic narrowband interference and white noise interference is decomposed by SVD.
- (2) According to the singular value distribution characteristics of the periodic narrowband interference signals, the singular value corresponding to periodic narrowband interference is determined and set to zero. Signal reconstruction is completed by an inverse SVD operation, and periodic narrowband interference suppression is realized.
- (3) The IMF component is obtained by EMD of the signal after SVD interference suppression.
- (4) Based on the improved 3σ criterion, the IMF components are statistically processed.
- (5) The IMF component after processing is reconstructed to achieve the suppression of white noise interference to obtain the PD signal.

5.2. Comparison of Interference Suppression Effects

The PD signals with periodic narrowband and white noise interference in Section 2.2 were suppressed according to the method described in this paper. As a comparison, the above PD signals were processed by the SVD and the SVD + EMD methods. The results are shown in Figure 14. Compared with Figure 14, it can be observed that the SVD method leads to an obvious inefficient suppression of white noise interference, and the PD signal cannot be effectively extracted. The residual noise of the waveform is larger after the



elimination of the interference by the EMD. The proposed method can effectively suppress periodic narrowband and white noise interference.

Figure 14. Results of interference suppression methods. (a) Interference suppression results of the proposed method. (b) Interference suppression results of SVD. (c) Interference suppression results of SVD + EMD.

The SNR, NCC, and MSE interference suppression results of the three methods were obtained and are listed in Table 3. It can be shown that the method proposed in this paper has a better effect on the suppression of periodic narrowband and white noise interference and can restore the PD pulse waveform more effectively.

Noise Reduction Method	Signal-to-Noise Ratio (SNR)	Normalized Correlation Coefficient (NCC)	Mean-Squared Error (MSE)
Method used in this paper	14.86	98.35%	0.01
SVD	0.52	65.05%	0.33
SVD + EMD	0.70	65.89%	0.29

Table 3. Denoising evaluation of simulation signal results.

6. Actual Measurement of PD Interference Suppression

To verify the effectiveness of the proposed interference suppression method for the measured PD signal, a PD detection experiment with 10 kV XLPE electric cables was conducted in the laboratory. The data acquisition card model used is PicoScope 6000 Series (the maximum sampling rate was 5 GS/s), the experimental circuit diagram is shown in Figure 15: T₁ is a voltage source, T₂ is a voltage regulator, T₃ is a transformer, R is protective resistance, C_X is the test object, C_K is coupling capacitance, and Z is detection impedance (GSJFY-3000, the bandwidth is 350 MHz). The measured PD signal is shown in Figure 16, where the sampling frequency is 100 M Samples/s and the sampling time is 20 µs. The measurement results may contain direct current (DC) components. It is necessary to calculate the mean value of the signal sequence to determine whether there are DC components. The average value of the signal sequence, m = 1.86, was obtained, and this average value was removed, i.e., $x_2(i) = x(i) - m$; the resulting signal with the DC component eliminated is shown in Figure 17.



Figure 15. Experimental circuit diagram.



Figure 16. Partial discharge measured in the laboratory.



Figure 17. Laboratory measurement signal with DC component removed.

The proposed method and the SVD and EMD methods are used for interference suppression processing of the measured signals, and the interference suppression results are shown in Figure 18.



Figure 18. Denoising results of partial discharge signal measured in the laboratory. (**a**) Denoising results of the proposed method. (**b**) Denoising results of SVD. (**c**) Denoising results of SVD + EMD.

The noise suppression ratio is used to evaluate the interference suppression results, and is calculated as follows:

$$\rho = 10(\lg\sigma_1^2 - \lg\sigma_2^2) \tag{15}$$

In Equation (15), σ_1 and σ_2 are the standard deviations of signals before and after interference suppression, respectively. The noise suppression ratio ρ can reflect the degree of interference suppression. The larger the value is, the higher the noise reduction rate is. The noise suppression ratio of the three methods was calculated, and the results are shown in Table 4. The comparison shows that the proposed method is more effective in suppressing periodic narrowband and white noise interference.

Table 4. Evaluation of denoising results of PD signals measured in the laboratory.

Noise Reduction Method	Method Used in This Paper	SVD	SVD + EMD
ρ	14.17	11.09	12.11

7. Conclusions

In this paper, a PD interference suppression method based on SVD and IEMD was proposed. This method can suppress periodic narrowband and white noise interference in PD signals. The effectiveness of the proposed method was verified based on the simulation and analysis of the measured results. The following conclusions were obtained:

- (1) The singular value distribution characteristics of periodic narrowband interference are obvious. SVD can effectively suppress the periodic narrowband interference in PD signals, but it has poor suppression effects on white noise interference.
- (2) EMD is better than SVD in suppressing white noise interference, but SVD has obvious advantages in suppressing periodic narrowband interference.
- (3) Based on the improved 3σ criterion, statistical processing of the IMF derived from EMD can effectively solve the problem of mode mixing of EMD and can more effectively suppress the interference of white noise.
- (4) Compared with SVD and SVD + EMD interference suppression methods, the proposed method yields larger SNR values, waveform similarity coefficients closer to unity, smaller MSE values, and larger noise suppression ratios. For the simulated and measured signals, the PD pulse waveform can be restored more effectively.

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